

# TPE-Det: A Tamper-Proof External Detector via Hardware Traces Analysis Against IoT Malware

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**Abstract**—With the widespread use of Internet of Things (IoT) devices, malware detection has become a hot spot for both academic and industrial communities. A series of solutions based on system calls, system logs, or hardware performance counters achieve promising results. However, such internal monitors are easily tampered with, especially against adaptive adversaries. In addition, existing system log records typically exhibit substantial volume, resulting in data explosion problems. In this article, we present **TPE-Det**, a side-channel-based external monitor to cope with these issues. Specifically, **TPE-Det** leverages the serial peripheral interface bus to extract the on-chip traces and designs a recovery pipeline for operating logs. The advantages of this external monitor are adversary-unperceived and tamper-proof. The restored logs mainly include file operation commands, which are lightweight compared to complete records. Meanwhile, we deploy a series of machine learning models with respect to statistical, sequence, and graph features to identify malware. Empirical evaluation shows that our proposal has tamper-proof capability, high-detection accuracy, and low-time/space overhead compared to state-of-the-art methods.

**Index Terms**—Internet of Things (IoT) security, malware detection, serial peripheral interface (SPI) bus, tamper-proof external monitor.

## I. INTRODUCTION

**M**ALWARE continues to be prevalent in Internet infrastructure nowadays and has caused profound attention from the security community [1]. Although malware is not a new threat, the boom of Internet of Things (IoT) [2], [3] broadens and amplifies its attack surface. In other words, the recent surge in embedded device adoption and the IoT revolution is rapidly changing the malware landscape. Unfortunately,

these IoT devices are often highly vulnerable to attack and might be used to create large, powerful botnets [4]. Most famously, Mirai was used to launch vast volumetric DDoS [5], [6], [7], [8], [9], e.g., Dyn, a DNS provider, suffered a 1.2 Tbps attack.

In recent years, researchers have proposed a series of methods to detect malware, but this arms race does not end there as adversaries deploy some counter-reconnaissance strategies. For example, some typical methods [10], [11] collect system logs or system calls [12] for malware detection. However, these solutions are adversary-perceived, i.e., attacker can be aware of the existence of the detection program through scanning processes or checking some dynamic fields [13]. Then, the attacker could try to inject fake state data into the system [14], tamper with system logs [15], or directly kill the monitor process [16]. This ultimately leads to detection failure, also for some hardware performance counters (HPCs) [17], [18]-based solutions.

In summary, existing solutions have the following limitations.

- 1) *Adversary-Perceived*: Given that most detection programs are deployed inside the system, adversary perception is possible through system state inspection or process scanning [13]. As shown in Fig. 1, such adversary perception capabilities may be the first step in subsequent counter-reconnaissance activities.
- 2) *Expose Risks for Tampering*: After attackers perceive the existence of an internal monitor, they may perform a series of tampering operations to hide or delete their attack traces. Since the log records used for detection are retained on the victim device, they can easily be maliciously tampered with [14] and [16]. In Fig. 1, on the one hand, the attacker may directly kill the internal monitoring program. On the other hand, they may also tamper with the recorded logs. Either process killing or wrong logs will directly cause the internal monitor to fail [15].
- 3) *Huge Logging Records*: Moreover, an additional problem is that the existing logging methods are redundant and bulky [19], [20]. Specifically, previous solutions, such as using syscall or syslog, usually consume >100-MB space overhead for recording behavior of ~10K malware. This is not practical in real-world scenarios because one of the characteristics of IoT devices is limited available resources [21].

Considering the above problems of internal monitors [22], we intend to develop an external monitor to advance this

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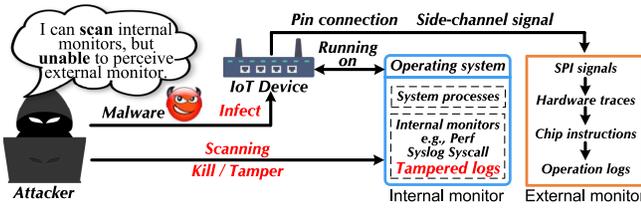


Fig. 1. Illustration of internal and external monitors.

79 landscape. In this article, we present TPE-Det, a Tamper-  
 80 Proof External monitor for malware Detection. We leverage  
 81 the hardware design knowledge of bus-connected system-  
 82 on-a-chip (SoC) and design TPE-Det based on the serial  
 83 peripheral interface (SPI) bus to monitor and analyze the  
 84 on-chip instructions. Then, we develop a suite of pipelines  
 85 to recover system file operation logs to realize information  
 86 collection in a side-channel manner (“orange box” in Fig. 1).  
 87 Finally, typical machine learning (ML) models and tailor-  
 88 made deep neural networks (DNNs) are deployed to identify  
 89 malware.

90 In a nutshell, we make the following contributions.

- 91 1) We investigate the limitations of existing malware detec-  
 92 tion schemes against adaptive adversaries. A series of  
 93 issues are revealed, including that internal detectors,  
 94 could be perceived by adversaries, monitoring processes  
 95 being killed by attackers, and the exposed risk of logs  
 96 being tampered with.
- 97 2) We propose a novel external monitor, named TPE-Det,  
 98 that leverages the SPI bus to capture on-chip traces  
 99 and design the operating logs recovery pipeline in a  
 100 side-channel manner. Since TPE-Det is external to the  
 101 device, it is tamper-proof and the adversary cannot  
 102 perceive the existence of TPE-Det. An extra benefit is  
 103 that the recorded logging of TPE-Det is concise.
- 104 3) We deploy a series of ML models and tailored DNNs  
 105 with respect to statistical, sequence, and graph features  
 106 to perform malware identification.
- 107 4) Empirical evaluations on our physical testbed demon-  
 108 strate that TPE-Det clearly outperforms state-of-the-art  
 109 (SOTA) methods, especially when against adaptive  
 110 adversaries. We also conduct a series of experiments for  
 111 concept drift, overhead evaluation, and providing more  
 112 deep insights.

## 113 II. RELATED WORK

114 Existing IoT malware detection approaches can be roughly  
 115 categorized into hardware-based (host-based) and network-  
 116 based ones, we outline the related work here.

### 117 A. Hardware/Host-Based Methods

118 Hardware/host-based methods [23] aim to extract the pro-  
 119 cessor fingerprint from different programs running on the IoT  
 120 devices. Some previous arts [17], [18], [24], [25] propose  
 121 to detect malware based on HPCs runtime information. The  
 122 hardware part design of TPE-Det is different from the HPC-  
 123 based method in the following two aspects. For one thing, the

124 previous methods use HPC to detect malware, which is the  
 125 classification problem. Our hardware-part design focuses on  
 126 recovering operation logs for forensic analysis. Log recovery  
 127 using HPC could be difficult because the available events  
 128 are very limited (e.g., *cpu-cycles*, *cpu-clock*, *L1-dcache-loads*,  
 129 etc.) and the count results are usually numeric variables. For  
 130 another, more importantly, the process (e.g., *perf* tool [19]) for  
 131 statistics HPC can be killed by adaptive adversaries like that  
 132 the attacker kills internal monitors (mentioned in Section I).  
 133 In addition, the number of available HPCs is limited on  
 134 today’s microprocessors. And HPCs rely on the operating  
 135 environment, especially existing work [26], [27] reveals that  
 136 measured HPC values collected for the same program running  
 137 inside a virtual machine (VM) substantially differ from those  
 138 collected on a bare-metal system. Costin et al. [28] con-  
 139 ducted a large-scale firmware analysis for embedded devices.  
 140 PREEMPT [26] repurposes the embedded trace buffer (ETB)  
 141 to collect signal values through the joint test action group  
 142 (JTAG) debug interface and connect the host machine via  
 143 universal asynchronous receiver-transmitter (UART). Different  
 144 from them, TPE-Det introduces a new direction that utilizes  
 145 side-channel SPI signals to recover logs.

146 Another typical scheme captures system calls, e.g.,  
 147 HRAT [12] constructs function call graph to profile malware’s  
 148 behavior. Moreover, system logs are usually used to analyze  
 149 whether there is malicious activity, e.g., Deeplog [11] deploys  
 150 recurrent neural network (RNN) and FedTrans [29] leverages  
 151 Transformer to model log records. IoTGuard [30] implements  
 152 a code instrument to collect the app’s information at run-  
 153 time by adding extra logic. Meanwhile, some technologies,  
 154 such as data compaction [31] and alternative tag propagation  
 155 semantics [32], are presented to combat dependence explo-  
 156 sion in long-term monitoring. However, these methods could  
 157 be adversary-perceived and the logs can be tampered with.  
 158 Therefore, TPE-Det explores a new perspective and utilizes  
 159 SPI signal to restore operation commands in a side-channel  
 160 manner, realizing tamper-proof capability.

### 161 B. Network-Based Methods

162 Network-based methods tend to profile the special traffic  
 163 pattern when the IoT devices are remoted intrusion [33], [34].  
 164 To profile the traffic pattern, some works [35], [36], [37]  
 165 design supervised learning methods based on statistical fea-  
 166 tures, e.g., random forests (RFs). And some other arts utilize  
 167 Markov [38] or RNNs [39], [40], [41] to portray the sequen-  
 168 tial features (e.g., packet length sequence) of attacks. For the  
 169 IoT devices, Gu et al. [42] presented IoTGaze to discover  
 170 the threats by sniffing event interaction in wireless traffic.  
 171 Wang et al. [43] performed a cross-analysis for mobile  
 172 companion apps to evaluate IoT devices’ security.

173 Although traffic capture programs, such as *tshark*, can also  
 174 be killed or packets could be tampered with, monitoring  
 175 network traffic is a promising approach, that is orthogonal to  
 176 host-based detection and they also can be combined [4]. A rep-  
 177 resentative art, Hawkware [10] combines traffic analysis and  
 178 system calls to detect malware. Overall, we select four ETB-  
 179 based models (from PREEMPT), 12 HPC-based ML/ensemble

180 models, HRAT, Deeplog, FedTrans, and Hawkware as the  
 181 baselines in evaluations.

### 182 III. MOTIVATION

183 In this section, we clarify the motivation for the design of  
 184 TPE-Det. First, we explain that even malware that infects  
 185 random access memory (RAM) will perform a series of file  
 186 operations on read only memory (ROM). Then, we introduce  
 187 the benefits of external monitors in terms of adversary-  
 188 unperceived and tamper-proof. Finally, we form the core idea  
 189 of designing an external monitor to track file operations using  
 190 SPI, and explain how it will be beneficial in some real-world  
 191 scenarios.

192 1) *Why Malware Infections Involve File Operations?* An  
 193 observation is that the evolution of IoT malware tends  
 194 to use many persistence methods, such as installing  
 195 themselves as either a service, a startup script, a system  
 196 module, or a backdoor [4]. This persistent malware  
 197 usually implants malware viruses into the electrically  
 198 erasable programmable ROM (EEPROM) to achieve  
 199 persistence on IoT devices. In addition, even typical  
 200 malware that infects RAM will perform a series of file  
 201 operations on ROM. For example, Mirai can read the  
 202 executable binary into RAM for malicious activities,  
 203 while it also involves some operations on ROM, such as  
 204 using *cat*, to analyze architecture (e.g., *e\_machine* field);  
 205 using *wget*, *ftp*, or *echo* to transfer the payload [44].  
 206 More details can be found in Section VI-E. These file  
 207 operations on ROM can be captured by SPI, so we intend  
 208 to leverage SPI signals to analyze on-chip traces.

209 2) *What Are the Benefits of Using an External Monitor?*  
 210 Using internal monitor to obtain details of malware  
 211 is a viable scheme, such as causality analysis for  
 212 system logs [45], [46], [47] or adopt system hooking for  
 213 investigation [30]. However, these proposed techniques  
 214 have some limitations. On the one hand, the internal  
 215 monitor could be adversary-perceived, e.g., the attacker  
 216 may detect the existence of a running monitor by  
 217 checking some dynamic fields [13]. On the other hand,  
 218 internal monitors are prone to be subverted, e.g., the  
 219 attacker could tamper with operation log files [14], [15]  
 220 even directly kill the monitoring process [16], [48].  
 221 Existing research [22], [49] suggests that if leveraging  
 222 hardware design knowledge to develop an external  
 223 monitor [50], such as a bus-connected SoC, it will tend  
 224 to be tamper-proof. PREEMPT [26] is a representative  
 225 external monitor, and we also compare it to illustrate  
 226 the advantages of TPE-Det in detection performance (in  
 227 Section VI).

228 3) *How Does TPE-Det Facilitate Real-World Security*  
 229 *Scenarios?* We elaborate here that TPE-Det could  
 230 promote typical security scenarios involving investi-  
 231 gation forensics and honeypots. For investigation  
 232 forensics [45], [46], [47], correct logs are necessary  
 233 to support practitioners in building threat intelligence,  
 234 correlation analysis, etc. The attacker could tamper  
 235 with logs or kill processes to cause the failure of

internal monitors [15], [16] (as stated above), which  
 will directly affect the forensic results (we develop the  
 adaptive adversary experiments in Section VI-D). For  
 IoT honeypots [51], [52], serve as critical tools in the  
 cybersecurity landscape, they are used to attract attack-  
 ers and capture/collect malicious behaviors. However,  
 an adaptive attacker [13], [53] will actively terminate  
 its attack behavior when it senses the presence of a  
 monitoring process, this will result in the honeypot  
 being unable to collect corresponding threat intelli-  
 gence and attack information. Given that TPE-Det is  
 adversary-unperceived and tamper-proof, it could facili-  
 tate investigation forensics and honeypot scenarios.

### 249 IV. ASSUMPTIONS AND THREAT MODEL

#### 250 A. Adversary Model

251 We consider strong/adaptive adversaries that adopt various  
 252 attack strategies. They could exploit remote transmission to  
 253 implant malware/viruses or leave them into the IoT devices'  
 254 built-in chips to achieve potential persistent attacks, including  
 255 malware, that infects RAM or residing in ROM, e.g., Mirai [5]  
 256 and Hajime [6]. These malicious activities/executions will  
 257 involve a series of file operations [5], [6], e.g., file creation,  
 258 writing, permission modification, and self-induced deletion.  
 259 More importantly, *adaptive adversaries* indicate that a series  
 260 of counter-reconnaissance technologies will be deployed.  
 261 Specifically, the attacker will scan the processes running on  
 262 the victim device, and once the presence of internal monitors  
 263 is discovered, they will directly kill the program or tamper  
 264 with the recorded logs.

#### 265 B. Assumptions

266 We explain some assumptions here. Given that TPE-Det  
 267 needs to collect SPI signals for the protected device, so  
 268 physical access is required. We admit that physical access may  
 269 not be convenient sometimes, but such an external monitor  
 270 is promising, especially in facilitating real-world security  
 271 scenarios, e.g., investigation forensics and honeypots (stated  
 272 in Section III). We also perform more security discussions in  
 273 Section VII-A. Although our physical testbed has a specific  
 274 architecture, our approach is not limited to architecture and  
 275 the detector has cross-architecture capabilities (Section VI-E).  
 276 Furthermore, we intend to enable hardware trace monitoring  
 277 before infection to avoid missing some malicious behavior.  
 278 This assumption is similar to typical anti-virus software, in  
 279 which practitioners usually run anti-virus programs in advance  
 280 to detect potential malware [54].

### 281 V. DESIGN OF TPE-DET

282 In Fig. 2, we depict the high-level architecture of TPE-Det.  
 283 Consider a running IoT device, which the SPI bus can be  
 284 used to dump content for Flash chips. We connect the SPI  
 285 bus in parallel with a logic analyzer that parses the digital  
 286 signals to the Flash traces. These traces will be recovered as  
 287 system operating logs, which could be fed to ML models for  
 288 classification.

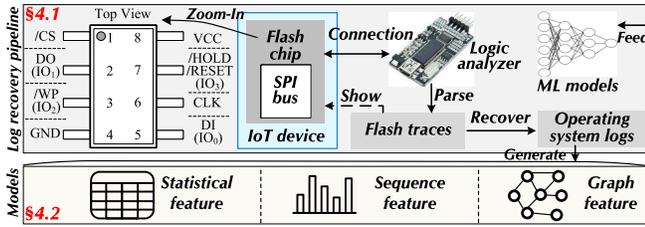


Fig. 2. Overview of TPE-Det.

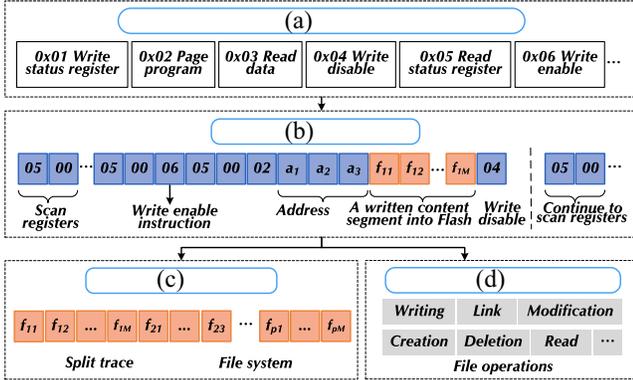


Fig. 3. Log recovery pipeline of external monitor. (a) SPI signal digitization (instruction). (b) Flash trace. (c) Structure file system. (d) Operation log recovery.

## 289 A. External Monitor and Log Recovery

290 We clarify here the proposed design pipeline to externally  
 291 recover the operation log in the file system, as shown in Fig. 3.  
 292 The so-called “externally recover logs” refers to the external  
 293 monitor (e.g., leveraging SPI signals), not the internal monitor,  
 294 so as to make the adversary imperceptible and tamper-proof.

295 *Collect the Digital Signals:* To acquire digital signals  
 296 emanating from the Flash chip integrated within an IoT device,  
 297 a logic analyzer is interfaced in parallel with the SPI bus’s  
 298 pins. This logic analyzer, serving the role of a physical probe,  
 299 is affixed to the SPI pins and executes periodic sampling  
 300 with the frequency  $F_l$ . Note that  $F_l > 2 \times F_o^{\max}$  should be  
 301 satisfied according to the Nyquist–Shannon sampling theorem,  
 302 where  $F_o^{\max}$  denotes the maximum frequency of the original  
 303 signals. The specific sampling frequency setting is explained  
 304 in Section VI-A. Upon collection, the resultant sampling data  
 305 are archived within an upper computer system.

306 *Extract the Flash Traces:* The collected digital signals  
 307 mainly consist of the chip instructions<sup>1</sup> and the content written  
 308 into Flash (i.e., the nonvolatile data). The chip instructions are  
 309 related to the chip type and the physical state, so the specific  
 310 instruction hex can be confirmed according to the correspond-  
 311 ing chip manual. For instance, the W25Q128BV [55] chip<sup>2</sup>  
 312 has some instructions, and their hexadecimal as follows.

313 1) 0x01: Write Status Register Instruction.

<sup>1</sup>They refer to the SPI instruction set and are fully controlled through the SPI bus, e.g., the W25Q128FV contains 45 basic instructions [55].

<sup>2</sup>Particularly, our design does not depend on a specific chip and only needs to satisfy the above-mentioned Nyquist–Shannon sampling theorem. According to product reports of the chip manufacturer, the maximum frequency of common SPI Flash chips is 80–133 MHz [56]. Modern logic analyzers support a sampling rate of 500 MS/s [57].

- 2) 0x02: Page Program Instruction. 314
- 3) 0x03: Read Data Instruction. 315
- 4) 0x04: Write Disable Instruction. 316
- 5) 0x05: Read Status Register Instruction. 317
- 6) 0x06: Write Enable Instruction. 318

319 These chip instructions are instrumental in analyzing the  
 320 SPI trace, enabling us to discern the executed operations, such  
 321 as “Read” and “Write.” Furthermore, they allow us to ascertain  
 322 the specific nonvolatile data content and its corresponding  
 323 address. As illustrated in Fig. 3(b), we can extract the Flash  
 324 traces, e.g.,  $\langle a_1, a_2, a_3 \rangle$  represents the 24-bit address and  
 325  $\langle f_{11}, f_{12}, \dots, f_{1M} \rangle$  refers to content segments written.

326 *Structure the File System:* In this step, TPE-Det will  
 327 meticulously structure the file system to assemble segments.  
 328 The primary objective of this process is to enhance the  
 329 comprehension of the nonvolatile data’s content and its precise  
 330 storage location within the device. This insight is invaluable  
 331 for practitioners, as it provides a deeper understanding of the  
 332 attack mechanisms, which is essential for forensic investiga-  
 333 tions. Note that this process does not influence the malware  
 334 detection phase, given the subsequent models rely solely on  
 335 the features derived from operation commands, as elaborated  
 336 in Section V-B.

337 In reality, the structuring process is inherently related to the  
 338 file system architecture. When employing various file systems,  
 339 the necessary adaptation is confined to modifying the mapping  
 340 procedure that correlates storage addresses with file direc-  
 341 tories, as well as the decompression algorithm (customarily  
 342 deployed to economize on space overhead) for the nonvolatile  
 343 data. We implement a prototype for the journaling flash  
 344 file system (JFFS2) [58] log structure<sup>3</sup> used in our testbed.  
 345 Specifically, within the JFFS2 framework, there are two data  
 346 entities that are intimately associated with file operations, i.e.,  
 347  $jffs2\_raw\_dirent$  and  $jffs2\_raw\_inode$ .

348 We can discern these two data entities by examining the  
 349 parameter  $magic + nodetype$ , and ascertain the entity length  
 350 utilizing the parameter  $totlen$ . The entity  $jffs2\_raw\_dirent$   
 351 is responsible for delineating the file’s location, specifically  
 352 within its parent directory, while  $jffs2\_raw\_inode$  is tasked  
 353 with retaining the file’s management information. Notably,  
 354 the latter contains the actual written content within the  
 355 Flash memory in its  $data$  parameter and leverages the  $mode$   
 356 parameter to document file types and modes. For example,  
 357  $\{S\_IXOTH: 01\}$  denotes the execute or search permission  
 358 bit for other users, and  $\{S\_IWOTH: 02\}$  denotes the write  
 359 permission bit for other users [60]. Based on these two entities,  
 360 we mount corresponding nodes to structure the tree-shaped  
 361 file system. Considering that the content may be compressed  
 362 to conserve space, we apply the corresponding decompression  
 363 algorithm (stored in the  $compr$  of  $jffs2\_raw\_inode$ ) to retrieve  
 364 the complete data. For example, the compression algorithms  
 365 of JFFS2 and their hexadecimal are  $\{ZERO: 0x01, RTIME:$   
 366  $0x02, RUBINMIPS: 0x03, COPY: 0x04, DYNRUBIN: 0x05,$   
 367  $ZLIB: 0x06, LZ0: 0x07\}$ . By employing the above process,

<sup>3</sup>JFFS2 is widely used in IoT devices due to its power-disconnected reliability and space-efficient properties [58], such as [59] mentioned that 333 firmware was collected from Axis Communications (a network camera device manufacturer), and about 85% of them use the JFFS2 file system.

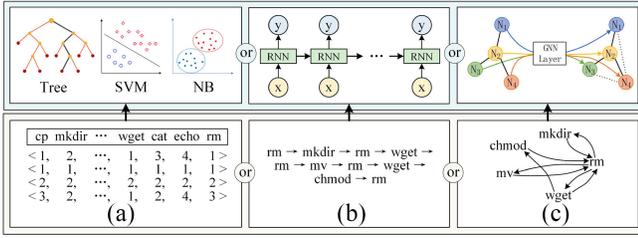


Fig. 4. Models regarding three types of features. (a) Statistical feature. (b) Sequence feature. (d) Graph feature.

we are able to accurately map file addresses and meticulously parse the contents of nonvolatile data.

*Recover the Operating System Logs:* Upon structuring the file system, we can glean a wealth of information, including file types, names, permissions, contents, access timestamps, and so on. This available comprehensive information on nodes can subsequently be harnessed to reconstruct the behavior logs of the operating system. For example, *emerging instances of entities*  $\rightarrow$  *file creation*; *changing the entities' contents*  $\rightarrow$  *file writing*; and *mounting the entities to the garbage collection node*  $\rightarrow$  *file deletion*. The logs that are recovered encompass a range of file operations, such as creation, deletion, reading, writing (including content), permission modifications, timestamps of the last modification, soft links, and more. Readers might be concerned about the potential impact on the log recovery process if adversaries were to tamper with system logs or eliminate binary scripts (as mentioned in Section IV). However, as long as the SPI signal collection is conducted proactively, TPE-Det can recover the operation log even if the malicious script is deleted, attacker's tampering will also be recorded. This robust capability stems from the design of TPE-Det as an external monitoring tool. All file operations, such as reading, permission modifications, deletions, and so forth, are meticulously recorded and archived on an upper computer for log recovery purposes.

### B. ML Models for Detection

As shown in Fig. 2, the system operation logs will be fed into ML models<sup>4</sup> for malware identification. In Fig. 4, we deploy TPE-Det with a series of models that regard the statistical feature, sequence feature, and graph feature.

1) The statistical feature refers to counting commands in a fixed order to form a vector. For example, given a statistical feature vector  $\{C_1:i_1, C_2:i_2, \dots, C_n:i_n\}$ , it means that  $i_1$   $C_1$  commands,  $i_2$   $C_2$  commands,  $\dots$ ,  $i_n$   $C_n$  commands are involved. We use a series of ML models to analyze the statistical feature, including decision tree (DT), RF, support vector machine (SVM), XGBoost (XGB), and Naive Bayes (NB). All these models are set with default parameters of Python *scikit-learn* library.

<sup>4</sup>System operation logs can also be combined with lightweight rule-matching methods for detection and analysis. Given the wide application of ML technology in IoT security [61], [62], [63], we tend to use a series of ML models for analysis here so that we can perform a fair comparison with existing works that use ML to analyze logs from HPC, *Syslog*, *Syscall*, etc.

2) The sequence feature refers to the command calling sequence of malware. Fig. 4(b) displays the partial command execution sequence of malware whose MD5 is *7044865a1cfd07535400d7e041786940*. It performs a series of operations, including *rm*, *mkdir*, *rm*, *wget*, etc. We use long short-term memory (LSTM) [64], a typical RNN model, to identify these sequence features to discover behavioral patterns commonly used by attackers. In the  $t$ th time step operation of the LSTM unit, the forget gate  $f_t$  can be calculated as

$$f_t = \sigma(W_f \cdot [h_{t-1}, X_t] + b_f) \quad (1)$$

where  $h_{t-1}$  is the current hidden state and  $X_t$  denotes the  $t$ th input, i.e., the one-hot encoded vector of  $t$ th operation. The memory gate  $v_t$  can be computed as follows:

$$v_t = \sigma(W_v \cdot [h_{t-1}, X_t] + b_v). \quad (2)$$

And the temporary memory cell  $\tilde{C}_t$  is computed by

$$\tilde{C}_t = \tanh(W_c \cdot [h_{t-1}, X_t] + b_c). \quad (3)$$

Then, the next cell state can be updated as follows:

$$C_t = f_t \cdot C_{t-1} + v_t \cdot \tilde{C}_t. \quad (4)$$

Finally, the output gate  $o_t$  can be obtained as

$$o_t = \sigma(W_o \cdot [h_{t-1}, X_t] + b_o). \quad (5)$$

And the next hidden state can be calculated as follows:

$$h_t = o_t \cdot \tanh(C_t). \quad (6)$$

Finally, the hidden state of the last step is used to obtain the final classification results  $\hat{Y}$  with a fully connected layer  $f_c$  ( $W_c$ ) and a Softmax function. Notably, the above parameter matrices  $W$  and  $b$  are all learnable parameters

$$\hat{Y} = \arg \max(\text{Softmax}(W_c \cdot h_t)). \quad (7)$$

3) The graph feature is formed in a similar way to the sequence feature, the difference is that the same commands correspond to one node in the graph structure. As Fig. 4(c) shows, it uses a directed graph record, i.e.,  $(N_1 \rightarrow N_2) \neq (N_2 \rightarrow N_1)$  since their order is different. Intuitively, graph-structure records focus on call dependencies and are relatively robust even in the presence of obfuscation operations. Then, we analyze the operation command graph based on the traditional graph neural network (GNN) model [65], whose node features iteratively with

$$h_v^{(k)} = \phi\left(h_v^{(k-1)}, f\left(\left\{h_u^{(k-1)} : u \in \mathcal{N}(v)\right\}\right)\right) \quad (8)$$

where  $\mathcal{N}(v)$  represents a set of nodes adjacent and reachable to the node  $v$ . Meanwhile, the function  $\phi$  is injective and  $f$  operates on the set of neighbor nodes' feature vectors, which are called multisets. Also, the initial features  $h_v^{(0)}$  of the graph node refer to its one-hot encoded vector.

In practice, we use multilayer perceptrons (MLPs) to model and learn the composition of two functions  $f^{(k+1)} \circ \phi^{(k)}$ ,

456 thanks to the universal approximation theorem [66]. In the first  
 457 iteration, we do not need MLPs before summation if input  
 458 features are one-hot encodings as their summation alone is  
 459 injective. Then, the graph model updates node representations  
 460 as

$$461 \quad h_v^{(k)} = \text{MLP}^{(k)} \left( (1 + \epsilon^{(k)}) \cdot h_v^{(k-1)} + \sum_{u \in \mathcal{N}(v)} h_u^{(k-1)} \right) \quad (9)$$

462 where  $\epsilon$  is a learnable parameter or a fixed scalar.

463 Furthermore, the graph-level readout is performed based  
 464 on information from all depths/iterations of the model, due  
 465 to a sufficient number of iterations is the key to achieving  
 466 good discriminative power. To this end, we achieve this by  
 467 an architecture similar to Jumping Knowledge Networks [67],  
 468 where we make graph representations concatenated across all  
 469 iterations/layers of the model as follows:

$$470 \quad h_G = \text{CONCAT} \left( \sum_{v \in G} h_v^{(k)} | k = 0, 1, \dots, K \right) \quad (10)$$

$$471 \quad \hat{Y} = \arg \max(\text{Softmax}(W_c \cdot h_G)). \quad (11)$$

472 Finally, similar to the sequence model, the final classification  
 473 results  $\hat{Y}$  can also be obtained with a fully connected layer  
 474 and a Softmax function, as described in (11). In this way, this  
 475 model possesses the superior discriminative/representational  
 476 power based on the neighbor aggregation and graph readout  
 477 functions, so as to identify the malicious operations better.

## 478 VI. EVALUATION

479 In this section, we comprehensively evaluate TPE-Det in  
 480 terms of detection performance and overhead. Moreover, we  
 481 perform a series of experiments, including time/space concept  
 482 drift, deep insights, and adaptive adversary evaluation. Our  
 483 code is available online.<sup>5</sup>

### 484 A. Experiment Setup

485 *Testbed:* Our testbed is established with wireless router  
 486 (installed the W25Q128BV Flash [55], SPI bus, and MT7620  
 487 SoC chip), a logic analyzer (the Saleae Logic Pro 8 [57],  
 488 supports a maximum sampling rate of 500 MS/s), an upper  
 489 computer (installed an i7-9700 CPU, and 64 GB memory).  
 490 Among them, the router is the victim IoT device, and the  
 491 upper computer runs TPE-Det. The wireless router runs  
 492 OpenWrt [68] which the file system is JFFS2. For the logic  
 493 analyzer, we set the sampling rate is 500 MS/s, which means  
 494 that it could achieve 3–6 times oversampling for common  
 495 SPI Flash chips [56] (i.e., satisfies Nyquist–Shannon sampling  
 496 theorem). One end of the logic analyzer is probed on pins 1,  
 497 2, 4, 5, and 6 of the Flash chip (Fig. 5), while the other end  
 498 is connected to the upper computer.

499 *Parameter Settings:* All ML classifiers use the default  
 500 parameters of the Python *scikit-learn* library. For the LSTM,  
 501 we set the time step as 128, the hidden layer as 400, the  
 502 number of layers as 2, and the learning rate as 1e-3. For the  
 503 GIN, we set the number of hidden units as 64, the dropout

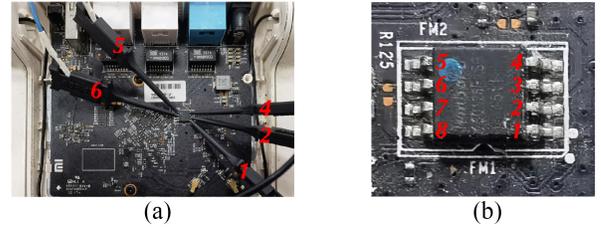


Fig. 5. Physical IoT device of TPE-Det testbed. (a) Connect pins to extract SPI signals. (b) Flash chip.

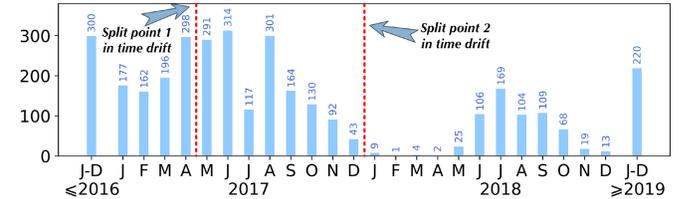


Fig. 6. Malware details of the dataset.

as 0.5, the GNN layers as 5, they are all consistent with the  
 original paper [65].

*Datasets:* The dataset used for evaluation is  
 ScriptDataset [16], including 3439 malicious Linux shell  
 scripts and 9337 benign firmware scripts. We depict the  
 distribution of malware over time in Fig. 6, spanning 2012  
 to 2020. Among them, most malware samples are mainly  
 concentrated in 2017 and 2018. For the dataset split, we  
 default to adapt  $\{train:test = 8:2\}$ . We also divide malware  
 as  $\{train:test = 5:5\}$  and  $\{train:test = 2:8\}$  to develop space  
 bias experiments and as two split points (red dotted lines) in  
 Fig. 6 to conduct time bias experiments [69]. Each group of  
 experiments will be performed 5 times with different random  
 seeds.

### 518 B. Detection Effect Evaluation

519 We first evaluate the malware detection effect of TPE-Det  
 520 and SOTA methods, including four ETB-based models, 12  
 521 HPC-based models, and four syscall/log-based schemes. For  
 522 four metrics (i.e., accuracy, precision, recall, and F1 score),  
 523 the average detection results and standard deviation are sum-  
 524 marized in Table I. We observe that our detectors based  
 525 on recovery command achieve dominant results, especially  
 526 GNN, XGB, RF, and LSTM (realize 95.87%–98.05% F1),  
 527 which clearly outperforms 20 baselines. For the baseline, the  
 528 syscall/syslog-based methods are generally better than ETB-  
 529 based and HPC-based schemes. Nonetheless, TPE-Det still  
 530 outperforms syscall/syslog-based methods by 3.91%–13.82%  
 531 F1 score. For ETB-based baselines (belonging to external  
 532 monitor), TPE-Det realizes >10.12% F1 score higher than  
 533 PREEMPT [26]. Regarding HPC-based baselines, we can  
 534 see that model ensembles indeed bring improvement, e.g.,  
 535 7.99%–30.99% F1 improvement. However, MLP-Boost (the  
 536 best in HPC-based) achieves 85.84% F1 (12.21% lower than  
 537 our GNN), this can be attributed to the amount of HPC  
 538 information is limited.

<sup>5</sup>Online repository: <https://github.com/Secbrain/TPE-Det/>.

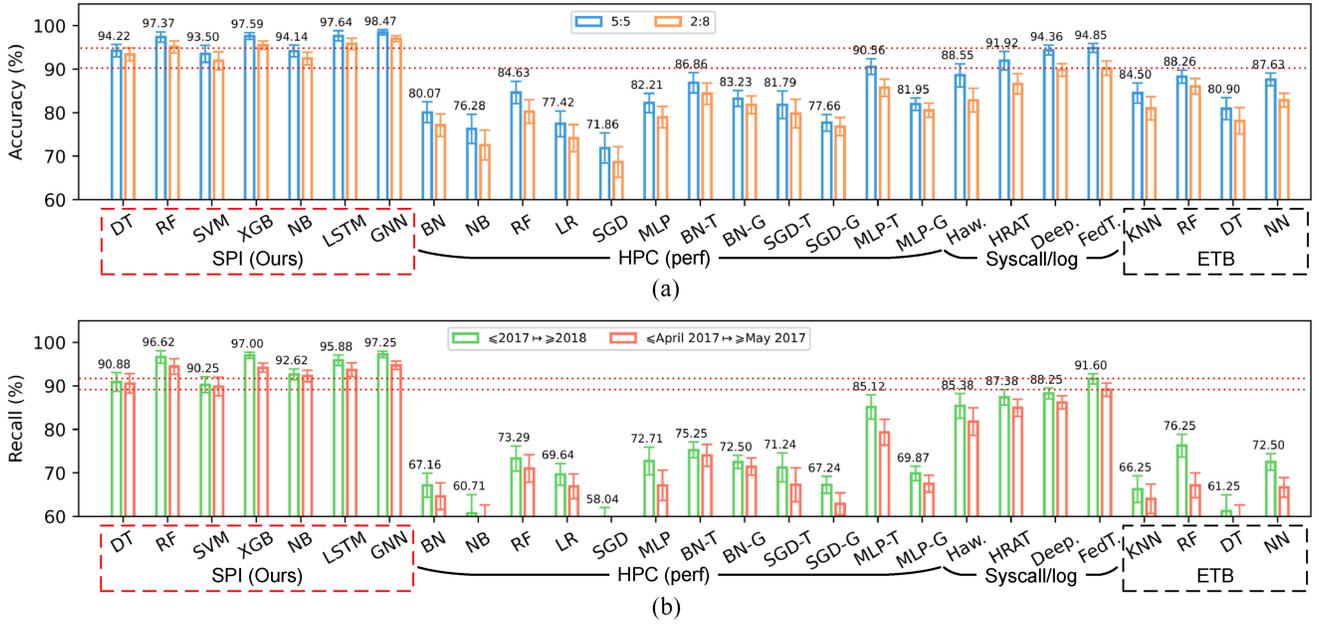


Fig. 7. Concept drift experiments in terms of space and time biases. (a) Space bias. (b) Time bias.

TABLE II  
DETECTION EFFECT (%) OF CONCEPT DRIFT EXPERIMENTS IN TERMS OF SPACE BIAS AND TIME BIAS

Drift Exper.	Model	Space bias								Time bias							
		{5 : 5}				{2 : 8}				≤2017 → ≥2018				≤April 2017 → ≥May 2017			
		Acc	Pre	Rec	F1	Acc	Pre	Rec	F1	Acc	Pre	Rec	F1	Acc	Pre	Rec	F1
SPI (ours)	DT	94.22	88.79	89.88	89.33	<b>93.39</b>	<b>86.49</b>	<b>89.39</b>	<b>87.92</b>	<b>93.51</b>	<b>87.91</b>	90.88	<b>89.37</b>	91.91	94.44	<b>90.53</b>	92.44
	RF	<b>97.37</b>	<b>94.44</b>	<b>95.87</b>	<b>95.15</b>	<b>95.09</b>	<b>90.18</b>	<b>91.75</b>	<b>90.95</b>	<b>96.44</b>	<b>91.91</b>	<b>96.62</b>	<b>94.21</b>	<b>94.49</b>	95.42	<b>94.44</b>	<b>94.93</b>
	SVM	93.50	87.60	88.37	87.98	<b>91.89</b>	<b>84.67</b>	<b>85.31</b>	<b>84.99</b>	92.65	85.95	90.25	88.05	91.16	93.74	<b>89.82</b>	91.74
	XGB	<b>97.59</b>	<b>95.21</b>	<b>95.87</b>	<b>95.54</b>	<b>95.50</b>	<b>91.10</b>	<b>92.29</b>	<b>91.69</b>	<b>96.85</b>	<b>92.82</b>	<b>97.00</b>	<b>94.87</b>	<b>94.90</b>	<b>96.41</b>	<b>94.18</b>	<b>95.28</b>
	NB	94.14	88.72	89.65	89.18	<b>92.46</b>	<b>85.64</b>	<b>86.48</b>	<b>86.06</b>	<b>94.41</b>	<b>89.17</b>	<b>92.62</b>	<b>90.86</b>	<b>93.10</b>	94.97	<b>92.27</b>	<b>93.60</b>
	LSTM	<b>97.64</b>	<b>95.01</b>	<b>96.28</b>	<b>95.64</b>	<b>95.82</b>	<b>91.83</b>	<b>92.73</b>	<b>92.28</b>	<b>95.88</b>	<b>90.88</b>	<b>95.88</b>	<b>93.31</b>	<b>94.61</b>	<b>96.34</b>	<b>93.69</b>	<b>95.00</b>
ETB	GNN	<b>98.47</b>	<b>96.88</b>	<b>97.44</b>	<b>97.16</b>	<b>96.99</b>	<b>93.80</b>	<b>95.09</b>	<b>94.44</b>	<b>97.98</b>	<b>96.05</b>	<b>97.25</b>	<b>96.65</b>	<b>95.94</b>	<b>97.80</b>	<b>94.71</b>	<b>96.23</b>
	KNN	84.50	69.09	76.73	72.71	80.98	63.94	67.28	65.57	78.63	63.86	66.25	65.03	68.91	75.39	64.03	69.23
	RF	88.26	77.08	80.22	78.62	86.04	72.64	77.21	74.85	84.43	73.05	76.25	74.62	73.52	81.19	67.11	73.49
	DT	80.90	63.14	69.75	66.28	78.08	58.96	61.11	60.01	74.50	56.98	61.25	59.04	62.83	68.75	58.67	63.31
	NN	87.63	75.96	79.06	77.48	82.83	66.90	71.76	69.23	82.56	70.30	72.50	71.38	71.82	78.53	66.67	72.12
	HPC (perf)	BN	80.07	62.58	64.51	63.53	77.11	57.12	60.09	58.57	79.30	65.01	67.16	66.07	76.54	89.53	64.62
NB		76.28	56.06	54.92	55.48	72.55	48.99	47.84	48.41	75.07	58.06	60.71	59.36	71.53	85.05	58.13	69.06
RF		84.63	71.12	72.19	71.65	80.24	63.01	64.45	63.72	82.94	70.86	73.29	72.05	81.69	94.05	70.98	80.90
LR		77.42	58.16	57.42	57.79	74.09	51.96	49.65	50.78	80.35	66.47	69.64	68.02	75.13	84.36	66.89	74.62
SGD		71.86	47.62	45.38	46.47	68.65	42.00	43.22	42.60	74.24	56.93	58.04	57.48	69.18	83.48	54.36	65.84
MLP		82.21	66.24	69.17	67.67	78.93	60.64	61.94	61.28	82.41	69.87	72.71	71.26	77.63	89.30	67.11	76.63
BN-Boost		86.86	74.64	77.55	76.06	84.34	70.26	72.56	71.39	84.36	73.33	75.25	74.28	83.00	93.54	74.00	82.63
BN-Bag		83.23	69.38	67.48	68.42	81.78	66.25	65.87	66.06	82.71	70.65	72.5	71.56	81.25	92.57	71.42	80.63
SGD-Boost		81.79	66.87	64.11	65.46	79.78	62.90	60.71	61.78	81.59	68.59	71.24	69.89	77.22	88.27	67.24	76.34
SGD-Bag		77.66	58.88	56.31	57.57	76.78	57.04	55.65	56.34	79.30	64.98	67.24	66.09	75.59	89.27	62.89	73.79
MLP-Boost	90.56	81.53	83.94	82.72	85.72	73.32	73.83	73.57	89.88	81.85	85.12	83.45	85.81	93.75	79.33	85.94	
MLP-Bag	81.95	66.87	65.27	66.06	80.54	64.20	62.63	63.40	81.21	68.25	69.87	69.05	79.04	92.00	67.51	77.88	
Syscall/log	Hawware	88.55	77.72	80.57	79.12	82.85	67.83	68.99	68.41	89.16	79.88	85.38	82.54	87.44	94.50	81.78	87.68
	HRAT	91.92	84.43	85.81	85.11	86.59	74.49	76.34	75.40	90.96	83.31	87.38	85.30	89.46	95.26	84.93	89.80
	Deeplog	94.36	88.94	90.29	89.61	89.78	80.32	82.19	81.24	91.30	83.65	88.25	85.89	90.38	95.80	86.18	90.73
	FedTrans	94.85	89.49	91.62	90.54	90.19	80.03	84.66	82.28	92.61	84.94	91.60	88.14	92.08	96.12	89.11	92.48

### 539 C. Concept Drift Experiments

540 Moreover, we conduct concept drift experiments in terms  
 541 of space bias and time bias [69]. 1) *Space bias* refers to  
 542 unrealistic assumptions about the ratio of benign/malware, we  
 543 divide the malware as  $\{train:test = 5:5\}$  and  $\{train:test = 2:8\}$   
 544 in Fig. 7(a) and the left part of Table II and 2) *Time bias* refers  
 545 to malware could behave differently over time, we set two  
 546 split points (Fig. 6) of malware samples. As shown in Fig. 7,  
 547 against spatial/temporal biases, TPE-Det still maintains good  
 548 performance compared to baselines. Particularly, both ETB-  
 549 based and HPC-based schemes are not robust enough when

550 against concept drift. Specifically, for accuracy results in  
 551 space bias experiments in Fig. 7(a), we observe that only  
 552 four models (RF, XGB, LSTM, and GNN) are superior to  
 553 the best baseline (i.e., FedTrans) when  $\{train:test = 5:5\}$ ,  
 554 while all seven models perform better than the baselines when  
 555  $\{train:test = 2:8\}$ . Similar results can also be observed in  
 556 Fig. 7(b), our seven SPI-based models all realize better recall  
 557 than the baselines when the setting refers to  $\leq April 2017 \mapsto$   
 558  $\geq May 2017$ .

559 We report more detailed results in Table II in terms of  
 560 the accuracy, precision, recall, and F1 score. From the left

TABLE I  
DETECTION EFFECT OF EACH MODEL AND BASELINES

Model		Acc (%)	Pre (%)	Rec (%)	F1 (%)
SPI (ours)	DT	95.77±1.24	90.38±2.95	94.32±2.07	92.31±2.53
	RF	<b>97.73±1.08</b>	<b>93.86±1.81</b>	<b>97.96±1.35</b>	<b>95.87±1.56</b>
	SVM	94.28±1.88	87.52±2.14	91.85±1.68	89.63±1.83
	XGB	<b>97.81±0.57</b>	93.52±1.51	<b>98.69±0.58</b>	<b>96.03±0.78</b>
	NB	96.44±1.20	90.71±1.61	<b>96.65±0.94</b>	93.59±1.37
	LSTM	<b>97.65±1.05</b>	<b>93.85±1.74</b>	<b>97.67±0.79</b>	<b>95.72±0.87</b>
	GNN	<b>98.94±0.47</b>	<b>97.14±1.09</b>	<b>98.98±0.42</b>	<b>98.05±0.74</b>
ETB	KNN	89.82±1.97	80.20±2.70	82.53±1.75	81.35±2.40
	RF	93.42±1.31	86.81±2.43	89.08±2.05	87.93±2.21
	DT	88.06±2.07	76.83±3.56	79.62±2.88	78.20±3.12
	NN	92.48±1.27	85.61±1.73	86.61±0.73	86.11±1.09
HPC (perfr)	BN	83.79±2.28	69.75±2.37	70.16±2.66	69.96±2.46
	NB	78.23±3.22	59.91±3.18	57.64±4.05	58.75±3.71
	RF	87.90±2.48	76.69±3.77	79.04±2.78	77.85±2.96
	LR	79.48±2.83	61.24±2.91	64.63±2.34	62.89±2.54
	SGD	75.96±3.25	55.42±3.07	54.29±3.92	54.85±3.56
	MLP	85.47±2.08	72.51±3.48	74.09±2.87	73.29±3.09
	BN-Boost	88.76±2.17	78.82±2.23	79.62±1.58	79.22±1.88
	BN-Bag	85.83±1.62	74.07±1.38	72.78±1.20	73.42±1.27
	SGD-Boost	82.97±2.93	68.53±2.38	67.83±2.75	68.18±2.57
	SGD-Bag	80.70±1.72	64.31±1.57	63.46±1.73	63.88±1.68
Syscall/log	Hawkware	91.23±2.49	81.58±3.38	87.05±2.67	84.23±2.86
	HRAT	93.27±1.94	86.32±2.26	89.08±1.57	87.68±1.75
	Deeplog	95.93±1.21	91.58±1.35	93.45±0.95	92.51±1.18
FedTrans	96.83±1.02	93.53±1.79	94.76±1.15	94.14±1.55	

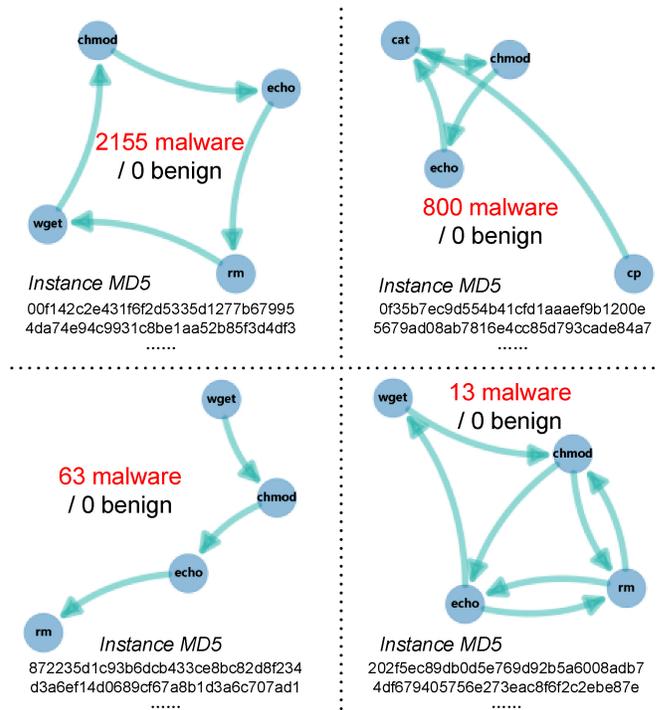


Fig. 8. Deep insights into TPE-Det.

part of Table II, we find that all SPI-based models achieve better performance (involving four metrics) than baselines when  $\{train:test = 2:8\}$ . This presents that our scheme can indeed extract effective and stable features via leveraging SPI to recover execution behaviors, even if only a small number of samples are used for training. From the right part of Table II, we see some different phenomena. Except for the recall, for the other three indicators, not all seven SPI-based models are higher than the baseline. This may be attributed to the fact that the attack behavior of malware has a more certain pattern (so TPE-Det can achieve a higher-detection rate even if under the time bias setting), while the execution activities of benign programs are more diverse. We then analyze some malware instances to obtain more insights.

As shown in Fig. 8, we visualize command graph patterns for some malware. It is clear that there are 2,155 malware that have the structure of  $wget \rightarrow chmod \rightarrow echo \rightarrow rm$ , while none benign present this pattern. In addition, Fig. 8 also displays that the other three command graph patterns are shared by 800, 63, and 13 malware, respectively. This can echo back the results in Table II, i.e., GNN performs the best performance, because many malware have isomorphic command graph structures. Overall, our SPI-based recovered operation commands are representative features for malware detection, even against space/time concept drift.

#### D. Adaptive Adversary Evaluation

We develop the adaptive adversary evaluation next.<sup>6</sup> For one thing, we consider adaptive adversaries who could perform

<sup>6</sup>Although PREEMPT is an external monitor, it is not clear how to recover file operations based on ETB trace [26], so PREEMPT does not support

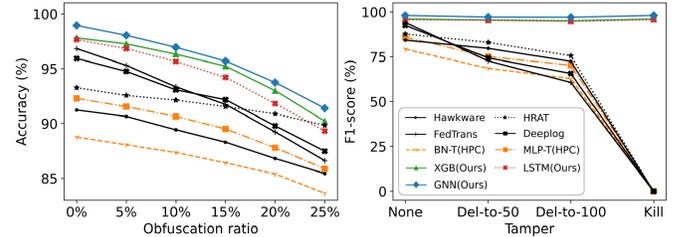


Fig. 9. Evaluation with obfuscation and tampering.

operation obfuscation. For another, strong attackers could directly kill the monitor process or tamper with recorded logs.

1) *Operation Obfuscation*: The attacker may add additional operations into the malicious script for obfuscation [70], [71]. We set the ratio as  $\{5\%, 10\%, 15\%, 20\%, 25\%$  to obfuscation randomly, the accuracy results are summarized in the left part of Fig. 9. We observe that HRAT is less affected by confusion since it takes feature interferences/modifications into account during model training [12]. The results of FedTrans and Deeplog are comparable. As the confusion ratio increases, the accuracy of most models tends to decrease slowly. When the obfuscation ratio is 25%, the top-5 performance models, in order, are GNN (ours) > XGB (ours) > HRAT > LSTM (ours) > Deeplog.

2) *Log Tampering*: To evaluate the tamper-proof capabilities, we consider the attackers could directly kill the internal monitor process or tamper with operation log files [14], [15], [16]. Specifically, we only save the first 50

operation log recovery and cannot be evaluated the tamper-proof capability against the adaptive adversary.

TABLE III  
 COMMAND RECOVERY AGAINST ADAPTIVE ADVERSARIES

Tamper	Method	<i>cat</i>	<i>chmod</i>	<i>cp</i>	<i>echo</i>
Kill	TPE-Det	<b>97.73%</b>	<b>99.18%</b>	<b>98.12%</b>	<b>97.27%</b>
	Syslog	0%	0%	0%	0%
Del-to-50	TPE-Det	<b>97.25%</b>	<b>99.18%</b>	<b>97.98%</b>	<b>96.86%</b>
	Syslog	69.21%	63.22%	72.63%	73.76%

Tamper	Method	<i>grep</i>	<i>ln</i>	<i>mkdir</i>	<i>mv</i>
Kill	TPE-Det	<b>97.82%</b>	<b>99.06%</b>	<b>99.13%</b>	<b>99.21%</b>
	Syslog	0%	0%	0%	0%
Del-to-50	TPE-Det	<b>97.43%</b>	<b>99.06%</b>	<b>99.13%</b>	<b>99.21%</b>
	Syslog	68.61%	76.21%	77.06%	52.13%

Tamper	Method	<i>rm</i>	<i>rmdir</i>	<i>touch</i>	<i>wget</i>
Kill	TPE-Det	<b>99.75%</b>	<b>99.64%</b>	<b>99.53%</b>	<b>99.67%</b>
	Syslog	0%	0%	0%	0%
Del-to-50	TPE-Det	<b>99.75%</b>	<b>99.64%</b>	<b>99.53%</b>	<b>99.62%</b>
	Syslog	45.62%	69.23%	76.93%	75.36%

```

wget http://XX/jackmymips; chmod +x jackmymips;
./jackmymips; rm -rf jackmymips;
wget http://XX/jackmysh4; chmod +x jackmysh4;
./jackmysh4; rm -rf jackmysh4;
wget http://XX/jackmyx86; chmod +x jackmyx86;
./jackmyx86; rm -rf jackmyx86;
wget http://XX/jackmyarmv6; chmod +x jackmyarmv6;
./jackmyarmv6; rm -rf jackmyarmv6;
wget http://XX/jackmysparc; chmod +x jackmysparc;
./jackmysparc; rm -rf jackmysparc;
.....
    
```

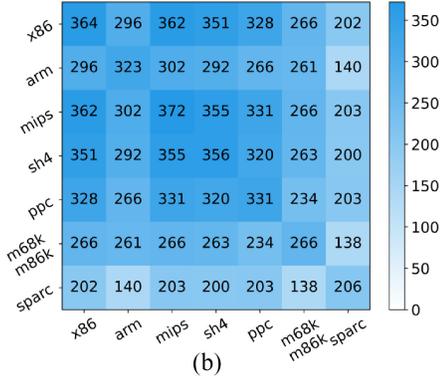


Fig. 10. Cross-architecture malware analysis. a) Arch-homogeneous malware. (b) Cross-arch heatmap.

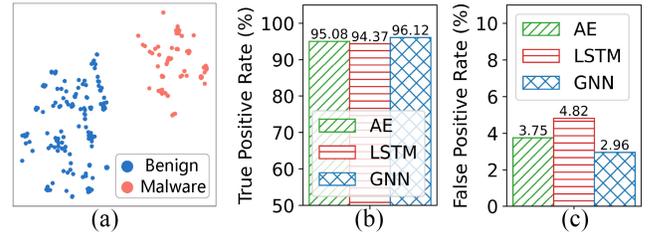


Fig. 11. Visualization and unknown detection evaluation. (a) t-SNE visualization. (b) TPR results. (c) FPR results.

609 (or 100) lines of generated logs after each malware execution to simulate adversary tampering, e.g., `cat /dev/null`  
 610 `> /var/log/syslog`, execute the malware script, and `cat /var/log/syslog | head -n 50 > save.txt`. The log recovery  
 611 results of TPE-Det and Syslog against the kill processes and tampering with logs are summarized in Table III. We find that  
 612 Syslog is greatly affected by tampering and fails directly when killed (corresponding to 0% command recovery in Syslog).  
 613 However, TPE-Det is almost unaffected whether by tampering or killing the process, i.e., achieve 97.25%–99.75% command  
 614 recovery. Compare the results between “Kill” and “Del-to-50,” we find that the command recovery results of TPE-Det for  
 615 `chmod`, `ln`, `mkdir`, `mv`, `rm`, `rmdir`, and `touch` are consistent. The recovery ratio of other commands changes because the  
 616 log deletion operation may involve those commands. For the right part of Fig. 9, it is clear that all methods based on  
 617 HPC (`perf`), `Syscall`, and `Syslog` are severely affected when tampered with and will fail when killed. In comparison, TPE-  
 618 Det always maintains superior detection, which echoes our original intention of such a tamper-proof design.  
 619

### 629 E. Deep Insights Into TPE-Det

630 In this section, we provide here more deep insights into TPE-Det with respect to cross-architecture analysis, operation  
 631 recovery case, and unknown detection.

633 1) *Cross-Architecture Analysis*: A variety of architectures is typically used on IoT devices, such as x86, ARM, MIPS,  
 634 etc., thus cross-architecture analysis is practical in the real world [72]. We analyze all malware instances in the dataset  
 635 and find that their command structures are completely isomorphic when different architectures are involved, as the top part  
 636 of Fig. 10 shows. Specifically, Fig. 10(a) corresponds to the malware with MD5 is `f6ff16d9b855beae3fcfb7d272c34582`.  
 637 There are a series of executable files for different architectures involve MIPS, SH4, x86, ARM, and so on. Nonetheless, their  
 638 command patterns are the same, refer to `wget`  $\rightarrow$  `chmod`  $\rightarrow$  `program execution`  $\rightarrow$  `rm`. This means that our proposal  
 639

645 supports cross-architecture malware detection. Furthermore, we count the frequency of various architectures appearing  
 646 simultaneously to draw the heatmap in Fig. 10(b). We observe that `x86`, `mips`, `sh4`, and `ppc` are the most common.  
 647

648 2) *Recovery Case*: We describe the log recovery case for Hajime [6] and Mirai [5], more details are stored in the online  
 649 repository..

650 3) *Unknown Detection*: We also explore unknown detection effects, statistical features are modeled with autoencoder  
 651 (AE), both LSTM and GNN are also reconstructed into encoder + decoder architectures. Then, training with benign  
 652 only and performing anomaly detection based on reconstruction loss. Fig. 11 shows the feasibility of unknown detection,  
 653 and the t-SNE visualization indicates that benign and malware are distinguishable under our feature space.  
 654

### 660 F. Overhead Evaluations

661 We measure the time and space overhead here. In Fig. 12, our ML classifiers introduce minimal time overhead, our  
 662 DNN models are the same level as the HPC-based model  
 663

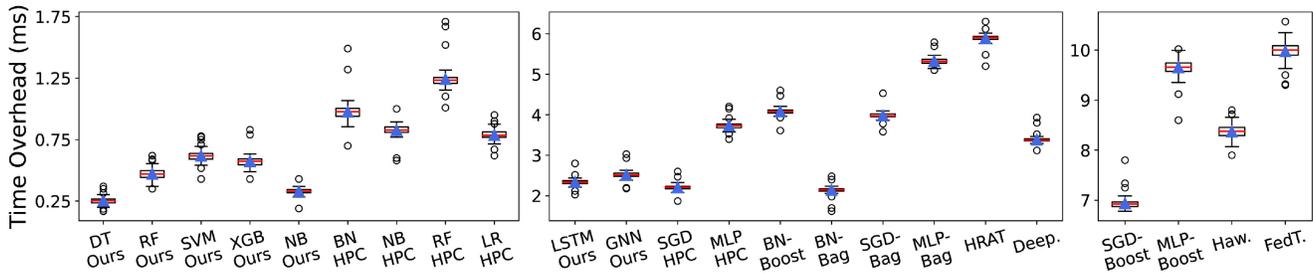


Fig. 12. Time overhead of TPE-Det and baselines.

664 ensemble. The most time-consuming is FedTrans because  
 665 it is based on the Transformer model. For the space over-  
 666 head, our models only induce 70.31–327.17 KB, the most  
 667 space-consuming is still FedTrans since it contains mas-  
 668 sive parameters. Noteworthy, among various log records in  
 669 Table IV, ours is the smallest, only needing 4.31 MB for all  
 670 benign/malware samples combined, while *Perf*, *Syscall*, and  
 671 *Syslog* all require more than 100 MB. For log recovery time, it  
 672 takes  $\sim 0.02$  s to analyze 5 MB SPI signals, which is acceptable  
 673 due to usually there are not so many traces generated.

### 674 G. Extended Experiments

675 We also perform extended experiments with different chips  
 676 and datasets. Specifically, we use another chip that installs  
 677 the W25X64 Flash [73] and SPI bus. Meanwhile, we consider  
 678 the BadThings [74] dataset, which contains binary malware  
 679 executables. The evaluation results of the GNN model in TPE-  
 680 Det are reported in Fig. 14. We observe that for different  
 681 chips, there is almost no impact on the performance of TPE-  
 682 Det, and the slight differences in classification metrics may  
 683 be due to factors, such as the changed frequency, during  
 684 the signal acquisition process. For the BadThings dataset,  
 685 the performance of TPE-Det decreases slightly (e.g.,  $\sim 1.2\%$   
 686 accuracy drop), probably because the BadThings corpora [74]  
 687 contains more malware samples. Overall, TPE-Det can detect  
 688 malware accurately and has good scalability, such as applying  
 689 to different chips and datasets.

## 690 VII. DISCUSSION, LIMITATIONS, AND FUTURE WORK

### 691 A. Security Discussion

692 As mentioned in the introduction, TPE-Det is dedicated  
 693 to performing the analysis of the side-channel information  
 694 external to the system, which can address the challenges  
 695 of tampering risks and huge logging records. In this way,  
 696 attackers are difficult to perceive the monitoring process or  
 697 manipulate the logs, so that the detection results of TPE-Det  
 698 can be guaranteed. Actually, physical access does increase the  
 699 possible attack surface [75]. While we would like to clarify  
 700 that considering security scenarios involving investigation  
 701 forensics and honeypots (as stated in Section III), such phys-  
 702 ical access is acceptable in the real world [26], [76]. In view of  
 703 scenarios, such as forensics and honeypots, practitioners are  
 704 allowed to have many permissions on the equipment, including  
 705 physical access support [45], [46], [52], to obtain as much  
 706 attack intelligence and information as possible [47], [51].

TABLE IV  
SPACE OVERHEAD OF LOGS AND MODELS

Log space overhead		Ours	perf	Syscall	Syslog
9,337 Benign		<b>1.45MB</b>	213.34MB	532.15MB	71.23MB
3,439 Malware		<b>2.86MB</b>	348.92MB	987.37MB	136.88MB
Model (Ours)	Size	Model	Size	Model	Size
DT	70.31KB	BN (HPC)	567.78KB	BN-Boost	2.33MB
RF	98.52KB	NB (HPC)	441.82KB	BN-Bag	2.24MB
SVM	132.17KB	RF (HPC)	721.73KB	SGD-Boost	4.95MB
XGB	154.55KB	LR (HPC)	357.29KB	SGD-Bag	3.69MB
NB	84.96KB	SGD (HPC)	695.78KB	MLP-Boost	8.84MB
LSTM	327.17KB	MLP (HPC)	2.83MB	MLP-Bag	7.51MB
GNN	251.34KB	Hawkware	2.75MB	HRAT	1.39MB
-	-	FedTrans	160.33MB	Deeplog	532.18KB

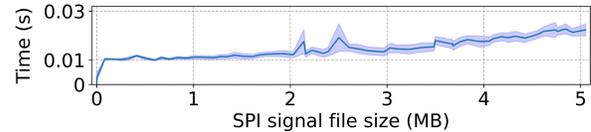


Fig. 13. Log recovery time of the hardware trace.

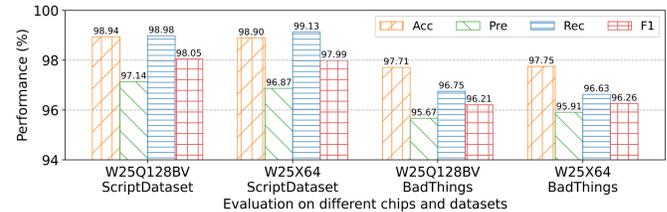


Fig. 14. Evaluate TPE-Det (GNN) on different chips and datasets.

707 Also, the Logic analyzer in TPE-Det prototype connects the  
 708 flash chip physically through pins so that the IoT device  
 709 system will not be directly affected. It can also be considered  
 710 for devising integrated customized solutions for production in  
 711 the future.

### 712 B. Practicality and Expandability

713 As experimented in Section VI-B, it is undeniable that  
 714 TPE-Det may yield some misclassifications, even if TPE-Det  
 715 proposes three designed models for the statistical, sequence,  
 716 and graph features. When customers have a low tolerance for  
 717 false negatives, we can improve the positive probability of  
 718 the classification or ensemble multiple models (e.g., voting  
 719 result is negative only if no positive). Meanwhile, TPE-Det  
 720 can leverage the traceability forensic analysis [21] to verify  
 721 and determine the detection reports based on the recovered  
 722 hardware-part operation. In addition, the high-level detection

logic in TPE-Det can be extended according to specific business scenarios. For example, we could focus on choosing the appropriate model of graph features for security applications that centered on continuous and various file operations. In addition to forensics and IoT honeypots, other scenarios that require recording correct device operation logs against adaptive adversaries can also benefit from TPE-Det.

### C. Limitations and Future Work

Although the evaluations mainly use the ScriptDataset dataset, other datasets, such as BinaryString and OpenWrtLogs, are still applicable given that previous work has extensively confirmed that malware does exhibit certain command patterns. We admit that physical access may not be convenient sometimes, but as a novel external monitor, TPE-Det can bring new perspectives. Meanwhile, a feasible direction is to devise integrated customized solutions for industrial production to advance this side-channel-manner analysis.

## VIII. CONCLUSION

In this article, we propose TPE-Det, a tamper-proof and lightweight external malware detector. In particular, TPE-Det leverages the SPI bus to monitor and extract the on-chip traces and we design a suite of operation log recovery pipeline in a side-channel manner. We implement TPE-Det and evaluate it extensively on our physical testbed. By comparing the SOTA methods involving HPC, ETB, *Syscall*, and *Syslog*, we demonstrate that TPE-Det can achieve remarkable detection results even against adaptive adversaries. Meanwhile, TPE-Det introduces negligible CPU and memory utilization. Furthermore, we develop a series of experiments in terms of concept drift, deep insights, cross-architecture analysis, unknown detection, and overhead evaluation to present the effectiveness, stability, scalability, lightness, and practicality of TPE-Det.

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