

CHAPTER I

THE SINGLE FIRST ORDER EQUATION

1. The linear and quasi-linear equations.

The first order equations, in general, present interesting geometric interpretations. It will be convenient then to restrict the discussion to the case of two independent variables, but it will be made clear that the theory can be extended immediately to any number of variables. We consider then equations of the form

$$(1) \quad F(x, y, u, u_x, u_y) = F(x, y, u, p, q) = 0$$

where we have used the notation $u_x = p$, $u_y = q$. A solution $z = u(x, y)$, when interpreted as a surface in three dimensional space, will be called an integral surface of the differential equation.

We begin with the general linear equation

$$(2) \quad a(x, y)u_x + b(x, y)u_y = c(x, y)u + d(x, y).$$

We notice that the left hand side of this equation represents the derivative of $u(x, y)$ in the direction $(a(x, y), b(x, y))$. Thus when we consider the curves in the x, y -plane whose tangents at each point have those directions, i.e. the one parameter family of curves defined by the ordinary differential equations

$$(3) \quad \frac{dy}{dx} = \frac{b(x, y)}{a(x, y)}, \quad \text{or} \quad \frac{dx}{dt} = a(x, y), \quad \frac{dy}{dt} = b(x, y),$$

they will have the property that along them $u(x, y)$ will satisfy the ordinary differential equation

$$(4) \quad \frac{du}{dx} = \frac{c(x, y)u + d(x, y)}{a(x, y)}, \quad \text{or} \quad \frac{du}{dt} = c(x, y)u + d(x, y).$$

The one parameter family of curves defined by equations (3) are called the characteristic curves of the differential equation.

Suppose now $u(x,y)$ is assigned an "initial" value at a point (x_0, y_0) in the x,y -plane. From the existence and uniqueness of the initial value problem for ordinary differential equations, equations (3) will define a unique characteristic curve, say

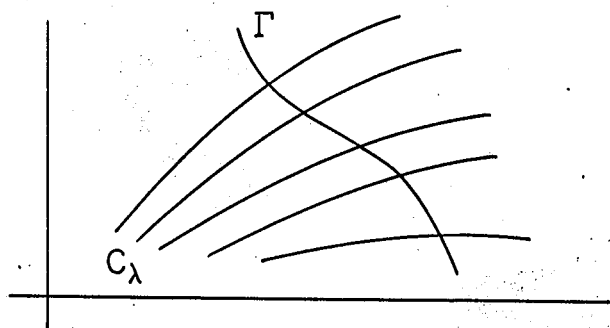
$$(5) \quad x = x(x_0, y_0, t), \quad y = y(x_0, y_0, t)$$

along which

$$(6) \quad u = u(x_0, y_0, t)$$

will be uniquely determined by equation (4). That is, if u is given at a point, it is determined along a whole characteristic curve through the point.

This suggests that if we were to assign initial values for u along some curve, say Γ of the figure below,



intersecting the characteristics C_λ , we may determine a unique solution $u(x,y)$ in the whole region covered by C_λ by means of (5) and (6).

The curve Γ , which we may call the initial curve, may not be chosen quite arbitrarily. For clearly it must not at any point coincide with a characteristic, since there u is determined as a solution of an ordinary differential equation.

A precise formulation of this initial problem, called the Cauchy initial



value problem, will be given for the more general quasi-linear equations to follow.

As an example we consider the P.D.E.

$$xu_x + yu_y = \alpha u$$

with initial conditions $u = \phi(x)$ for $y = 1$. The characteristic curves are given by the equation

$$\frac{dy}{dx} = \frac{y}{x}.$$

having solutions

$$y = cx.$$

Along such a curve u satisfies the equation

$$\frac{du}{dx} = \frac{\alpha u}{x},$$

whose solution is

$$u = kx^\alpha.$$

As k may differ from characteristic to characteristic, i.e. depend on c , we have the general solution

$$u = k(c)x^\alpha = k\left(\frac{y}{x}\right)x^\alpha$$

where k is an "arbitrary" function. If we apply the initial condition for $y = 1$ we obtain

$$\phi(x) = k\left(\frac{1}{x}\right)x^\alpha$$

or

$$k(s) = \phi\left(\frac{1}{s}\right)s^\alpha,$$

and hence the required solution

$$u = \phi\left(\frac{x}{y}\right)y^\alpha.$$

The general quasi-linear equation may be written

$$(7) \quad a(x,y,u)u_x + b(x,y,u)u_y = c(x,y,u).$$

A solution $u(x,y)$ defines an integral surface $z = u(x,y)$ in the x,y,z -space. The direction numbers of the normal to the surface are $(u_x, u_y, -1)$, so that equation (7) can be interpreted as the condition that the integral surface at each point has the property that the vector (a,b,c) is tangent to the surface.

Thus the P.D.E. defines a direction field (a,b,c) , called the characteristic directions, having the property that a surface $z = u(x,y)$ is an integral surface if and only if at each point the tangent plane contains the characteristic direction.

It is suggestive then that we consider the integral curves of this field, i.e. the family of space curves whose tangent coincides with the characteristic direction. They are called the characteristic curves and are given by the equations

$$(8) \quad \frac{dx}{a(x,y,z)} = \frac{dy}{b(x,y,z)} = \frac{dz}{c(x,y,z)}.$$

Calling the common value of these ratios dt , we can write (8) also in the form

$$(9) \quad \frac{dx}{dt} = a(x, y, z), \quad \frac{dy}{dt} = b(x, y, z), \quad \frac{dz}{dt} = c(x, y, z).$$

[This notion differs from the one used in the linear case. The projection of the present curves on the x, y -plane will be the curves previously called characteristic.] Through each point (x_0, y_0, z_0) there passes one characteristic curve

$$x = x(x_0, y_0, z_0, t), \quad y = y(x_0, y_0, z_0, t), \quad z = u(x_0, y_0, z_0, t).$$

One important property of the characteristic curves is immediately evident from the geometric interpretation of equation (7). Namely, every surface generated by a one parameter family of characteristics is an integral surface. Moreover, the converse is also true. For suppose $z = u(x, y)$ is a given integral surface Σ . Consider the solution of

$$\frac{dx}{dt} = a(x, y, u(x, y)), \quad \frac{dy}{dt} = b(x, y, u(x, y))$$

with $x = x_0, y = y_0$ for $t = 0$. Then for the corresponding curve

$$x = x(t), \quad y = y(t), \quad z = u(x(t), y(t))$$

also

$$\frac{dz}{dt} = u_x \frac{dx}{dt} + u_y \frac{dy}{dt} = a(x, y, u)u_x + b(x, y, u)u_y = c(x, y, u) = c(x, y, z)$$

from (7). Hence the curve satisfies condition (9) for characteristic curves, and also lies on Σ by definition. Thus Σ contains with each point also the characteristic curve through the point. Therefore Σ consists of integral curves. Furthermore, if two integral surfaces intersect in a point then they intersect along the whole characteristic through this point; and the curve of intersection of two integral surfaces must be characteristic.

At this point the solution to the Cauchy initial value problem, i.e. of finding a solution $u(x,y)$ satisfying prescribed initial values along a curve in the x,y -plane, becomes evident. For we may take as the solution the integral surface consisting of the family of characteristics passing through each initial point in space.

We will again have to exclude initial curves which are characteristic at any point, i.e. satisfy (8). We shall even have to exclude initial curves satisfying the one equation $\frac{dx}{a} = \frac{dy}{b}$, as otherwise u would have unbounded derivatives. The precise formulation and proof of the existence theorem follows:

Theorem: Consider the first order quasi-linear partial differential equation

$$(10) \quad a(x,y,u)u_x + b(x,y,u)u_y = c(x,y,u),$$

where a,b,c have continuous partial derivatives with respect to x,y,u . Suppose that along the initial curve $x = x_0(s)$, $y = y_0(s)$ the initial values $u = u_0(s)$ are prescribed, x_0, y_0, u_0 being continuously differentiable functions for $0 \leq s \leq 1$. Furthermore, let

$$(11) \quad \frac{dy_0}{ds} a(x_0(s), y_0(s), u_0(s)) - \frac{dx_0}{ds} b(x_0(s), y_0(s), u_0(s)) \neq 0.$$

Then there exists one and only one solution $u(x,y)$ defined in some neighborhood of the initial curve, which satisfies the P.D.E. and the initial conditions

$$(12) \quad u(x_0(s), y_0(s)) = u_0(s).$$

Proof: We consider the ordinary differential equations

$$\begin{aligned}
 (13) \quad \frac{dx}{dt} &= a(x, y, u) \\
 \frac{dy}{dt} &= b(x, y, u) \\
 \frac{du}{dt} &= c(x, y, u).
 \end{aligned}$$

From the existence and uniqueness theorem for ordinary differential equations we may solve for a unique family of characteristics

$$\begin{aligned}
 (14) \quad x &= x(x_0, y_0, u_0, t) = x(s, t) \\
 y &= y(x_0, y_0, u_0, t) = y(s, t) \\
 u &= u(x_0, y_0, u_0, t) = u(s, t),
 \end{aligned}$$

whose derivatives with respect to the parameters s, t are continuous and such that they satisfy the initial conditions

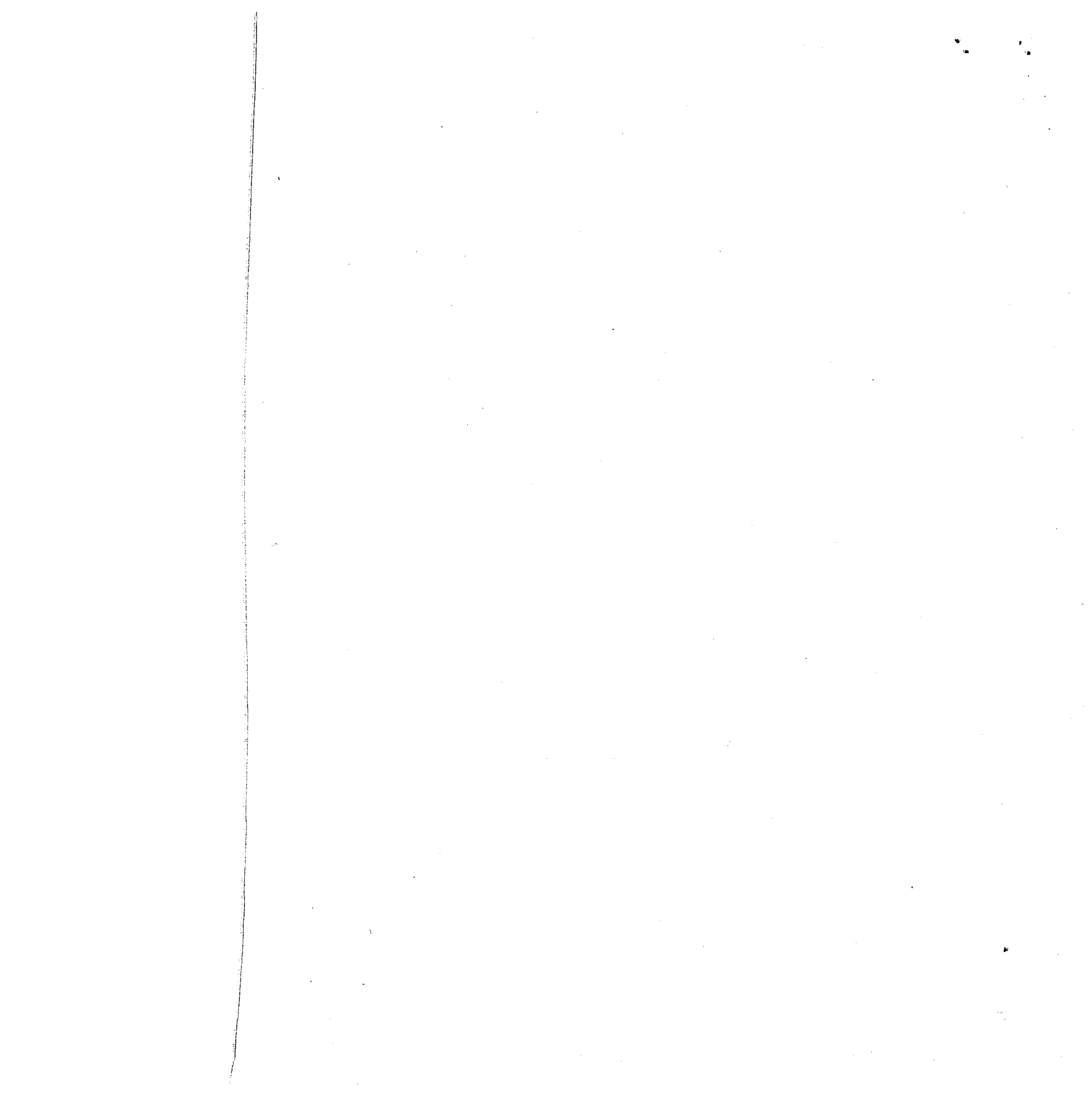
$$\begin{aligned}
 x(s, 0) &= x_0(s) \\
 y(s, 0) &= y_0(s) \\
 u(s, 0) &= u_0(s).
 \end{aligned}$$

We note that the Jacobian

$$\frac{\partial(x, y)}{\partial(s, t)} \Big|_{t=0} = \begin{vmatrix} x_s & x_t \\ y_s & y_t \end{vmatrix} \Big|_{t=0} = \left(\frac{dx_0}{ds} b - \frac{dy_0}{ds} a \right) \neq 0$$

by condition (11). Thus in (14) we may solve for s, t in terms of x, y in the neighborhood of the initial curve $t = 0$, obtaining from (14) a candidate for the solution

$$\phi(x, y) = u(s(x, y), t(x, y)).$$



$\phi(x,y)$ clearly satisfies the initial conditions; for

$$\phi(x,y)_{t=0} = u(s,0) = u_0(s).$$

Moreover it satisfies the differential equations. For

$$\begin{aligned} a\phi_x + b\phi_y &= a(u_s s_x + u_t t_x) + b(u_s s_y + u_t t_y) \\ &= u_s(as_x + bs_y) + u_t(at_x + bt_y) \\ &= u_s(s_x x_t + s_y y_t) + u_t(t_x x_t + t_y y_t) \\ &= u_s \cdot 0 + u_t \cdot 1 \\ &= c, \end{aligned}$$

since from the equations

$$\begin{aligned} s &= s(x,y) \\ t &= t(x,y), \end{aligned}$$

we have

$$\begin{aligned} s_t &= 0 = s_x x_t + s_y y_t \\ t_t &= 1 = t_x x_t + t_y y_t. \end{aligned}$$

Moreover, $\phi(x,y)$ is unique. For suppose $\bar{\phi}(x,y)$ is any other solution satisfying the initial conditions and x', y' an arbitrary point in the neighborhood of the initial curve. We consider the characteristic curve

$$x = x(s',t), \quad y = y(s',t), \quad u = u(s',t)$$



where $s' = s(x', y')$. At $t = 0$ this curve passes through both surfaces since here it passes through the initial curve at the point

$$x(s', 0) = x_0(s'), \quad y(s', 0) = y_0(s'), \quad u(s', 0) = u_0(s')$$

But if a characteristic curve has one point in common with an integral surface it lies entirely on the surface. Thus the characteristic curve lies on both surfaces, and in particular for t' we have

$$\bar{\phi}(x', y') = \bar{\phi}(x'(s', t'), y'(s', t')) = u(s', t') = \phi(x', y').$$

As an example consider the P.D.E.

$$uu_x + u_y = 1$$

with initial conditions $x = s, y = s, u = \frac{1}{2}s$ for $0 \leq s \leq 1$. We note that condition (11) is satisfied; for

$$\frac{dy_a}{ds} - \frac{dx_b}{ds} = \frac{1}{2}s - 1 \neq 0 \quad \text{for } 0 \leq s \leq 1.$$

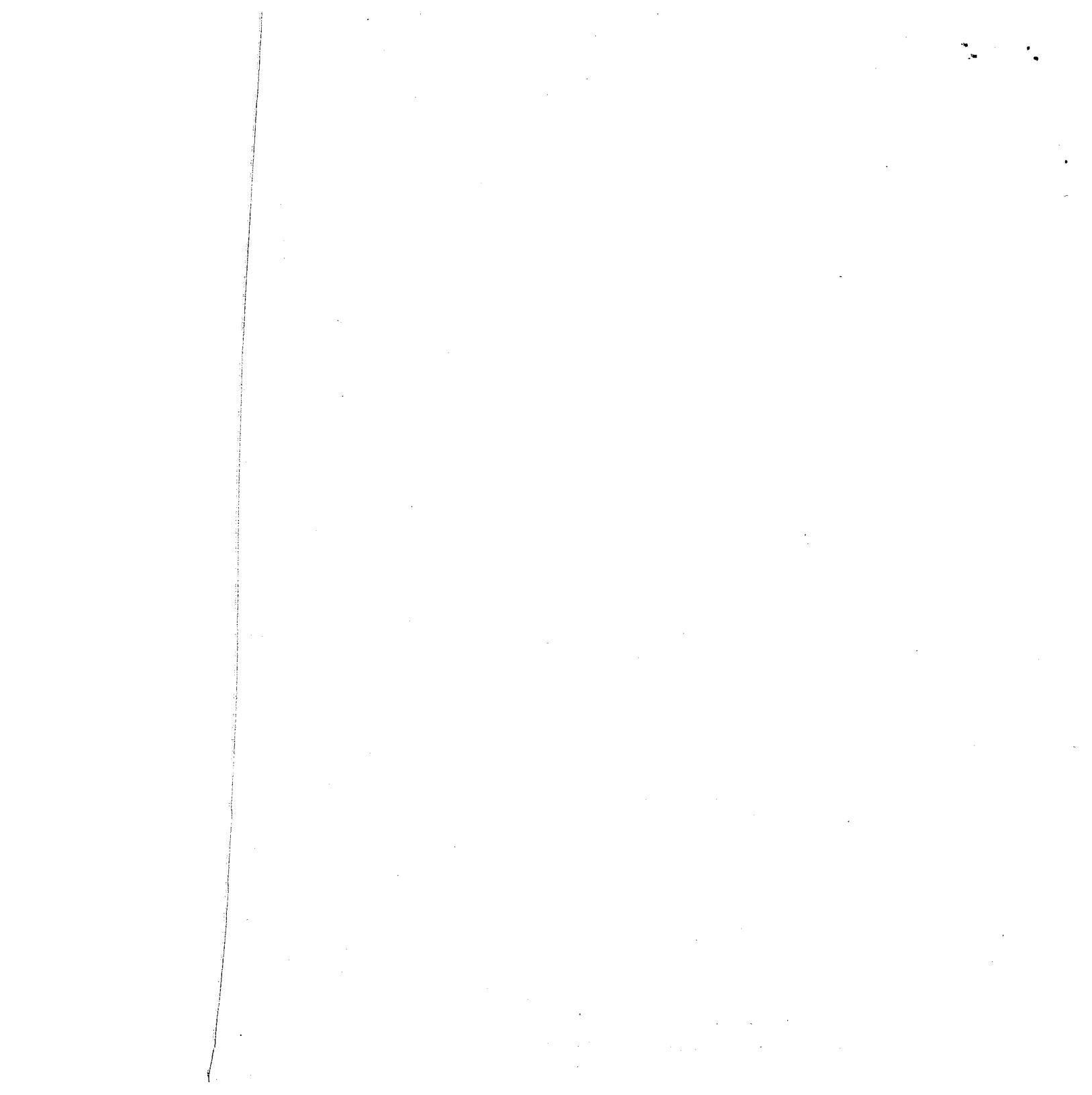
Solving the ordinary differential equations

$$\frac{dx}{dt} = u, \quad \frac{dy}{dt} = 1, \quad \frac{du}{dt} = 1$$

with the initial conditions

$$x(s, 0) = s, \quad y(s, 0) = s, \quad u(s, 0) = \frac{1}{2}s,$$

we find the family of characteristics



$$x = \frac{1}{2}t^2 + \frac{1}{2}st + s$$

$$y = t + s$$

$$u = t + \frac{s}{2}$$

When we solve for s and t in terms of x and y , we obtain

$$s = \frac{x - \frac{y^2}{2}}{1 - \frac{y}{2}}, \quad t = \frac{y - x}{1 - \frac{y}{2}},$$

and finally the solution

$$u = \frac{2(y-x) + (x - \frac{y^2}{2})}{2 - y}.$$

2. The general first order equation for a function of two variables.

The general first order partial differential equation for a function of two variables $z(x,y)$ and its derivatives $z_x = p$, $z_y = q$ can be written

$$(1) \quad F(x, y, z, p, q) = 0.$$

It will be assumed that F has continuous second derivatives with respect to its variables x, y, z, p, q .

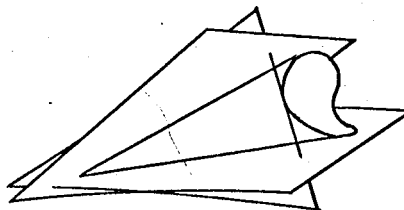
Surprisingly enough the problem of solving even the most general first order equation reduces to that of solving a system of ordinary differential equations. The geometry, though, is not nearly as simple as for the quasi-linear equations, where we were concerned principally with integral curves. In the general case we will require, as we will see, more complicated geometric objects, called "strips".

Suppose now at some point in space (x_0, y_0, z_0) we consider a possible integral surface $z = z(x,y)$ and the direction numbers $(p, q, -1)$ of its tangent plane. The equation states that there is a relation

$$F(x_0, y_0, z_0, p, q) = 0$$

between the direction numbers p and q . That is, the differential equation will restrict its solutions to those surfaces having tangent planes belonging to a one parameter family.

In general this one parameter family of planes will envelope a cone (see figure) called the Monge cone. Thus the dif-



ferential equation (1) describes a field of cones having the property

that a surface will be an integral surface if and only if it is tangent to a cone at each point. We note that in the quasi-linear case the cone degenerates into a straight line.

Let us consider for a moment that we have a one parameter family of integral surfaces

(2)

$$z = f(x, y, c),$$

where we assume f has continuous second derivatives with respect to its variables x, y, c . As we may suspect from the geometric interpretation of the differential equation, the envelope, if it exists, will again be a solution.

We may find the envelope of a family of surfaces by considering the points of intersection of "neighboring surfaces"

$$z = f(x, y, c)$$

and

$$z = f(x, y, c + \Delta c).$$

Subtracting and dividing by Δc ,

$$0 = \frac{f(x, y, c) - f(x, y, c + \Delta c)}{\Delta c},$$

and passing to the limit $\Delta c \rightarrow 0$, we have the envelope defined by the two equations

$$(3) \quad \begin{aligned} z &= f(x, y, c) \\ 0 &= f_c(x, y, c). \end{aligned}$$

If we may solve for c in the second equation and eliminate in the first, we have the envelope expressed as

$$z = g(x, y) = f(x, y, c(x, y)).$$

The envelope will satisfy the differential equation. For

$$(4) \quad \begin{aligned} g_x &= f_x + f_c c_x = f_x \\ g_y &= f_y + f_c c_y = f_y, \end{aligned}$$

since $f_c \equiv 0$. That is, the envelope will have the same derivatives as a member of the family, and the differential equation is just a relation between these derivatives to be satisfied.

Finding one more solution when we already have a whole family of them is not much gain. However, suppose we know a two parameter family of integral surfaces, say

$$(5) \quad z = f(x, y, a, b).$$

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Then we can find solutions depending on an arbitrary function. For if we let

$$b = \phi(a)$$

where ϕ is differentiable, we obtain the family

$$z = f(x, y, a, \phi(a)),$$

and its envelope

$$z = f(x, y, a, \phi(a))$$

$$0 = f_a + f_b \phi'(a)$$

will be an integral surface depending on the function ϕ .

This suggests that if we were given a two parameter family of integral surfaces, we may be able to select a one parameter family of these surfaces whose envelope contains a given curve in space, i.e. find a solution to the initial value problem. We note that it is quite reasonable to expect the existence of a two parameter family of solutions. For suppose we are given to begin with an arbitrary family of surfaces, say

$$(6) \quad z = f(x, y, a, b).$$

If we may solve for the parameters a and b in the two derivatives

$$p = z_x = f_x(x, y, a, b)$$

$$q = z_y = f_y(x, y, a, b),$$

we can eliminate in equation (6) and obtain the partial differential equation

$$(7) \quad z - f(x, y, a(x, y, p, q), b(x, y, p, q)) = 0$$

having the given family as solutions. We will call a two parameter family of solutions a complete solution of the differential equation.

Suppose now we have a complete solution $z = f(x, y, a, b)$ and wish to find an envelope containing the initial curve, say

$$x = x(s), \quad y = y(s), \quad z = z(s).$$

We consider the two equations

$$(8) \quad G(s, a, b) \equiv z(s) - f(x(s), y(s), a, b) = 0$$

and

$$(9) \quad G_s(s, a, b) = z'(s) - f_x x'(s) - f_y y'(s) = 0,$$

obtaining a relation between a and b , say in terms of the parameter s :

$a = a(s)$, $b = b(s)$. The envelope

$$(10) \quad \begin{aligned} z &= f(x, y, a(s), b(s)) \\ 0 &= f_a a'(s) + f_b b'(s) \end{aligned}$$

will contain the initial curve. For both equations are satisfied identically in s by $x(s)$, $y(s)$, $z(s)$; the first as a direct consequence of equation (8), and the second from the derivative of the first

$$z'(s) = f_x x'(s) + f_y y'(s) + f_a a'(s) + f_b b'(s),$$

or

$$0 = f_a a'(s) + f_b b'(s),$$

where we used equation (9).

For example, we consider the two parameter family of planes which are of unit distance from the origin, i.e. the planes touching the unit sphere. They are given by the equation

$$z = \frac{-a}{\sqrt{1 - (a^2 + b^2)}} x - \frac{b}{\sqrt{1 - (a^2 + b^2)}} y + \frac{1}{\sqrt{1 - (a^2 + b^2)}},$$

and can be shown to be a complete solution of the P.D.E.

$$(z - px - qy)^2 - (1 + p^2 + q^2) = 0.$$

If we wish to find an integral surface containing the initial curve, say the circle of radius $\frac{1}{2}$ about the z -axis,

$$z = 1, \quad x = \frac{1}{2} \cos \theta, \quad y = \frac{1}{2} \sin \theta, \quad 0 \leq \theta \leq 2\pi$$

we would obtain from the given family of planes the equations

$$G(\theta, a, b) = \sqrt{1 - (a^2 + b^2)} + \frac{a}{2} \cos \theta + \frac{b}{2} \sin \theta - 1 = 0$$

$$G_\theta(\theta, a, b) = a \sin \theta - b \cos \theta = 0,$$

which lead to the relations

$$a = \frac{4}{5} \cos \theta, \quad b = \frac{4}{5} \sin \theta, \quad \text{or} \quad a^2 + b^2 = \frac{16}{25}.$$

The required integral surface is then the envelope of the family

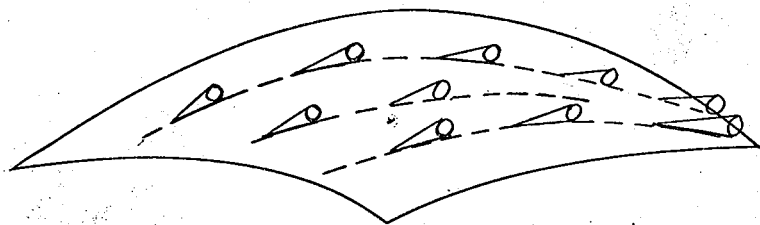
$$z = -\frac{4}{3}x \cos \theta - \frac{4}{3}y \sin \theta + \frac{5}{3},$$

which can be computed to be the cone

$$z = -\frac{4}{3}\sqrt{x^2 + y^2} + \frac{5}{3}.$$

All this is very well if we already have a two parameter family of integral surfaces. We continue therefore with a more systematic attack with the object in mind to describe a system of ordinary differential equations the solutions of which will lead to a solution of the given partial differential equation.

Suppose we are given an integral surface $z = z(x, y)$ having continuous second derivatives with respect to x and y . At each point the surface will be tangent to a Monge cone. See figure below. The lines of contact between the tangent



planes of the surface and the cones define a field of directions on the surface called the characteristic directions, and the integral curves of this field define a family of characteristic curves.

In order to describe the characteristic curves, we obtain first an analytic expression for the Monge cone at some fixed point (x_0, y_0, z_0) . It is the envelope of the one parameter family of planes

$$z - z_0 = p(x - x_0) + q(y - y_0)$$

where p and q satisfy

$$(11) \quad F(x_0, y_0, z_0, p, q) = 0, \quad \text{or} \quad q = q(x_0, y_0, z_0, p),$$

and therefore can be given by the equations

$$(12) \quad \begin{aligned} z - z_0 &= p(x - x_0) + q(x_0, y_0, z_0, p)(y - y_0) \\ 0 &= (x - x_0) + (y - y_0) \frac{dq}{dp}. \end{aligned}$$

From equations (11) we obtain

$$(13) \quad \frac{dF}{dp} = F_p + F_q \frac{dq}{dp} = 0$$

so that $\frac{dq}{dp}$ may be eliminated from (12) and the equations describing the Monge cone written

$$(14) \quad \begin{aligned} F(x_0, y_0, z_0, p, q) &= 0 \\ z - z_0 &= p(x - x_0) + q(y - y_0) \\ \frac{x - x_0}{F_p} &= \frac{y - y_0}{F_q}. \end{aligned}$$

We note that given p and q the last two equations define a generating line of the cone, i.e. the line of contact between the tangent plane and the cone.

Thus on our given integral surface, where at each point $p_0 = p(x_0, y_0)$ and $q_0 = q(x_0, y_0)$ are known, the tangent plane

$$z - z_0 = p_0(x - x_0) + q_0(y - y_0)$$

together with the equation

$$\frac{x - x_0}{F_p} = \frac{y - y_0}{F_q}$$

determine the line of contact with the Monge cone

$$\frac{x-x_0}{F_p} = \frac{y-y_0}{F_q} = \frac{z-z_0}{pF_p + qF_q},$$

or characteristic direction

$$(F_p, F_q, pF_p + qF_q).$$

It follows then that the characteristic curves are determined by the system of ordinary differential equations

$$(14) \quad \frac{dx}{F_p} = \frac{dy}{F_q} = \frac{dz}{pF_p + qF_q}$$

or

$$(15) \quad \frac{dx}{dt} = F_p, \quad \frac{dy}{dt} = F_q, \quad \frac{dz}{dt} = pF_p + qF_q.$$

If the integral surface is as yet unknown, it is clear that the three equations (14) or (15) will not be enough to determine the characteristic curves comprising the surface. For one thing the equations contain two too many unknown functions, namely p and q . However more information concerning the behavior of p and q along a characteristic curve can be obtained. For along such a curve on the given integral surface we have

$$(16) \quad \begin{aligned} \frac{dp}{dt} &= p_x \frac{dx}{dt} + p_y \frac{dy}{dt} = p_x F_p + p_y F_q, \\ \frac{dq}{dt} &= q_x \frac{dx}{dt} + q_y \frac{dy}{dt} = q_x F_p + q_y F_q. \end{aligned}$$

Returning to the differential equation (1) and differentiating first with respect to x and then with respect to y , we have

$$F_x + F_z p + F_p p_x + F_q q_x = 0$$

$$F_y + F_z q + F_p p_y + F_q q_y = 0,$$

so that equations (16) may be written

$$(17) \quad \begin{aligned} \frac{dp}{dt} &= -F_x - F_z p \\ \frac{dq}{dt} &= -F_y - F_z q \end{aligned}$$

where we have used $p_y = q_x$.

We have then associated with the given integral surface $z = z(x, y)$ a family of characteristic curves on the surface such that the coordinates of the curve $x(t)$, $y(t)$, $z(t)$, and along the curve, the numbers $p(t)$, $q(t)$ are related by the system of five ordinary differential equations (15) and (17). These five ordinary differential equations are called the characteristic differential equations related to the given P.D.E. (1).

Suppose now the integral surface is as yet to be determined. We are led by the previous discussion to consider the partial differential equation (1) together with the system of characteristic equations (15) and (17), as a system of six equations

$$(18) \quad \begin{aligned} F(x, y, z, p, q) &= 0 \\ \frac{dx}{dt} &= F_p \\ \frac{dy}{dt} &= F_q \\ \frac{dz}{dt} &= pF_p + qF_q \\ \frac{dp}{dt} &= -F_x - F_z p \\ \frac{dq}{dt} &= -F_y - F_z q \end{aligned}$$

for the five unknown functions $x(t)$, $y(t)$, $z(t)$, $p(t)$, $q(t)$. This system is overdetermining; however the finite equation $F(x, y, z, p, q) = 0$ is not much of a restriction. For along a solution of the last five equations,

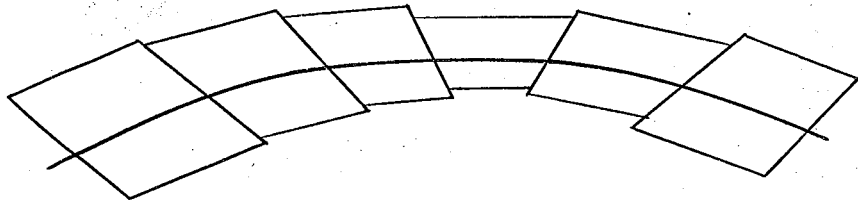
$$\frac{dF}{dt} = F_x \frac{dx}{dt} + F_y \frac{dy}{dt} + F_z \frac{dz}{dt} + F_p \frac{dp}{dt} + F_q \frac{dq}{dt}$$

$$= F_x F_p + F_y F_q + p F_z F_p + q F_z F_q - F_p F_x - F_p F_z p - F_q F_y - F_q F_z q \\ = 0.$$

Showing that $F = \text{const.}$ is an integral of the ordinary differential equations.

It is clear then that if $F = 0$ is satisfied at an initial "point", say x_0, y_0, z_0, p_0, q_0 for $t = 0$, the five characteristic equations will determine a unique solution $x(t), y(t), z(t), p(t), q(t)$ passing through this point and along which $F = 0$ will be satisfied for all t .

A solution to (18) can be interpreted as a strip. That is, a space curve $x = x(t), y = y(t), z = z(t)$ and along it a family of tangent planes defined by the direction numbers $(p, q, -1)$. See figure below.



For fixed t_0 the five numbers x_0, y_0, z_0, p_0, q_0 will be said to define an element of the strip, i.e. a point on the curve and the corresponding tangent plane.

Note not any set of five functions can be interpreted as a strip. Namely we require that the planes be tangent to the curve, which is the condition

$$(19) \quad \frac{dz(t)}{dt} = p(t) \frac{dx(t)}{dt} + q(t) \frac{dy(t)}{dt},$$

called the strip condition. In our case the strip condition is guaranteed by the first three characteristic equations.

We will call the strips which are solutions to (18) characteristic strips and their corresponding curves characteristic curves.

We will show that if a characteristic strip has one element x_0, y_0, z_0, p_0, q_0 in common with an integral surface $z = u(x, y)$, it lies completely on the surface.

For, given a solution u , consider the two ordinary differential equations

$$(20) \quad \frac{dx}{dt} = F_p(x, y, u(x, y), u_x(x, y), u_y(x, y))$$

$$\frac{dy}{dt} = F_q(x, y, u(x, y), u_x(x, y), u_y(x, y))$$

for $x(t), y(t)$ with initial conditions $x(0) = x_0, y(0) = y_0$. They will uniquely determine a curve $x = x(t), y = y(t)$ along which the corresponding curve on the integral surface

$$(21) \quad x = x(t), y = y(t), z = u(x(t), y(t))$$

satisfies

$$(22) \quad \frac{du}{dt} = u_x \frac{dx}{dt} + u_y \frac{dy}{dt} = u_x F_p + u_y F_q,$$

$$(23) \quad \frac{du_x}{dt} = u_{xx} F_p + u_{xy} F_q,$$

and

(24)

$$\frac{du_y}{dt} = u_{yx} F_p + u_{yy} F_q,$$

where $u(0) = u(x_0, y_0) = z_0$, $u_x(0) = u_x(x_0, y_0) = p_0$, and $u_y(0) = u_y(x_0, y_0) = q_0$.

By assumption

(25)

$$F(x, y, u(x, y), u_x(x, y), u_y(x, y)) = 0,$$

and thus

$$F_x + F_u u_x + F_{ux} u_{xx} + F_{uy} u_{yx} = 0$$

$$F_y + F_u u_y + F_{ux} u_{xy} + F_{uy} u_{yy} = 0,$$

so that equations (22) and (23) can be written

(26)

$$\frac{du_x}{dt} = -F_x - F_z u_x,$$

and

(27)

$$\frac{du_y}{dt} = -F_y - F_z u_y,$$

where we used $u_{xy} = u_{yx}$.

Examine now the five functions $x = x(t)$, $y = y(t)$, $z = u(x(t), y(t))$,

$p = u_x(x(t), y(t))$, $q = u_y(x(t), y(t))$. They determine a characteristic strip.

For they satisfy the five characteristic equations, (20), (21), (22), (26), (27), and the finite equation (25). Moreover, they determine the unique characteristic strip with the initial element x_0, y_0, z_0, p_0, q_0 . But this strip lies on the surface by definition, and thus the theorem is proved.

It is clear now from previous considerations how we may proceed to solve the Cauchy initial value problem with the help of these characteristic strips. For consider some arbitrary initial curve

$$x = x_0(s), \quad y = y_0(s), \quad z = z_0(s).$$

If along this curve we can assign functions $p_0(s)$ and $q_0(s)$ such that together with the initial curve $x_0(s), y_0(s), z_0(s)$ we will have defined a family of appropriate initial elements, i.e. satisfying the equation

$$(28) \quad F(x_0(s), y_0(s), z_0(s), p_0(s), q_0(s)) = 0,$$

and being tangent to the initial curve, i.e. satisfying as well the strip condition

$$(29) \quad \frac{dz_0}{ds} = p_0 \frac{dx_0}{ds} + q_0 \frac{dy_0}{ds},$$

we may expect to construct the integral surface by means of the characteristic strips issuing from the initial elements.

The initial elements $x_0(s), y_0(s), z_0(s), p_0(s), q_0(s)$ satisfying equations (28) and (29) will be said to define an initial strip through the initial curve.

Note that there can be more than one integral surface passing through the initial curve. For there can be more than one pair of functions p_0 and q_0 satisfying the two equations (28) and (29). However, once $p_0(s)$ and $q_0(s)$ are chosen, that is once an initial strip is determined we can expect the solution to be unique. In the quasi-linear case we note that both equations (28) and (29) are linear in p and q and thus only one solution in general occurs.

Again we will require that the initial strip be non-characteristic. In fact, again we will require a more stringent condition

$$\frac{dx_0}{F_p} \neq \frac{dy_0}{F_q}.$$

The ~~complete~~ formulation of the initial value theorem and proof follows:

Theorem. Consider the partial differential equation

$$(30) \quad F(x, y, z, p, q) = 0,$$

where F has continuous second derivatives with respect to its variables x, y, z, p, q . Suppose that along the initial curve $x = x_0(s)$, $y = y_0(s)$, $0 \leq s \leq 1$, the initial values $z = z_0(s)$ are assigned, x_0, y_0, z_0 having continuous second derivatives. Suppose further that continuously differentiable functions $p_0(s)$, $q_0(s)$ have been determined satisfying the two equations

$$(31) \quad \begin{aligned} F(x_0(s), y_0(s), z_0(s), p_0(s), q_0(s)) &= 0 \\ \frac{dz_0}{ds} &= p_0 \frac{dx_0}{ds} + q_0 \frac{dy_0}{ds}. \end{aligned}$$

Finally, suppose that the five functions x_0, y_0, z_0, p_0, q_0 satisfy

$$(32) \quad \frac{dx_0}{ds} F_q(x_0, y_0, z_0, p_0, q_0) - \frac{dy_0}{ds} F_p(x_0, y_0, z_0, p_0, q_0) \neq 0.$$

Then in some neighborhood of the initial curve there will exist one and only one solution $z = u(x, y)$ of (30) containing the initial strip, i.e. such that

$$z(x_0(s), y_0(s)) = z_0(s), \quad z_x(x_0(s), y_0(s)) = p_0(s),$$

$$z_y(x_0(s), y_0(s)) = q_0(s).$$

Proof. We consider the system of characteristic equations

$$(33) \quad \begin{aligned} \frac{dx}{dt} &= F_p, & \frac{dy}{dt} &= F_q, & \frac{dp}{dt} &= -F_x - pF_z, \\ \frac{dz}{dt} &= pF_p + qF_q, & \frac{dq}{dt} &= -F_y - qF_z, \end{aligned}$$

with the family of initial conditions $x = x_0(s)$, $y = y_0(s)$, $z = z_0(s)$, $p = p_0(s)$, $q = q_0(s)$ for $t = 0$. From the existence and uniqueness theorem of the initial value problem for ordinary differential equations we can obtain a family of solutions depending on the initial parameter s

$$(34) \quad \begin{aligned} x &= X(s, t), & y &= Y(s, t), & z &= Z(s, t), & p &= P(s, t), \\ & & & & & & q &= Q(s, t), \end{aligned}$$

where X, Y, Z, P, Q have continuous derivatives with respect to s and t and such that they satisfy the initial conditions

$$(35) \quad \begin{aligned} X(s, 0) &= x_0(s), & Y(s, 0) &= y_0(s), & Z(s, 0) &= z_0(s), \\ P(s, 0) &= p_0(s), & Q(s, 0) &= q_0(s). \end{aligned}$$

Having determined then the characteristic strips issuing from the initial elements we would like to show that the characteristic curves of these strips

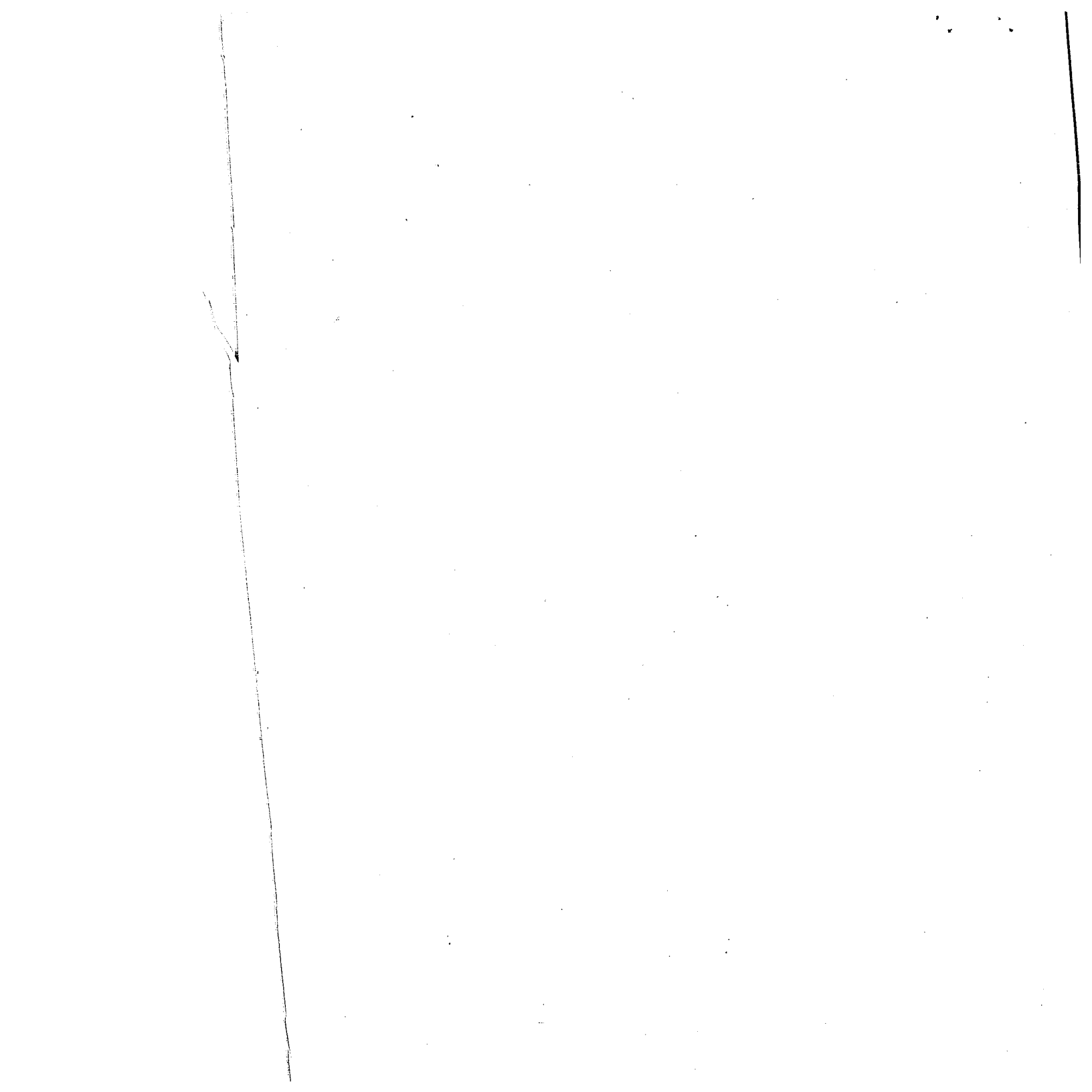
$$x = X(s, t), \quad y = Y(s, t), \quad z = Z(s, t)$$

indeed form a surface. Namely we would like to solve for s and t in terms of x and y in the first two equations then, substituting in the last, obtain the surface $z = Z(s(x, y), t(x, y)) = z(x, y)$ as a function of the two variables x and y . This can be done for some neighborhood $N(\xi, \eta)$ about each point (ξ, η) on the initial curve since along the initial curve the Jacobian

$$(36) \quad \left. \frac{\partial(X, Y)}{\partial(s, t)} \right|_{t=0} = \begin{vmatrix} X_s & X_t \\ Y_s & Y_t \end{vmatrix}_{t=0} = \frac{dx_0}{ds} F_q - \frac{dy_0}{ds} F_p \neq 0,$$

by condition (32).

We have then defined in $N(\xi, \eta)$ the functions



$$\begin{aligned}
 s &= s(x,y), \quad x \equiv X(s(x,y), t(x,y)), \\
 t &= t(x,y), \quad y \equiv Y(s(x,y), t(x,y)), \\
 (37) \quad z &= Z(s(x,y), t(x,y)) = z(x,y), \\
 p &= P(s(x,y), t(x,y)) = p(x,y), \quad q = Q(s(x,y), t(x,y)) = q(x,y).
 \end{aligned}$$

We wish to show that $z(x,y)$ as a solution to the P.D.E. (30), i.e.

$$F(x, y, z(x, y), z_x(x, y), z_y(x, y)) = 0.$$

Since we know from previous considerations of characteristic strips that

$$F(x, y, z, p, q) = 0,$$

all that remains to be proved is that

$$p = z_x \quad \text{and} \quad q = z_y.$$

We consider the expression

$$(38) \quad U(s, t) \equiv Z_s - pX_s - qY_s.$$

For $t = 0$

$$U(s, 0) = \frac{dz_0}{ds} - p_0 \frac{dx_0}{ds} - q_0 \frac{dy_0}{ds} = 0,$$

by the strip condition for the initial elements (31). We would like to show that $U = 0$ for all t , which expresses the fact that the characteristic strips fit smoothly together. To do this we consider the derivative of U with respect to t

$$\begin{aligned}
\frac{\partial U}{\partial t} &= Z_{st} - P_t X_s - Q_t Y_s - P X_{st} - Q Y_{st} \\
&= \frac{\partial}{\partial s}(Z_t - P X_t - Q Y_t) + P_s X_t + Q_s Y_t - Q_t Y_s - P_t X_s \\
&= 0 + F_p P_s + F_q Q_s + (F_x + F_z P) X_s + (F_y + F_z Q) Y_s,
\end{aligned}$$

where we made use of the characteristic equations (33). We have further, by adding and subtracting $F_z Z_s$ and then rearranging terms

$$\begin{aligned}
\frac{\partial U}{\partial t} &= F_x X_s + F_y Y_s + F_z Z_s + F_p P_s + F_q Q_s - F_z (Z_s - P X_s - Q Y_s) \\
&= F_s - F_z U \\
&= -F_z U,
\end{aligned}$$

since $F_s \equiv 0$ in s and t .

That is for fixed s the function U satisfies the ordinary differential equation

$$\frac{\partial U}{\partial t} = -F_z U,$$

having the solution

$$U = U(0) e^{-\int_0^t F_z dt}.$$

Since $U = 0$ for $t = 0$ it follows that $U \equiv 0$ for all t , i.e.

$$Z_s = P X_s + Q Y_s.$$

We observe now the four equations

$$Z_s = P X_s + Q Y_s$$

$$Z_t = P X_t + Q Y_t$$

$$Z_s = z_x X_s + z_y Y_s$$

$$Z_t = z_x X_t + z_y Y_t.$$

The first follows from the previous discussion, the second is just the third characteristic equation, and the last two are obtained by differentiating the identities of (37).

The four quantities P, Q, z_x, z_y can be considered as two solutions for two linear equations in two unknowns. However, since near (ξ, η) the determinant

$$\begin{vmatrix} X_s & Y_s \\ X_t & Y_t \end{vmatrix} \neq 0$$

by virtue of equation (36) the two solutions must be identical, i.e.

$$P(s, t) = z_x(x(s, t), y(s, t))$$

$$Q(s, t) = z_y(x(s, t), y(s, t)),$$

or

$$(40) \quad p(x, y) = z_x(x, y)$$

$$q(x, y) = z_y(x, y),$$

as was to be shown.

The solution $z = z(x, y)$ contains the initial strip. For

$$z(x_0, y_0) = z(x(s, 0), y(s, 0)) = Z(s, 0) = z_0(s)$$

$$z_x(x_0, y_0) = p(x_0, y_0) = p(x(s, 0), y(s, 0)) = P(s, 0) = p_0(s)$$

$$z_y(x_0, y_0) = q(x_0, y_0) = q(x(s, 0), y(s, 0)) = Q(s, 0) = q_0(s),$$

by virtue of equations (35), (37), and (40). To show that $z = z(x, y)$ so determined is unique we suppose there exists some other solution $z = z'(x, y)$ defined in $N(\xi, \eta)$ and containing the initial strip. We choose an arbitrary point (x', y') in $N(\xi, \eta)$ and solve for the s' and t' associated with it from the equations

$$s = s(x, y)$$

$$t = t(x, y).$$

We consider now the initial element $x_0(s'), y_0(s'), z_0(s'), p_0(s'), q_0(s')$.

By assumption this element lies on both integral surfaces. Thus the uniquely determined characteristic strip issuing from this element

$$\begin{aligned} x &= X(s', t), \quad y = Y(s', t), \quad z = Z(s', t), \quad p = P(s', t), \\ q &= Q(s', t), \end{aligned}$$

must also be contained in both surfaces. That is

$$z'(X(s', t), Y(s', t)) = Z(s', t) = z(X(s', t), Y(s', t)),$$

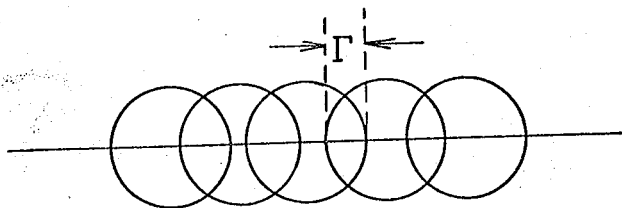
and in particular for t' we have

$$z'(x', y') = z'(X(s', t'), Y(s', t')) = Z(s', t')$$

$$z(X(s', t'), Y(s', t')) = z(x', y').$$

Note that so far we have only constructed a unique solution for a neighborhood $N(\xi, \eta)$ about a point (ξ, η) on the initial curve. We would like to have the solution extended to include the complete curve. This can be done with the help of the uniqueness proof and a proper covering of the initial curve with such neighborhoods $N(\xi, \eta)$.

We suppose then that a region about the initial curve is mapped homeomorphically onto say the u, v -plane such that the initial curve maps into a portion Γ of the line $u = 0$. The system of neighborhoods $N(\xi, \eta)$ will map into a system of neighborhoods $N(u, v)$ which by properly restricting the size of the $N(\xi, \eta)$ we may assume to be circular. We consider now a finite covering S of Γ by the $N(u, v)$. This can be done since the initial curve and thus its image Γ is compact. The intersections of this covering will have a minimum distance, say r . See figure below.



Suppose now we cover Γ with a second set T of the $N(u, v)$ having a maximum diameter of $r/2$. This covering T will then have the property that intersections of any of its neighborhoods will lie entirely within at least one of the neighborhoods of the covering S .

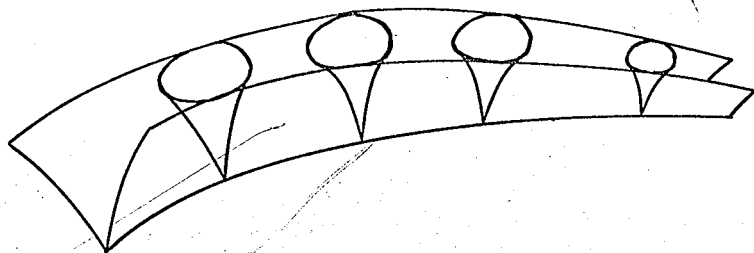
Consider the solutions $z_T(x, y)$ which have been constructed for the neighborhoods of the covering T . It is clear that they will define a solution of the Cauchy problem for the whole curve. For all that has to be shown is that the z_T agree along the intersections of their respective neighborhoods. But this is clear by the uniqueness proof for the neighborhoods of the first covering S .

We have seen before that we can solve the Cauchy problem with the help of a complete integral. There is yet another type of solution which is also convenient for this purpose. Namely, at each point (x_0, y_0, z_0) in space there is a one parameter family of elements $x_0, y_0, z_0, p_0(s), q_0(s)$ through each of which we can pass characteristic strips. This one parameter family of strips will in general form a certain conical surface with a singularity at the point (x_0, y_0, z_0) .



It can be proved in a manner similar to what has been done in the existence theorem that this surface, called a conoid, will be an integral surface. Note that the first approximation to the conoid at the singular point is given by the Monge cone.

The figure below indicates how a conoid may be used to solve the initial problem.



Namely, it is plausible that the envelope of the family of conoids whose singular points lie on the given initial curve will be a solution containing this curve. This envelope may consist of several sheets corresponding to the various integral surfaces which may pass through the given curve.

A complete integral $z = f(x, y, a, b)$, besides being useful to solve the Cauchy problem, can also be used to obtain all characteristic strips and conoids. For suppose the parameter b is given as a function of a . We consider the envelope

$$b = b(a)$$

$$z = f(x, y, a, b)$$

$$0 = f_a + f_b b'(a)$$

for a fixed a the above expression represents a curve of contact between the envelope and family. The curve of contact is bound to be characteristic. The associated functions p and q are given by

$$p = f_x$$

$$q = f_y$$

We need not take b as a function of a . We can consider instead the equations

$$(41) \quad \begin{aligned} z &= f(x, y, a, b) \\ 0 &= f_a + f_b c \\ p &= f_x \\ q &= f_y. \end{aligned}$$

For any a, b, c we will obtain a characteristic strip. For a function b can be found for which $b \equiv b(a)$ and $c \equiv b'(a)$. The conoids are obtained by taking the family of strips which pass through a given point.

3. The general first order equation for a function of n independent variables.

The general first order P.D.E. for a function of n variables $z = u(x_1, \dots, x_n)$ with first partial derivatives $p_i = u_{x_i}$, $i = 1, \dots, n$, can be written

$$(1) \quad F(x_1, \dots, x_n, z, p_1, \dots, p_n) = 0.$$

A solution $z = u(x_1, \dots, x_n)$ will appear as a certain n dimensional hypersurface imbedded in the $n+1$ space $(z, x_1, \dots, x_n)$.

The theory of characteristics can be extended to equations (1) in a manner simply analogous to what has been done for the case $n = 2$. Namely, we consider the P.D.E. (1) together with the system of characteristic equations

$$(2) \quad \begin{aligned} \frac{dx_i}{dt} &= F_{p_i} & i &= 1, \dots, n \\ \frac{dz}{dt} &= \sum_{i=1}^n p_i F_{p_i} \\ \frac{dp_i}{dt} &= -F_{x_i} - p_i F_z & i &= 1, \dots, n. \end{aligned}$$

12/1

2-13-73

6:30-8:30 on Tuesday at lounge; next week on Thursday ask Sec about room

Elliptic 2nd order PDE

$$c^2 (u_{xx} + u_{yy} + u_{zz}) = u_{tt} + \gamma u_t \quad \text{3-D telegraphic equation}$$

$\gamma \rightarrow 0$ wave equation

$c \rightarrow \infty$ parabolic

$\frac{\partial}{\partial t} = 0$ static deformations

$$\Delta u = 0 \quad \text{Laplace's Equation}$$

$$\Delta u = -f(x, y, z, t) \quad \text{Poisson's Equation}$$

B.C.:

1. Specify $u|_{\Sigma} = f_1$: Dirichlet Region T and surface Σ
2. $\frac{\partial u}{\partial n}|_{\Sigma} = f_2$: Neumann $\frac{\partial}{\partial n}$ = deriv in direct of normal to Σ
3. $\frac{\partial u}{\partial n} + h(u - f_3) = 0$: mixed

Applied to Exterior and interior regions

Interior Σ is bounded and closed and contains T



Exterior Σ is bounded and closed T is outside Σ & unbounded



Applications : static fields

u : temp field, stress field, E-M potential, velocity potential in incompressible, inviscid, irrotational flows.

Cartesian $u_{xx} + u_{yy} + u_{zz} = 0$ x, y, z

Spherical $\frac{1}{r^2} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial u}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u}{\partial \phi^2} = 0$ r, θ, ϕ

Cylindrical $\frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial u}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 u}{\partial \phi^2} + \frac{\partial^2 u}{\partial z^2} = 0$ ρ, ϕ, z

3 dim $\frac{\partial}{\partial \theta}, \frac{\partial}{\partial \phi} = 0 \Rightarrow \frac{d}{dr} \left(r^2 \frac{du}{dr} \right) = 0 \Rightarrow u = \frac{c_1}{r} + c_2$

Fund to 3 dim Laplace Equ is $u(r) = \frac{1}{r}$ ($r \neq 0$)

$u(x, y, z) = \frac{1}{\sqrt{x^2 + y^2 + z^2}}$

Cylindrical $\frac{\partial}{\partial \phi}, \frac{\partial}{\partial z} = 0$ (2 dim)

$\frac{d}{d\rho} \left(\rho \frac{du}{d\rho} \right) = 0$ $u = c_1 \ln \rho + c_2$

Fund to 2 dim $u = \ln \left(\frac{1}{\rho} \right)$ $\rho \neq 0$

$w = f(z)$ where $w = u + iv$ $z = x + iy$

Define $\frac{dw}{dz} = \lim_{\Delta z \rightarrow 0} \left[\frac{f(z + \Delta z) - f(z)}{\Delta z} \right]$

as $\Delta z \rightarrow 0$ in any direction

If lim exists then w is called analytic at z

$\frac{dw}{dx} = u_x + i v_x = \frac{dw}{dz} \frac{dz}{dx} = \frac{dw}{dz}$

$\frac{dw}{dy} = u_y + i v_y = \frac{dw}{dz} \frac{dz}{dy} = i \frac{dw}{dz}$

$$\frac{dw}{dz} = u_x + i v_x = -i u_y + v_y$$

then $u_x = v_y$ $v_x = -u_y$ Cauchy-Riemann Equations

$\Rightarrow u_{xx} + u_{yy} = v_{xx} + v_{yy} = 0$ i.e. Real & Imaginary parts of an analytic function satisfy Laplace's Equation - called conjugate harmonic functions.

In general a fn satisfying Laplace's Equation is called a harmonic function

Properties of Harmonic Fns.

- ① Principle of the maximum
 - ② Uniqueness
 - ③ Boundary value problems
- } Green's Formula.

$$\iiint_T \left(\frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} \right) d\tau = \iint_\Sigma (P \cos \alpha + Q \cos \beta + R \cos \gamma) d\sigma$$

$$d\tau = dx dy dz \quad \underline{n} \cdot \underline{i} = \cos \alpha \quad \underline{n} \cdot \underline{k} = \cos \gamma$$

$$\underline{n} = \text{exterior normal} \quad \underline{n} \cdot \underline{j} = \cos \beta$$

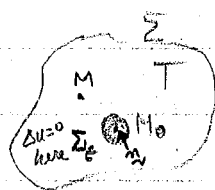
$$\text{let } P = u \frac{\partial v}{\partial x} \quad Q = u \frac{\partial v}{\partial y} \quad R = u \frac{\partial v}{\partial z}$$

$$\iiint_T (u \Delta v) d\tau = \iint_\Sigma u \frac{\partial v}{\partial n} d\sigma - \iiint_T (\nabla u) \cdot (\nabla v) d\tau$$

$$\text{let } P = v \frac{\partial u}{\partial x} \quad Q = v \frac{\partial u}{\partial y} \quad R = v \frac{\partial u}{\partial z}$$

and subtract

$$\iiint_T (u \Delta v - v \Delta u) d\tau = \iint_\Sigma \left(u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} \right) d\sigma \quad (1)$$



test fn $U_0(M) = \frac{1}{r}$ satisfies Laplace's Equation
where r = distance between M and $M_0 \in T$

let $u(M)$ satisfy $\Delta u = 0$

$\nabla u \in C'$ in $T \setminus \Sigma$

In (1) let $v = \frac{1}{r} = U_0(M)$ - singular at M_0

Consider a sphere K_ϵ center M_0 , radius ϵ . Use (1) in region $T - K_\epsilon$

$$\iiint_{T-K_\epsilon} (u \Delta v - v \Delta u) d\sigma = 0$$

$$0 = \iint_{\Sigma} \left(u \frac{\partial}{\partial n} \left(\frac{1}{r} \right) - \frac{1}{r} \frac{\partial u}{\partial n} \right) d\sigma + \iint_{\Sigma_\epsilon} u \frac{\partial}{\partial n} \left(\frac{1}{r} \right) d\sigma - \iint_{\Sigma_\epsilon} \frac{1}{r} \frac{\partial u}{\partial n} d\sigma$$

$$\frac{\partial}{\partial n} \text{ on sphere is } -\frac{\partial}{\partial r} \quad \frac{\partial}{\partial n} \left(\frac{1}{r} \right) = -\frac{\partial}{\partial r} \left(\frac{1}{r} \right) = \frac{1}{r^2} = \frac{1}{\epsilon^2} \text{ on } \Sigma_\epsilon$$

$$\iint_{\Sigma_\epsilon} u \frac{\partial}{\partial n} \left(\frac{1}{r} \right) d\sigma = \frac{1}{\epsilon^2} \iint_{\Sigma_\epsilon} u d\sigma = \frac{1}{\epsilon^2} 4\pi \epsilon^2 u^* \quad (2)$$

where u^* is an average value of u over Σ_ϵ ; $u^* = \frac{1}{4\pi \epsilon^2} \iint_{\Sigma_\epsilon} u d\sigma$

$$\iint_{\Sigma_\epsilon} \frac{1}{r} \frac{\partial u}{\partial n} d\sigma = \frac{1}{\epsilon} 4\pi \epsilon^2 \left(\frac{\partial u}{\partial n} \right)^* \quad (3) \quad \left(\frac{\partial u}{\partial n} \right)^* = \frac{1}{4\pi \epsilon^2} \iint_{\Sigma_\epsilon} \frac{\partial u}{\partial n} d\sigma$$

let $\epsilon \rightarrow 0 \Rightarrow \Sigma_\epsilon \rightarrow M_0 \quad (2) \rightarrow 4\pi u|_{M_0} \quad \epsilon \rightarrow 0$

$$\iint_{\Sigma} \left(u \frac{\partial}{\partial n} \left(\frac{1}{r} \right) - \frac{1}{r} \frac{\partial u}{\partial n} \right) d\sigma + 4\pi u|_{M_0} \stackrel{(3)}{=} 0 \rightarrow 0$$

$$u(M_0) = \frac{1}{4\pi} \iint_{\Sigma} \left[\frac{1}{r} \frac{\partial u}{\partial n} - u \frac{\partial}{\partial n} \left(\frac{1}{r} \right) \right] d\sigma$$

distance between $M_0, P \quad P \in \Sigma$

ie the value of harmonic fn $u(M_0)$ at an arbitrary interior pt M_0 is determined in terms of its values & its normal deriv on the boundary of the region [D'Alembert?]

Consequences

1. If v is harmonic in T then $\iint_{\Sigma} \frac{\partial v}{\partial n} d\sigma = 0$

Proof: Put $u=1$ in Green's formula

$$\Delta v = 0 \quad \Delta u = 0 \quad \frac{\partial u}{\partial n} = 0$$

2. Prescribe $\frac{\partial u}{\partial n}$ on Σ (Neumann) = f then $\iint_{\Sigma} f d\sigma = 0$ for a soln to exist

3. Spherical Region Σ_a , center M_0

$$u(M_0) = \frac{1}{4\pi a^2} \iint_{\Sigma_a} u d\sigma$$

$$\text{Proof: } 4\pi u(M_0) = - \iint_{\Sigma_a} \left[u \frac{\partial}{\partial n} \left(\frac{1}{r} \right) - \frac{1}{r} \frac{\partial u}{\partial n} \right] d\sigma$$

$$\frac{1}{a} \iint_{\Sigma_a} \frac{\partial u}{\partial n} d\sigma = \frac{1}{a} \cdot 0 = 0$$

$$\frac{\partial}{\partial n} \left(\frac{1}{r} \right) \Big|_{\Sigma_a} = -\frac{1}{a^2}$$



$$u(M_0) = \frac{1}{4\pi a^2} \iint_{\Sigma_a} u d\sigma \quad \text{spherical mean}$$

4. Principle of the Max

If a fn $u(M)$ is continuous and defined on a closed region $T + \Sigma$ and satisfies $\Delta u = 0$ in the interior of T , then it assumes its max and min on the boundary Σ

Proof: by contradiction

Let u attain its max at M_0 interior to T

Then $u(M) \leq u(M_0) \quad \forall M \in T$

Enclose M_0 with a sphere, center M_0 , rad ρ

lying entirely in T . Then $u(M_0) = \frac{1}{4\pi\rho^2} \iint_{\Sigma_\rho} u(M) d\sigma$

$$\leq \frac{1}{4\pi\rho^2} \iint_{\Sigma_\rho} u(M_0) d\sigma = u(M_0)$$

Let $u(M) < u(M_0)$ some $M \in \Sigma_\rho \Rightarrow$ contradiction
otherwise

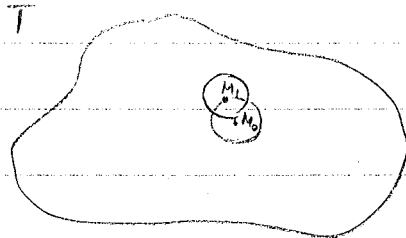
$$u(M_0) < u(M_0) \quad \therefore u(M) = u(M_0) \quad \forall M \in \Sigma_\rho$$

this argument holds for all radii $\leq \rho$ of initial sphere $\Rightarrow u(M) = u(M_0)$ in sphere

Take any M_1 in surface Σ_ρ , $u(M_1) = u(M_0) = \max$ of u

Consider sphere center M_1 , radius ρ , entirely in T

same argument $\Rightarrow u(M) = u(M_1) \quad \forall M$ in Σ_ρ



Type of Heine-Borel Covering Thm.
of T

By continuation $u(M) = u(M_0)$ in T

$\Rightarrow u(M) = \text{constant in } T.$

Consequences of Principle of Maximum

1. If u & U are continuous in $T + \Sigma$ & harmonic in T and if $u \leq U$ on Σ then $u \leq U$ inside T

Proof: $V = u - U$ $V \leq 0$ on $\Sigma \Rightarrow V \leq 0$ in T

2. Similarly if $|u| \leq U$ on Σ then $|u| \leq U$ in T

Uniqueness of Solution

For First B.V. Problem: Dirichlet

Consider region T bounded by Σ . Dirichlet Problem for $\Delta u = 0$ is: determine u s.t.

1. $\Delta u = 0$ interior of T
2. u is defined and continuous on $T + \Sigma$
3. u assumes a prescribed value on Σ

Theorem Soln of Dirichlet Problem is unique

Proof let u_1 and u_2 satisfy (1-3)

Define $V = u_1 - u_2$; Then V satisfies 1) and 2)
and $V|_{\Sigma} = 0$

V satisfies conditions for principle of maximum $\Rightarrow V \equiv 0$ in T
i.e. $u_1 = u_2$ & Soln is unique

Stability of Soln - continuous dependence on boundary data

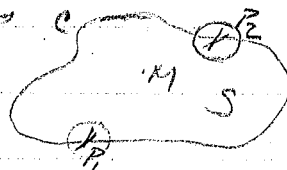
Small changes in boundary data induces small changes in solution

Let u_1 and u_2 satisfy (1-3) $\therefore$ on T by $|u_1 - u_2| < \epsilon$
 Then by consequence $|u_1 - u_2| < \epsilon$ in T

First B.V. problem (2-D)
 for discontinuous boundary data

Let a piecewise continuous fn $f(P)$ be defined on a curve C which bounds the region S . We seek $u(M)$ such that

- 1) $u(M)$ is harmonic in S
- 2) $u(M)$ continuously approaches $f(P)$ as $M \rightarrow P$ whenever f is continuous



- 3) $u(M)$ is bounded in $S+C$ [only needed near to P_i]

Thm: The soln of Dirichlet problem with piecewise continuous boundary data is unique

Proof: Let u_1 & u_2 be 2 soln $V = u_1 - u_2$

- V satisfies
- 1) V is harmonic
 - 2) $V(M) \rightarrow 0$ as $M \rightarrow P$ except at P_i
 - 3) V is bounded in $S+C$ ($|V| < A$)

Construct a fn $U(M)$ $M \in S$ $U(M) = \epsilon \sum_{i=1}^n \frac{D}{r_i(M)}$

where D is $\max |M_1 - M_2|$ $M_1, M_2 \in S+C$

$r_i(M) = |M - P_i| \Rightarrow D > r_i(M) \Rightarrow U(M) > 0$

Enclose each P_i with a circle K_i : center P_i , rad δ

Sufficiently small $\Rightarrow \epsilon \ln(D/\delta) > A$

$U(M) > A$ on $K_i \Rightarrow$ on K_i $|U(M)| > |V|$

In $S - K_i$ $U(M)$ and $|V|$ satisfy $\Delta u = 0$ and are continuous.
 $\Rightarrow u(M) > |V| \quad \forall M$ in $S - K_i$

Then fix M and let $\epsilon \rightarrow 0 \Rightarrow u(M) \rightarrow 0 \Rightarrow |V| \rightarrow 0$

But δ arbitrarily small $\Rightarrow$ let $\delta \rightarrow 0$ when $K_i \rightarrow P_i$
 $\Rightarrow V = u_1 - u_2 \equiv 0$ everywhere in $S + C$ except at P_i

Proved uniqueness except at P_i

Prepare Lecture

Separation of Variables § 4.3, 4 Pg 270

2-27-73

Extension

All pts inside a region u can be made continuous if not already or $u = \infty$ at the pt no jump discontinuities allowable
 i.e. If a bdd fn $u(M)$ is harmonic in the interior of S with the exception of P , then $u(M)$ at P can be defined
 $\Rightarrow u(M)$ is harmonic for all of S .

harmonic fn can only have unbounded singularity in the interior of a region

1. $\lim_{M \rightarrow P} u(M) = \infty$ or $\lim_{M \rightarrow P} u(M)$ exists a finite

Define $u(P) = \lim_{M \rightarrow P} u(M) \Rightarrow u$ harmonic in all of S

Same then holds for 3 dimensions. $\nabla^2 = \frac{1}{r}$

if $u(M)$ harmonic in nbd of P & s.t. $|u| < \underline{\varepsilon(r)}$
 & $\varepsilon(r) \rightarrow 0$ as $r \rightarrow 0$ Then u is bdd $\lim_{r \rightarrow 0} u$ &
 can choose $u(P)$ s.t. u is harmonic at P .

Regularity of Harmonic Fns at ∞ .

Conditions for regularity at ∞ are $|u| < \frac{A}{r}$ $|\frac{\partial u}{\partial x}|, |\frac{\partial u}{\partial y}|, |\frac{\partial u}{\partial z}| < \frac{A}{r^2}$
 $\Rightarrow u$ regular at ∞

Then

if a fn u is harmonic outside of a closed surface Σ & as
 $r \rightarrow \infty$ $u \rightarrow 0$ uniformly, then u is regular at ∞ .

Proof Kelvin Transformation: if u harmonic then v is harmonic

where $v(r', \theta, \varphi) = r u(r, \theta, \varphi)$ $r' = \frac{1}{r}$

$u \rightarrow 0$ $r \rightarrow \infty \Rightarrow \exists$ a fn $\varepsilon^*(r)$ s.t. $|u| < \varepsilon^*(r)$ & $\varepsilon^*(r) \rightarrow 0$
 as $r \rightarrow \infty$. v is harmonic & satisfies

$|v| < \varepsilon^*\left(\frac{1}{r'}\right) \frac{1}{r'} = \underline{\varepsilon(r')}$ where $\varepsilon(r') \rightarrow 0$ as $r' \rightarrow 0$

$\Rightarrow$ limit exists as $r' \rightarrow 0$ $r' \Rightarrow |v| < A$ as $r' \rightarrow 0$

$\Rightarrow |ru| < A$ as $r \rightarrow \infty \Rightarrow |u| < \frac{A}{r}$ as $r \rightarrow \infty$

By writing $u = \frac{v}{r}$ & differentiating wrt x, y, z
 derivatives of v are bdd as $r \rightarrow \infty$ (v harmonic)

$|\frac{\partial u}{\partial x_i}| < \frac{A}{r^2}$ as $r \rightarrow \infty \Rightarrow u$ regular at ∞

Exterior ∇^2 BVP Dirichlet



T unbd

Σ bdy closed curve (surface) $\subset T$

Find $u(x, y, z) \exists$.

1. $\Delta u = 0$ in T

2. $u \in C^2$ in T and ∂T

3. $u|_{\Sigma} = f(x, y, z)$

4. $u(M) \xrightarrow{\text{unif}} 0$ as $M \rightarrow \infty$

(3-dim case) ($u(M)$ must be bdd for 2-dim case)

Condition 4 is necessary for uniqueness

Choose $\Sigma =$ sphere radius R

$f = f_0 =$ constant on R

$u_1 = f_0 \quad u_2 = f_0 \frac{R}{r}$ - non uniqueness if $|u| \not\rightarrow 0$ as $r \rightarrow \infty$

Theorem The exterior FBVP for the 3-dim Laplace equation has a unique soln.

Proof Let u_1, u_2 be solns to 1-4)

define $u = u_1 - u_2 \Rightarrow u$ satisfies 1-4) except $u|_{\Sigma} = 0$

Condition 4) tells us any $\epsilon > 0 \exists R^* \exists |u| < \epsilon$ for

$r = |M| \quad r > R^*$

Let S_{Σ} be any sphere $\exists$ for r on surface of sphere

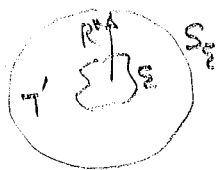
then $r > R^* \Rightarrow$ on $S_{\Sigma} \quad |u| < \epsilon$ let T' be the

region between Σ and S_{Σ} . $|u| < \epsilon$ on S_{Σ} and $|u| \equiv 0$ on Σ

$\Rightarrow |u| < \epsilon$ on bdy of T'

$\Rightarrow$ principle of max $\Rightarrow |u| < \epsilon \quad \forall M \in T'$

But ϵ arbitrary small $\Rightarrow u \equiv 0$



Result also true $\forall r > R^* \Rightarrow u \equiv 0$ in T

2-D case 1-3 same 4) $u(M)$ bdd as $M \rightarrow \infty$

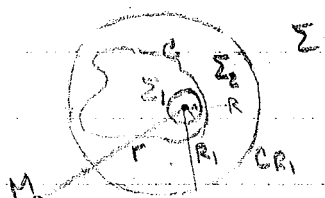
i.e. $\exists N$ s.t. $|u(M)| \leq N \quad \forall M$

Theorem: solution to 2-dim exterior f.b.v.p is unique

Proof then let u_1 & u_2 satisfy 1-4

Define $u = u_1 - u_2$

$\Rightarrow u$ satisfies 1, 2 except $u|_C = 0$ and $|u| \leq N_1 + N_2$
triangle inequality



$\Delta u = 0$ in Σ

let $M_0 \in \Sigma_1$ let circle radius R , center M_0
lie in Σ_1 then if $r = r_{MM_0}$, where $M \in \Sigma$
 $r/R > 1$ and $\ln(r/R) > 0$ & harmonic Σ

Consider R_1 s.t. C_{R_1} about M_0 is entirely in Σ

Construct $U_{R_1}(M) = N \frac{\ln(r/R)}{\ln(R/R_1)}$

$\ln(R/R_1) > 0$ const, $U_{R_1}(M)$ harmonic $= N$ on C_{R_1}

$u = 0$ on $C \Rightarrow |u| \leq N$ on bdy of Σ_2

where $C < \Sigma_2 < C_{R_1}$

$\Rightarrow |u| \leq |U_{R_1}(M)|$ on bdy of Σ_2

principle of maximum $\Rightarrow |u| \leq |U_{R_1}(M)|$ in Σ_2

keep M fixed and let $R_1 \rightarrow \infty \Rightarrow |U_{R_1}| \rightarrow 0$

$$|u| \leq |u_2| \Rightarrow |u| = 0 \quad \& \quad u_1 \equiv u_2$$

Proves uniqueness of exterior f.b.v.p for 2-D.

Neumann Problem ^{second} SBVP
 case where $\frac{\partial u}{\partial n} \Big|_{\Sigma} = f(M)$

Theorem

Solution to SBVP is uniquely determined to within an arbitrary constant. Interior problem

Proof

Assume u_1, u_2 satisfy

1) $\Delta u = 0$

3. $u \in C^2$ in $T \cup \Sigma$

2) $\frac{\partial u}{\partial n} \Big|_{\Sigma} = f$

$\Rightarrow u$ satisfies 1-3) and $\frac{\partial u}{\partial n} \Big|_{\Sigma} = 0$

Green's Formula

$$\iiint_T u \Delta v \, d\tau = \iint_{\Sigma} u \frac{\partial v}{\partial n} \, d\sigma - \iiint_T (\nabla u \cdot \nabla v) \, d\tau$$

In this formula let $u = v \Rightarrow \Delta v = 0 \quad \frac{\partial u}{\partial n} = \frac{\partial v}{\partial n} = 0$

$$GF \Rightarrow \iiint_T \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 \right] d\tau = 0$$

by condition 3 $\Rightarrow \frac{\partial u}{\partial x} = \frac{\partial u}{\partial y} = \frac{\partial u}{\partial z} = 0$ in $T \Rightarrow u \equiv \text{const}$

$$u_1 = u_2 + \text{const.}$$

Exterior 2nd BVP

Same result but must show that G. Formula is true
for u & v regular at ∞ . Then proof same.

MY LECTURE

Hw. P. 330 1/2 done

3 hr class 2 wks.

§ 4.3 Solution of the B. V. Problems for simple Regions by Separation of variables

limit our discussion to those problems which can be solved by trig functions alone.

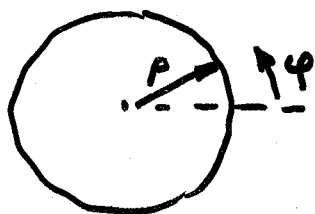
I. The first BVP for the circle

Q: Can we find a fn u which satisfies Laplace's equation of the interior of a circle along with the condition of a prescribed displacement f on the boundary

Find a fn u s.t. $\Delta u = 0$ u in R

$$u = f \quad u \text{ on } \partial R$$

A. Assume $f \in C^1$ and use ρ, φ as coord.



$$\Delta u = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial u}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 u}{\partial \varphi^2} = 0 \quad (1)$$

$$\text{let } u(\rho, \varphi) = R(\rho) \Phi(\varphi) \quad (2)$$

placing (2) into (1) and assuming $\rho, \Phi, R \neq 0$

$$\frac{\rho}{R} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial R}{\partial \rho} \right) = - \frac{\Phi''}{\Phi} = \lambda^2 \quad (3)$$

then (3) gives $\Phi'' + \lambda^2 \Phi = 0$ (4a,b)

and $\rho \frac{d}{d\rho} \left(\rho \frac{dR}{d\rho} \right) - \lambda^2 R = 0$

$$\text{let } p \frac{d}{dp} = \frac{d}{dq}$$

$$dq = \frac{dp}{p}$$

$$R = e^{-c_1 q} + e^{c_2 q}$$

$$q = \ln p$$

$$R = e^{-c_1 \ln p} + e^{c_2 \ln p}$$

$$R = p^{-c_1}, R = p^{c_2} \checkmark$$

from (4a) $\Phi(\varphi) = A \cos \lambda \varphi + B \sin \lambda \varphi$

With the stipulation that φ is periodic in 2π
 $\Rightarrow \lambda = \text{integer}$ call it n

$$\therefore \Phi_n(\varphi) = A_n \cos n\varphi + B_n \sin n\varphi \quad (5a)$$

to solve (4b) let $R(\rho) = \rho^k$

put into 4b one obtains $(k^2 - \lambda^2)\rho^k = 0$

then $k^2 = \lambda^2 = n^2 \therefore k = \pm n \quad n > 0$

then $R(\rho) = C\rho^n + D\rho^{-n} \quad (5b)$

1. Interior problem $D \equiv 0$ if solution is to be harmonic i.e. no singularities in region
2. Exterior problem $C \equiv 0$ if solution is to remain bounded in region

Then for a circle of radius a and let

$$\underline{A}_n = C A_n \quad \underline{B}_n = C B_n$$

$$\overline{A}_n = D A_n \quad \overline{B}_n = D B_n \quad \text{the solutions are}$$

$$u_n(\rho, \varphi) = (\underline{A}_n \cos n\varphi + \underline{B}_n \sin n\varphi) \rho^n \quad \rho \leq a$$

$$u_n(\rho, \varphi) = (\overline{A}_n \cos n\varphi + \overline{B}_n \sin n\varphi) \rho^{-n} \quad \rho \geq a$$

by superposition principle of linear operators

$$(6) \quad \begin{aligned} u(\rho, \varphi) &= \sum_{n=0}^{\infty} (\underline{A}_n \cos n\varphi + \underline{B}_n \sin n\varphi) \rho^n \quad \text{interior} \\ u(\rho, \varphi) &= \sum_{n=0}^{\infty} (\overline{A}_n \cos n\varphi + \overline{B}_n \sin n\varphi) \rho^{-n} \quad \text{exterior} \end{aligned}$$

1. The first part of the document is a letter from the President of the United States to the Congress.

2. The second part is a report from the Secretary of the Treasury on the state of the Union.

3. The third part is a report from the Secretary of the Navy on the state of the Navy.

4. The fourth part is a report from the Secretary of the War on the state of the War.

5. The fifth part is a report from the Secretary of the Interior on the state of the Interior.

6. The sixth part is a report from the Secretary of the Agriculture on the state of the Agriculture.

7. The seventh part is a report from the Secretary of the Commerce on the state of the Commerce.

8. The eighth part is a report from the Secretary of the Education on the state of the Education.

9. The ninth part is a report from the Secretary of the Health on the state of the Health.

10. The tenth part is a report from the Secretary of the Labor on the state of the Labor.

11. The eleventh part is a report from the Secretary of the Finance on the state of the Finance.

12. The twelfth part is a report from the Secretary of the Justice on the state of the Justice.

13. The thirteenth part is a report from the Secretary of the State on the state of the State.

14. The fourteenth part is a report from the Secretary of the War on the state of the War.

15. The fifteenth part is a report from the Secretary of the Navy on the state of the Navy.

16. The sixteenth part is a report from the Secretary of the Interior on the state of the Interior.

17. The seventeenth part is a report from the Secretary of the Agriculture on the state of the Agriculture.

18. The eighteenth part is a report from the Secretary of the Commerce on the state of the Commerce.

19. The nineteenth part is a report from the Secretary of the Education on the state of the Education.

20. The twentieth part is a report from the Secretary of the Health on the state of the Health.

since f is prescribed on ∂R the $f = f(\varphi)$ only
and @ $\rho = a$ for ~~interior~~ ^{exterior} problem

$$u(a, \varphi) = \sum_{n=0}^{\infty} (\bar{A}_n \cos n\varphi + \bar{B}_n \sin n\varphi) a^n = f(\varphi) \quad (7)$$

we can use fourier series . $\therefore$

$$f(\varphi) = \frac{\alpha_0}{2} + \sum_{n=1}^{\infty} (\alpha_n \cos n\varphi + \beta_n \sin n\varphi) \quad (8)$$

$$\text{where } \alpha_0 = \frac{1}{\pi} \int_{-\pi}^{\pi} f(\varphi) d\varphi \quad \alpha_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(\varphi) \cos n\varphi d\varphi$$

$$\beta_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(\varphi) \sin n\varphi d\varphi$$

comparison of (7) and (8)

$$\bar{A}_0 = \frac{\alpha_0}{2} \quad \bar{A}_n = \frac{\alpha_n}{a^n} \quad \bar{B}_n = \frac{\beta_n}{a^n} \quad (9a)$$

for ~~interior~~ ^{exterior} problem

$$\underline{A}_0 = \frac{\alpha_0}{2} \quad \underline{A}_n = \alpha_n a^n \quad \underline{B}_n = \beta_n a^n \quad (9b)$$

therefore place (9a) and (9b) in (6a, 6b)

$$\text{inter } u(\rho, \varphi) = \frac{\alpha_0}{2} + \sum_{n=1}^{\infty} \left(\frac{\rho}{a}\right)^n [\alpha_n \cos n\varphi + \beta_n \sin n\varphi] \quad (10)$$

$$\text{exter } u(\rho, \varphi) = \frac{\alpha_0}{2} + \sum_{n=1}^{\infty} \left(\frac{a}{\rho}\right)^n [\alpha_n \cos n\varphi + \beta_n \sin n\varphi]$$

B To prove solution to problems are given by (10) must show the superposition principle applies by showing convergence of series, term wise differentiability and continuity of f_n on the circumference.

for interior problem $t = \rho/a \leq 1$ $\rho \leq a$

exterior problem $t = a/\rho \leq 1$ $\rho \geq a$

write (10) as

$$u(\rho, \varphi) = \frac{\alpha_0}{2} + \sum_{n=1}^{\infty} t^n (\alpha_n \cos n\varphi + \beta_n \sin n\varphi)$$

1. The first part of the report is a general
introduction to the subject.

2. The second part is a detailed description
of the methods used.

3. The third part is a discussion of the
results obtained.

4. The fourth part is a conclusion
based on the results.

5. The fifth part is a list of
references.

6. The sixth part is a list of
figures.

7. The seventh part is a list of
tables.

8. The eighth part is a list of
appendices.

9. The ninth part is a list of
acknowledgments.

10. The tenth part is a list of
concluding remarks.

suppose $\exists$ an ~~upper~~ M s.t. $|\alpha_n|, |\beta_n| < M \quad \forall n$
 then the fourier coefficients are bounded ~~above~~.

To prove differentiability of each term set

$$u_n = t^n (\alpha_n \cos(n\varphi) + \beta_n \sin(n\varphi)) \quad t < 1$$

$$\text{and calculate } \frac{\partial^k u_n}{\partial \varphi^k} = n^k t^n \left(\alpha_n \cos\left(n\varphi + \frac{k\pi}{2}\right) + \beta_n \sin\left(n\varphi + \frac{k\pi}{2}\right) \right) \\ \leq n^k t^n [|\alpha_n| + |\beta_n|] \leq 2M n^k t^n$$

choose some $\rho_0 < a$ $t_0 = \rho_0/a < 1$ interior problem

$a^2/\rho_0 = \rho_1 > a$ $t_0 = a/\rho_1 < 1$ exterior problem

Then $|t| \leq t_0 < 1$ and arbitrary k

$$\sum_{n=1}^{\infty} t^n n^k (|\alpha_n| + |\beta_n|) \leq \sum_{n=1}^{\infty} 2M t_0^n n^k \Rightarrow \text{U.C. of series on } k$$

$\Rightarrow$ (10) can be ~~arbitrarily~~ diff as often as we please wrt φ .

thus the superposition principle is applicable and (10) define
 fns which satisfy $\Delta u = 0$ for $t < 1$

B. to show continuity of solutions in closed region $t \leq 1$

$$\text{note: } f(\varphi) = \sum_{n=1}^{\infty} (\alpha_n \cos n\varphi + \beta_n \sin n\varphi) + \frac{a_0}{2}$$

$$\text{but } f(\varphi) - \frac{a_0}{2} \leq \sum_{n=1}^{\infty} (|\alpha_n| + |\beta_n|) \text{ converges}$$

$$\text{but } |t^n \alpha_n \cos n\varphi| \leq |\alpha_n| \\ |t^n \beta_n \sin n\varphi| \leq |\beta_n|$$

so that (10) converges uniformly for $t \leq 1$

note: $\sum_{n=1}^{\infty} (|\alpha_n| + |\beta_n|)$ shows that the solution of exterior prob
 is bdd at infinity.

1. The first part of the report is a general introduction to the project.

2. The second part of the report is a detailed description of the methodology used.

3. The third part of the report is a discussion of the results of the study.

4. The fourth part of the report is a conclusion and a list of references.

5. The fifth part of the report is an appendix containing additional data and figures.

6. The sixth part of the report is a bibliography of the sources used in the study.

7. The seventh part of the report is a list of the authors and their affiliations.

8. The eighth part of the report is a list of the titles of the papers presented at the conference.

9. The ninth part of the report is a list of the titles of the papers presented at the symposium.

10. The tenth part of the report is a list of the titles of the papers presented at the workshop.

11. The eleventh part of the report is a list of the titles of the papers presented at the round table.

12. The twelfth part of the report is a list of the titles of the papers presented at the panel discussion.

13. The thirteenth part of the report is a list of the titles of the papers presented at the plenary session.

14. The fourteenth part of the report is a list of the titles of the papers presented at the closing ceremony.

15. The fifteenth part of the report is a list of the titles of the papers presented at the opening ceremony.

16. The sixteenth part of the report is a list of the titles of the papers presented at the first session.

17. The seventeenth part of the report is a list of the titles of the papers presented at the second session.

18. The eighteenth part of the report is a list of the titles of the papers presented at the third session.

19. The nineteenth part of the report is a list of the titles of the papers presented at the fourth session.

20. The twentieth part of the report is a list of the titles of the papers presented at the fifth session.

II. Poisson's Integral

Placing (9) into (10) and because of U.C. we can interchange limit and integral, for interior problem

$$\begin{aligned} u(p, \varphi) &= \frac{1}{\pi} \int_{-\pi}^{\pi} f(\psi) \left\{ \frac{1}{2} + \sum_{n=1}^{\infty} \left(\frac{p}{a}\right)^n [\cos n\psi \cos n\varphi + \sin n\psi \sin n\varphi] \right\} d\psi \\ &= \frac{1}{\pi} \int_{-\pi}^{\pi} f(\psi) \left\{ \frac{1}{2} + \sum_{n=1}^{\infty} \left(\frac{p}{a}\right)^n [\cos n(\psi - \varphi)] \right\} d\psi \quad (11) \end{aligned}$$

but let $t = p/a < 1$

$$t^n \cos n(\varphi - \psi) = \frac{1}{2} [t^n e^{in(\varphi - \psi)} + t^n e^{-in(\varphi - \psi)}]$$

Can be obtained from De Moivre's Rule $e^{i\theta} = \cos \theta + i \sin \theta$
 $e^{-i\theta} = \cos \theta - i \sin \theta$

note that $\sum_{n=1}^{\infty} t^n e^{in(\varphi - \psi)} = t e^{i(\varphi - \psi)} \underbrace{\sum_{n=0}^{\infty} [t e^{i(\varphi - \psi)}]^n}_{\text{power series}} = t e^{i(\varphi - \psi)} \frac{1}{1 - t e^{i(\varphi - \psi)}}$

$$\begin{aligned} \text{then } u(p, \varphi) &= \frac{1}{\pi} \int_{-\pi}^{\pi} f(\psi) \left\{ 1 + \frac{t e^{i(\varphi - \psi)}}{1 - t e^{i(\varphi - \psi)}} + \frac{t e^{-i(\varphi - \psi)}}{1 - t e^{-i(\varphi - \psi)}} \right\} d\psi \\ &= \frac{1}{\pi} \int_{-\pi}^{\pi} \frac{f(\psi)}{2} \left[\frac{1 - t^2}{1 - 2t \cos(\varphi - \psi) + t^2} \right] d\psi \end{aligned}$$

$$\text{and } = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(\psi) \frac{a^2 - p^2}{a^2 - 2ap \cos(\varphi - \psi) + p^2} d\psi \quad (12)$$

(12) is the solution to first bvp for interior of circle and is known as Poisson integral

$K(p, \varphi, a, \psi) = \frac{a^2 - p^2}{a^2 - 2ap \cos(\varphi - \psi) + p^2}$ is the Poisson kernel
 which is > 0 for $p < a$

For $\rho = a$ Poisson integral degenerates to

$$u(a, \varphi) = f(\varphi) \quad (12b)$$

$\therefore$ for interior problem

$$u(\rho, \varphi) = \begin{cases} \frac{1}{2\pi} \int_{-\pi}^{\pi} f(\psi) \frac{a^2 - \rho^2}{\rho^2 - 2a\rho \cos(\varphi - \psi) + a^2} d\psi & \rho < a \\ f(\varphi) & \rho = a \end{cases} \quad (12)$$

for exterior problem

$$u(\rho, \varphi) = \begin{cases} \frac{1}{2\pi} \int_{-\pi}^{\pi} f(\psi) \frac{\rho^2 - a^2}{\rho^2 - 2a\rho \cos(\varphi - \psi) + a^2} d\psi & \rho > a \\ f(\varphi) & \rho = a \end{cases} \quad (13)$$

from the above note that $f(\varphi)$ need only be continuous

A. Proof of the continuity of $u(\rho, \varphi)$ as $\rho \rightarrow a$

Choose any sequence of continuous & diff fns

$f_1(\varphi), \dots, f_k(\varphi), \dots$ which are U.C. toward $f(\varphi)$

~~the sequence of diff fns correspond to a sequence of harmonic fns defined by (13)~~
by U.C. it follows that for $\epsilon > 0 \exists k_0(\epsilon) \ni$

$$|f_k(\varphi) - f_{k+1}(\varphi)| < \epsilon \text{ whenever } k > k_0(\epsilon) > 0$$

by the principle of the maximum

$$|u_k(\rho, \varphi) - u_{k+1}(\rho, \varphi)| < \epsilon \text{ for } \rho \leq \rho_0 \text{ } k > k_0(\epsilon)$$

then the sequence $\{u_k\}$ converges uniformly. The limit fn $u(\rho, \varphi)$ is continuous in the closed region since

all the fns $u_k(\rho, \varphi)$ are continuous in the closed region

Dear Mr. [Name],

I have received your letter of the 10th inst.

and am glad to hear from you.

I am sorry that I cannot

reply to you more fully at present.

I am, however, very

grateful for your interest

in my work.

I am, Sir, very

truly yours,

[Signature]

[Name]

[Address]

[City]

[State]

[Country]

[Post Office]

[Telephone]

[Telex]

[Fax]

Since $u(p, \varphi) = \lim_{n \rightarrow \infty} u_n(p, \varphi) \stackrel{\text{then}}{=} \begin{cases} \frac{1}{2\pi} \int_{-\pi}^{\pi} K(p, \varphi, a, \psi) f(\psi) d\psi \\ f(\varphi) \end{cases}$ 7

since $f_n(\varphi)$ converges uniformly to $f(\varphi)$

B. Discontinuous b.v.

we will show that (12) and (13) represent the solution of b.v.P. for every piecewise continuous $f(\varphi)$

Problem: Show that $\exists \delta > 0 \quad \forall \epsilon > 0 \quad \Rightarrow |u(p, \varphi) - f(\varphi_0)| < \epsilon$

if $|p - a| < \delta(\epsilon) \quad \& \quad |\varphi - \varphi_0| < \delta(\epsilon)$

By continuity of $f(\varphi)$ a $\delta_0(\epsilon)$ can be found $\Rightarrow$

$$|f(\varphi) - f(\varphi_0)| < \epsilon/2$$

for $|\varphi - \varphi_0| < \delta_0(\epsilon)$

Consider 2 cont. diff fns $\bar{f}(\varphi)$ and $\underline{f}(\varphi)$ where

$$\bar{f}(\varphi) = f(\varphi_0) + \epsilon/2 \quad |\varphi - \varphi_0| < \delta_0(\epsilon)$$

$$\bar{f}(\varphi) \geq f(\varphi) \quad |\varphi - \varphi_0| > \delta_0(\epsilon)$$

and

$$\underline{f}(\varphi) = f(\varphi_0) - \epsilon/2 \quad |\varphi - \varphi_0| < \delta_0(\epsilon)$$

$$\underline{f}(\varphi) \leq f(\varphi) \quad |\varphi - \varphi_0| > \delta_0(\epsilon)$$

which are otherwise arbitrary and which satisfy (10a)

define $\bar{u}(p, \varphi)$ $\underline{u}(p, \varphi)$ which satisfy (10a)

such that $\bar{u}(p, \varphi) \rightarrow \bar{f}(\varphi)$ as $p \rightarrow a$ $\underline{u}(p, \varphi) \rightarrow \underline{f}(\varphi)$

Since Poisson's Kernel > 0

$$\underline{u}(p, \varphi) \leq u(p, \varphi) \leq \bar{u}(p, \varphi)$$

since

$$\underline{f} \leq f \leq \bar{f}$$

1. The first part of the paper discusses the importance of maintaining accurate records of all transactions. This is essential for the proper management of the company's finances and for ensuring that all parties involved are kept up to date on the current status of the business.

2. The second part of the paper discusses the importance of maintaining accurate records of all transactions. This is essential for the proper management of the company's finances and for ensuring that all parties involved are kept up to date on the current status of the business.

3. The third part of the paper discusses the importance of maintaining accurate records of all transactions. This is essential for the proper management of the company's finances and for ensuring that all parties involved are kept up to date on the current status of the business.

4. The fourth part of the paper discusses the importance of maintaining accurate records of all transactions. This is essential for the proper management of the company's finances and for ensuring that all parties involved are kept up to date on the current status of the business.

5. The fifth part of the paper discusses the importance of maintaining accurate records of all transactions. This is essential for the proper management of the company's finances and for ensuring that all parties involved are kept up to date on the current status of the business.

6. The sixth part of the paper discusses the importance of maintaining accurate records of all transactions. This is essential for the proper management of the company's finances and for ensuring that all parties involved are kept up to date on the current status of the business.

7. The seventh part of the paper discusses the importance of maintaining accurate records of all transactions. This is essential for the proper management of the company's finances and for ensuring that all parties involved are kept up to date on the current status of the business.

from continuity of $\bar{u}(p, \varphi)$ & $u(p, \varphi)$ on bdy for $\varphi = \varphi_0$

$$\exists \delta_1(\epsilon) \quad .\exists.$$

$$|\bar{u}(p, \varphi) - \bar{f}(\varphi_0)| \leq \epsilon/2 \quad (1')$$

$$\text{for } |p-a| < \delta_1(\epsilon) \quad |\varphi - \varphi_0| < \delta_1(\epsilon)$$

$$\text{and} \quad |u(p, \varphi) - f(\varphi_0)| \leq \epsilon/2 \quad (2')$$

$$\text{for } |p-a| < \delta_1(\epsilon) \quad |\varphi - \varphi_0| < \delta_1(\epsilon)$$

$$\text{from (1')} \quad \bar{u}(p, \varphi) \leq \bar{f}(\varphi_0) + \epsilon/2 = f(\varphi_0) + \epsilon$$

$$(2') \quad u(p, \varphi) \geq f(\varphi_0) - \epsilon/2 = f(\varphi_0) - \epsilon$$

$$\text{for } |p-a| < \delta(\epsilon), \quad |\varphi - \varphi_0| < \delta(\epsilon) \quad \delta = \min(\delta_0, \delta_1)$$

Now since

$$\underline{u} \leq u \leq \bar{u} \quad \text{then}$$

$$f(\varphi_0) - \epsilon \leq \underline{u} \leq u \leq \bar{u} \leq f(\varphi_0) + \epsilon$$

$$\text{or} \quad |u(p, \varphi) - f(\varphi_0)| < \epsilon \quad \text{for } |p-a| < \delta, \quad |\varphi - \varphi_0| < \delta$$

and thus $u(p, \varphi)$ is cont at (a, φ_0)

c. To show boundedness of solution

since $K(p, \varphi, a, \psi) > 0$ then if $|f(\varphi)| < M$ then

$$u(p, \varphi) < \frac{M}{2\pi} \int_{-\pi}^{\pi} \frac{a^2 - p^2}{a^2 + p^2 - 2ap \cos(\varphi - \psi)} d\psi$$

$$\text{as } p \rightarrow a \quad \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{a^2 - p^2}{a^2 + p^2 - 2ap \cos(\varphi - \psi)} d\psi \rightarrow 1$$

thus $u(p, \varphi) < M$ and therefore is bdd.

Consider now a problem which doesn't give trig
fn solution, i.e. Axisym temp distrib in solid sphere

$$\nabla^2 u = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial u}{\partial r} \right) + \frac{1}{r^2 \sin \varphi} \frac{\partial}{\partial \varphi} \left(\sin \varphi \frac{\partial u}{\partial \varphi} \right) = 0$$

where $u(a, \varphi) = f(\varphi)$

let $u(r, \varphi) = R(r) \Phi(\varphi)$ this gives

$$\Phi \frac{\partial}{\partial r} \left(r^2 \frac{\partial R}{\partial r} \right) + \frac{R}{\sin \varphi} \frac{\partial}{\partial \varphi} \left(\sin \varphi \frac{\partial \Phi}{\partial \varphi} \right) = 0$$

or $\frac{1}{R} (r^2 R')' = - \frac{1}{\Phi \sin \varphi} (\sin \varphi \Phi')' = k^2$

then $(r^2 R')' - k^2 R = 0$

$$\frac{1}{\sin \varphi} \frac{d}{d\varphi} \left(\sin \varphi \frac{d\Phi}{d\varphi} \right) + k^2 \Phi = 0$$

which is a Legendre equation if $k^2 = n(n+1)$

then $\Phi = A_n P_n(\cos \varphi) + B_n Q_n(\cos \varphi)$

$$R = C_n r^n + D_n r^{-n-1}$$

for finiteness of solution at z axis $\varphi = 0, \pi$ $B_n = 0$ n integer
 $D_n = 0$ for finiteness of $R(r)$ at $r = 0$

then $u(r, \varphi) = \sum_{n=0}^{\infty} c_n \left(\frac{r}{a} \right)^n P_n(\cos \varphi)$ where $A_n C_n = \frac{c_n}{a^n}$

and $f(\varphi) = \sum c_n P_n(\cos \varphi)$

and since the Legendre fns are an orthonormal set of fns
like the sin, cos series in Fourier expansion
we can define c_n by

$$\int_{-\pi}^0 f(\varphi) P_m(\cos \varphi) \sin \varphi d\varphi = c_n \int_{-\pi}^0 P_n(\cos \varphi) P_m(\cos \varphi) \sin \varphi d\varphi$$

10

by the fact that $\int_{\pi}^0 -P_n(\cos\varphi) P_m(\cos\varphi) \sin\varphi d\varphi = \frac{2}{2n+1} \begin{matrix} n=m \\ 0 & n \neq m \end{matrix}$

$$\text{then } c_n = \frac{2n+1}{2} \int_0^{\pi} f(\varphi) P_n(\cos\varphi) \sin\varphi d\varphi$$

§ 4-4 Green's Function (Source T_n)

Discuss basic properties of G.Fn. of $\Delta u = 0$ as well as construction of G.Fn. for a class of simple regions by method of images in electrostatics.

1. Let $u(M)$ be C^1 on $\Sigma = \partial T$
 $u(M)$ be C^2 in T

then

$$u(M_0) = \frac{1}{4\pi} \int_{\Sigma} \left[\frac{1}{r_{PM_0}} \frac{\partial u}{\partial n} - u(P) \frac{\partial}{\partial n} \left(\frac{1}{r_{PM_0}} \right) \right] d\sigma_P - \frac{1}{4\pi} \iiint_T \frac{\Delta u}{r_{MM_0}} d\tau \quad (1)$$

if u is harmonic $\Delta u = 0$ if u satisfies $\Delta u = f$ ✓

Let $u(M)$ be a harmonic fn which nowhere is singular $\nabla u \neq 0$
 then by Green's second formula

$$\iiint_T [u \Delta v - v \Delta u] d\tau = \int_{\Sigma} \left(u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} \right) d\sigma$$

then yields

$$0 = \iint_{\Sigma} \left(v \frac{\partial u}{\partial n} - u \frac{\partial v}{\partial n} \right) d\sigma - \iiint_T v \Delta u d\tau \quad (2)$$

ADD 1 & 2 then

$$u(M_0) = \int_{\Sigma} \left[G \frac{\partial u}{\partial n} - u \frac{\partial G}{\partial n} \right] d\sigma - \iiint_T \Delta u \cdot G d\tau \quad (3)$$

where $G = \text{[redacted]}$ $G(M, M_0) = \frac{1}{4\pi r_{MM_0}} + v \quad (4)$

$M_0 = M_0(x, y, z) \quad M = M(\xi, \eta, \zeta)$

In interior of T G is harmonic except at $M = M_0$

Choose $v(M) \ni G|_{\Sigma} = 0$ i.e. $v|_{\Sigma} = -\frac{1}{4\pi r}$

knowledge of G allows the BVP to be solved
for any bc $u|_{\Sigma} = f$ while G itself is determined
only for BVP having $v|_{\Sigma} = -1/4\pi r$

G is G.F. of first BVP for Laplacian on u , $\Delta u = 0$
 G is also defined as an instantaneous pt source of the F.B.V.P.
 of $\Delta u = 0$; from (3)

$$u(M_0) = - \int_{\Sigma} u \frac{\partial G}{\partial n} d\sigma = - \int_{\Sigma} f \frac{\partial G}{\partial n} d\sigma \quad f = u|_{\Sigma} \quad (5)$$

A.M. Liapunov showed that under general assumption on u (5) is a representation of the solution of FBVP for a wide class of boundaries.

* * * *

Properties of Green's T_n . where G exists in T and $\frac{\partial G}{\partial n}$ is cont. and Green's formula applicable on Σ

- 1a. G.F. > 0 in interior of T ; $G = 0$ on $\partial T = \Sigma$ and $G > 0$ on surface of small sphere about pole. G must be positive according to max principle in T .
 1b. $dG/dn|_{\Sigma} \leq 0$ since $G > 0$ in T $G = 0$ on $\partial T = \Sigma$
2. G.F. symmetric with respect to arguments
 $G(M, M_0) = G(M_0, M) \Rightarrow$ source at M has same effect at M_0 as " " M_0 having effect at M

for 2-D case GF is defined by

1. $\Delta G = 0$ in S except at $M = M_0$
2. at $M = M_0$ $G(M, M_0)$ has singularity of form $\frac{1}{2\pi} \ln \frac{1}{r_{MM_0}}$
3. $G|_C = 0$ C is curve bdy of S .

$$G(M, M_0) = \frac{1}{2\pi} \ln \frac{1}{r_{MM_0}} + v(M, M_0)$$

where v satisfies $\Delta v = 0$ in S $v|_C = -\frac{1}{2\pi} \ln \frac{1}{r_{MM_0}}$

and solution of FBVP for $\Delta u = 0$ is given by

$$u(M_0) = - \int_C f \frac{\partial G}{\partial n} ds, \quad f = u|_C$$

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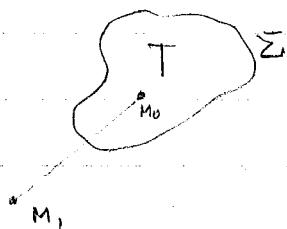
(b) ... the ... of the ...
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Calculation of Green's $\mathcal{M}$: Method of Images



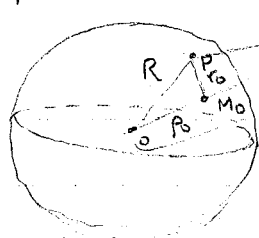
$$\Delta G = 0 \quad \text{have singularity } \frac{1}{r} \\ \text{and } G|_{\Sigma} = 0$$

pick an image pt $\ni$ influence of singularity of M_0, M_1 on $\Sigma = 0$

Sphere

G.F. for sphere of radius R

M_0 inside sphere P on ∂T



$$\text{Choose } M_1 \ni |OM_0| |OM_1| = R^2 \\ P_0 P_1 = R^2$$

$$\Delta OPM_0 \sim \Delta OM_1P$$

$$1) \text{ common } \angle POM_0 = \angle POM_1$$

$$2) OM_0/OP = \frac{OP}{OM_1}$$

$$\frac{r_0}{r_1} = \frac{P_0}{R} = \frac{R}{P_1}$$

$$r_0 = \frac{P_0 r_1}{R}$$

$$\frac{1}{r_0} = \frac{R}{P_0 r_1}$$

$$G(P, M_0) = \frac{1}{4\pi r_{PM_0}} + U = \frac{1}{4\pi} \left(\frac{1}{r_0} - \frac{R}{P_0 r_1} \right)$$

satisfies Laplace, $G|_{\Sigma} = 0$ and singularity of $\frac{1}{r}$

$$\frac{\partial G}{\partial n} = \frac{1}{4\pi} \left[\frac{\partial}{\partial n} \left(\frac{1}{r_0} \right) - \frac{R}{P_0} \frac{\partial}{\partial n} \left(\frac{1}{r_1} \right) \right] \quad \text{where } n \text{ is exterior normal}$$

$$\frac{\partial}{\partial n} \left(\frac{1}{r_0} \right) = \frac{\partial}{\partial r_0} \left(\frac{1}{r_0} \right) \frac{\partial r_0}{\partial n} = -\frac{1}{r_0^2} \cos(r_0, n)$$

$$\frac{\partial}{\partial n} \left(\frac{1}{r_1} \right) = \frac{\partial}{\partial r_1} \frac{\partial r_1}{\partial n} = -\frac{1}{r_1^2} \cos(r_1, n)$$

Cosine law

$$\cos(r_0, n) = \frac{R^2 + r_0^2 - \rho_0^2}{2Rr_0}, \quad \cos(r_1, n) = \frac{R^2 + r_1^2 - \rho_1^2}{2Rr_1}$$

$$\text{on } \Sigma, r_1 = \frac{Rr_0}{\rho_0} \quad \cos(r_1, n) = \frac{\rho_0^2 + r_0^2 - R^2}{2\rho_0 r_0}$$

$$\left. \frac{\partial G}{\partial n} \right|_{\Sigma} = \frac{1}{4\pi} \left[-\frac{1}{r_0^2} \frac{R^2 + r_0^2 - \rho_0^2}{2Rr_0} + \frac{\rho_0^2}{R^2 r_0^2} \frac{R}{\rho_0} \frac{\rho_0^2 + r_0^2 - R^2}{2\rho_0 r_0} \right]$$

$$= -\frac{1}{4\pi} \frac{R^2 - \rho_0^2}{Rr_0^3}$$

F.B.V.P.

$$u(M_0) = \frac{1}{4\pi R} \iint_{\Sigma} f(P) \left(\frac{R^2 - \rho_0^2}{r_0^3} \right) d\sigma_P$$

In spherical polars $(\rho_0, \theta_0, \varphi_0)$

$$u(\rho_0, \theta_0, \varphi_0) = \frac{R}{4\pi} \int_0^{2\pi} \int_0^{\pi} f(\theta, \varphi) \frac{R^2 - \rho_0^2}{(R^2 - 2R\rho_0 \cos \gamma + \rho_0^2)^{3/2}} \sin \theta d\theta d\varphi$$

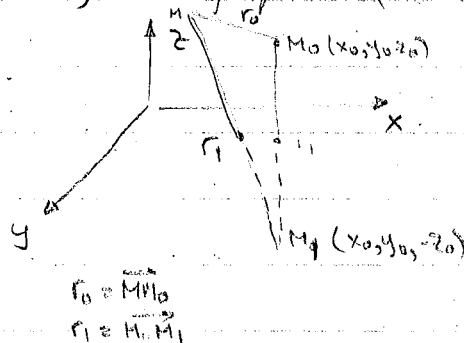
$$\text{where } \cos \gamma = \cos \theta \cos \theta_0 + \sin \theta \sin \theta_0 \cos(\varphi - \varphi_0)$$

Poisson integral for sphere

On 2-D for circle $\log(1/r)$ as fund sol.

$$u(\rho_0, \theta_0) = \frac{1}{2\pi} \int_0^{2\pi} \frac{R^2 - \rho_0^2}{R^2 + \rho_0^2 - 2R\rho_0 \cos(\theta - \theta_0)} f(\omega) d\theta$$

G.F. for half space (3 dim)



$$G \sim \frac{(z-z_0)^2 + (z+z_0)^2}{4\pi} \left(\frac{1}{r_0} - \frac{1}{r_1} \right)$$

$$\text{as } M_0 \rightarrow \pi(z=0) \quad G \rightarrow 0$$

$$\left. \frac{\partial G}{\partial n} \right|_{z=0} = - \left. \frac{\partial G}{\partial z} \right|_{z=0} = - \frac{1}{4\pi} \left[\frac{-z-z_0}{r_0^3} + \frac{(z+z_0)}{r_1^3} \right]_{z=0}$$

$$\left. \frac{\partial G}{\partial n} \right|_{z=0} = - \frac{z_0}{2\pi r_0^3}$$

$$u(M_0) = \frac{1}{2\pi} \iint_{z=0} \frac{z_0}{r_{M_0 P}^3} f(P) d\sigma_P$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{z_0 f(x,y) dx dy}{[(x-x_0)^2 + (y-y_0)^2 + (z-z_0)^2]^{3/2}}$$

where $u = f(x,y)$ on $z=0$

$$\Delta u = -f \quad u = u_1 + u_2$$

$$\Delta u_1 = 0 \quad \Delta u_2 = -f \text{ particular soln.}$$

$$3D \quad \begin{cases} u_2 = \frac{1}{4\pi} \iiint_V \frac{f}{r} d\tau \end{cases}$$

$$2D \quad \begin{cases} u_2 = \frac{1}{2\pi} \iint_S f \ln r d\sigma \end{cases}$$

HW P331 3, 6, 7, 8

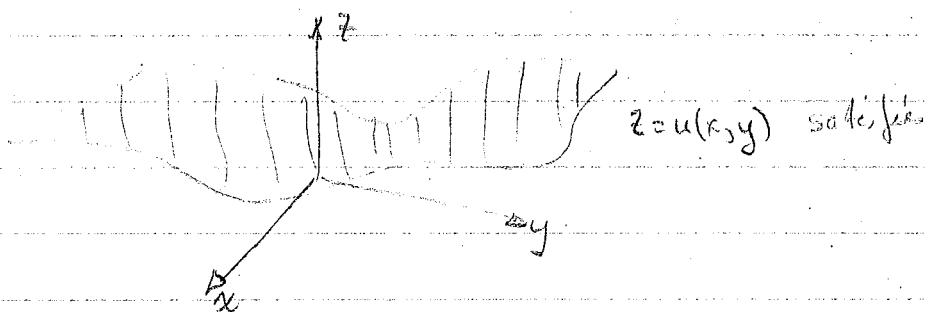
Single First Order PDE

2 indep variables (can be generalized to n indep variables)

$$F(x, y, u, u_x, u_y) = F(x, y, u, p, q) = 0 \quad (1)$$

where $p = u_x$ $q = u_y$

Any solution is called an integral surface



1. Linear Case

$$a(x, y) u_x + b(x, y) u_y = c(x, y) u + d(x, y) \quad (2)$$

consider LHS as directional deriv

$$\frac{du}{dt} = u_x x_t + u_y y_t = c(x, y) u + d \quad 3^*$$

$$\text{choose } x_t = a \quad y_t = b \quad \frac{dy}{dx} = \frac{b(x, y)}{a(x, y)} \quad (3)$$

} distance
in some
sense along
char curve

(3) gives curves in x, y plane: characteristic curves of diff eq:

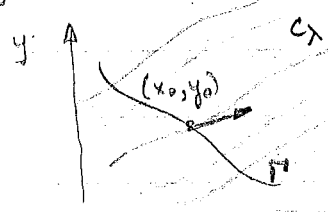
$$\frac{du}{dx} = \frac{cu + d}{a} \quad \text{along } \frac{dy}{dx} = \frac{b}{a}$$

i.e. one first order pde reduced to 2 ode

We will assume all existence, uniqueness theorems of ODE.

Given $u = u_0$ at (x_0, y_0) (3) $\Rightarrow$ $\exists$ char curve $x = x(x_0, y_0, t)$

$y = y(x_0, y_0, t)$ (3') $\Rightarrow u = u(x_0, y_0, t)$



$\Rightarrow$ given $u = u(x_0, y_0)$ we know u along whole char curve thru (x_0, y_0)

Γ = initial curve.

C_x = char curves intersecting Γ

C_x exist & are indep of Γ however Γ cannot be chosen indep of C_x

Γ cannot be parallel to char curves anywhere. Since along C_x u satisfies a definite eqn & cannot be prescribed arbitrarily.

Example:

$$xu_x + yu_y = \alpha u$$

prescribe $u = \phi(x)$ along initial line $y = 1$

$$\text{Characteristic: } \frac{dy}{dx} = \frac{y}{x} \quad \ln y = \ln x + C \quad y = Cx$$

$$\left. \frac{du}{dx} \right|_{\text{char.}} = \frac{\alpha u}{x} \quad u = kx^\alpha \quad k \text{ is const along a charact}$$

$$k = k(c) \quad \text{since } u = \phi(x) \text{ along } y = 1$$

$$k = k(y/x) \quad u = k(y/x) x^\alpha \quad - \text{unknown } k(s)$$

$$\text{on } y = 1 \quad u = \phi(x) \Rightarrow \phi(x) = k(1/x) x^\alpha \quad \text{get } k \text{ as fn of arg}$$

$$\therefore k(s) = \phi(1/s) s^\alpha$$

$$u = \phi\left(\frac{y}{x}\right) \left(\frac{y}{x}\right)^{\alpha} x^{\alpha} = \phi\left(\frac{y}{x}\right) y^{\alpha} \text{ solution}$$

$$\text{satisfy } xu_x + yu_y = \alpha x \text{ and } y=1 \quad u = \phi(x)$$

$$\text{let } y=x \quad u = \phi(x)$$

$$u = k\left(\frac{y}{x}\right) x^{\alpha}$$

$$\phi(x) = k(1) x^{\alpha} \quad \text{find } k \text{ as fn of its argument.}$$

ie ϕ must be a soln of eqn. does not determine $k(s)$

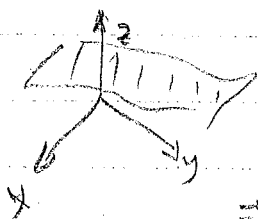
General Quasi linear case

linear in highest derivative

$$a(x,y,u)u_x + b(x,y,u)u_y = c(x,y,u)$$

$$(a,b,c) \cdot \begin{pmatrix} u_x \\ u_y \\ -1 \end{pmatrix} = 0$$

if $z = u(x,y)$ is an integral surface



$(u_x, u_y, -1)$ is vector normal to surface

$\Rightarrow (a,b,c)$ must be tangent to plane

Directional field (a,b,c) are called the char directions

The properties of char dir are that $z = u(x,y)$ is an integral surface iff at each point the tangent plane contains the char direct.

$$\frac{dx}{a(x,y,z)} = \frac{dy}{b(x,y,z)} = \frac{dz}{c(x,y,z)}$$

In terms of param t along charac

$$\frac{dx}{dt} = a \quad \frac{dy}{dt} = b \quad \frac{dz}{dt} = c$$

define an integral surface from a one param family of char curves,

Consider soln of

$$\frac{dx}{dt} = a(x, y, u(x, y)), \quad \frac{dy}{dt} = b(x, y, u(x, y))$$

where $u(x, y)$ is a soln of diff eq

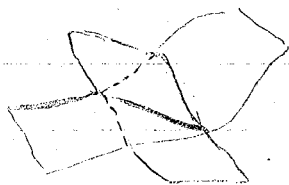
with $x = x_0, y = y_0$ when $t = 0$

Then the char curves are $x = x(t), y = y(t), z = u(x(t), y(t))$

$$\frac{dz}{dt} = \frac{du}{dx} \frac{dx}{dt} + \frac{du}{dy} \frac{dy}{dt} = au_x + bu_y = c \quad \text{by diff eq}$$

$\Rightarrow$ curve is characteristic since it satisfies all three eqs.

If two integral surfaces intersect they must intersect along a whole char line



Cauchy IVP $u|_C = f$ & u cannot be specified along characteristic

3-20-73

$$au_x + bu_y = c \quad a, b, c \text{ fns of } (x, y, u)$$

Quasi linear - linear in highest derivatives

Special form of $F(x, y, u, u_x, u_y) = 0$ General first order PDE in 2 indep var

linear case $\frac{dy}{dx} = -\frac{b}{a}(x,y)$

$\frac{du}{dx}$

linear case uncouples; for quasilinear case eqs are coupled
can't prescribe initial conditions along a curve which is anywhere tangent to a characteristic

Theorem Cauchy IVP for the quasilinear case

Consider a first order p.d.e.

$$a(x,y,u)u_x + b(x,y,u)u_y = c(x,y,u)$$

where a, b, c have cont partial deriv wrt x, y, u

Suppose that along the initial curve $x=x_0(s), y=y_0(s)$ the initial values $u=u_0(s)$ are prescribed, x_0, y_0, u_0 being continuous by differentiable fns. for $0 \leq s \leq 1$. Let $\frac{dy_0}{ds} a(x_0, y_0, u_0) - \frac{dx_0}{ds} b(x_0, y_0, u_0) \neq 0$

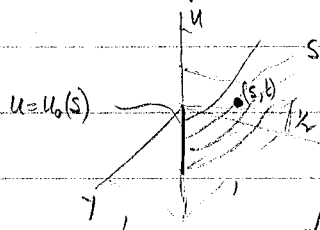
Then there exists one & only one solution $u(x,y)$ defined in some nbhd of the initial curve which satisfies the P.D.E. + Init cond.

$$u(x_0(s), y_0(s)) = u_0(s)$$

Proof: in notes give

$$uu_x + u_y = 1$$

I.C. $x=s \quad y=s \quad u = \frac{1}{2}s \quad 0 \leq s \leq 1$



look at characteristic crossing this curve. It will be a one param family, $f(s)$

Characteristic eqns

$$\frac{dx}{dt} = u \quad \frac{dy}{dt} = 1 \quad \frac{du}{dt} = 1$$

subject to $x(s, 0) = s \quad y(s, 0) = s \quad u(s, 0) = s/2$

$$u(s, t) = t + s/2$$

$$y(s, t) = t + s$$

$$x(s, t) = t^2/2 + st/2 + s$$

$$s = \frac{x - y^2/2}{1 - y/2}$$

$$t = \frac{y - x}{1 - y/2}$$

$$u = \frac{2(y - x) + (x - y^2/2)}{2 - y}$$

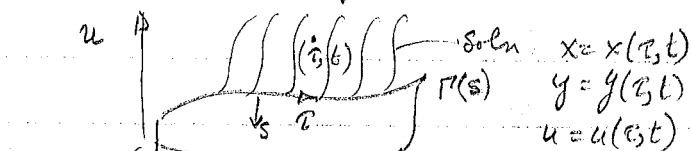
$$u = x/2, y/2 \text{ when } x=y$$

$$u = \frac{x - x^2/2}{2 - x} = \frac{x(2 - x)}{2(2 - x)} = \frac{x}{2} \quad \checkmark$$

check that $\frac{dy}{ds} a - \frac{dx}{ds} b \neq 0 \quad \therefore (1 \cdot a - 1b) = -(a - b) = -(u - 1) = -(s/2 - 1) \neq 0$
on initial line $s \neq 2$

In general. Initial curve will be given in one param

$$\Gamma: \quad x = \varphi(\tau) \quad y = \psi(\tau) \quad u = w(\tau)$$



$$\text{soln } \begin{cases} x = x(\tau, t) \\ y = y(\tau, t) \\ u = u(\tau, t) \end{cases}$$

given in terms of two parameters
if it satisfies diff eq it is called an integral surface.

Integral surface generated by a one param family of characteristics

Methods to find general soln both theoretical

- 1) Takes an initial curve Γ & vary it with respect to a new param
- 2) Take a 2 param family of characteristics & from them choose any one param family

each of these will be an integral surface.

2) is usually better; Theoretically:

$$\frac{dx}{a} = \frac{dy}{b} = \frac{du}{c}$$

Find two independent integrals to $\frac{dx}{a} = \frac{dy}{b}$, $\frac{dy}{b} = \frac{du}{c}$

$$\Phi(x, y, u) = \alpha$$

$$\Psi(x, y, u) = \beta$$

α, β arbitrary constants of integration

each represents one param family of surfaces. Intersection of the two will give characteristics. Together they give a two param family of curves - their curves of intersection happens to be their characteristics.

Let one be a fn of the other symmetrically let

$$F(\alpha, \beta) = 0 \text{ where } F \text{ is an arbitrary fn.}$$

this yields a one parameter family of curves each of which lies on the surface $F(\Phi(x, y, u), \Psi(x, y, u)) = 0$

This does satisfy the diff eq & doesn't depend on initial conditions & is called the general soln.

Note: general solution doesn't contain all solns of p.d.e. Usually contains most.

Since F is arbitrary general soln is not unique.

Example

$$u(xu_x - yu_y) = y^2 - x^2$$

$$\left[\frac{dx}{ux} = \frac{dy}{-uy} \right] = \frac{du}{y^2 - x^2} \quad \text{char eq}$$

$$\ln xy = \ln \alpha \quad \boxed{xy = \alpha}$$

$$\frac{dx}{ux} = \frac{du}{y^2 - x^2} \quad ; \quad y^2 dx - x dx = u du$$

$$d \frac{dx}{x} = \frac{du}{y} \quad \therefore \quad -y dy - x dx = u du$$

$$-y^2/2 - x^2/2 = u^2/2 + C$$

$$\boxed{y^2 + x^2 + u^2 = \beta}$$

$$\phi(x, y, u) = xy = \alpha$$

$$\psi(x, y, u) = y^2 + x^2 + u^2 = \beta$$

$$F(xy, x^2 + y^2 + u^2) = 0 \quad \text{General Soln.}$$

for an arbitrary fn F . write $\beta = G(\alpha)$

$$\therefore y^2 + x^2 + u^2 = G(xy)$$

$$u = \sqrt{G(xy) - (x^2 + y^2)} \quad \Leftarrow \text{arbitrary fn } G \quad \text{General Soln.}$$

or $\frac{dx+dy}{u(x-y)} = \frac{du}{y^2 - x^2} \quad \text{since } d(xy) = 0$

$$(dx+dy)(y+x) = -u du$$

$$(x+y)^2/2 = -u^2/2 + C^* \quad \left| (x+y)^2 + u^2 = \beta^* \right| \quad \beta^* = G^*(\alpha)$$

$$u = \sqrt{G^*(xy) - (x+y)^2} \quad G^*(\alpha) = G(\alpha) + 2\alpha$$

The inverse problem: complete integral

O.D.E. $\phi(x, y, c) = 0 \quad c = \text{arbitrary param}$

Quest: what ODE does this family of curves satisfy?

the o.d.e must be independent of c

usually eliminated by differentiation of ϕ

Question: for 1st order PDE what do you do

Given an arbitrary fn $F(\alpha, \beta) = 0$ & two fixed (i.e. definite) fns $\Phi(x, y, u)$ & $\Psi(x, y, u)$ so that $F(\Phi, \Psi) = 0$ what is the p.d.e. for which this is the general solution.

Must eliminate F ; but the resulting p.d.e. will depend on the choice of Φ & Ψ .

Differentiate wrt x, y ; treat u as a fn of x, y

$$F(\alpha, \beta) = 0 \quad \alpha = \Phi \quad \beta = \Psi$$

$$F_\alpha (\Phi_x + \Phi_u u_x) + F_\beta (\Psi_x + \Psi_u u_x) = 0$$

$$F_\alpha (\Phi_y + \Phi_u u_y) + F_\beta (\Psi_y + \Psi_u u_y) = 0$$

$$\text{Requiring } F_\alpha^2 + F_\beta^2 \neq 0$$

then

$$\begin{vmatrix} \Phi_x + \Phi_u u_x & \Psi_x + \Psi_u u_x \\ \Phi_y + \Phi_u u_y & \Psi_y + \Psi_u u_y \end{vmatrix} = 0$$

$$(\Phi_x + \Phi_u u_x)(\Psi_y + \Psi_u u_y) - (\Phi_y + \Phi_u u_y)(\Psi_x + \Psi_u u_x) =$$

$$\underbrace{\Phi_x \Psi_y - \Psi_x \Phi_y}_{c(x, y, u)} = u_x (\underbrace{\Psi_u \Phi_y - \Phi_u \Psi_y}_{a(x, y, u)}) + u_y (\underbrace{\Phi_u \Psi_x - \Psi_u \Phi_x}_{b(x, y, u)})$$

Independent of F

Method 2 from a fn depending on 2 parameters

$$u = f(x, y, \alpha, \beta)$$

define implicitly by $F(x, y, u, \alpha, \beta) = 0$

Now F is not arbitrary α, β arbitrary

Eliminate α, β to find P.D.E. Differentiate F wrt x, y

$$\left. \begin{array}{l} F_x + F_u u_x = 0 \\ F_y + F_u u_y = 0 \\ F = 0 \end{array} \right\} \text{3 eq we can "in theory" eliminate } \alpha \text{ \& } \beta \text{ to yield a first order p.d.e.}$$

this method will not necessarily yield a quasi linear eq

2nd method usually is more useful

Definition of a complete integral

A fn of two parameters which is an integral of a first order p.d.e. in 2 indep variables is called a complete integral of the p.d.e

The complete integral & the general solution are connected in that one can be obtained from the other

Then the general soln of the P.D.E. can, in theory, be obtained from a complete integral of the P.D.E.

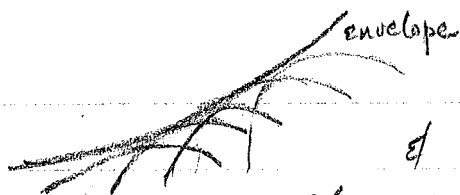
Proof Let $F(x, y, u, \alpha, \beta) = 0$ be a complete integral

Geometrically this is a two param family of surfaces - must represent this in terms of an arbitrary fn - Do this by letting one parameter depend on the other in an arbitrary way - $\beta = G(\alpha)$

Then u defined implicitly

$$F(x, y, u, \alpha, G(\alpha)) = 0 \quad (1)$$

These are one parameter family of surfaces depending on α . We must find sol of p.d.e which satisfies (1) but which is indep of α do this by constructing the envelope of all solns of (1) as α varies



Find envelope by diff wrt α

& eliminating α

i.e.
$$\left. \begin{aligned} F_\alpha + G'(\alpha) F_\beta &= 0 \\ F &= 0 \end{aligned} \right\} \Rightarrow \text{envelope}$$

"in theory" $\alpha = \alpha(x, y, u)$ from $F_\alpha + G'(\alpha) F_\beta = 0$

then $F[x, y, u, \alpha(x, y, u), G(\alpha(x, y, u))] = 0$

is the general soln to same p.d.e. as was complete integral

now depends on the arbitrary fn G instead of (α, β)

Note: This holds for all first order P.D.E.

in practice take particular G_0 at $F_\alpha + G'(\alpha) F_\beta = 0$, stage
& get F in terms of G .

Ex Clairaut's Eqn.

$$u = x u_x + y u_y + u x u_y$$

Complete integral

$$u = \alpha x + \beta y + \alpha \beta$$

Choose $\beta = 1/\alpha \quad \therefore u = \alpha x + y/\alpha + 1 \quad (1)$

$$\frac{\partial}{\partial \alpha} (1) \quad 0 = x - y/\alpha^2 \quad \alpha = \sqrt{y/x}$$

$$u = \sqrt{y/x} x + y/\sqrt{y/x} + 1 = 2\sqrt{yx} + 1 \quad \text{new soln.}$$

1/W

Solve linear 1st order pde subject to IC

1. $(x+2)u_x + 2y u_y = 2u \quad \text{IC} : u(-1, y) = \sqrt{y}$

2. $x^2 u_x - y^2 u_y = 0$

IC: $u(1, y) = F(y)$

} draw sketch of char & init line

3. Find general solns of

a) $x u_x (u - 2y^2) = (u - u_y y) (u - y^2 - 2x^3)$

b) $u_x + u^2 u_y = 1$

April 3, 1973

$$a(x, y, u) u_x + b(x, y, u) u_y = c(x, y, u)$$

General Nonlinear First Order P.D.E.

$$F(x, y, u, p, q) = 0$$

$$p = u_x \quad q = u_y$$

for quasi linear case given x_0, y_0, u_0

then a, b, c are determined uniquely

- know that normals to integral surfaces

through (x_0, y_0, u_0) are all perpendicular to (a_0, b_0, c_0)

$$(a, b, c) \cdot \begin{pmatrix} u_x \\ u_y \end{pmatrix} = 0 \quad (a, b, c) \text{ tangent}$$

one parameter family of normals all perpendicular to (a_0, b_0, c_0)

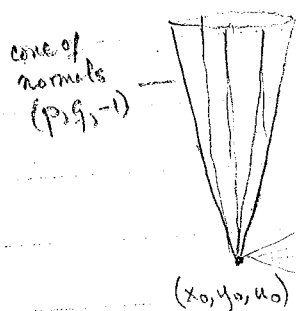
yield one parameter family of integral surfaces thru (x_0, y_0, u_0)

General Nonlinear

$$\text{Given } (x_0, y_0, u_0) \Rightarrow F(x_0, y_0, u_0, p, q) = 0 \quad (1)$$

yields a one parameter family of normals satisfying (1)

all go through pt (x_0, y_0, u_0)



each has a corresponding tangent

cone of tangents

Monge Cone

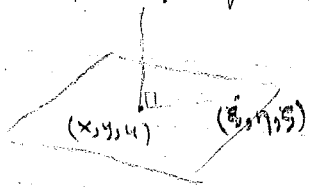
Monge Cone: envelope of the tangent planes thru (x_0, y_0, u_0)

in quasi linear case cone collapses onto line (a_0, b_0, c_0)

By definition generators of Monge cone are characteristics
 To find characteristics - we find the eqs of the generators
 of Monge cone.

Let $\Theta(x, y, u, \alpha) = 0$ be one param family of tangent planes
 $\Theta_\alpha(x, y, u, \alpha) = 0 \rightarrow$ eliminate α to give envelope

Equation of tangent plane



$$p(\xi - x) + q(\eta - y) = S - u \quad (2)$$

where p, q are connected thru $F(x, y, u, p, q) = 0$

Assume we can solve for $q = q(p)$ from $F = 0$,
 yielding a one param family of tangent

insert $q = q(p)$ into (2)
 planes depending on p

Differentiate wrt p

$$(\xi - x) + q'(p)(\eta - y) = 0 \quad (3)$$

Now equation of Monge cone is obtained by eliminating p from
 (2, 3) - usually this cannot be done explicitly,
 need generators of cone.

Eliminate $q'(p)$ by differentiating F wrt p

$$F = 0 \Rightarrow F_p + q' F_q = 0$$

$$q' = -F_p / F_q$$

$$\frac{(\xi - x)}{F_p} = \frac{(\eta - y)}{F_q}$$

Original eqn of tangent plane

$$p \frac{(\xi - x)}{(\eta - y)} + q = \frac{(S - u)}{(\eta - y)}$$

$$F_p/F_q = \frac{(\xi-x)}{(\eta-y)}$$

$$p \frac{F_p}{F_q} + q = \frac{\xi-u}{\eta-y}$$

$$\frac{\eta-y}{F_q} = \frac{\xi-u}{pF_p+qF_q} = \frac{\xi-x}{F_p}$$

Eqs of generators of Monge cone

"On the small" $\frac{dy}{F_q} = \frac{du}{pF_p+qF_q} = \frac{dx}{F_p}$

Characteristic eqns

$$\frac{dx}{dt} = F_p \quad \frac{dy}{dt} = F_q \quad \frac{du}{dt} = pF_p + qF_q$$

rhs depends on x, y, u, p, q

From $F=0$ these give one parameter family of characteristic direction from (x, y, u)

Quasi-linear

$$F(x, y, u, p, q) = ap + bq - c (=0)$$

$$F_p = a(x, y, u)$$

$$F_q = b(x, y, u)$$

$$pF_p + qF_q = ap + bq = c(x, y, u)$$

$F=0$ is a redundant eqn.

} indep of p & q
 $\Rightarrow$ unique char direction (a, b, c)

For general case - need two more eqns.

look for eqns for dp/dt & dq/dt

$$p = p(x, y) \quad q = q(x, y)$$

$$dp/dt = p_x x_t + p_y y_t = p_x F_p + p_y F_q$$

$$dq/dt = q_x x_t + q_y y_t = q_x F_p + q_y F_q$$

Differentiate $F(x, y, u, u_x, u_y)$ wrt x, y

$$F_x + F_p p_x + F_q q_x + F_u p = 0$$

$$F_x + \frac{dp}{dt} + F_u p = 0$$

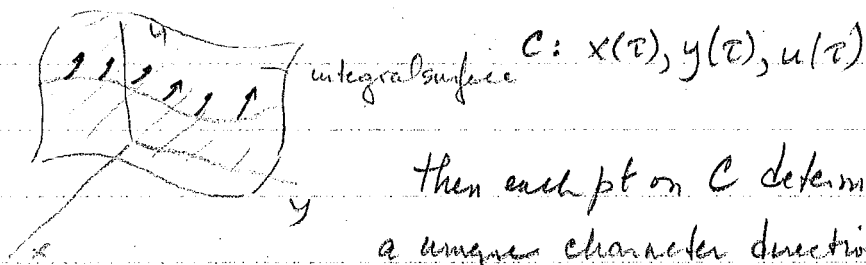
$$F_y + F_p p_y + F_q q_y + F_u q = 0$$

$$F_y + \frac{dq}{dt} + F_u q = 0$$

$$\therefore \left. \begin{aligned} \frac{dp}{dt} &= -F_x - F_u p \\ \frac{dq}{dt} &= -F_y - F_u q \\ \frac{dx}{dt} &= F_p \quad \frac{dy}{dt} = F_q \quad \frac{du}{dt} = p F_p + q F_q \end{aligned} \right\} \begin{array}{l} \text{Char eq} \\ \text{for} \\ F(x, y, u, p, q) = 0 \end{array}$$

Cauchy problem - IVP

Quasi-linear case - initial curve nowhere characteristic



then each pt on C determines a unique character direction

→ yields unique integral surface.

General Nonlinear

five for $x(t), y(t), u(t), p(t), q(t)$ needed to give a well posed problem i.e. specify a curve together with a direction at each pt on the curve - this is called an initial strip

by choosing p & q at each pt we are picking a particular generator to the Monge cone at each pt.

need extra condition for smooth data: strip condition

$$u' = p x' + q y' \quad ' = \frac{d}{dt}$$

this ensures we have a "smooth" initial strip
i.e. that we are picking generators of the Monge cones in a
"continuous" manner.

A strip is a set of five (x, y, u, p, q) satisfying the strip condition.

A soln to diff eq can be interpreted as a strip since it is
defined in terms of x, y, u, p, q & automatically satisfies
strip condition

$$p x_t + q y_t = p F_p + q F_q = u_t$$

Strips which are also solutions to the original pde are
called characteristic strips. (x, y, u, p, q)

- their corresponding curves are called characteristic
curves (x, y, u)

For fixed $t = t_0$, $(x_0, y_0, u_0, p_0, q_0)$ defines an
element of the strip. i.e. an element is a pt + a tangent
plane.

If a characteristic strip has one element $(x_0, y_0, u_0, p_0, q_0)$
in common with an integral surface $u = u(x, y)$ then it lies
completely on the surface.

Given the solution $u = u(x, y)$ & one element
show that this defines a unique characteristic strip
lying in u .

Consider 2 ode

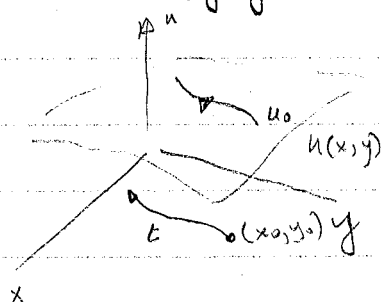
$$x_t = F_p(x, y, u(x, y), u_x(x, y), u_y(x, y)) \quad u(x, y) \text{ is known}$$

$$y_t = F_q(x, y, u(x, y), u_x(x, y), u_y(x, y))$$

for $x(t), y(t)$ subject to initial conditions

$$x(0) = x_0, y(0) = y_0$$

These define $x = x(t), y = y(t)$ in x - y plane.



x, y will determine a unique curve in the integral surface

$$x = x(t), y = y(t)$$

$$u = u(x(t), y(t))$$

Now determine eqns satisfied by this curve

$$\frac{du}{dt} = \frac{du}{dx} \frac{dx}{dt} + \frac{du}{dy} \frac{dy}{dt} = u_x F_p + u_y F_q$$

$$\frac{du_x}{dt} = u_{xx} F_p + u_{xy} F_q$$

$$\frac{du_y}{dt} = u_{xy} F_p + u_{yy} F_q$$

$$\text{where } u(0) = u_0 = u(x_0, y_0), u_x(0) = u_x(x_0, y_0) = p_0$$

$$u_y(0) = u_y(x_0, y_0) = q_0$$

$$\text{use } F(x, y, u(x, y), u_x(x, y), u_y(x, y)) = 0$$

$$\frac{dF}{dx} = \frac{dF}{dy} = 0$$

$$\frac{dF}{dx} = F_x + F_u u_x + F_p u_{xx} + F_q u_{xy} = 0$$

$$\frac{dF}{dy} = F_y + F_u u_y + F_p u_{xy} + F_q u_{yy} = 0$$

use fact $u_{xy} = u_{yx}$

$$\left. \begin{aligned} \frac{du}{dt} &= -F_x - F_u u_x \\ \frac{du}{dt} &= -F_y - F_u u_y \end{aligned} \right\} \begin{array}{l} \text{ship} \\ \text{equations} \end{array}$$

i.e. $u(x,y)$ together with init cond (initial element) determines a unique characteristic strip including the element x_0, y_0, u_0, p_0, q_0
 - this strip by defn of u lies entirely on the integral surface
 - hence if char strip has one element in common with $u(x,y)$ it lies entirely on u .

Formulation of Cauchy problem (IVP)
 details of proof in printed handout notes:
 Prescribe initial strip by five fns

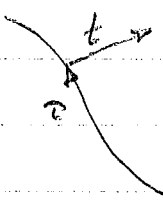
$$\left. \begin{aligned} x &= \phi(\tau) \\ y &= \psi(\tau) \\ u &= \omega(\tau) \end{aligned} \right\} \begin{array}{l} p = p(\tau) \\ q = r(\tau) \end{array} \left. \begin{array}{l} \text{subject to strip} \\ \text{conditions } \omega' = p\phi' + r\psi', \text{ etc} \end{array} \right\}$$

then: find a soln. of $F(x,y,u,p,q) = 0$ which contains initial strip.

Method of Solution :- write down five eq.

$$\left. \begin{aligned} \frac{dx}{dt} &= \\ \vdots \\ \frac{dq}{dt} &= \end{aligned} \right\} \begin{array}{l} \text{solve them subject} \\ \text{to initial conditions} \\ x(0,\tau) = \phi(\tau) \\ y(0,\tau) = \psi(\tau) \text{ etc} \\ u(0,\tau) = \omega(\tau) \end{array}$$

these yield

$$\left. \begin{aligned} x &= f(t, \tau) \\ y &= g(t, \tau) \\ u &= h(t, \tau) \\ &\text{etc.} \end{aligned} \right\} (4)$$


$$x, y, u, p, q = (x, y, u, p, q)(t, \tau)$$

All that is needed that the initial strip is nowhere characteristic is that Jacobian of transformation is nonzero

$$\left. \begin{aligned} x_t &= f_t \\ y_t &= g_t \end{aligned} \right\} \phi' f_g - \psi' f_p \neq 0$$

Soln is given in terms of 2 parameters (t, τ)

Theoretically: solve first two of (4) for t & τ

in terms of (x, y) then substitute them into 3rd of (4)

to give $u(x, y)$

- will also get $p(x, y)$ & $q(x, y)$

check $u_x = p$ & $u_y = q$ @ any pt.

Showing that strip condition holds at any point.

$$u_\tau(t, \tau) = p(t, \tau) x_\tau(t, \tau) + q(t, \tau) y_\tau(t, \tau)$$

Initially this is true by definition of initial strip - i.e. holds for $t=0$. Must show $U(t, \tau) = u_\tau - p x_\tau - q y_\tau = 0$

We know that $U(0, \tau) = 0$

Show that $U_t(t, x) = 0$

$$U_t = U_{xt} - p_t x_t - p x_{1t} - q_t y_t - q y_{xt}$$

$$= (p F_p + q F_q)_t + (F_x + F_u p) x_t - p (F_p)_t - q (F_q)_t \\ + (F_y + q F_u) y_t \quad \text{by char equations.}$$

$$= p_t F_p + q_t F_q + (F_x + F_u p) x_t + (F_y + q F_u) y_t$$

since $F=0$

$$0 = F_x x_t + F_y y_t + F_u u_t + F_p p_t + F_q q_t$$

$$F_u u_t = - (\quad)$$

$$\therefore U_t = F_u (p x_t + q y_t - u_t)$$

$$U_t = -F_u U \quad \text{linear ode for } U$$

$$\Rightarrow U_t \geq 0 \text{ since } U(0, x) = 0$$

$$\Rightarrow U \equiv 0$$

Must show soln satisfies $F=0$

$$F_t = F_x x_t + F_y y_t + F_u u_t + F_p p_t + F_q q_t$$

$$= F_x F_p + F_y F_q + F_u (p F_p + q F_q) - F_p (F_x + p F_u) - F_q (F_y + q F_u) \\ = 0$$

$F_t = 0$ along a char strip

But $F=0$ at initial element

$\Rightarrow F \equiv 0$ on strip

Charpit's Method for finding complete integral

1) Write down five characteristic eq
find one integral from these
 $\Phi(x, y, u, p, q) = \alpha$ const of integration

2) Solve Φ & F for p, q in terms of x, y, u, α

$\rightarrow P(x, y, u, \alpha) = p \quad Q(x, y, u, \alpha) = q$
then form $du = Pdx + Qdy$ (note that P, Q contain u)
 $\rightarrow$ this can be integrated = in form of perfect differential

$$\Rightarrow u = u(x, y, \alpha, \beta)$$

Example: $p^2 + qy - u = 0$

$$\frac{dx}{dt} = F_p = 2p \quad \frac{dy}{dt} = F_q = y \quad \frac{du}{dt} = F_u = -2p^2 + qy = u$$

$$\frac{dx}{2p} = \frac{dy}{y} = \frac{du}{u} = \frac{dp}{p} = \frac{dq}{0} \quad \begin{array}{l} F_y = q, qF_u = -q \end{array}$$

$$Q = q = \alpha \quad p = \sqrt{u - \alpha y} = P$$

$$du = \sqrt{u - \alpha y} dx + \alpha dy$$

$$\frac{(du - \alpha dy)}{\sqrt{u - \alpha y}} = dx$$

$$2\sqrt{u - \alpha y} = x + \beta$$

$$2\sqrt{u - \alpha y} - x = \beta$$

$$u = \alpha y + \frac{1}{2}(x + \beta)^2$$

How find complete integral of

$$1. \quad p^2 + q^2 - px - qy + \frac{1}{2}xy = 0$$

$$2. \quad \sqrt{p} + \sqrt{q} = 2x$$

$$3. \quad u - x + \log(pq) = 0$$

April 10, 1973

if the deriv occur in complicated way and coeff occurs in simple way. if we interchange the roles we can simplify the problem.
Legendre Transformation $(u, x, y) \rightarrow (x, y)$

General Idea change from point coords to line or tangent plane coords

if (x, y, u) are a pt on $u = u(x, y)$ then the tangent plane is $\alpha \xi + \beta \eta + \gamma = \delta$

where (ξ, η, γ) are running coords (corres to (x, y, u))

$$\alpha = u_x \quad \beta = u_y \quad \gamma = \alpha x + \beta y - u$$

The transform $(x, y) \rightarrow (\alpha, \beta)$ is 1:1 provided $\frac{\partial(\alpha, \beta)}{\partial(x, y)} \neq 0$

$$= u_{xx}u_{yy} - u_{xy}^2 \neq 0$$

If this is true: given (x, y, u) then (α, β) are determined

$\Rightarrow \gamma$ is determined uniquely $\Rightarrow$ transformation $(x, y, u) \rightarrow (\alpha, \beta, \gamma)$ is 1:1.

we need inverse transformation

$$\gamma_\alpha = \alpha x_\alpha + x + \beta y_\alpha - u_\alpha$$

$$\gamma_\beta = \alpha x_\beta + y + \beta y_\beta - u_\beta$$

But $u_\alpha = u_x x_\alpha + u_y y_\alpha = \alpha x_\alpha + \beta y_\alpha$

$u_\beta = u_x x_\beta + u_y y_\beta = \alpha x_\beta + \beta y_\beta$

$\Rightarrow \delta_\alpha = x$

$x = \delta_\alpha$

$\delta_\beta = y$

$y = \delta_\beta$

$\delta = x\alpha + y\beta - u ; \quad u = \alpha\delta_\alpha + \beta\delta_\beta - \delta$

} inverse Legendre transformation

Example $xu_x^2 + yu_y^2 = 1$

Nonlinear in u_x & u_y

$x = \delta_\alpha$

$u_x = \alpha$

$y = \delta_\beta$

$u_y = \beta$

$\delta = \dots$

Linear in δ_α & δ_β $\alpha^2 \delta_\alpha + \beta^2 \delta_\beta = 1$

$\frac{d\beta}{d\alpha} = \frac{\beta^2}{\alpha^2}$

$\frac{d\delta}{d\alpha} = \frac{1}{\alpha^2}$

Can be extended to higher orders

$\alpha_j = u_{x_j}$

$\delta = \sum \alpha_j x_j - u$

$j=1, \dots, n$

There are n independent variables

Systems of First Order P.D.E.

Linear

$\sum_{k=1}^n [a_{jk}(x,y) u_x^{(k)} + b_{jk}(x,y) u_y^{(k)}] = \sum_{k=1}^n c_j(x,y,u) u^{(k)}$

$j=1, \dots, n$

an equation where

r.h.s. can be nonlinear is called semilinear

$c_j(x,y,u)$

dependent variables are $(u^{(1)}, \dots, u^{(n)})$

rewrite as $A(x,y) U_x + B(x,y) U_y = C(x,y) U$
 where $A = (a_{jk})$ $B = (b_{jk})$ $C = (c_j)$
 and $U^t = [u^{(1)}, u^{(2)}, \dots, u^{(n)}]$

Classify $\rightarrow$ simplify by writing in terms of directed derivatives by taking linear combinations of the n equations so that all derivatives are in same direction.

notation $D_{jk} = a_{jk} \frac{\partial}{\partial x} + b_{jk} \frac{\partial}{\partial y}$
 $\Rightarrow n^2$ directional derivatives since j, k go from $1, \dots, n$
 $\sum_{k=1}^n D_{jk} u^{(k)} = c_j$

each $u^{(k)}$ differentiated in a different direction.

take linear combinations: i.e. mult j th eqn by λ_j and add

$$\sum_{j=1}^n \sum_{k=1}^n \{ \lambda_j a_{jk} u^{(k)} + \lambda_j b_{jk} u_y^{(k)} \} = \sum_{j=1}^n \lambda_j c_j$$

Now direction no. of derivatives are $(\sum \lambda_j a_{jk}, \sum \lambda_j b_{jk})$

We want these to be same direction for all k

$$\Rightarrow \sum_{j=1}^n \lambda_j a_{jk} = \mu \sum_{j=1}^n \lambda_j b_{jk} \quad k=1, \dots, n$$

$$\sum_{j=1}^n \lambda_j (a_{jk} - \mu b_{jk}) = 0 \quad k=1, \dots, n$$

for non trivial sol must have $\det |a_{jk} - \mu b_{jk}| = 0$

i.e. that μ is ev for $A - \mu B$ & that $\Lambda = (\lambda_1, \dots, \lambda_n)$

is the corresponding $\vec{EV}$.

det $|A(x,y) - \mu B(x,y)| = 0$ is n th order eq for $\mu(x,y)$

these are local conditions, real

Suppose there are r distinct roots $\mu_1, \dots, \mu_r$ $r \leq n$ physically real

for each root there is a corresponding left EV $\Lambda_k \quad k=1, \dots, r$

Using each component will yield $(\lambda_{1k}, \lambda_{2k}, \dots)$
 r distinct eqns in which all u 's differentiated in the same direction

$$\sum_{j=1}^n \sum_{k=1}^r \lambda_j b_{jk} (\mu u_x^{(k)} + u_y^{(k)}) = \sum \lambda_j g_j$$

$$\sum_j \lambda_j^{(0)} b_{jk} = \beta_k^{(0)}(x, y)$$

$$\sum_k \beta_k (\mu u_x^{(k)} + u_y^{(k)}) = \sum_j \lambda_j^{(0)} g_j^{(0)}$$

$$\sum_l \beta_k^{(l)} D_l u^{(k)} \quad D_l = \mu \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \quad l=1, \dots, r$$

$$\sum \beta_k^{(0)} D_l u^{(k)} = D \sum \beta_k^{(0)} u^{(k)} - \sum (D \beta_k^{(0)}) u^{(k)}$$

$$\hat{u}^{(0)} = \sum \beta_k^{(0)} u^{(k)}$$

$$\begin{aligned} \hat{c} &= \sum \lambda_k^{(0)} c_k^{(0)} + \sum (D \beta_k^{(0)}) u^{(k)} \\ &= \sum [\lambda_k c_k + (D \beta_k^{(0)}) u^{(k)}] \\ &= \hat{c}(x, y, \underline{u}) \end{aligned}$$

$$D_l \hat{u}^{(0)} = \hat{c}^{(l)} \quad l=1, 2, \dots, r$$

r th order system.

For $r < n$ must add $n-r$ of original equations to determine $u^{(k)}$. This mixed problem difficult will not be considered

$r=0$ no real root — elliptic

$r=n$ all real roots hyperbolic

$r=n$ with all distinct totally hyperbolic

Example Cauchy Riemann Eq

$$u_x = v_y$$

$$u_y = -v_x$$

$$\underline{u} = \begin{pmatrix} u \\ v \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} u_x \\ v_x \end{pmatrix} + \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} u_y \\ v_y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

EV of $A = \mu$

det

$$\begin{vmatrix} 1 - \mu & -1 \\ 1 & \mu \end{vmatrix} = 0$$

$$\mu^2 + 1 = 0$$

no real roots

elliptic

C-R satisfy $\Delta u = \Delta v = 0$ ✓

$$u_x = v_y$$

$$u_y = -v_x$$

$$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \underline{u}_x + \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \underline{u}_y = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\det \begin{pmatrix} 1 & -\mu \\ \mu & -1 \end{pmatrix} = 0$$

$$\mu^2 - 1 = 0$$

$$\mu = \pm 1$$

two distinct real roots

totally hyperbolic

$$\nabla \nabla u = \nabla \nabla v = 0$$

char direction:

$$\frac{\partial}{\partial x} + \frac{\partial}{\partial y}$$

$$\frac{\partial}{\partial x} - \frac{\partial}{\partial y}$$

$$\frac{dy}{dx} = \pm 1$$

$$D_\ell = \mu \frac{\partial}{\partial x} + \frac{\partial}{\partial y}$$

Directional deriv in x, y plane have

slope μ

these are called char

direction. Curves $\perp$ to char dir

are given by $dy/dx = \frac{1}{\mu}$

these define char curves.

Totally hyperbolic case $p=1, 2, \dots, n$

$$\begin{cases} u_x - v_y = 0 \\ u_y - v_x = 0 \end{cases} \quad \frac{dy}{dx} = \pm 1$$

$$\frac{\partial}{\partial x} + \frac{\partial}{\partial y} \quad \frac{\partial}{\partial x} - \frac{\partial}{\partial y}$$

$C^\pm$ - label two char curves

$$\begin{aligned} y &= x + \alpha \\ y &= -x + \beta \end{aligned} \quad \begin{aligned} \alpha &= y - x \\ \beta &= y + x \end{aligned}$$

$$C^+ \quad \left(\frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right) (u-v) = 0$$

$$D_1 \hat{u}^{(1)} = 0 \quad (u-v) = f(\beta)$$

$$C^- \quad \left(\frac{\partial}{\partial x} - \frac{\partial}{\partial y} \right) (u+v) = 0$$

$$D_2 \hat{u}^{(2)} = 0 \quad u+v = g(\alpha)$$

$$u = f(\beta) + g(\alpha) \quad v = g(\alpha) - f(\beta)$$

Quasi linear case - all the same except w.r.t. p depends on u as well

$$A(x, y, u) u_x + B(x, y, u) u_y = C(x, y, u)$$

Characteristics

$$\frac{dy}{dx} = \frac{1}{\lambda_1(x, y, u)}, \quad \lambda_j(x, y, u)$$

i.e. Characteristics depend on the soln.

Full nonlinear case $\rightarrow$ unnecessary since it reduces to quasi-linear
we can always reduce a single nonlinear p.d.e. into a system
of 3 quasi-linear. We can reduce n nonlinear system
to a system of $3n$ quasi-linear.

$$F(x, y, u, p, q) = 0 \quad \text{reduced}$$

to a system of 3 in p, q, u

F_x, F_y are obtained

$$F_x + F_p p_x + F_u p + F_q q_x = 0$$

$$F_y + F_p p_y + F_u q + F_q q_y = 0$$

$$F_p p + F_g g = F_p u_x + F_g u_y$$

Char direct.

$$\frac{dx}{dt} = F_p \quad \frac{dy}{dt} = F_g \quad \text{using these into the two give}$$

$$\frac{dp}{dt} = -(F_x + F_p u_p) \quad \frac{dg}{dt} = -(F_y + F_g u_g) \quad \frac{du}{dt} = p F_p + g F_g$$

p, g, u are the $\hat{u}$

$$\begin{pmatrix} p \\ g \\ u \end{pmatrix}' = \begin{pmatrix} -F_u & 0 & 0 \\ 0 & -F_u & 0 \\ F_p & F_g & 0 \end{pmatrix} \begin{pmatrix} p \\ g \\ u \end{pmatrix} + \begin{pmatrix} -F_x \\ -F_y \\ 0 \end{pmatrix}$$

The hodograph transformation

particularly useful for medium unsteady & two dim. steady compressible gas flow

Eulerian eqns. steady 2d, irrot, isentropic - two quasilin

Hodograph transf converts them into linear equations

(x, y) don't occur in coefficients

(u, v) are components of velocity in (x, y) directions

$$u_y - v_x = 0 \quad \text{Continuity}$$

$$[c^2(q) - u^2] u_x - uv(u_y + v_x) + [c^2(q) - v^2] v_y = 0$$

$$q = \sqrt{u^2 + v^2} \quad \text{speed at a pt.} \quad c^2(q) \quad c^2 \text{ as a fn of } q$$

Coeff are not fns of x, y ; depend on u, v only

$$(x, y) \rightarrow u, v$$

$$J = \begin{vmatrix} u_x & u_y \\ v_x & v_y \end{vmatrix} \neq 0$$

$$u_x = J_{yv} \quad u_y = -J_{xv}$$

$$v_x = -J_{yu} \quad v_y = J_{xu}$$

put into 2 eq

$$x_v - y_u = 0 \quad \& \quad (c^2 - u)y_v + uv(x_v + y_u) + (c^2 - v)x_u = 0$$

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 & -1 & 0 \\ c^2 - v & uv & uv & c^2 - u \end{pmatrix} \begin{pmatrix} x_u \\ x_v \\ y_u \\ y_v \end{pmatrix}$$

One dim Gas Eq
Eulerian Co-ord

$$\begin{array}{ll} \text{Cont} & \rho_t + (\rho u)_x = 0 \\ \text{Momentum} & u_t + uu_x + \frac{1}{\rho} p_x = 0 \\ \text{Entropy const} & S_t + u S_x = 0 \end{array} \left. \begin{array}{l} \text{full} \\ \text{Eq} \\ \text{Energy Eq} \end{array} \right\} \begin{array}{l} \rho = \text{density} \\ p = \text{pressure} \\ u = \text{velocity in } x \text{ direct} \end{array}$$

Eq of State defines particular material

$S = \text{entropy}$

$$p = p(p, S)$$

$$\frac{\partial p}{\partial \rho} > 0 \quad \& \text{ has dimensions of velocity squared}$$

$$c^2 = \frac{\partial p}{\partial \rho}(p, S)$$

$$\begin{pmatrix} \cdot \\ \cdot \end{pmatrix} \begin{pmatrix} u \\ p \\ S \end{pmatrix}_x + \begin{pmatrix} \cdot \\ \cdot \end{pmatrix} \begin{pmatrix} u \\ p \\ S \end{pmatrix}_t = 0$$

HW

a) Find characteristics

b) Classify system

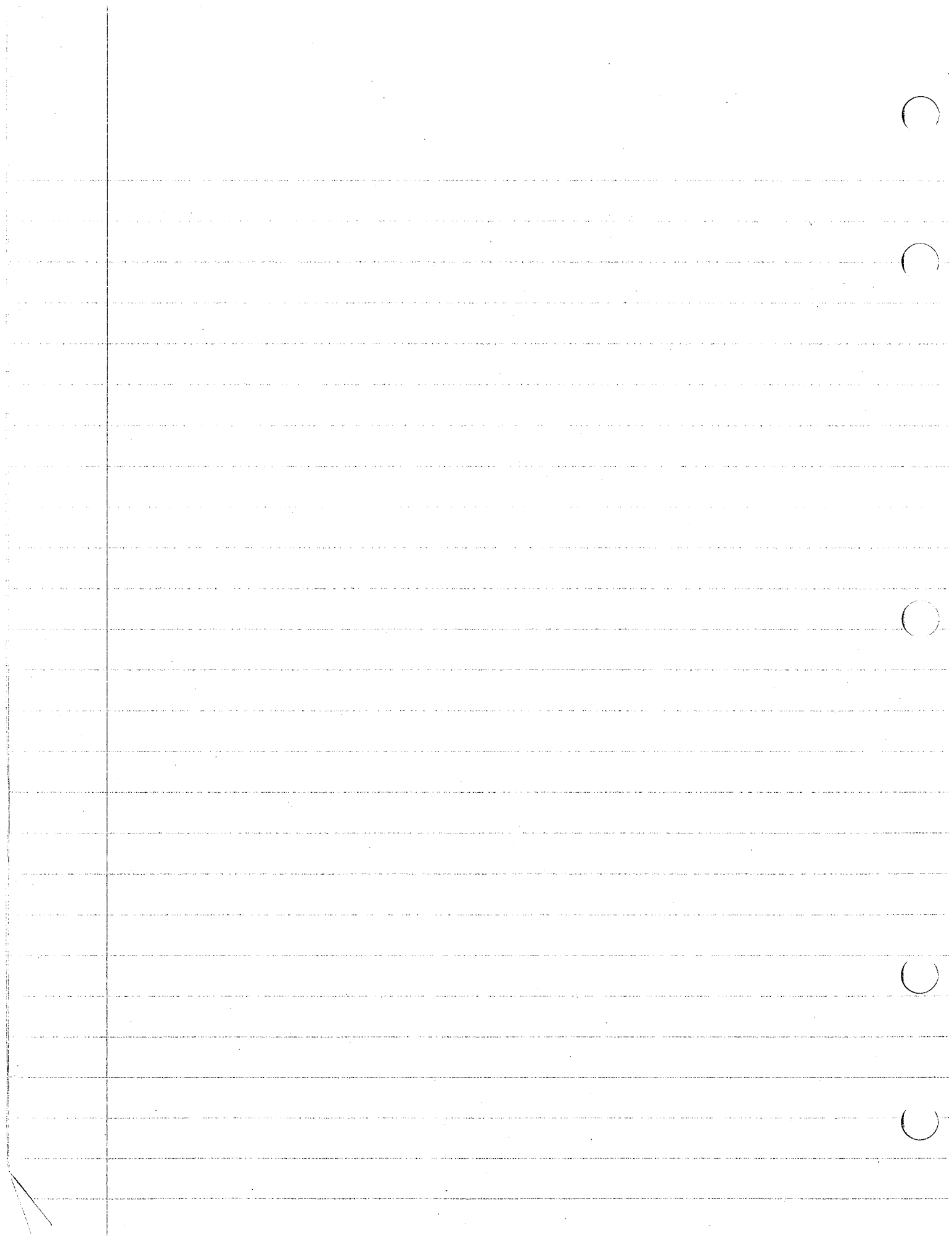
c) Put in canonical form $D_t \hat{u}^T = \hat{C}^T$ (where possible)

$$\begin{array}{l} 1. \quad u_x + 2u_t + v_x + 3v_t - u + v = 0 \\ \quad 3u_x + u_t - 2v_x - v_t - 2v = 0 \end{array}$$

$$\begin{array}{l} 2. \quad \rho u_x + u p_x + p_t = -2\rho \frac{u}{x} \\ \quad \rho u u_x + \rho u_t + c^2 p_x = 0 \end{array}$$

$$\begin{aligned} 3) \quad & (x+y) u_x + v_y = 0 \\ & (x-y) v_x + u_y = 0 \end{aligned}$$

$$\begin{aligned} 4) \quad & u_x + u_y + u - v_x = 0 \\ & 2 u_y + u^2 - 1 - v_y = 0 \end{aligned}$$



One Dimensional Compressible Flow

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Eulerian eqns [field eqns]

$$\rho_t + (\rho u)_x = 0 \quad \text{continuity}$$

$$u_t + u u_x + \frac{1}{\rho} p_x = 0 \quad \text{Newton 2nd Law}$$

$$S_t + u S_x = 0 \quad \text{Entropy does not change of a particle}$$

ρ = density (linear)
 u = velocity in x direction

p = pressure
 S = entropy

Egn of state

$$p = f(p, S) \quad \text{describes particular gas}$$

Physically $f_p > 0$ & has dimension of velocity²
put $c^2 = f_p(p, S)$

$$\Rightarrow p_t = c^2 \rho_t + f_S S_t$$

$$u p_x = u c^2 p_x + u f_S S_x$$

$$\text{adding} \quad p_t + u p_x = c^2 (\rho_t + u \rho_x) + f_S (S_t + u S_x)$$

$$\Rightarrow \rho_t + u \rho_x + c^2 \rho u_x = 0$$

$\swarrow = \rho(p, S)$

Using

$$u_t + u u_x + \frac{1}{\rho} p_x = 0$$

$$\text{and } S_t + u S_x = 0$$

we have, looking on $\rho = \rho(p, S)$, a system of 3 quasilinear f.d.e in p, u, S

Characteristics

$$\begin{pmatrix} u & c^2 \rho & 0 \\ 1/\rho & u & 0 \\ 0 & 0 & u \end{pmatrix} \begin{pmatrix} p_x \\ u_x \\ S_x \end{pmatrix} + \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} p_t \\ u_t \\ S_t \end{pmatrix} = 0$$

$$\Rightarrow \begin{vmatrix} u-\mu & c^2 \rho & 0 \\ 1/\rho & u-\mu & 0 \\ 0 & 0 & u-\mu \end{vmatrix} = 0$$

$$\Rightarrow (u-\mu)((u-\mu)^2 - c^2) = 0$$

~~$\mu = u$~~ $\mu = u, u \pm c$ three char directions

$$C_0 : \quad \frac{dx}{dt} = u \quad (\text{particle trajectories})$$

$$C_{\pm}^{\pm} : \quad \frac{dx}{dt} = u \pm c$$

To find diff. eqns along characteristics must find eigenvectors. Let $(\lambda_1^{(0)}, \lambda_2^{(0)}, \lambda_3^{(0)})$ be eigenvector for

$\mu = u.$

$$(\lambda_1^{(0)}, \lambda_2^{(0)}, \lambda_3^{(0)}) \cdot \begin{pmatrix} 0 & c^2 \rho & 0 \\ \gamma_p & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = 0$$

$$\Rightarrow \lambda_2^{(0)} = \lambda_3^{(0)} = 0, \lambda_1^{(0)} \text{ arb.} \Rightarrow (0, 0, 1) \text{ is eigenvector}$$

$$\Rightarrow S_t + u S_x = 0 \text{ given eqn.}$$

ie. along particle trajectories no change in entropy - no dissipative mechanism present.

$$\text{For } C_{\pm}^{\pm} : (\lambda_1^{\pm}, \lambda_2^{\pm}, \lambda_3^{\pm}) \begin{pmatrix} \mp c & c^2 \rho & 0 \\ \gamma_p & \mp c & 0 \\ 0 & 0 & \mp c \end{pmatrix} = 0$$

$$\Rightarrow \left. \begin{aligned} c \lambda_1^{\pm} \mp \lambda_2^{\pm} &= 0 \\ c^2 \rho \lambda_1^{\pm} \mp c \lambda_2^{\pm} &= 0 \\ \lambda_3^{\pm} &= 0 \end{aligned} \right\} \Rightarrow c \rho \lambda_1^{\pm} = \pm \lambda_2^{\pm}$$

$$\Rightarrow \underline{(1, \pm c \rho, 0) \text{ eigenvectors}}$$

$$\Rightarrow p_t + u p_x + c^2 \rho u_x \pm c \rho (u_t + u u_x \pm \frac{1}{\rho} p_x) = 0$$

$$\Rightarrow p_t + (u \pm c) p_x \pm c \rho [u_t + (u \pm c) u_x] = 0$$

Both p & u diff. in direction with direction nos.

$(1, u \pm c)$. If $s_{\pm}$ parameter in $C^{\pm}$ directions

$$\frac{\partial p}{\partial s_{\pm}} \pm c \rho \frac{\partial u}{\partial s_{\pm}} = 0 \quad \text{on } C^{\pm}$$

Since c depends on S these last two eqns. coupled to entropy eqn. $\rightarrow$ simplifies if S constant

$$\Rightarrow \underline{\text{isentropic flow}} \quad f_{,S} = 0$$

$$\text{Then } p = f(\rho), \quad c^2 = f'(\rho)$$

Now more convenient to eliminate p from eqns

$$p_x = c^2 \rho_x$$

$$\Rightarrow \left. \begin{aligned} u_t + u u_x + \frac{c^2}{\rho} \rho_x &= 0 \\ \rho_t + \rho u_x + u \rho_x &= 0 \end{aligned} \right\} \begin{array}{l} \text{two eqns} \\ \text{for } (\rho, u) \end{array}$$

$$\begin{pmatrix} u & \rho \\ c^2/\rho & u \end{pmatrix} \begin{pmatrix} p_x \\ u_x \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} p_t \\ u_t \end{pmatrix} = 0$$

$$\Rightarrow \begin{vmatrix} u-\mu & \rho \\ c^2/\rho & u-\mu \end{vmatrix} = 0$$

$$(u-\mu)^2 - c^2 = 0$$

$$\mu = u \pm c$$

Eigenvectors: $(\lambda_1^\pm, \lambda_2^\pm)$ are soln. of

$$(\lambda_1^\pm, \lambda_2^\pm) \begin{pmatrix} \mp c & \rho \\ c^2/\rho & \mp c \end{pmatrix} = 0$$

i.e. $c \lambda_1^\pm = \pm \frac{c^2}{\rho} \lambda_2^\pm$

$$\pm \frac{c}{\rho} (\rho_t + \rho u_x + u \rho_x) + (u_t + u u_x + \frac{c^2}{\rho} \rho_x) = 0$$

$$\Rightarrow \pm \frac{c}{\rho} [\rho_t + (u \pm c) \rho_x] + [u_t + (u \pm c) u_x] = 0$$

$$\pm \frac{c}{\rho} d\rho + du = 0 \quad \text{on } C^\pm$$

Most conveniently written in terms of Riemann
Invariants

Since $c^2 = f'(p)$, write $c = c(p)$

$$L(p) = \int_{p_0}^p \frac{c(p)}{p} dp$$

Then $d[L(p) \pm u] = 0$ on $C^\pm$

or $L(p) \pm u = \text{const}$ on $C^\pm$

Let $L(p) + u = 2r$ on C^+

$L(p) - u = 2s$ on C^-

r & s called Riemann Invariants

r is a constant on a C^+ , s is a const. on C^- but not the same constant on each curve.

$\Rightarrow r$ varies on a C^- + s varies on a C^+

$\Rightarrow$ take s as parameter on C^+ , r as parameter on C^-

$$\left. \begin{aligned} \frac{dx}{ds} &= (u+c) \frac{dt}{ds} & \text{on } C^+ \\ \frac{dx}{dr} &= (u-c) \frac{dt}{dr} & \text{on } C^- \end{aligned} \right\} \text{Regarding } \begin{aligned} x &= x(r,s) \\ t &= t(r,s) \end{aligned}$$

these become two p.d.e's for x, t :

$$x_s = (u+c) t_s$$

$$x_r = (u-c) t_r$$

Solve them for x, t (r, s) - invert to give r, s as fns of $(u, c$ known by below)

x, t . Then solve $L \pm u = 2r$ to give p, u

$$\left. \begin{array}{l} L(p) = r+s \\ u = r-s \end{array} \right\} \text{ gives } u \text{ \& } p \text{ as fns of } r, s$$

Thus original problem reduced to solving linear system for x, t in terms of r, s . Can eliminate x from them yielding:

$$(u_r + c_r) t_s + (u+c) t_{rs} = (u-c) t_{rs} + (u_r - c_r) t_r$$

$$\text{But } u_r = 1, u_s = -1, L'(p) p_r = L'(p) p_s = 1$$

$$\Rightarrow p_r = p_s = p/c$$

$$\text{and } c_r = \frac{dc}{dp} p_r = \frac{p}{c} \frac{dc}{dp}, c_s = \frac{p}{c} \frac{dc}{dp}$$

$$\Rightarrow \left(1 + \frac{p}{c} c_p\right) t_s + 2c t_{rs} = - \left(1 + \frac{p}{c} c_p\right) t_r$$

$$\Rightarrow$$

$$t_{rs} + [\phi(r+s)] (t_r + t_s) = 0$$

where $\phi(r+s) = \frac{1 + \frac{p}{c} \frac{dc}{dp}}{2c}$

is just a fn. of $r+s$ since it is just a fn. of p

Special case : polytropic gas - large no. of actual gases

$$p = A \rho^\gamma$$

γ = ratio of spec. heats
= 1.4 for air.

$$\Rightarrow p = \gamma A \rho^{\gamma-1} \quad ($$

$$\Rightarrow c(p) = \sqrt{\gamma A} \rho^{\gamma/2} \quad (p_0 = 0)$$

$$L(p) = \frac{2\sqrt{\gamma A}}{\gamma-1} \rho^{\frac{\gamma-1}{2}} = \frac{2c}{\gamma-1}$$

To find $\phi(r+s)$, $\frac{dc}{dp} = \frac{c}{p} \cdot \left(\frac{\gamma-1}{2}\right)$

$$\Rightarrow \frac{p}{c} \frac{dc}{dp} = \frac{\gamma-1}{2}, \quad \phi(r+s) = \frac{\gamma+1}{2(2c)}$$

$$= \frac{\gamma+1}{2(\gamma-1)L}$$

But $L = r+s$

$$\Rightarrow \phi(r+s) = \frac{\gamma+1}{2(\gamma-1)(r+s)}$$

Let $K = \frac{1}{2} \frac{\gamma+1}{\gamma-1}$

$$t_{rs} + \frac{K}{r+s} (t_r + t_s) = 0$$

Can eliminate first deriv. terms with subst.

$$t = \psi(r+s) \omega(r,s)$$

$$\begin{aligned} t_r &= \psi' \omega + \psi \omega_r & t_{rs} &= \psi'' \omega + \psi' \omega_s + \psi' \omega_r + \psi \omega_{rs} \\ t_s &= \psi' \omega + \psi \omega_s \end{aligned}$$

where ω is new dep. var. & ψ chosen s.t. $\omega_r + \omega_s$ terms vanish

$$\Rightarrow \psi \omega_{rs} + \left(\psi' + \frac{K\psi}{r+s} \right) (\omega_r + \omega_s) + \left(\psi' + \frac{2K\psi'}{r+s} \right) \omega = 0$$

Let $\psi = (r+s)^{-K}$

so that $t(r,s) = \frac{\omega(r,s)}{(r+s)^K}$

$$\omega_{rs} + \frac{K(1-K)}{(r+s)^2} \omega = 0$$

1st. telegraph eqn. with variable coeff.
soln. straight forward. not given

Simple Waves : all previous analysis presupposes
can change variables $(x, t) \rightarrow (r, s)$

- can't do this if r & s are not independent

i.e. if $\exists F(r, s)$ s.t. $F(r, s) = 0$
but $F_r^2 + F_s^2 \neq 0$

$$\Rightarrow F_r dr + F_s ds = 0$$

Consider characteristic C^+ — r is a constant
 $\Rightarrow dr = 0$

$$\& F_s ds = 0 \text{ on } C^+$$

$$F_r dr = 0 \text{ on } C^-$$

If $F_s \neq 0$ s is also constant on C^+

If $F_r \neq 0$ r is also constant on C^-

$\Rightarrow$ if $F_r \neq 0$ & $F_s \neq 0$ r & s must both be

constants in whole region covered by characteristics.

$\Rightarrow u$ & p both constant (d.p.a.s.) $\Rightarrow$ have constant state
(not at rest $u=0$ nec.)

Now consider cases for one of F_r, F_s nonzero.

1) $F_r = 0, F_s \neq 0$

2) $F_s = 0, F_r \neq 0$

1) $F_r = 0, F_s \neq 0 \Rightarrow$ both r & s constant along C^+
(since $F_s ds = 0$ on C^+ & r already const. there)

$\Rightarrow u$ & p constant on C^+ 's $\Rightarrow$ slopes of C^+

characteristics $\left(\frac{dx}{dt} = u + c\right)$ are constant i.e.

straight lines. However they are not parallel

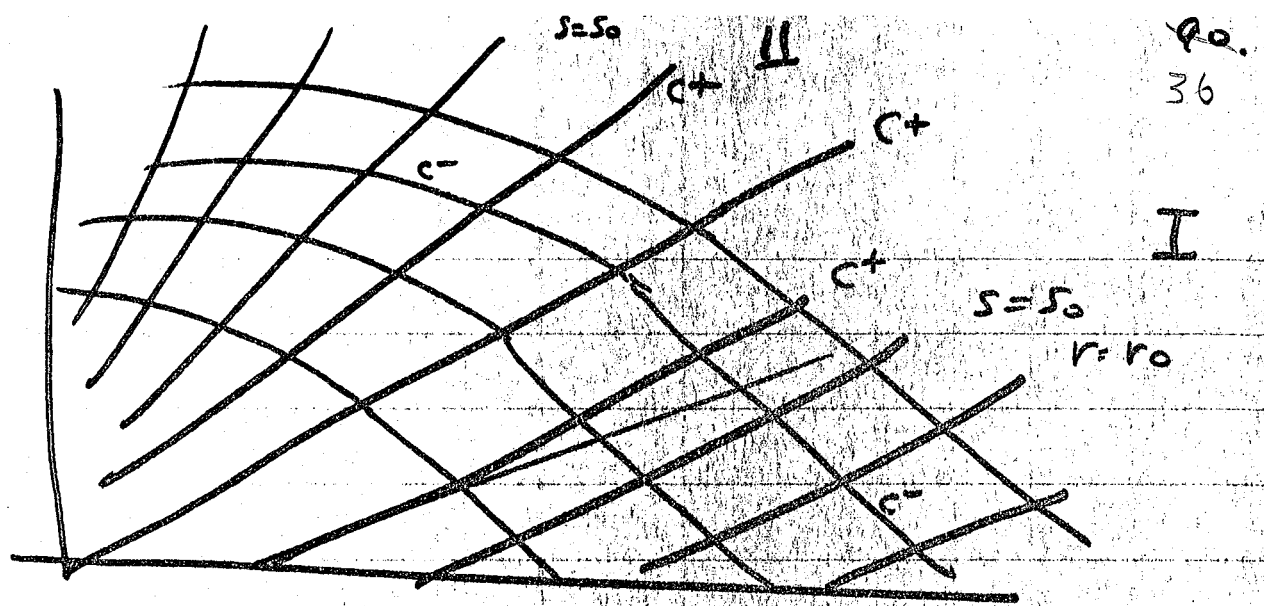
since r varies with C^- i.e. r is a different constant

on each C^+ . Hence u & p are different constants on

each C^+ & each C^+ has different slope.

A flow in which one family of the characteristics consists of straight lines is called a simple wave. In

fact the flow in a region adjacent to a constant state is always a simple wave.



Consider constant state $r=r_0$, $s=s_0$, and an adjacent region where u & p vary. Curve separating two regions must be a characteristic — let it be a C^+ .

Then the curves entering region II from I are C^- characteristics. Along these s is a constant & it must be same const. on each C^- , $s=s_0$. Now consider any C^+ char. in II. On it r is a constant by defn.

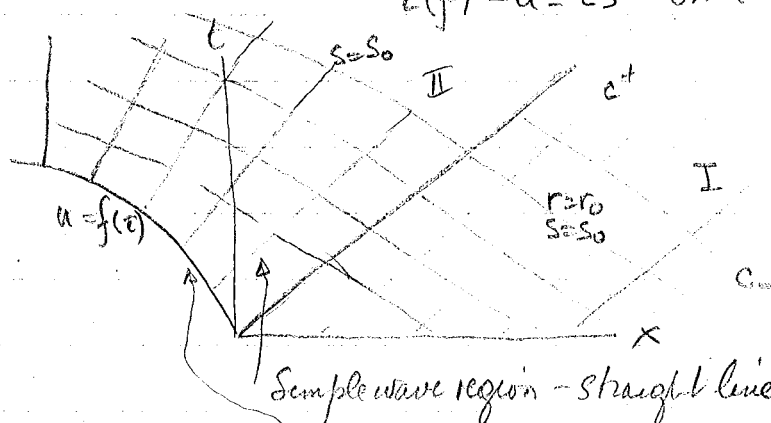
& also s is a constant $\Rightarrow u$ & p const on any C^+ in II

$\Rightarrow$ characteristics straight lines in II

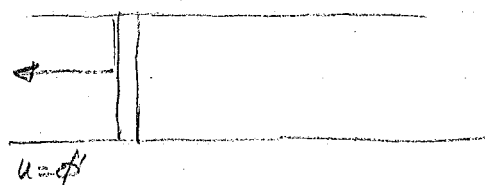
$\Rightarrow$ simple wave

4-24-73

Riemann Invariants
$$\left. \begin{aligned} L(p) + u &= 2r \quad \text{on } c^+ \\ L(p) - u &= 2s \quad \text{on } c^- \end{aligned} \right\} \frac{dx}{dt} = u \pm c(p)$$



Piston Problem $x = \phi(t)$ piston path $u = \phi'$



i) Rarefaction wave piston accelerates in $-x$ direction

$$\phi(0) = 0 \quad \phi'(0) = 0 \quad \phi''(t) < 0$$

at piston $u = \phi'(t)$

Region I : $\frac{dx}{dt} = \pm c_0 = \pm c(p_0)$

II $\frac{dx}{dt} = u + c(p)$ on c^+ and on c^-

i.e. char $c^\pm$ are straight lines

To find slope - know $u = \phi'(t)$ - must find p

$$L(p) = u + L(p_0) \rightarrow \text{gives } p \text{ as a fn of } t$$

$\Rightarrow$ have c as a fn of t

$\Rightarrow$ have $u + c = \frac{dx}{dt}$ as a fn of t , param along piston-path

to show non convergence of char

find $m(r) = u + c$ slope of C^+

what property of ϕ do we want for char to be diverging

ie. $m' < 0$.

$$m'(r) = u'(r) + c_r = \phi''(r) + c_r$$

$$L(p) = L(p_0) + u = L(p_0) + \phi'(r)$$

$$L'(p) p_r = \phi''(r)$$

$$L = \int \frac{c(p)}{p} dp$$

$$\frac{c}{p} p_r = \phi'(r)$$

$$c^2(p) = f'(p) \Rightarrow 2c c_r = f''(p) p_r \quad p = f(p)$$

$$c_r = \frac{f''}{2c} p_r = \frac{f''}{2c} \frac{\phi}{c} p$$

$$m'(r) = \left(1 + \frac{p f''}{2c^2}\right) \phi''(r)$$

physically $f'' > 0 \Rightarrow m'(r) = \text{sign}(\phi''(r)) \Rightarrow$ characteristics fan out for ϕ'' negative. Rarefaction wave.

$$u = L(p) - L(p_0) = \int_{p_0}^p \frac{c(r)}{r} dr$$

Since $p > 0$ & $c > 0$ if $u \downarrow \rightarrow p \downarrow$

for case at which piston leaves gas behind ie $p=0$

$$\text{if } u_{\infty} = \int_{p_0}^0 \frac{c(r)}{r} dr = - \int_0^{p_0} \frac{c(r)}{r} dr \quad \text{Escape veloc.}$$

$$t_2 = 1 + \frac{[x - \phi(\tau)] m'(\tau)}{(u+c)^2} - \frac{\phi'(\tau)}{u+c} \rightarrow 0$$

$$\frac{c(u+c) - (x - \phi)m'}{(u+c)^2} = 0$$

$$m' = \left(1 + \frac{pf''}{2c^2}\right) \phi''$$

for char to intersect @ $x = x_s$ $c(u+c) - (x_s - \phi) \left[1 + \frac{pf''}{2c^2}\right] \phi'' = 0$
 cond: $\underbrace{c(u+c) > 0 \quad x_s > \phi}$

$\Downarrow$
 $\phi'' > 0$ for intersection to occur

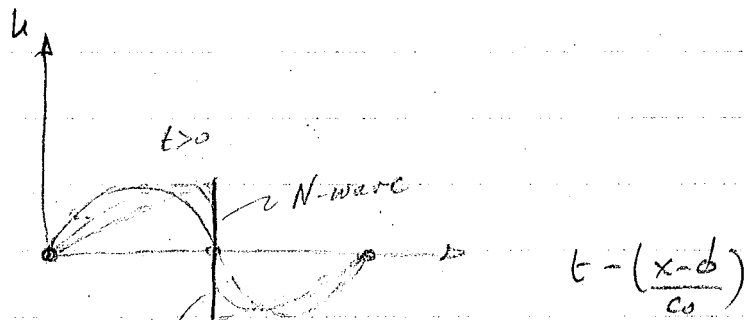
i.e. char intersect only after piston accelerates in positive direction
 $\Rightarrow$ if $\phi'' > 0$ Characteristics converge & will always intersect
 @ some x_s .

$$\left. \begin{aligned} u(p) &= u = \phi'(v) \\ t &= \tau + \frac{x - \phi(v)}{c(u+c)} \end{aligned} \right\}$$

$u=0$ $p=p_0$ is a characteristic $t = \tau_0 + \frac{x - \phi(\tau_0)}{c(p_0)}$

i.e. those characteristics carrying $u=0$
 have the linear speed $c(p_0)$, those carrying $u > 0$ have speed $u+c > c_0$
 Those carrying $u < 0$ have speed $u+c < c_0$

Suppose $u = x' = -\epsilon 2\pi \sin 2\pi t$
 $x = 6 \cos 2\pi t$

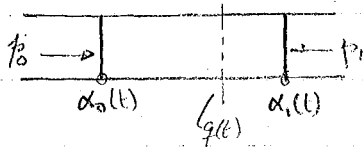


Shock conditions needed

which
how fast shock forms depends on $\phi''(0)$ not on $|u|$; that determines
how fast shock forms is $|u|$

N-wave asymptotic shape that a wave will take for large t .
magnitude of N-wave depends on distance between zeroes.

Shock relations



① Conservation of mass

$$\frac{d}{dt} \int_{\alpha_0}^{\alpha_1} \rho dx = 0$$

② Conservation of Mom

$$\frac{d}{dt} \int_{\alpha_0}^{\alpha_1} \rho u dx = p(\alpha_0, t) - p(\alpha_1, t)$$

③ Conservation of Energy

$$\frac{d}{dt} \int_{\alpha_0}^{\alpha_1} \rho \left(\frac{u^2}{2} + e \right) dx = p(\alpha_0)u(\alpha_0) - p(\alpha_1)u(\alpha_1)$$

e internal energy

④ non decrease in entropy $\Delta S \geq 0$

determines sign of discant.

$$\frac{d}{dt} \int_{\alpha_0}^{\alpha_1} \rho S dx \geq 0$$

$$\frac{dQ}{dt}, \quad Q = \int_{\alpha_0}^{\alpha_1} \bar{\Psi}(x) dx$$

$$\text{let } Q = \int_{\alpha_0}^q + \int_q^{\alpha_1}$$

$$\text{Def } \Psi_0 = \lim_{x \rightarrow q_-} \bar{\Psi} \quad \Psi_1 = \lim_{x \rightarrow q_+} \bar{\Psi}$$

$$\text{Define: speed of discont } \frac{dq}{dt} = U(t); \quad u_j' = \frac{d\alpha_j}{dt} \quad j=0,1$$

$$\begin{aligned} \frac{dQ}{dt} &= \bar{\Psi}_0 U - \bar{\Psi}(\alpha_0) u_0 + \int_{\alpha_0}^q \bar{\Psi}_0 dx + \bar{\Psi}(\alpha_1) u_1 - \bar{\Psi}_1 U + \int_q^{\alpha_1} \bar{\Psi}_1 dx \\ &= (\bar{\Psi}_0 - \bar{\Psi}_1) U + \underbrace{\bar{\Psi}(\alpha_1) u_1}_{\downarrow \bar{\Psi}_1} - \underbrace{\bar{\Psi}(\alpha_0) u_0}_{\downarrow \bar{\Psi}_0} + \int_{\alpha_0}^{\alpha_1} \bar{\Psi}_0 dx \end{aligned}$$

$$\text{Now let } \alpha_0 \rightarrow q^- \quad \alpha_1 \rightarrow q^+ \quad \text{always } \alpha_0 < q < \alpha_1$$

$$\begin{aligned} \frac{dQ}{dt} &= \bar{\Psi}_0 (U + u_0) - \bar{\Psi}_1 (U + u_1) \\ &= v_1 \bar{\Psi}_1 - v_0 \bar{\Psi}_0 \end{aligned} \quad \text{let } v_j = u_j' - U \quad \begin{array}{l} \text{relative} \\ \text{flow speed} \\ \text{on either side} \\ \text{of discont} \end{array}$$

$$Q = \rho \quad (1) \quad \rho_0 v_0 = \rho_1 v_1 = m \quad \text{mass flux across discont}$$

$$\rho u \quad (2) \quad \rho_1 u_1 v_1 - \rho_0 u_0 v_0 = p_0 - p_1, \text{ or } m u_0 + p_0 = m u_1 + p_1$$

$$\rho(u^2/2 + e) \quad (3) \quad v_1 p_1 (e_1 + \frac{1}{2} u_1^2) - p_0 (e_0 + \frac{1}{2} u_0^2) v_0 = p_0 u_0 - p_1 u_1$$

$$\text{define } e = \frac{1}{\rho} \text{ specific vol. } m(e_0 + \frac{1}{2} v_0^2 + p_0 v_0) = m(e_1 + \frac{1}{2} v_1^2 + p_1 v_1)$$

$$\rho S \quad (4) \quad \rho_1 v_1 S_1 \geq \rho_0 v_0 S_0 \quad \text{or} \quad m S_1 \geq m S_0$$

2 cases

- ① $m=0$ - no mass flow across disc. contact discontinuity
- ② $m \neq 0$ - gas flow across disc. called a shock

Case 1

since $m=0$ & $\rho_0' \neq 0 \Rightarrow v_1 = v_0 \Rightarrow \boxed{u_0 = u_1}$ velocity of
 $\Rightarrow \boxed{p_0 = p_1}$ pressure
 cont.

Case 2 $m \neq 0$ define Enthalpy $j = e + p\tau$

$$\textcircled{3} \rightarrow j_0 + \frac{1}{2} v_0^2 = j_1 + \frac{1}{2} v_1^2$$

Equation of state $e = e(p, \tau)$ 3 equations for seven quantities $u_0, u_1, \rho_0, \rho_1, p_0, p_1, U$

Must be given four of them to determine others 3.

e.g. $u_0, \rho_0, p_0 + \begin{cases} u_1 \\ \rho_1 \\ p_1 \end{cases}$ or U all fns of x, t Given $e = e(p, \tau)$ ③ is written as $(\tau_0 - \tau_1)(p_0 + p_1) = e(\tau_1, p_1) - e(\tau_0, p_0)$ Define $H(\tau, p) = e(\tau, p) - e(\tau_0, p_0) + (\tau - \tau_0)^2 (p + p_0)$

Hugoniot Function

State on other side of shock given by $H(\tau, p) = 0$ Curve $H(\tau, p) = 0$ in (τ, p) space is called the Hugoniot curve.For polytropic gas: $e = \frac{p\tau}{\gamma-1}$ define $\mu = \frac{\gamma-1}{\gamma+1}$

$$2\mu^2 H(\tau, p) = (\tau - \mu^2 \tau_0)p - (\tau_0 - \mu^2 \tau)p_0$$

 $H=0$

$$\frac{p_1}{p_0} = \frac{\tau_0 - \mu^2 \tau_1}{\tau_1 - \mu^2 \tau_0} = \frac{\rho_1 - \mu^2 \rho_0}{\rho_0 - \mu^2 \rho_1}$$

$$\frac{p_0}{p_1} = \frac{\rho_1}{\rho_0} = \frac{p_1 + \mu^2 p_0}{p_0 + \mu^2 p_1}$$

Since $\gamma p = \rho c^2$ $j = e + p c^2 = \frac{\gamma}{\gamma-1} p/\rho = \left(\frac{1-\mu^2}{2\mu^2}\right) c^2$

$$\mu^2 v_0^2 + (1-\mu^2) c_0^2 = \mu^2 v_1^2 + (1-\mu^2) c_1^2 = c_*^2$$

After much algebra can then show

$$v_0 v_1 = c_*^2 \quad \text{critical speed.}$$

$$\Rightarrow (1-\mu^2)(U-u_0)^2 - (u_1-u_0) = (1-\mu^2)c_0^2 \times (U-u_0)$$

gives U in terms of $u_1, u_0, c_0 = c_0(p_0)$

H.W. Consider Ahead of shock $u=0$ $p=p_0$ $\rho=\rho_0$
 Piston starts instantaneously from rest with $u_p > 0$ ^{const.}
 Find TJ & rest of unknowns behind shock & draw (t, x) diagram explaining the sol. look at case $u_p = u_p(t)$

H.W. look at non lin wave eq
 $w_{tt} = c^2(w_x) w_{xx}$

Change variables to put it in a system of 2 first order pde
 Find Characteristics & Riemann Invariant: suggest
 if $c = c(w_x, x)$

5-1-73

$$u_{,t} + \underline{A}(u, x) u_{,x} = \underline{B}(u, x)$$

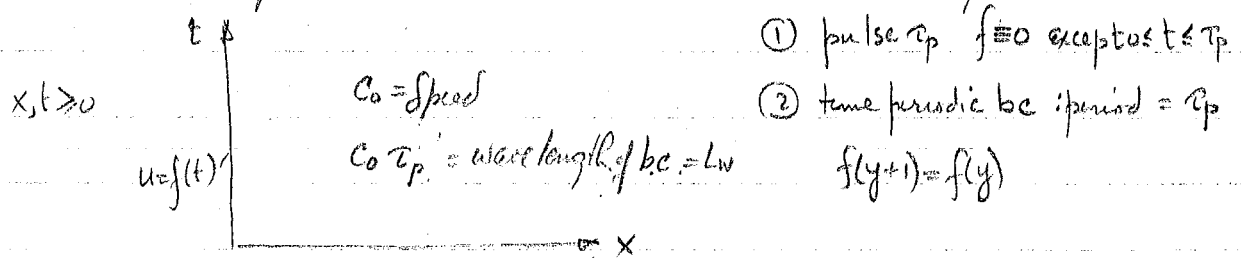
$\underline{A}$ due to stratification $\underline{B}$ relaxation or geometric effects

high frequency: if L_d = length scale defined by the dissipative mechanisms:

1. relaxation or rate dependence of medium
2. stratification (reflection due to change in media prop.)
3. geometric dissipation (length scale: radius of curvature)

1. distance of prop. $\Rightarrow$ wave length is reduced by $1/2$
2. $|A|/|A'|$
3. radius of curvature

Always talk about results w/ what occurs at bdy



$u(0, t) = f(t/c_p)$ small error since data depends only on small t interval
 $f(y+1) = f(y) \rightarrow \int_0^1 f' = 0$ to give small error.

Let $\frac{L_d}{L_w} = \omega$ high freq $\omega \gg 1 \xrightarrow{\text{AKA}}$ geometrical acoustics or optics

high freq $\Rightarrow$ small stratification or small relaxation or geometric effects. (almost plane wave)

Let $\bar{t} = t/L_d c_0^{-1}$ $L_d c_0^{-1}$ = dissipation time
 $u(0, t) = f(\bar{t} L_d c_0^{-1} / c_p) = f(\bar{t} \frac{L_d}{L_w}) = f(\bar{t} \omega)$

when $\begin{cases} \underline{A}(u, x) = \underline{A}(x) \\ \underline{B}(u, x) = \text{linear in } u \end{cases}$ linear geometrical acoustics Developed by Keller

We will look at.

- 1) Acceleration wave: discontinuity in $du/dt = \text{accel.}$ $r_p \rightarrow 0$ $\omega \rightarrow \infty$
 - a) exact
 - b) introduces noticeably the length scales.

- 2) linear geometrical acoustics

- a) expansion scheme for $\omega \gg 1$

3. N.L. geom. acoustics.

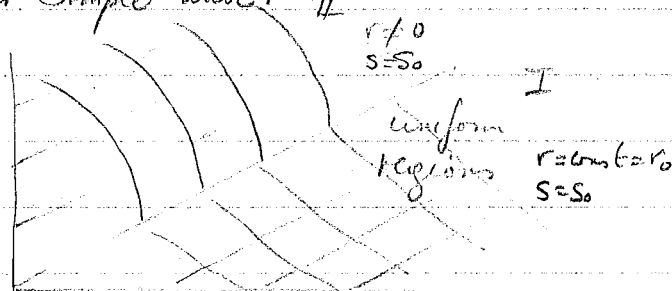
- a) ad hoc "rules" - Whitham '56 & '53

keep linear eq but adjust characteristics as non linear char.

- b) expansion schemes for $\omega \gg 1$ & $|u| \ll 1$

- c) Shock propagation

- 4) Modulated Simple wave. Π



Modulated $S = S_0(x)$ slow varying

r varies very fast as compared to S .

finite amplitude case.

I Accel Wave

$$u_t - c^2(v, x) v_x = \psi(u, x) \quad (*)$$

$$v_t - u_x = 0$$

$$t \geq 0 \quad x \geq 0$$

Acceleration front: a propagating surface $\alpha = \alpha(x, t) = \text{const}$ where the particle "acceleration" u_t changes discontinuously

@ x as the wave front passes while u remains continuous

Change variables $(x, t) \rightarrow (x, \alpha)$

Define $G(x, \alpha) = g(x, t)$

$G_{tx} = g_{tx} + T_{tx} g_t$ where $t = T(x, \alpha)$ is the arrival time of $\alpha = \text{const}$ at position x .

$$u_t + T_x c^2 v_t = c^2 v_x + \psi \quad \text{cont in } x$$

$$v_t + T_x u_t = U_x$$

denote $[f] = f_+ - f_-$

Characteristic Cond $\begin{pmatrix} 1 & c^2 T_x \\ T_x & 1 \end{pmatrix} \begin{pmatrix} [u_t] \\ [v_t] \end{pmatrix} = \underline{0}$ $\begin{pmatrix} [u_t] \\ [v_t] \end{pmatrix}$ $c = c(v, x)$ $c_0 = c(0, x)$ take jumps & evaluate everythg ahead of front.

Discontinuity ahead of front $u = v = 0$

$c_0(x)$ is measure of stratification ahead of wave.

$$T_{tx} c_0(x) = \pm 1 \Rightarrow T_{tx} = 1/c_0(x) \text{ for wave, to right}$$

$$\begin{pmatrix} 1 & c_0(x) \\ 1/c_0 & 1 \end{pmatrix} \begin{pmatrix} [u_t] \\ [v_t] \end{pmatrix} = \underline{0} \Rightarrow [u_t] = -c_0(x) [v_t] = \sigma(x)$$

strength of the accel front

Differentiate original eq (*) w.r.t. t & then transform to (x, α) cond.

$$u_{tt} - c^2(v, x) v_{xt} = 2cc_v v_x v_t + \psi_u u_t$$

$$v_{tt} - u_{xt} = 0$$

$$\text{let } \cdot \text{ be diff wrt } t \quad u_{xt} = U_x^\circ - T_{tx} u_{tt}$$

$$v_{tt} + T_{tx} u_{tt} = U_x^\circ$$

$$u_{tt} + c^2 T_{tx} v_{tt} = c^2 v_x^\circ + 2cc_v v_x v_t + \psi_u u_t$$

now take jumps & eval everythg at front.

$$\begin{pmatrix} T_{tx} & 1 \\ 1 & c^2 T_{tx} \end{pmatrix} \begin{pmatrix} [u_{tt}] \\ [v_{tt}] \end{pmatrix} = \begin{pmatrix} T[U_x^\circ] \\ c^2 [v_x^\circ] + 2cc_v [v_t v_x] + \psi_u [u_t] \end{pmatrix}$$

use $T_{tx} = 1/c$

$$c_0^2 [V_x^2] + 2c_0 c_v [V_t V_x] + \psi_u [u_t] - c_0 [U_x^2] = 0$$

$$[u_x^2] = \sigma_x(x) \quad [V_x^2] = \left(\frac{\sigma_x(x)}{-c_0} \right)_{,x}$$

$$[U_x^2] = [u_t]_x - \frac{1}{c_0} [u_t]_t$$

$$[u_t] = \sigma \quad [V_t V_x] = -\frac{1}{c_0} [V_t^2]$$

$$[g^2] = g_+^2 - g_-^2 = (g_+ - g_-)(-g_+ + g_- + 2g_+) = -[g]^2 + [g] 2g_+ \quad \text{if } g_+ = 0 \text{ then } [g^2] = -[g]$$

$$[V_t V_x] = \frac{1}{c_0} [V_t^2] = \frac{\sigma^2}{c_0^3}$$

Transport Eq. but jump varies w $\alpha = \text{const}$

$$-c_0^2 \left(\frac{\sigma}{c_0} \right)_{,x} + 2 \frac{c_v}{c_0^2} \sigma^2 + \psi_u \sigma - c_0 \sigma_x = 0$$

statif

dissip

$$c_v = c_v(0, x) \quad \psi_u = \psi_u(0, x)$$

$$-2c_0 \sigma_x + \sigma c_0' + 2 \frac{c_v(x)}{c_0^2} \sigma^2 + \psi_u \sigma = 0$$

$$\sigma_x + \Omega(x) \sigma - A(x) \sigma^2 = 0$$

relax. stat

$$\Omega(x) = \frac{c_0' + \psi_u}{-2c_0} = L_r' + L_s' \quad L_r = -\frac{2c_0}{\psi_u} \quad L_s = -\frac{2c_0}{c_0'}$$

$$A(x) = -\frac{c_v}{c_0^3} \quad \text{only non lin contrib}$$

For 3d case $L_c = 1 - 2\Omega_0(a, b)X + K_0(a, b)X^2$ corresponds to distance along charac. $\Omega_0(a, b) - K_0(a, b)X$

where $\underline{X} = \underline{X}(a, b)$ is initial surface & Ω_0, K_0 are mean & Gaussian curvatures.

$\Omega_0 = K_0 = 0$ corresponds to a plane surface.

$\sigma_x + \Omega(x)\sigma - \Lambda(x)\sigma^2 = 0$ Riccati Eq. in $\frac{1}{\sigma}$
 rewrite as $-\left(\frac{1}{\sigma}\right)_{,x} + \Omega(x)\left(\frac{1}{\sigma}\right) - \Lambda(x) = 0$ subject to $\sigma = \sigma(0)$ @ $x=0$

$$\sigma(x) = \exp\left(-\int_0^x \Omega(r) dr\right) \sigma(0)$$

$$\left[1 - \sigma(0) \int_0^x \Lambda(r) \exp\left(-\int_0^r \Omega(s) ds\right) dr\right]$$

linear sol $\Lambda \equiv 0$ $\sigma_L(x) = \sigma(0) \exp\left(-\int_0^x \Omega(r) dr\right)$

Hw. 1. For $0 \leq x \leq y$ under what conditions is $\sigma_L(x)$ a good approx to $\sigma(x)$

2. $A_t + (Au)_x = 0$ Go through accel front anal
 $A(u + uu_x) + px = -\gamma u$ propagating into $A = A_0(x)$
 $p = K(A, x)$ $u=0$

Flow in a flexible tube $u = \text{velocity}$, $A = \text{cross-sectional area}$.

$p = \text{pressure}$. Should get Riccati Eq.

References T.Y. Thomas "Plastic Flow & Fracture" 1961

Varley & Cumberbatch (65) Journal of Inst of Math & its Appl

May 8, 1973

No final HWS will be final.

$$u_t + A(u, x) u_x = B(u, x)$$

$$[u_x] = \Omega(x) \sigma(x)$$

Geometrical acoustics $\equiv$ high frequency — assoc with BE is large wrt

natural freq of material $\Rightarrow$ wavelength $\ll$ dissipative length $\approx \Omega^{-1}(x)$

High freq is local condition we will use it as a global condition

1) Pulse < time which we prescribe by data > $0 \leq t \leq \tau_p$

2) time periodic bdy data. $\tau_p = \text{period}$

non dim eq non dim x w.r.t wavelength or dissipative length.

dissipative length determined by eq & not bc will enter only in bc.

wavelength " " b.d "not eq" " " " in eq.

Example $u(0, \bar{t}) = u_0 f(\bar{t}/\tau_p)$ normalize let $t = \bar{t}/\tau_d$

$u(0, \tau_d t) = u_0 f\left(\frac{\tau_d}{\tau_p} t\right)$ let $\omega = \tau_d/\tau_p \gg 1 \Rightarrow \tau_d \gg \tau_p$

$$u(0, \omega t \tau_p) = u_0 f(\omega t)$$

$$\tau_d \sim \frac{1}{|B|} \quad \tau_d \sim \frac{1}{|A_{,x}|}$$

Linear Geometrical Acoustics linearize eq $A(u, x) = A_0(x) + A_n(x)u + \dots$

$$\underline{u}_t + \underline{A}_0(x) \underline{u}_x = \underline{B}_0(x) \underline{u}$$

$$A_0(x) = A_0(x)$$

non dim w.r.t dissipative length

$$B_0(x) = B_0(x)$$

$$\underline{B}_0(x) = 0 \text{ in eq.}$$

Char condition $\det [c(x)I - A] = 0$

$$\frac{dt}{dx} = \frac{1}{C_r(x)} \text{ on } C_r \quad r=1, \dots, n \text{ where } C_r \text{ is an eigenvector of } A_0.$$

Consider only $C = C_0(x)$ $\alpha = t - \int_0^x \frac{ds}{C_0(s)}$

Choose $\alpha \Rightarrow \alpha = t$ on $x=0$.

$\alpha = \text{slow characteristic variable.}$

boundary condition is written in terms of a fast variable $\beta = \omega \alpha = \omega(t - \int_0^x \frac{ds}{C_0(s)})$

on $x=0$ $\beta = \omega t \Rightarrow u = f(\beta)$

choose β, x as new variables $(x, t) \rightarrow (x, \beta)$ $\beta = \beta(x, t)$

Change to new coords & use $\omega \gg 1$

$$\tilde{u}(x, t) = \tilde{U}(x, \beta)$$

$$\tilde{u}_t = \tilde{U}_\beta \omega \quad \tilde{U}_x - \frac{\omega}{c_0} \tilde{U}_\beta = \tilde{u}_x$$

$$\omega(\tilde{U}_\beta + A_0 \tilde{U}_x) - \frac{\omega}{c_0} A_0 \tilde{U}_\beta = B_0 u$$

$$(c_0 I - A_0) \tilde{U}_\beta = \frac{c_0}{\omega} [B_0 \tilde{U} - A_0 \tilde{U}_x]$$

Geometrical Acoustics Expansion: progress wave valid until freq dispersion is not negligible, i.e. $x \ll \omega$

$$\tilde{u}(x, t) = \tilde{U}(x, \beta, \omega) = \sum_{n=0}^{\infty} \omega^{-n} h_n(\beta) \tilde{U}^{(n)}(x)$$

h_n are phase fns.; $\tilde{U}^{(n)}$ amplitude fns.; β is the phase variable

$$\beta = \phi(x, t) \quad U_1(0, \beta) = f(\beta) \Rightarrow h_0(\beta) = f(\beta) \quad U_1^{(0)} = 1 \text{ on } x \geq 0$$

1st comp of U

$$h'_{n+1}(\beta) = h_n(\beta) \quad f \text{ is prescribed signal fn.}$$

1) pulse: $f \equiv 0$ except for $0 < \beta < 1$

2) semi-periodic: $f(\beta) = f(\beta+1)$ measure f s.t. $\int_0^1 f(s) ds = 0$ by choice of reference state.

1) pulse
$$h_n(\beta) = \frac{1}{(n-1)!} \int_0^\beta s^{n-1} f(\beta-s) ds \quad (h_n(0) = 0)$$

error will be small due to $\eta_p \ll 1$

2) periodic ($\int_0^1 h_n(s) ds = 0$) error will have zero mean

$$h_n(\beta) = -\frac{1}{n!} \int_0^1 B_n(s) f(\beta-s) ds$$

$B_n(s)$ = n th degree Bernoulli poly B_n satisfies $B_n' = n B_{n-1}$

② $B_n(1) = B_n(0) \quad (n \geq 2) \quad B_0(s) \equiv 1, \quad B_1(1) = -B_1(0) = 1/2$

define an iteration scheme.

$$(c_0 I - A_0) \tilde{U}^{(n+1)} = c_0 [B_0 \tilde{U}^{(n)} - A_0 \tilde{U}_x^{(n)}] \text{ with } \tilde{U}^{(0)}(x) = 0$$

Zeroth order

$$(c_0 I - A_0) \tilde{U}^{(0)}(x) = 0$$

$$\tilde{U}^{(0)}(x) = \tilde{r}(x) \tilde{r}_L(x) \quad \tilde{r}(x) \text{ is right EV of } A_0$$

corresponding to $c = c_0(x)$ where $\tilde{r}_L(x) \equiv 1 \Rightarrow$ choose $\tilde{r} \geq 0$, $\tilde{r}_L(x)$ measures 1st component variation in U .

Compatibility Condition $\Rightarrow \underline{l}(x) [\underline{B}_0 \underline{U}'' - \underline{A}_0 \underline{U}_x''] = 0$
 where $\underline{l}$ is any left EV of $\underline{A}_0$. Known: transport Equation

$$\underline{U}'' = \underline{r}(x) \underline{\sigma}_L(x)$$

$$\underline{l} (\underline{B}_0 \underline{r} \underline{\sigma}_L - \underline{A}_0 \{ \underline{r}' \underline{\sigma}_L + \underline{r} \underline{\sigma}_L' \}) = 0$$

$$\underline{l} (c_0 \underline{I} - \underline{A}) \underline{r} = 0 \Rightarrow c_0 \underline{l} \underline{r} = (\underline{A} \underline{r})$$

where $\underline{r}$ solves:

$$\underline{\sigma}_L' + \underline{\Omega} \underline{\sigma}_L = 0$$

$$\underline{\Omega} = \underline{L} \underline{F}' + \underline{L}' \underline{S}$$

$$\underline{L} \underline{r} = - \frac{c_0 \underline{l} \underline{r}}{\underline{l} \underline{B}_0 \underline{l}} \quad \underline{L} \underline{s} = \frac{\underline{l} \cdot \underline{r}}{\underline{l} \cdot \underline{r}'}$$

$$\underline{U}(x, \beta) = \int(\beta) \underline{r}(x) \exp(-\int_0^x \underline{\Omega}(s) ds) \quad \underline{\sigma}_L = \int(\beta) \exp(-\int_0^x \underline{\Omega}(s) ds)$$

for general n

$$(\underline{I} - \underline{A}_0 / c_0) \underline{U}^{(n+1)} = \underline{B}_0 \underline{U}^{(n)} - \underline{A}_0 \underline{U}_x^{(n)} \quad \text{with } \underline{U}^{(-1)} = 0$$

(m-1) indep eq

mth eq is

$$\underline{l} \underline{A}_0 \underline{U}_x^{(n+1)} - \underline{l} \underline{B}_0 \underline{U}^{(n+1)} = 0$$

forms eq for m unknowns $\underline{U}^{(n+1)}$ in terms of $\underline{U}^{(n)}$

Example

$$u_t - c^2 v_x = \psi \quad c(v)$$

$$\text{with } c_x = 0$$

$$c(v, x) = c(0, x) + c_v(0, x) v + c_{xx}(0, x) v^2$$

$$v_t - u_x = 0$$

linearized
also let $(v, u) = (\bar{v}, \bar{u})$

$$\bar{u}_t - c^2 \bar{v}_x = \psi_u \bar{u}$$

$$\bar{v}_t - \bar{u}_x = 0$$

All coeff are const $c, \psi_u = \text{const}$

Normalize wrt relax length $-\frac{2c}{\psi_u} = L_r$

$$L_s = \infty$$

non dim (x, t) wrt $(L_r \& c) \quad \psi_u \Rightarrow c=1 \quad \psi_u = -2$

define new variable

$$u = \bar{u} / u_0$$

$$v = \bar{v} / u_0 c^{-1}$$

$$t = \bar{t} / c^{-1} L_r$$

$$x = \bar{x} / L_r$$

$$\left. \begin{aligned} u_t \frac{u_0}{c^2 L_r} - c^2 v_x \frac{u_0}{c L_r} &= \psi_u u_0 u \\ v_t - u_x &= 0 \end{aligned} \right\} \text{normalized}$$

$$\text{or } v_t - u_x = 0$$

$$u_t - v_x = \left(\frac{\psi_u L_r}{c} \right) u^{-2}$$

$$A_0^{u,v} = \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} u_x \\ v_x \end{pmatrix} B_0^u = \begin{pmatrix} -2 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} \quad \underline{r} = \underline{\tilde{r}} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\sigma_L' + \Omega \sigma_L = 0 \quad \Omega = \frac{1}{L_r} = \frac{-l \cdot r}{\tilde{l} \cdot B_0 \underline{r}} = \frac{-2}{-2} = 1$$

$$\sigma_L' + \sigma_L = 0 \quad \boxed{\sigma_L = e^{-x}}$$

$$\underline{u} = \begin{pmatrix} u \\ v \end{pmatrix} = f(\beta) e^{-x} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

or

$$\begin{aligned} u_t - v_x &= -2u \\ v_t - u_x &= 0 \end{aligned} \quad (x, t) \rightarrow (\beta, x) \quad \beta = \omega(t-x)$$

$$\begin{aligned} U_\beta + V_\beta &= \omega^{-1} (V_x - 2U) \\ V_\beta + U_\beta &= \omega^{-1} (U_x) \end{aligned}$$

using the eqs for next order

$$U^{(n+1)} + V^{(n+1)} = (V_x^{(n)} - 2U^{(n)}) \quad (1)$$

$$V^{(n+1)} + U^{(n+1)} = U_x^{(n)} \quad (2)$$

Compatibility, $V_x^{(n)} - 2U^{(n)} = U_x^{(n)}$ use $n \rightarrow n+1$ (3)

use $2 \neq 3$

$$U^{(0)} = -V^{(0)} \quad U_x^{(0)} = -V_x^{(0)} \quad \therefore -2U^{(0)} = U_x^{(0)} - V_x^{(0)} = 2U_x^{(0)} \text{ from (3)}$$

fn 1 with $U^{(n)} = 0$ $V^{(-1)} = 0 \Rightarrow V_x = 0$

Zeroth order Sol

$$V^{(0)} = -U^{(0)}$$

$$U_x^{(0)} + U^{(0)} = 0$$

$$V^{(0)} = -e^{-x}$$

$$\Rightarrow U^{(0)} = e^{-x}$$

diff with x

$$\begin{cases} V^{(1)} + U^{(1)} = U_x^{(0)} = -e^{-x} \\ V_x^{(1)} - 2U^{(1)} = U_x^{(1)} \\ V_x^{(1)} + U_x^{(1)} = e^{-x} \end{cases} \text{ subtract}$$

$$U_x^{(1)} + 2U^{(1)} = e^{-x}$$

$$U^{(1)} = \frac{x e^{-x}}{2}$$

with $U^{(1)}(0) = 0$ $\frac{1}{2}$ throws out homog term.

$$V^{(1)} = -U^{(1)} - e^{-x} = -e^{-x} \left(\frac{x}{2} + 1 \right)$$

$$\underline{u} = \begin{pmatrix} U \\ V \end{pmatrix} = f(\beta) \underline{r} e^{-x} + \omega^{-1} h_1(\beta) \left\{ \frac{x}{2} \underline{r} + r^{(1)} \right\} e^{-x}$$

$$\underline{r} = \begin{pmatrix} 1 \\ -1 \end{pmatrix} \quad r^{(1)} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

dispersive term

n th term will have a term $\propto (x \omega^{-1})^n$

when $y = x \omega^{-1}$

$$e^x \underline{U} = \sum_0^\infty g_n(\beta) y^n$$

error of expansion for exp up to ω^{-n} is $\omega^{-(n+1)}$

range of validity $(n+1)$ th term $\sim n$ th term. because of growth with x .

since linear separable.

HW Do linear geom acoustics for

$$u_t = c^2(x) v_x = 0$$

$$v_t - u_x = 0$$

calculate first two terms.

$$L_r = \infty$$

$$L_s = \frac{lr}{\partial r'}$$

subject to $u(0, t) = f(\omega t)$ where $B = \omega t - \int^x ds$

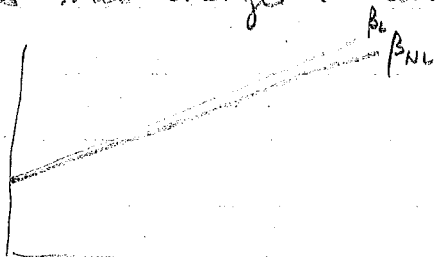
5-15-73

if rth comp. of U is excited right $\bar{E}V$ $\underline{r}(x)$ must have a 1 in the r^{th} row we have done work for 1 component going in 1 direction only!

for linear case sol is variable separable now characteristics depend on sol for non linear case.

Whitham 53 or 56 ^{Pared} Com of Δ applied Math J Fluid Mech.

Whitham's Rule $u = f(\beta)E(x)$ linear sol $\beta = t - \int_0^x \frac{ds}{c}$ linear char.
non zero $\beta_{NL} \stackrel{=}{=} \beta_L$ keeps variation of u on a characteristic to be same but change variation of characteristic.



$$t_x = \frac{1}{c(u,x)} \quad \text{Expand for small } u = \frac{1}{c(0,x)} - \frac{c_u(0,x)u}{c^2(0,x)} + \dots$$

Whitham's
Rule

put for $u = f(\beta)E(x)$ with $|u| \ll 1$

$$\beta = t - \int_0^x \frac{ds}{c(0,s)} - f(\beta) \int_0^x \frac{c_u(0,s)E(s)ds}{c^2(0,s)}$$

for shock formation $t_\beta = 0$

$$t_\beta = 1 + f'(\beta) \int_0^x \frac{c_u}{c^2} E ds = 0$$

if $\exists x_s \ni t_\beta = 0$ shock will form.

another dependent variable is time of arrival of wave @ a pt.

for linear acoustics time of arrival is known since that is known
use same technique as linear

$$u(x, t) = U(x, \beta) \quad \beta = \beta_{\text{arr}}$$

$$t_x / \beta = c(u, x)$$

for high freq $\|U_x\|_\beta \ll \|u_x\|_t \sim \|u_t\|_x$

motivation is same as linear (iteration procedure) and an extra
eq on arrival time,

$$u_t + A(u, x) u_x = B(u, x)$$

Non dim w/o $|\Omega|^{-1} (\underline{I} - T_x A(u, x)) u_t = \underline{B} - A \underline{U}_x$ $\neq \underline{t} = T(x, \beta)$
arrival time at x of wavelet $\beta = \text{const.}$

with fact that $\underline{U}_x = \underline{u}_x + T_x \underline{u}_t$ $T_x = T_x / \beta$

subject to $u_1 = f(\omega t)$ $\omega = \frac{c' L_d}{L_p} \gg 1$

because choose on $x=0$ $\beta = \omega t \therefore u_1 = f(\beta)$ β is measure of fast variation
" " " " of slow stratification

$\Rightarrow T_\beta = O(1/\omega)$ since $\beta = \omega t$ $i = \omega t_\beta = \omega T_\beta \Rightarrow T_\beta \sim O(1/\omega)$
 $\underline{u} = \underline{U}(x, \beta)$ $U_1(0, \beta) = f(\beta)$ $\& \text{ assume } U(x, 0) = 0$
 $\underline{t} = T(x, \beta)$ $T(0, \beta) = \beta/\omega$ $f(0) = 0$

Convert $(\underline{I} - T_x A(u, x)) u_t = \underline{B} - A \underline{U}_x$ into β coord

$$u_t = U_\beta \beta_t = U_\beta \omega = U_\beta \frac{1}{T_\beta}$$

$$\therefore (I - T_x A(u, x)) U_\beta = (B - A U_x) T_\beta$$

$$T_x \text{ is } \frac{1}{\text{EV of } A} = \frac{1}{c(u, x)}$$

$$\therefore (I - \frac{A}{c}) U_\beta = (B - A U_x) T_\beta$$

$$\text{or } (Ic - A) = 0$$

Small Amplitude - nonlinear solution i.e. $|u| \ll 1$

$\Rightarrow$ expand c, A, B in powers of u

$$u = \tilde{U} = \omega^{-1} \sum_{n=0}^{\infty} \omega^{-n} \tilde{U}^{(n)}(x, \beta)$$

where $\tilde{U}$ is small $|\tilde{U}| \ll 1$

$$T = \int_0^x \frac{ds}{c(s, x)} = \omega^{-1} \sum_{n=0}^{\infty} \omega^{-n} T_n(x, \beta)$$

Compatibility $k(u, x) [B(u, x) - A(u, x) U_x] = 0$ transfer eq for bilinear amplitude

put Expressions into governing eq

$$\text{order } \frac{1}{\omega} \text{ eq: } \left[I - \frac{A(0, x)}{c(0, x)} \right] \tilde{U}_{\beta}^{(0)} = 0 \Rightarrow \tilde{U}_{\beta}^{(0)}(x, \beta) = \tilde{r}^{(0)}(x) g'(\beta)$$

$\tilde{r}^{(0)}(x)$ is right EV for $A(0, x)$ & $c(0, x)$

$$\therefore U^{(0)}(x, \beta) = \tilde{r}^{(0)}(x) g(\beta) + \tilde{v}(x)$$

$$\text{use } \tilde{r}^{(0)} \text{ for variation of } U, \quad \text{scalar}$$

$$= \tilde{r}^{(0)}(x) \sigma(x) f(\beta) + \tilde{v}(x)$$

where $\tilde{r}^{(0)}(x) \equiv 1 \Rightarrow \sigma$ measures variation of u with x
 $\sigma(0) = 1$ to satisfy to BC

to satisfy initial cond $\tilde{v}(x) \equiv 0$

$$\text{i.e. } \sigma(x) = \tilde{r}_1^{(0)}(x)$$

$$T_{,x} = \frac{1}{c(0,x)} - \frac{c_u u}{c^2(0,x)} + o(u^2)$$

$$\cancel{\frac{1}{c(0,x)}} + \omega^{-1} T_{0,x} + o(\frac{1}{\omega}) = \cancel{\frac{1}{c(0,x)}} - \frac{c_u(0,x)}{c^2(0,x)} \bar{r}^{(0)}(x) \sigma(x) f(\beta) \omega^{-1}$$

$$T_0(\beta, x) = -f(\beta) \int_0^x \frac{c_u(0,s) \bar{r}^{(0)}(s) \sigma(s)}{c^2(0,s)} ds + \text{const}$$

$$\text{for bc \& expansion of } T \Rightarrow T_0(0, \beta) = \beta \quad T_n(0, \beta) = 0 \quad n > 0$$

$$\therefore \text{const} = \beta$$

to find σ get to transport from computability
 zeroth order put in expansion for U $B(0, x) = 0$ since you prefer to do regular state

$$\bar{L}^{(0)}(x) [B_u(0, x) \bar{U}^{(0)} - A(0, x) \bar{U}_x^{(0)}] = 0$$

linear transport eq start process

$$\bar{L}(\bar{B}_u r \sigma - \bar{L} A(r \sigma' + (r' \sigma))) = 0$$

$$\Omega = \frac{\bar{L} B_u r - \bar{L} A r'}{-\bar{L} A r}$$

relax process we get $\sigma' + \Omega \sigma = 0$ $\Omega = \bar{L} r' + \bar{L} g'$

$$\sigma = \sigma(0) \exp\left(-\int_0^x \Omega(s) ds\right) \quad U(0) = 1 \text{ previously}$$

Zeroth order sol

$$\bar{U}^{(0)}(x, \beta) = \bar{r}^{(0)}(x) f(\beta) \exp\left(-\int_0^x \Omega(s) ds\right)$$

$$\text{where } T = \int_0^x \frac{ds}{c(0,s)} = \frac{\beta}{\omega} - \frac{f(\beta)}{\omega} \int_0^x \frac{c_u(0,s)}{c^2(0,s)} \bar{r}^{(0)}(s) \exp\left(-\int_0^s \Omega(r) dr\right) ds$$

this is Whitham's rule. Note: Soln is implicit

Ex: $B = -2u$ $\sigma = e^{-x}$ $\bar{r} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ for linear case

$\tilde{U}^{(0)} = \begin{pmatrix} 1 \\ -1 \end{pmatrix} f(\beta) e^{-x}$ with $c=1$

now let $c = 1 + \beta v$ $k = c_v$

$c(0, x) = 1$ $c = c(v)$ only $\therefore c_v = \text{const}$

$\therefore$ secondary $\Rightarrow$

$$T-x = \frac{\beta}{\omega} - \frac{f(\beta)}{\omega} \int_0^x \frac{c_v \cdot \bar{r}^{(0)}}{1} e^{-s} ds$$

$$c_u \cdot \bar{r} = \begin{pmatrix} 0 \\ c_v \end{pmatrix}^T \begin{pmatrix} 1 \\ -1 \end{pmatrix} = -c_v$$

$$T-x = \frac{\beta}{\omega} + \frac{f(\beta)}{\omega} \int_0^x c_v e^{-s} ds$$

$$= \frac{\beta}{\omega} + \frac{f(\beta) c_v}{\omega} [1 - e^{-x}]$$

$$= \omega^{-1} \{ \beta + f(\beta) c_v (1 - e^{-x}) \}$$

Shock form when $T\beta = 0$

$$\therefore T\beta = \omega^{-1} \{ 1 + f' c_v (1 - e^{-x}) \} = 0$$

or when $f' = \frac{-1}{c_v(1-e^{-x})}$ for small x $1 - e^{-x} \sim x$

Simple wave $B=0$ $T\beta = \omega^{-1} (1 + f' c_v x) \Rightarrow f' c_v < 0$ for

some β then a shock forms.

if in nl case $-f' c_v < 1$ no shock form

if f is velocity & if $-f'(v)$ accel on boundary $\leq \frac{1}{c_v} = A_c$ is a critical accel.

must put an accel $> A_c$ to have shock form.

Ans. do second order sol for this problem.

$$\left\{ U^{(0)} = a' \begin{pmatrix} 1 \\ -1 \end{pmatrix} f(\beta) e^{-x} + \mu \int_0^x f(s) ds \right\}$$

$\text{with } c = \omega^{-2} c_v f^2(\beta) X(-)$

$$\text{System } \begin{cases} u_t - c^2(v) v_x = -2u - B u^2 \\ v_t - u_x = 0 \end{cases}$$

$$c(v) = 1 + c_v v + c_w v^2 + \dots$$

Subject to $u(0, t) = f(\omega t) = f(\beta)$

$$T(0, \beta) = \beta/\omega \quad \omega \gg 1$$

$$\tilde{U} = \omega^{-1} \sum y^{(n)}(x, \beta) \omega^{-n} \quad U = \begin{pmatrix} u \\ v \end{pmatrix}$$

get U^0, U^1
 T^0, T^1

$$T-x = \omega^{-1} \sum \omega^{-n} T_n$$

will $u(x, 0) = 0 \quad f(\omega) = 0$

Tidal flow
App. Varley, Venkataiah, Gumber, batch J. Fluid Mech 71
Advection pulse
Varley & Gumber, batch J. Fluid Mech 70

1. from prob. $f(\varphi) = A \cos \varphi$

$$\alpha_0 = \frac{1}{\pi} \int_{-\pi}^{\pi} A \cos \varphi d\varphi = \frac{A}{\pi} \sin \varphi \Big|_{-\pi}^{\pi} = 0$$

$$\alpha_1 = \frac{A}{\pi} \int_{-\pi}^{\pi} \cos^2 \varphi d\varphi = \frac{A}{2\pi} \int_{-\pi}^{\pi} (1 + \cos 2\varphi) d\varphi$$

$$\alpha_1 = \frac{A}{2\pi} \left[\varphi + \frac{\sin 2\varphi}{2} \right]_{-\pi}^{\pi} = \frac{A}{2\pi} [\pi + 0 + \pi + 0] = A$$

$$\therefore \text{solution is } u(\rho, \varphi) = \sum_{n=1}^{\infty}$$

$$\alpha_n = \frac{A}{\pi} \int_{-\pi}^{\pi} \cos \varphi \cos n\varphi d\varphi$$

since f is even $\beta_n = 0$

$$\frac{A}{2\pi} \int_{-\pi}^{\pi} \{ \cos(n+1)\varphi + \cos(n-1)\varphi \} d\varphi$$

$$\frac{A}{2\pi} \left[\frac{\sin(n+1)\varphi}{n+1} + \frac{\sin(n-1)\varphi}{n-1} \right]_{-\pi}^{\pi} = 0$$

$$A_n \quad n > 1 \neq 0$$

$$\therefore u(\rho, \varphi) = \frac{\rho}{a} A \cos \varphi$$

$$f(\varphi) = A + B \sin \varphi \quad \text{this is an odd function} \therefore \alpha_n = 0$$

$$\alpha_0 = \frac{1}{\pi} \int_{-\pi}^{\pi} (A + B \sin \varphi) d\varphi = \frac{1}{\pi} [A\varphi - B \cos \varphi]_{-\pi}^{\pi} = \frac{1}{\pi} [A\pi + B + A\pi - B]$$

$$= 2A$$

$$\alpha_n = \frac{1}{\pi} \int_{-\pi}^{\pi} A \cos n\varphi d\varphi + \frac{B}{2\pi} \int_{-\pi}^{\pi} \{ \sin(1+n)\varphi + \sin(1-n)\varphi \} d\varphi$$

$$= 0$$

or

$$\beta_1 = B$$

$$\beta_n \quad n > 1 \neq 0$$

$$\therefore \text{if } n \text{ even } \frac{-1}{1+n} + \frac{-1}{1-n} - \frac{(-1)}{1+n} - \frac{(-1)}{1-n}$$

$$\text{odd } \frac{1}{1+n} + \frac{1}{1-n} - \frac{1}{1+n} - \frac{1}{1-n}$$

$$\therefore u(\rho, \varphi) = A + \frac{\rho}{a} B \sin \varphi$$

(2)

$$\Delta u = u_{xx} + u_{yy} = 0$$

$$X''Y + Y''X = 0$$

$$X'' + \lambda^2 X = 0$$

$$\frac{X''}{X} = -\frac{Y''}{Y} = -\lambda^2 \quad \lambda > 0$$

$$Y'' - \lambda^2 Y = 0$$

$$X = A_1 \sin \lambda x + B_1 \cos \lambda x$$

$$Y = C_1 e^{\lambda y} + D_1 e^{-\lambda y} = C_1 \sinh \lambda y + D_1 \cosh \lambda y$$

$$X(x)Y(y) = A_1 C_1 \sin \lambda x e^{\lambda y} + B_1 C_1 e^{\lambda y} \cos \lambda x + D_1 A_1 \sin \lambda x e^{-\lambda y}$$

$$+ B_1 D_1 e^{-\lambda y} \cos \lambda x$$

$$f_1(y) = B_1 C_1 e^{\lambda y} + B_1 D_1 e^{-\lambda y}$$

$$f_2(y) =$$

$$u(0, y) = f_1(y) \quad u(x, 0) = f_2(x) \quad u(a, y) = 0 \quad u(x, b) = 0$$

$$f_1(y) = C_1 e^{\lambda y} + D_1 e^{-\lambda y} = C_1 \sinh \lambda y + D_1 \cosh \lambda y$$

$$f_2(x) = A_1 \sin \lambda x + B_1 \cos \lambda x$$

$$0 = A_1 \sin \lambda a + B_1 \cos \lambda a$$

$$0 = C_1 e^{\lambda b} + D_1 e^{-\lambda b} = C_1 \sinh \lambda b + D_1 \cosh \lambda b$$

$$\begin{bmatrix} \sinh \lambda y & \cosh \lambda y \\ \sinh \lambda b & \cosh \lambda b \end{bmatrix} \begin{pmatrix} C_1 \\ D_1 \end{pmatrix} = \begin{pmatrix} f_1(y) \\ 0 \end{pmatrix}$$

$$C_1 = \frac{f_1(y) \cosh \lambda b}{\sinh \lambda y \cosh \lambda b - \cosh \lambda y \sinh \lambda b}$$

$$D_1 = \frac{f_1(y) \sinh \lambda b}{\sinh \lambda y \cosh \lambda b - \cosh \lambda y \sinh \lambda b}$$

$$C_1 = \frac{f_1(y) \cosh \lambda b}{\sinh \lambda (y-b)}$$

$$D_1 = \frac{-f_1(y) \sinh \lambda b}{\sinh \lambda (y-b)}$$

$$Y = f_1(y) \left[\cosh \lambda b \sinh \lambda y - \sinh \lambda b \cosh \lambda y \right] \frac{\sinh \lambda (y-b)}{\sinh \lambda (y-b)} + \left[\sinh \lambda y \cosh \lambda b - \cosh \lambda y \sinh \lambda b \right] \frac{\sinh \lambda (y-b)}{\sinh \lambda (y-b)}$$

where b_n are defined as $b_n = \frac{2}{b} \int_0^b f_1(y) \sin \frac{n\pi y}{b} dy$

$$U(x, y) = u(x, y) + v(x, y) = \sum_{n=1}^{\infty} \left\{ a_n \frac{\sinh \frac{n\pi}{a}(b-y)}{\sinh \frac{n\pi}{a}b} \sin \frac{n\pi x}{a} + b_n \frac{\sinh \frac{n\pi}{b}(a-x)}{\sinh \frac{n\pi}{b}a} \sin \frac{n\pi y}{b} \right\}$$

where $a_n = \frac{2}{a} \int_0^a f_2(x) \sin \frac{n\pi x}{a} dx$ $b_n = \frac{2}{b} \int_0^b f_1(y) \sin \frac{n\pi y}{b} dy$

$$U(0, y) = u(0, y) + v(0, y) = \sum_{n=1}^{\infty} b_n \sin \frac{n\pi y}{b} = f_1(y)$$

$$U(a, y) = u(a, y) + v(a, y) = 0$$

$$U(x, 0) = u(x, 0) + v(x, 0) = \sum a_n \sin \frac{n\pi x}{a} = f_2(x)$$

$$U(x, b) = u(x, b) + v(x, b) = 0$$

$$\Delta U = 0 \quad \Delta(u+v) = \Delta u + \Delta v = 0$$

to show convergence of series. if $|f_2(x)|$ and $|f_1(y)|$ are bounded by M

$$\text{then } |a_n| \leq \frac{2}{a} M \int_0^a \left| \sin \frac{n\pi x}{a} \right| dx \leq 2M \quad |b_m| \leq \frac{2}{b} M \int_0^b \left| \sin \frac{m\pi y}{b} \right| dy \leq 2M$$

$$U(x, y) \leq 2M \sum \left\{ \sinh \frac{n\pi x}{a} + \sinh \frac{n\pi y}{b} \right\} \leq 2M \sum \left\{ \frac{\sinh \frac{n\pi}{a}b}{\sinh \frac{n\pi}{a}b} + \frac{\sinh \frac{n\pi}{b}a}{\sinh \frac{n\pi}{b}a} \right\}$$

$$u_n = A_n \left[\frac{\sinh \frac{n\pi}{a} (b-y)}{\sinh \frac{n\pi b}{a}} \right] \sin \frac{n\pi x}{a}$$

$$\text{at } x=0 \quad u=0$$

$$\text{at } x=a \quad u=0$$

$$\text{at } y=0 \quad \sin \frac{n\pi x}{a}$$

$$\text{at } y=b \quad u=0$$

$$u = \sum u_n$$

$$u(x,0) = \sum u_n(x,0) = f_2(x) = \sum A_n \sin \frac{n\pi x}{a}$$

$$f_2(x) \sin \frac{n\pi x}{a} = \sum A_n \sin \frac{n\pi x}{a} \sin \frac{n\pi x}{a}$$

$$\int_0^a f_2(x) \sin \frac{n\pi x}{a} dx = A_n \int_0^a \sin^2 \frac{n\pi x}{a} dx$$

$$A_n = \frac{2}{a} \int_0^a \sin \frac{n\pi x}{a} f_2(x) dx = \frac{2}{a} \int_0^a \sin \frac{n\pi x}{a} f_2(x) dx$$

$$u(x,y) \text{ which satisfies } \Delta u = 0 \text{ in } R \text{ and } \begin{array}{ll} x=0 & u=0 \\ x=a & u=0 \\ y=0 & u=f_2(x) \\ y=b & u=0 \end{array}$$

Now find a fn which satisfies

$$x=0 \quad u=0$$

$$x=a \quad u=0$$

$$y=0 \quad u=0$$

$$y=b \quad u=0$$

$$v(x,y) = \sum v_n(x,y) = \sum B_n \frac{\sinh \frac{n\pi}{a} (a-x)}{\sinh \frac{n\pi}{a} a} \sin \frac{n\pi y}{b}$$

$$\text{thus } U(x,y) = \sum_{n=1}^{\infty} \left\{ \frac{a_n \sinh \frac{n\pi}{a}(b-y)}{\sinh \frac{n\pi b}{a}} \sin \frac{n\pi x}{a} + b_n \frac{\sinh \frac{m\pi}{b}(a-x)}{\sinh \frac{m\pi a}{b}} \sin \frac{m\pi y}{b} \right\}$$

$$\text{where } a_n = \frac{2}{a} \int_0^a f_2(\xi) \sin \frac{n\pi \xi}{a} d\xi \quad b_m = \frac{2}{b} \int_0^b f_1(\xi) \sin \frac{m\pi \xi}{b} d\xi$$

to show convergence of $U(x,y)$ if $|f_2(x)|, |f_1(y)|$ are bdd by M

$$\text{then } |a_n| \leq \frac{2}{a} M \int_0^a |\sin \frac{n\pi \xi}{a}| d\xi \leq 2M \quad |b_m| \leq \frac{2}{b} M \int_0^b |\sin \frac{m\pi \xi}{b}| d\xi \leq 2M$$

$$\text{then } |U(x,y)| \leq 2M \sum_{n=1}^{\infty} \left\{ \frac{|\sinh \frac{n\pi}{a}(b-y)|}{\sinh \frac{n\pi b}{a}} + \frac{|\sinh \frac{m\pi}{b}(a-x)|}{\sinh \frac{m\pi a}{b}} \right\}$$

$$\text{but } \sinh \frac{\pi b}{a} < \sinh \frac{n\pi b}{a} \Rightarrow \frac{1}{\sinh \frac{\pi b}{a}} > \frac{1}{\sinh \frac{n\pi b}{a}} \quad \text{now take the smaller:}$$

$$|U(x,y)| \leq \frac{2M}{r} \sum_{n=1}^{\infty} \left\{ |\sinh \frac{n\pi}{a}(b-y)| + |\sinh \frac{m\pi}{b}(a-x)| \right\} \left(\frac{1}{\sinh \frac{n\pi b}{a}}, \frac{1}{\sinh \frac{m\pi a}{b}} \right)$$

but $\sinh$ is an exponential fn and the exponential fn is known to converge everywhere.

$$\frac{\partial u_n}{\partial x} = a_n \frac{\cosh}{\sinh} \left(\frac{n\pi}{a} \cos \frac{n\pi x}{a} \right) + b_n \frac{m\pi}{b} \frac{\cosh \frac{m\pi}{b}(a-x)}{\sinh} \sin \frac{m\pi y}{b}$$

$$\frac{\partial^2 u_n}{\partial x^2} = a_n \frac{\sinh}{\sinh} \left(\frac{n^2 \pi^2}{a^2} \sin \frac{n\pi x}{a} \right) + b_n \frac{m^2 \pi^2}{b^2} \frac{\sinh \frac{m\pi}{b}(a-x)}{\sinh} \sin \frac{m\pi y}{b}$$

$$\frac{\partial u_n}{\partial y} = -a_n \frac{n\pi}{a} \frac{\cosh}{\sinh} \sin \frac{n\pi x}{a} + b_n \frac{m\pi}{b} \frac{\sinh}{\sinh} \cos \frac{m\pi y}{b}$$

$$\frac{\partial^2 u_n}{\partial y^2} = a_n \frac{n^2 \pi^2}{a^2} \frac{\sinh}{\sinh} \sin \frac{n\pi x}{a} + b_n \left(\frac{m^2 \pi^2}{b^2} \right) \frac{\sinh}{\sinh} \sin \frac{m\pi y}{b}$$

$$\int_a^b \cos \frac{\pi}{2a} x \sin \frac{n\pi x}{a} dx \quad \text{let } \cos \frac{\pi}{2a} x dx = dv \quad u = \sin \frac{n\pi x}{a}$$

$$\frac{2a}{\pi} \sin \frac{\pi}{2a} x = u \quad dv = \frac{n\pi}{a} \cos \frac{n\pi x}{a}$$

$$\frac{2a}{\pi} \sin \frac{n\pi x}{a} \sin \frac{\pi x}{2a} = \left[\frac{2a}{\pi} \cdot \frac{n\pi}{a} \sin \frac{\pi x}{2a} \cos \frac{n\pi x}{a} \right]$$

$$\frac{2a}{\pi} \sin \frac{n\pi x}{a} \sin \frac{\pi x}{2a} \Big|_0^a - 2n \int_0^a \sin \frac{\pi x}{2a} \cos \frac{n\pi x}{a} dx$$

$$\sin \frac{\pi}{2a} x dx = dv$$

$$u = \cos \frac{n\pi x}{a}$$

$$-\frac{2a}{\pi} \cos \frac{\pi}{2a} x = v$$

$$du = -\frac{n\pi}{a} \sin \frac{n\pi x}{a}$$

$$-2n \left[-\frac{2a}{\pi} \cos \frac{\pi x}{2a} \cos \frac{n\pi x}{a} \Big|_0^a - 2n \int_0^a \cos \frac{\pi x}{2a} \sin \frac{n\pi x}{a} dx \right]$$

$$\int_0^a = \frac{4an}{\pi} \cos \frac{\pi x}{2a} \cos \frac{n\pi x}{a} \Big|_0^a + 4n^2 \int_0^a \cos \frac{\pi x}{2a} \sin \frac{n\pi x}{a} dx$$

$$= \frac{1}{1-4n^2} \cdot \frac{4an}{\pi} \cos \frac{\pi x}{2a} \cos \frac{n\pi x}{a} \Big|_0^a = \frac{4an}{\pi(1-4n^2)} \left[\cos \frac{\pi}{2} \cos n\pi - \cos 0 \cdot \cos 0 \right]$$

$$\frac{4an}{\pi(4n^2-1)}$$

$$b \int y \sin \frac{m\pi y}{b} dy - \int y' \sin \frac{m\pi y}{b} dy$$

$$dv = \sin \frac{m\pi y}{b} dy$$

$$u = y$$

$$u = y^2$$

$$v = -\frac{b}{m\pi} \cos \frac{m\pi y}{b}$$

$$du = dy$$

$$du = 2y dy$$

$$b \left[-\frac{yb}{m\pi} \cos \frac{m\pi y}{b} \Big|_0^b + \frac{b}{m\pi} \frac{b}{m\pi} \sin \frac{m\pi y}{b} \Big|_0^b \right] - \left[-\frac{y^2 b}{m\pi} \cos \frac{m\pi y}{b} \Big|_0^b + \frac{2b}{m\pi} \int_0^b y \cos \frac{m\pi y}{b} dy \right]$$

$$\text{let } dv = \cos \frac{m\pi y}{b} dy$$

$$u = y$$

$$v = \frac{b}{m\pi} \sin \frac{m\pi y}{b}$$

$$du = dy$$

$$\int_0^b y \cos \frac{m\pi y}{b} dy = \frac{by}{m\pi} \sin \frac{m\pi y}{b} \Big|_0^b + \frac{b}{m\pi} \frac{b}{m\pi} \cos \frac{m\pi y}{b} \Big|_0^b$$

$$b \left[-\frac{yb}{m\pi} \cos \frac{m\pi y}{b} \Big|_0^b + \frac{b^2}{m^2\pi^2} \sin \frac{m\pi y}{b} \Big|_0^b \right] + \frac{y^2 b}{m\pi} \cos \frac{m\pi y}{b} \Big|_0^b - \frac{2b^2}{m^3\pi^3} y \sin \frac{m\pi y}{b} \Big|_0^b - \frac{2b^3}{m^3\pi^3} \cos \frac{m\pi y}{b} \Big|_0^b$$

$$-\frac{yb^3}{m\pi} \{(-1)^m\} + \frac{b^3}{m\pi} \{(-1)^m\} - \frac{2b^3}{m^3\pi^3} [(-1)^m - 1]$$

Problem #1 Find the fn u $\exists$ $\Delta u = 0$ in a circle of radius a and on the circumference C assumes the value

(a) $u|_C = A \cos \varphi$
(b) $u|_C = A + B \sin \varphi$

(a) since $\Delta u = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial u}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 u}{\partial \varphi^2} = 0$

we obtain $u(\rho, \varphi)$ by assuming $u(\rho, \varphi) = R(\rho) \Phi(\varphi)$
to which the solutions are

$$R(\rho) = \rho^n$$

$$\Phi(\varphi) = A_n \cos n\varphi + B_n \sin n\varphi$$

from this

$$u(\rho, \varphi) = \sum_{n=0}^{\infty} \rho^n (A_n \cos n\varphi + B_n \sin n\varphi)$$

since $u(a, \varphi) = A \cos \varphi$ then $A \cos \varphi = \sum_{n=0}^{\infty} a^n (A_n \cos n\varphi + B_n \sin n\varphi)$

note that we can define A_n, B_n by fourier analysis $\exists$.

$$A_0 = \frac{1}{2\pi} \int_{-\pi}^{\pi} A \cos \psi d\psi \quad A_n = \frac{1}{a^n \pi} \int_{-\pi}^{\pi} A \cos \psi \cos n\psi d\psi \quad n \geq 1$$

$$B_n = \frac{1}{a^n \pi} \int_{-\pi}^{\pi} A \cos \psi \sin n\psi d\psi \quad n \geq 0$$

but $A \cos \psi$ is an even fn $\therefore B_n \equiv 0 \quad A_0 = 0 \quad \& \quad A_n \neq 0 \quad \forall n \geq 2$

the only term left is $A_1 = \frac{A}{a\pi} \int_{-\pi}^{\pi} \cos^2 \psi d\psi = \frac{A}{2a\pi} \left[\psi + \frac{\sin 2\psi}{2} \right]_{-\pi}^{\pi} = \frac{A}{a}$

$\therefore u(\rho, \varphi) = A \frac{\rho}{a} \cos \varphi$ ✓

(b) since $u(a, \varphi) = A + B \sin \varphi$ then $A + B \sin \varphi = \sum_{n=0}^{\infty} a^n (A_n \cos n\varphi + B_n \sin n\varphi)$

define as before $A_0 = \frac{1}{2\pi} \int_{-\pi}^{\pi} (A + B \sin \psi) d\psi$, $A_n = \frac{1}{a^n \pi} \int_{-\pi}^{\pi} (A + B \sin \psi) \cos n\psi d\psi \quad n \geq 1$

$$B_n = \frac{1}{a^n \pi} \int_{-\pi}^{\pi} (A + B \sin \psi) \sin n\psi d\psi \quad n \geq 0$$

but $A + B \sin \psi$ is an odd fn (A is even, $B \sin \psi$ is odd: ~~even odd odd~~)

$\therefore A_n = 0 \quad \forall n \geq 1 \quad B_n = 0 \quad \forall n \geq 2$

the only terms left are $A_0 = \frac{1}{2\pi} [A\psi - B \cos \psi]_{-\pi}^{\pi} = \frac{1}{2\pi} [A \cdot 2\pi + B - B] = A$

$\& \quad B_1 = \frac{1}{a\pi} \left[-A \cos \psi + \frac{B}{2} \left(\psi - \frac{\sin 2\psi}{2} \right) \right]_{-\pi}^{\pi} = \frac{1}{a\pi} \left[+A - A + \frac{B}{2} (2\pi - 0) \right] = \frac{B}{a}$

$$\therefore u(\rho, \varphi) = A + B \frac{\rho}{a} \sin \varphi$$

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Problem #2 Find a fn $U(x,y) \Rightarrow \Delta U = 0$ in a rectangle $0 \leq x \leq a, 0 \leq y \leq b$ and on ∂R

$$U(0,y) = f_1(y) \quad U(a,y) = 0 \quad U(x,0) = f_2(x) \quad U(x,b) = 0$$

we will solve the problem in two parts

$$1) \text{ find a fn } u \Rightarrow \Delta u = 0 \text{ in } R \quad u(0,y) = u(a,y) = 0 \quad u(x,0) = f_2(x) \quad u(x,b) = 0$$

$$2) \text{ find a fn } v \Rightarrow \Delta v = 0 \text{ in } R \quad v(0,y) = f_1(y), v(a,y) = 0 \quad v(x,0) = 0 \quad v(x,b) = 0$$

By separation of variables in part 1 $X(0) = X(a) = 0$ where $X = A \sin \lambda x + B \cos \lambda x$
this leads to a normal mode solution $X(x) = \sin \frac{n\pi x}{a}$

also since $Y(0) = \text{constant}$ & $Y(b) = 0$ one obtains for $Y(y) = C_1 \sinh \lambda y + D_1 \cosh \lambda y$
that the form of $Y(y) = \frac{\sinh \frac{n\pi}{a}(b-y)}{\sinh \frac{n\pi}{a}b}$

$$\therefore u_n(x,y) = \frac{\sinh \frac{n\pi}{a}(b-y) \sin \frac{n\pi x}{a}}{\sinh \frac{n\pi}{a}b}$$

$$\text{now let } u(x,y) = \sum_{n=0}^{\infty} u_n(x,y) \text{ then } u(x,0) = \sum_{n=0}^{\infty} u_n(x,0) = f_2(x) = \sum_{n=0}^{\infty} a_n \sin \frac{n\pi x}{a}$$

$$\text{using fourier series one now shows that } a_n = \frac{2}{a} \int_0^a f_2(\xi) \sin \frac{n\pi \xi}{a} d\xi$$

in the same manner one shows that for $v(x,y)$, the form of $Y(y)$ is

$$Y(y) = \sin \frac{m\pi y}{b}$$

and that the form of $X(x)$ is

$$X(x) = \frac{\sinh \frac{m\pi}{b}(a-x)}{\sinh \frac{m\pi}{b}a}$$

$$\therefore v_m(x,y) = \frac{\sinh \frac{m\pi}{b}(a-x) \sin \frac{m\pi y}{b}}{\sinh \frac{m\pi}{b}a}$$

$$\text{let } v(x,y) = \sum_{n=0}^{\infty} v_n(x,y) \text{ then } v(0,y) = \sum_{n=0}^{\infty} v(0,y) = \sum_{n=0}^{\infty} b_m \sin \frac{m\pi y}{b}$$

$$\text{using fourier series one shows that } b_m = \frac{2}{b} \int_0^b f_1(\xi) \sin \frac{m\pi \xi}{b} d\xi$$

$$\text{then } U(x,y) = \sum_{n=1}^{\infty} \left\{ a_n \frac{\sinh \frac{n\pi}{a}(b-y)}{\sinh \frac{n\pi b}{a}} \sin \frac{n\pi x}{a} + b_n \frac{\sinh \frac{n\pi}{b}(a-x)}{\sinh \frac{n\pi a}{b}} \sin \frac{n\pi y}{b} \right\}$$

$$\text{where } a_n = \frac{2}{a} \int_0^a f_2(\xi) \sin \frac{n\pi \xi}{a} d\xi \quad b_n = \frac{2}{b} \int_0^b f_1(\zeta) \sin \frac{n\pi \zeta}{b} d\zeta$$

note that $f_2(\xi)$ and $f_1(\zeta)$ need not be differentiable but only piecewise continuous. If piecewise continuous then the integral can be separated into several integrals over 2 adjacent pts having a differentiable discontinuity. Suppose that $\frac{d}{d\xi} f_2(\xi)$ is discontinuous at pts $\xi_1, \xi_2, \dots, \xi_n = a$

$$\text{then } a_n = \frac{2}{a} \int_0^a f_2(\xi) \sin \frac{n\pi \xi}{a} d\xi = \frac{2}{a} \left[\int_0^{\xi_1} + \int_{\xi_1}^{\xi_2} + \dots + \int_{\xi_{n-1}}^{\xi_n} \right] f_2(\xi) \sin \frac{n\pi \xi}{a} d\xi$$

where $f_2(\xi)$ is piecewise continuous in each of the intervals $[0, \xi_1], \dots, [\xi_{n-1}, \xi_n]$ and this can be done also for $f_1(\zeta)$.

$$\text{if } f_1(y) = Ay(b-y) \quad \text{and } f_2(x) = B \cos \frac{\pi x}{2a}$$

$$\text{then } a_n = \frac{2}{a} B \int_0^a \cos \frac{\pi x}{2a} \sin \frac{n\pi x}{a} dx = \frac{2B}{a\pi} \left(\frac{4na}{4n^2-1} \right) = \frac{8Bn}{\pi(4n^2-1)}$$

$$\text{since } \int_0^a \cos \frac{\pi x}{2a} \sin \frac{n\pi x}{a} dx = \frac{1}{1-4n^2} \left[\frac{2a}{\pi} \sin \frac{n\pi x}{a} \sin \frac{\pi x}{2a} \Big|_0^a + \frac{4an}{\pi} \cos \frac{\pi x}{2a} \cos \frac{n\pi x}{a} \Big|_0^a \right]$$

$$\text{and } b_m = \frac{2}{b} A \int_0^b y(b-y) \sin \frac{m\pi y}{b} dy = \frac{2A}{b} \left[\frac{2b^3}{m^3\pi^3} (1 - (-1)^m) \right] = \frac{4Ab^2}{m^3\pi^3} [1 + (-1)^{m+1}]$$

$$\text{since } \int_0^b (by-y^2) \sin \frac{m\pi y}{b} dy = b \left[-\frac{yb}{m\pi} \cos \frac{m\pi y}{b} \Big|_0^b + \frac{b^2}{m^2\pi^2} \sin \frac{m\pi y}{b} \Big|_0^b \right] + \frac{y^2 b}{m\pi} \cos \frac{m\pi y}{b} \Big|_0^b - \frac{2b^2 y}{m^2\pi^2} \sin \frac{m\pi y}{b} \Big|_0^b = \frac{2b^3}{m^3\pi^3} \cos \frac{m\pi y}{b}$$

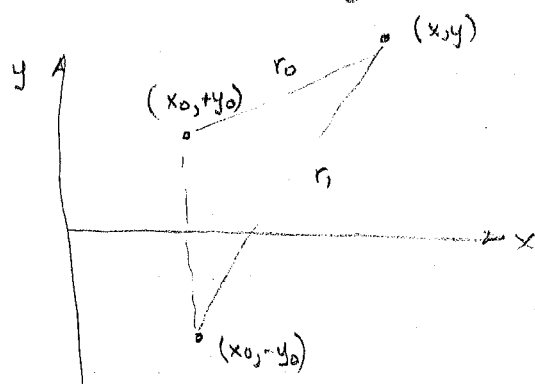
$$\therefore \text{ if } f_1(y) = Ay(b-y) \quad \& \quad f_2(x) = B \cos \frac{\pi x}{2a} \quad \text{then}$$

$$U(x,y) = \sum_{n=1}^{\infty} \left\{ a_n \frac{\sinh \frac{n\pi}{a}(b-y)}{\sinh \frac{n\pi b}{a}} \sin \frac{n\pi x}{a} + b_n \frac{\sinh \frac{n\pi}{b}(a-x)}{\sinh \frac{n\pi a}{b}} \sin \frac{n\pi y}{b} \right\}$$

$$a_n = \frac{8Bn}{\pi(4n^2-1)}$$

$$b_m = \frac{4Ab^2}{m^3\pi^3} [1 + (-1)^{m+1}]$$

Since $u(M_0) = \int_{\Sigma} \left(G \frac{\partial u}{\partial n} - u \frac{\partial G}{\partial n} \right) ds = \iint_{\Gamma} \Delta u \cdot G d\sigma$



$$r_0 = \sqrt{(x-x_0)^2 + (y-y_0)^2}$$

$$r_1 = \sqrt{(x-x_0)^2 + (y+y_0)^2}$$

$$G(M, M_0) = \frac{1}{2\pi} \ln \frac{1}{r_0} - \frac{1}{2\pi} \ln \frac{1}{r_1}$$

$$\frac{\partial G}{\partial n} \Big|_{y=0} = - \frac{\partial G}{\partial y} \Big|_{y=0} = \frac{1}{2\pi} \left(\frac{r_0}{1} \right) \frac{\partial}{\partial y} \left(\frac{1}{r_0} \right) - \frac{1}{2\pi} \left(\frac{r_1}{1} \right) \frac{\partial}{\partial y} \left(\frac{1}{r_1} \right)$$

$$\frac{r_0}{2\pi} \left(-\frac{1}{r_0^2} \right) \frac{1}{2r_0} \cdot 2(y-y_0) - \frac{r_1}{2\pi} \left(-\frac{1}{r_1^2} \right) \frac{1}{2r_1} \cdot 2(y+y_0)$$

$$\frac{\partial G}{\partial y} = - \frac{1}{2\pi r_0^2} (y-y_0) + \frac{1}{2\pi r_1^2} (y+y_0)$$

$$\therefore - \frac{\partial G}{\partial y} \Big|_{y=0} = \frac{1}{2\pi r_0^2} [-y_0] - \frac{1}{2\pi r_1^2} [y_0] = - \frac{y_0}{\pi r_0^2}$$

where $r_0 = \sqrt{(x-x_0)^2 + y_0^2}$

$$\therefore u(M_0) = - \int_c u \frac{\partial G}{\partial n} ds = \frac{1}{\pi} \int_c \frac{y_0}{(x-x_0)^2 + y_0^2} \cdot f(x) dx$$

$$u(M_0) = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{y_0}{(x-x_0)^2 + y_0^2} f(x) dx$$

$$= \frac{1}{\pi} \int_{-\infty}^0 \frac{y_0}{(x-x_0)^2 + y_0^2} \cdot 0 dx + \frac{1}{\pi} \int_0^{+\infty} \frac{y_0 u_0}{(x-x_0)^2 + y_0^2} dx$$

$$\arctan \left(\frac{x-x_0}{y_0} \right) = \frac{1}{1 + \left(\frac{x-x_0}{y_0} \right)^2} \cdot \frac{dx}{y_0} = \frac{y_0^2 + (x-x_0)^2}{y_0^2} \cdot \frac{dx y_0}{y_0^2} = \frac{y_0}{y_0^2 + (x-x_0)^2} dx$$

$$u(M_0) = \frac{u_0}{\pi} \arctan \left(\frac{x-x_0}{y_0} \right) \Big|_0^{\infty} = \frac{u_0}{\pi} \left[\arctan \right]$$

25/27

Clear heavy T63.2/31

#3 Solve $\Delta u = 1$ for a circle of radius a with b.c. $u|_{\rho=a} = 0$

let u_1 be s.t. $\Delta u_1 = 1$ a solution is $u_1 = \frac{\rho^2}{4}$

but $u_1|_{\rho=a} = \frac{a^2}{4}$

let u_2 be s.t. $\Delta u_2 = 0$ with $u_2|_{\rho=a} = -\frac{a^2}{4}$

$$u_{2n} = R(\rho) \Phi(\varphi) = (C\rho^n + D\rho^{-n})(A_n \cos n\varphi + B_n \sin n\varphi)$$

since $\Delta u_2 = 0$ in interior of circle $D = 0$

$$\therefore u_2 = \sum_{n=0}^{\infty} (A_n \cos n\varphi + B_n \sin n\varphi) \rho^n$$

$$u_2|_{\rho=a} = -\frac{a^2}{4} = \sum_{n=0}^{\infty} (A_n \cos n\varphi + B_n \sin n\varphi) a^n$$

by use of Fourier series $\frac{\alpha_0}{2} + \sum_{n=1}^{\infty} (\alpha_n \cos n\varphi + \beta_n \sin n\varphi)$ where $\underline{A}_0 = \frac{\alpha_0}{2}$, $\underline{A}_n = \alpha_n a^n$
 $\underline{B}_n = \beta_n a^n$

one obtains $\frac{\alpha_0}{2} = -\frac{a^2}{4} \cdot \frac{1}{\pi} \cdot 2\pi = -\frac{a^2}{4}$

$$\alpha_n = \frac{1}{\pi} \left(-\frac{a^2}{4}\right) \int_{-\pi}^{\pi} \cos n\varphi d\varphi = 0$$

$$\beta_n = \frac{1}{\pi} \left(-\frac{a^2}{4}\right) \int_{-\pi}^{\pi} \sin n\varphi d\varphi = 0$$

$$\therefore u_2 = -\frac{a^2}{4}$$

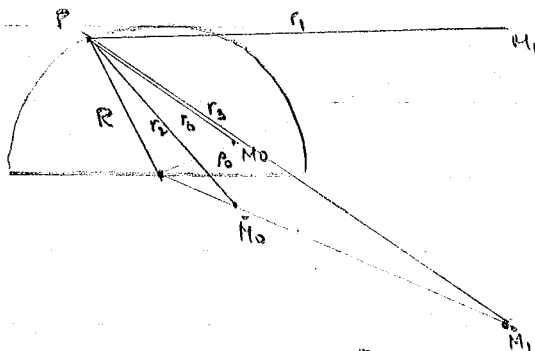
hence $u = u_1 + u_2 = \frac{\rho^2 - a^2}{4}$

u satisfies $\Delta u = 1$ with $u|_{\rho=a} = 0$

5

#6 Find the green's fn for a half circle, ring, a layer 0 ≤ z ≤ l

1. half circle: place two points of singularity one at (ρ_0, θ_0) & one at $(\rho_0, -\theta_0)$



$$\text{let } PM_0 = r_2 \quad PM_1 = r_0$$

$$PM_1 = r_3 \quad PM_0 = r_1$$

$$\therefore G(P, M_0, \bar{M}_0) = \frac{1}{2\pi} \left[\left(\ln \frac{1}{r_0} - \ln \frac{R}{\rho_0} \frac{1}{r_1} \right) - \left(\ln \frac{1}{r_2} - \ln \frac{R}{\rho_0} \frac{1}{r_3} \right) \right]$$

notice that when P lies on (r, θ) or $(r, -\theta)$ $r_0 = r_2$, $r_1 = r_3$

thus $G|_{\partial} = 0$ & $\Delta G = 0$ in the interior of the half-circle

2. ring

$$G(P, M_0) = -\frac{1}{2\pi} \ln \frac{1}{r_{PM_0}} + U$$

$$\text{where } \Delta U = 0 \text{ & } U|_{\Sigma} = -\frac{1}{2\pi} \ln \frac{1}{r_{PM_0}}$$

$$\text{Solution to } U \text{ is } U(\rho, \theta) = a_0 + b_0 \ln \rho + \sum_{n=1}^{\infty} \left\{ (a_n \rho^n + b_n \rho^{-n}) \cos n\theta + (a_n \rho^n + b_n \rho^{-n}) \sin n\theta \right\}$$

$$\text{on } \Sigma_1, \quad U|_{\Sigma_1} = -\frac{1}{2\pi} \ln \frac{a}{\rho_0} \frac{1}{r_1}$$

$$\text{on } \Sigma_2, \quad U|_{\Sigma_2} = -\frac{1}{2\pi} \ln \frac{R}{\rho_0} \frac{1}{r_2}$$

$$\therefore U|_{\Sigma_1} = -\frac{1}{2\pi} \ln \frac{a}{\rho_0} \frac{1}{r_1} = a_0 + b_0 \ln a + \sum_{n=1}^{\infty} \left\{ [a_n (a^n) + b_n (a^{-n})] \cos n\theta + [a_n (a^n) + b_n (a^{-n})] \sin n\theta \right\}$$

$$U|_{\Sigma_2} = -\frac{1}{2\pi} \ln \frac{R}{\rho_0} \frac{1}{r_2} = a_0 + b_0 \ln R + \sum_{n=1}^{\infty} \left\{ [a_n (R^n) + b_n (R^{-n})] \cos n\theta + [a_n (R^n) + b_n (R^{-n})] \sin n\theta \right\}$$

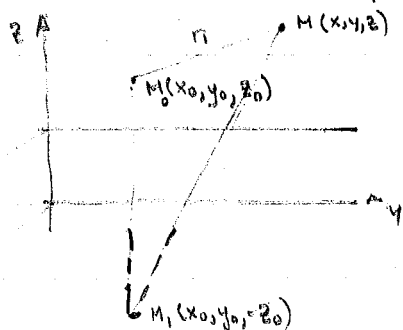
& a_0, b_0, a_n, b_n can be obtained

$$\therefore G(P, M_0) = -\frac{1}{2\pi} \ln \frac{1}{r_{PM_0}} + a_0 + b_0 \ln \rho + \sum_{n=1}^{\infty} \left\{ (a_n \rho^n + b_n \rho^{-n}) \cos n\theta + (a_n \rho^n + b_n \rho^{-n}) \sin n\theta \right\}$$

where a_0, b_0, a_n, b_n are from the above two eqs.

5

3. a layer $0 \leq z \leq l$: the green's fn is of the form $\frac{1}{4\pi r}$. We must place an infinite number of pts of singularity along a line $x=x_0, y=y_0$



$\frac{1}{4\pi r_1} - \frac{1}{4\pi r_0}$ will be zero at $z=0$, but at $z=l$

G will have a residual of $\frac{1}{4\pi \bar{r}_1} - \frac{1}{4\pi \bar{r}_0}$ $\bar{r}_1 = \sqrt{(x-x_0)^2 + (y-y_0)^2 + (z-l)^2}$
 $\bar{r}_0 = \sqrt{\quad \quad \quad + (z-0)^2}$

now add $\frac{1}{4\pi \bar{r}_2} - \frac{1}{4\pi \bar{r}_3}$ $\bar{r}_2 = \bar{r}_0$ & $\bar{r}_3 = \bar{r}_1$ at $z=l$

but now these pts will contribute to lower bdy so one must add

two new pts to counteract their effect, etc.

$$\therefore G(M, M_0, M_1, \dots) = \frac{1}{4\pi} \sum_{i=0}^{\infty} \left[\frac{1}{\sqrt{(x-x_0)^2 + (y-y_0)^2 + (z-z_0+2il)^2}} - \frac{1}{\sqrt{(x-x_0)^2 + (y-y_0)^2 + (z-z_0-2il)^2}} \right]$$

where $2il$ is the necessary placement of an image pt so that its corresponding singularity is zero either at $z=l$ or $z=0$

3

Question: if one solves $\Delta G=0$ in the slab with $G=0$ at $z=0, l$

will one obtain G of form: $\sin n\pi z e^{-k|y|}$ $\uparrow$ $\sin \sqrt{k^2 - n^2\pi^2} x$ $k^2 > n^2\pi^2$

& $\sin n\pi z e^{-k|y| - \sqrt{n^2\pi^2 - k^2}|x|}$ $\uparrow$

for $k^2 < n^2\pi^2$ $\uparrow$

should be no preference for x or y

7 Determine a harmonic fn in a ring $a \leq \rho \leq b$ and satisfying

$$u|_{\rho=a} = f_1(\theta) \quad u|_{\rho=b} = f_2(\theta)$$

Solution: $\nabla^2 u = u_{\rho\rho} + \frac{1}{\rho} u_{\rho} + \frac{1}{\rho^2} u_{\theta\theta} = 0$ with $u = R(\rho) \Theta(\theta)$

gives

$$\rho^2 R'' + \rho R' - k^2 R = 0$$

$$\Theta'' + k^2 \Theta = 0$$

$$\text{or } \left. \begin{aligned} R &= A_k \rho^k + B_k \rho^{-k} \\ \Theta &= C_k \cos k\theta + D_k \sin k\theta \end{aligned} \right\} k \neq 0$$

$$R = A_0 + B_0 \log \rho$$

$$\Theta = C_0 + D_0 \theta$$

since u is single valued c_0 & $d_0 = 0$ where $c_0 = A_0 D_0$, $d_0 = D_0 B_0$

and therefore $k = \text{integer } n$

$$\therefore u = (a_0 + b_0 \ln \rho) + \sum_{n=1}^{\infty} [(a_n \rho^n + b_n \rho^{-n}) \cos n\theta + (c_n \rho^n + d_n \rho^{-n}) \sin n\theta]$$

at bdy

$$f_1(\theta) = (a_0 + b_0 \ln a) + \sum_{n=1}^{\infty} [(a_n a^n + b_n a^{-n}) \cos n\theta + (c_n a^n + d_n a^{-n}) \sin n\theta]$$

$$f_2(\theta) = (a_0 + b_0 \ln b) + \sum_{n=1}^{\infty} [(a_n b^n + b_n b^{-n}) \cos n\theta + (c_n b^n + d_n b^{-n}) \sin n\theta]$$

by fourier series $a_0 = \frac{1}{2\pi} \int_0^{2\pi} [f_1(\theta) \ln b - f_2(\theta) \ln a] d\theta$
 $\ln b - \ln a$

$$b_0 = \frac{1}{2\pi} \int_0^{2\pi} [f_2(\theta) - f_1(\theta)] d\theta$$

$$\ln b - \ln a$$

$$a_n = \frac{1}{\pi} \int_0^{2\pi} \frac{[f_1(\theta) b^{-n} \cos n\theta - f_2(\theta) a^{-n} \cos n\theta] d\theta}{\left(\frac{a}{b}\right)^n - \left(\frac{b}{a}\right)^n}$$

2

$$b_n = \frac{1}{\pi} \int_0^{2\pi} [f_2(\theta) a^n \cos n\theta - f_1(\theta) b^n \cos n\theta] d\theta$$

$$\left(\frac{a}{b}\right)^n - \left(\frac{b}{a}\right)^n$$

$$c_n = \frac{1}{\pi} \int_0^{2\pi} [f_1(\theta) b^n \sin n\theta - f_2(\theta) a^n \sin n\theta] d\theta$$

$$\left(\frac{a}{b}\right)^n - \left(\frac{b}{a}\right)^n$$

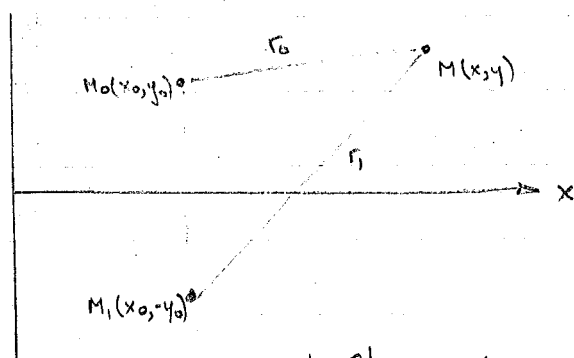
$$d_n = \frac{1}{\pi} \int_0^{2\pi} [f_2(\theta) a^n - f_1(\theta) b^n] \sin n\theta d\theta$$

$$\left(\frac{a}{b}\right)^n - \left(\frac{b}{a}\right)^n$$

#8

Determine solution to $\Delta u = 0$ in half plane $y \geq 0$ with bc.

$$u(x, 0) = \begin{cases} 0 & x < 0 \\ u_0 & x > 0 \end{cases}$$



$$G(M, M_0) = \frac{1}{2\pi} \ln \frac{1}{r_0} - \frac{1}{2\pi} \ln \frac{1}{r_1}$$

$$\text{since } u(M_0) = \int_{\Sigma} \left(G \frac{\partial u}{\partial n} - u \frac{\partial G}{\partial n} \right) ds - \iint_T \Delta u \cdot G dz$$

and $G|_{\Sigma} = 0$, $\Delta u = 0$ in T then

$$u(M_0) = - \int_{\Sigma} u \frac{\partial G}{\partial n} ds \quad u|_{\Sigma} = f(s)$$

$$\text{now } r_0 = \sqrt{(x-x_0)^2 + (y-y_0)^2} \quad r_1 = \sqrt{(x-x_0)^2 + (y+y_0)^2}$$

$$\frac{\partial G}{\partial n} \Big|_{y=0} = - \frac{\partial G}{\partial y} \Big|_{y=0} = - \frac{y_0}{\pi r_0'^2}$$

$$r_0' = \sqrt{(x-x_0)^2 + y_0^2}$$

$$\therefore u(x_0, y_0) = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{y_0}{(x-x_0)^2 + y_0^2} f(x) dx = \frac{1}{\pi} \int_0^{\infty} \frac{y_0 u_0 dx}{(x-x_0)^2 + y_0^2}$$

$$= \frac{u_0}{\pi} \arctan \left(\frac{x-x_0}{y_0} \right) \Big|_0^{\infty} = \frac{u_0}{2} + \frac{u_0}{\pi} \tan^{-1} \left(\frac{x_0}{y_0} \right)$$

$$\therefore u(x, y) = \frac{u_0}{2} + \frac{u_0}{\pi} \tan^{-1} \left(\frac{x}{y} \right)$$

5

✓

11/11/54

[The body of the document contains several paragraphs of text that are extremely faint and largely illegible due to the quality of the scan. The text appears to be a formal report or memorandum, possibly detailing a meeting or a set of instructions. Some words like "The following information was obtained" and "The results of the investigation" are faintly visible.]

P330

1. Find u harmonic in circle of radius a and on the circle assumes the value

a) $u|_c = A \cos \phi$

b) $u|_c = A + B \sin \phi$

Separation of Variables $\Rightarrow u(\rho, \phi) = \sum_{n=0}^{\infty} \rho^n (A_n \cos n\phi + B_n \sin n\phi) \quad *$

where, if $u|_c = f(\phi)$

$$A_0 = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(s) ds, \quad A_n = \frac{1}{a^n \pi} \int_{-\pi}^{\pi} f(s) \cos ns ds \quad n \geq 1$$

$$B_n = \frac{1}{a^n \pi} \int_{-\pi}^{\pi} f(s) \sin ns ds \quad n \geq 0$$

Then a) $\Rightarrow u = A \frac{\rho}{a} \cos \phi$

b) $\Rightarrow u = A + B \frac{\rho}{a} \sin \phi$

(these solns can be obtained by finding A_n, B_n through the integrals or simply by equating coefficients in $*$)

2. Solve $\Delta u = 0$ in rectangle $0 \leq x \leq a$, $0 \leq y \leq b$ with

$$u|_{x=0} = f_1(y), \quad u|_{y=0} = f_2(x), \quad u|_{x=a} = 0, \quad u|_{y=b} = 0$$

Let $u = u_1 + u_2$ where $\Delta u_1 = 0$, $\Delta u_2 = 0$ in rectangle

and $u_1 = 0$ on boundary except $u_1|_{x=0} = f_1(y)$,
 $u_2 = 0$ on boundary except $u_2|_{y=0} = f_2(x)$.

Separation of variables $\Rightarrow u_2 = \sum_{n=0}^{\infty} u_n^{(2)}(x, y)$

where
$$u_n^{(2)} = \frac{a_n \sinh \frac{\pi n}{a} (b-y) \sin \left(\frac{n\pi x}{a} \right)}{\sinh \left(\frac{n\pi b}{a} \right)}$$

so that
$$u_n^{(2)}(x, 0) = a_n \sinh \left(\frac{n\pi x}{a} \right)$$

$$\Rightarrow a_n = \frac{2}{a} \int_0^a f_2(\xi) \sin \left(\frac{n\pi \xi}{a} \right) d\xi$$

Similarly,
$$u_n^{(1)} = \frac{b_m \sinh \frac{m\pi}{b} (a-x) \sin \left(\frac{m\pi}{b} y \right)}{\sinh \left(\frac{m\pi a}{b} \right)}$$

$$u_n^{(1)}(0, y) = b_m \sin \left(\frac{m\pi}{b} y \right)$$

$$\Rightarrow b_m = \frac{2}{b} \int_0^b f_1(\xi) \sin \left(\frac{m\pi \xi}{b} \right) d\xi$$

When $f_1 = Ay(b-y)$, $b_m = \frac{4Ab^2}{m^3\pi^3} [1 + (-1)^{m+1}]$

$f_2 = B \cos \frac{\pi x}{a}$, $a_n = \frac{4B}{\pi} \left[\frac{2n}{4n^2-1} \right]$

3. $\Delta u = 1$ for circles radius a , s.t. $u|_{\rho=a} = 0$.

let $u = u_1 + u_2$ s.t. $\Delta u_1 = 1$, $\Delta u_2 = 0$
 $u_2|_a = -u_1|_a$

let $u_1 = \frac{\rho^2}{4}$, $\frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial u_1}{\partial \rho} \right) = 1$

on $\rho = a$, $u_1|_{\rho=a} = \frac{a^2}{4} \Rightarrow u_2|_a = -\frac{a^2}{4}$

Separation of variables $\Rightarrow$

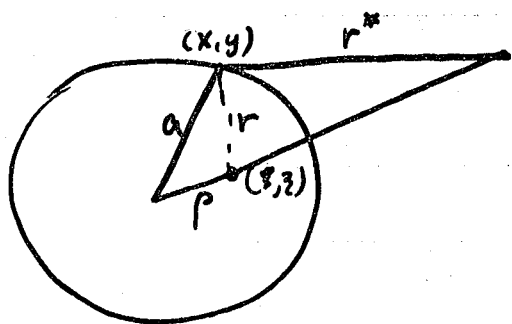
$$u_2 = \sum_{n=0}^{\infty} (A_n \cos n\phi + B_n \sin n\phi) \rho^n$$

Equating coefficients $\Rightarrow B_n = 0$ all n , $A_n = 0$ $n \geq 1$
 $A_0 = -\frac{a^2}{4}$

$$\Rightarrow \underline{u = \frac{\rho^2 - a^2}{4}}$$

6 a) G.F. for $\frac{1}{2}$ circle, radius a

G.F. for disk, $G(x, y; \xi, \eta) = \frac{1}{2\pi} \ln r - \frac{1}{2\pi} \ln \left(\frac{\rho}{a} r^* \right)$



$$= \frac{1}{2\pi} \ln \left(\frac{ar}{\rho r^*} \right)$$

$$r^2 = (x - \xi)^2 + (y - \eta)^2$$

$$r^{*2} = \left(x \frac{a^2}{\rho^2} - \xi \right)^2 + \left(y \frac{a^2}{\rho^2} - \eta \right)^2$$

In polar co-ords $(x, y) \rightarrow (r, \theta)$
 $(z, \bar{z}) \rightarrow (v, \phi)$

$$r^2 = v^2 - 2vp \cos(\phi - \theta) + p^2$$

$$r^{*2} = v^2 - 2 \frac{a^2 v}{p} \cos(\phi - \theta) + \frac{a^4}{p^2}$$

$$\Rightarrow G(v, \theta; p, \phi) = \frac{1}{4\pi} \ln \left\{ \frac{a^2(v^2 - 2vp \cos(\theta - \phi) + p^2)}{a^4 - 2a^2 v p \cos(\theta - \phi) + v^2 p^2} \right\}$$

Thus $G = 0$ when $v = a$.

$G(v, \theta; p, -\phi)$ is G.F. for a disk of radius a with pole at $(p, -\phi)$ i.e. image of (p, ϕ) in $\phi = 0$.

Thus $G^*(v, \theta; p, \phi) = G(v, \theta; p, \phi) - G(v, \theta; p, -\phi)$

satisfies $G^* = 0$ when $v = a$ and $G^* = 0$ when $\phi = 0$

i.e it is G.F. for semi-circle.

Hence $G^*(v, \theta; p, \phi) = \frac{1}{4\pi} \ln \left\{ \frac{(v^2 - 2vp \cos(\theta - \phi) + p^2)}{(a^4 - 2a^2 v p \cos(\theta - \phi) + v^2 p^2)} \cdot \frac{(a^4 - 2a^2 v p \cos(\theta + \phi) + v^2 p^2)}{(v^2 - 2vp \cos(\theta + \phi) + p^2)} \right\}$

ring $a \leq \rho \leq b$ ($= D$)

$$6b) \quad G(x, y; z, \bar{z}) = \frac{1}{2\pi} \ln \frac{1}{r} + V$$

$$\begin{aligned} (X, y) &\rightarrow (\rho, \theta) \\ (z, \bar{z}) &\rightarrow (r, \phi) \end{aligned}$$

where $\Delta V = 0$ in D , $V|_{\partial D} = -\frac{1}{2\pi} \ln \frac{1}{r}$

Sepn. of variables $\Rightarrow$

$$\begin{aligned} V = & \alpha_0 + \beta_0 \ln \rho + \sum_{n=1}^{\infty} \left[(\alpha_n \rho^n + \beta_n \rho^{-n}) \cos n\theta \right] \\ & + \sum_{n=1}^{\infty} \left[(\gamma_n \rho^n + \delta_n \rho^{-n}) \sin n\theta \right] \end{aligned} \quad (1)$$

$$r^2 = r^2 - 2\rho r \cos(\phi - \theta) + \rho^2$$

$$\Rightarrow \text{on } \rho = a \quad V = -\frac{1}{2\pi} \ln \frac{1}{r_a}$$

$$r_a = (r^2 - 2ar \cos(\phi - \theta) + a^2) = \bar{f}(\theta)$$

$$r_b = (r^2 - 2br \cos(\phi - \theta) + b^2) = \bar{g}(\theta)$$

$$\text{let } -\frac{1}{2\pi} \ln \frac{1}{\bar{f}(\theta)} = f(\theta), \quad -\frac{1}{2\pi} \ln \frac{1}{\bar{g}(\theta)} = g(\theta)$$

$$\text{B.C. are now: } V|_{\rho=a} = f(\theta), \quad V|_{\rho=b} = g(\theta) \quad (2)$$

substituting (1) into (2) & using expansion of f & g

yields =

$$\left. \begin{aligned} \alpha_0 + \beta_0 \ln b &= a_0 \\ \alpha_n b^n + \beta_n b^{-n} &= a_n \\ \gamma_n b^n + \delta_n b^{-n} &= b_n \end{aligned} \right\}$$

$$a_n = \frac{1}{\pi} \int_0^{2\pi} g(\theta) \cos n\theta d\theta$$

$$b_n = \frac{1}{\pi} \int_0^{2\pi} g(\theta) \sin n\theta d\theta$$

$$\left. \begin{aligned} \alpha_0 + \beta_0 \ln a &= c_0 \\ \alpha_n a^n + \beta_n a^{-n} &= c_n \\ \gamma_n a^n + \delta_n a^{-n} &= d_n \end{aligned} \right\}$$

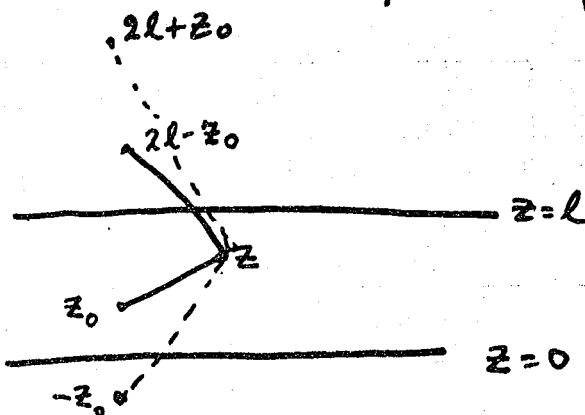
$$c_n = \frac{1}{\pi} \int_0^{2\pi} f(\theta) \cos n\theta d\theta$$

$$d_n = \frac{1}{\pi} \int_0^{2\pi} f(\theta) \sin n\theta d\theta$$

These determine v and hence G .

This also solves Q.7.

6c) G.F. for a layer $0 \leq z \leq l$.



z_0 reflected in $z=0$ & $z=l$.

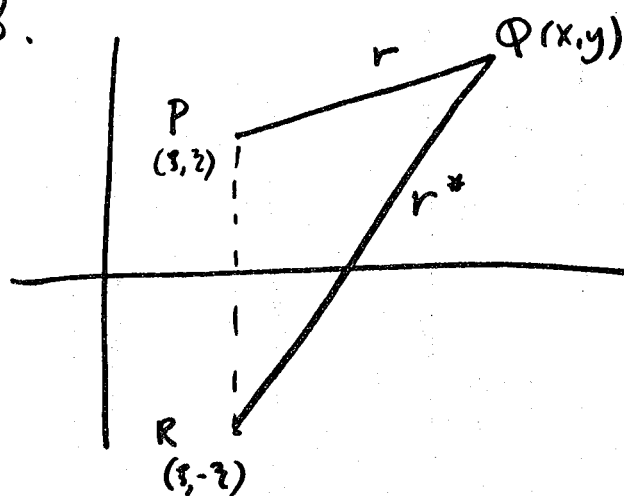
both images reflected in both
 $z=0$ & $z=l$

yields a series of images
at $z = \pm z_0 \pm 2nl$

Green's fn is

$$G = \frac{1}{4\pi} \sum_{n=0}^{\infty} \left\{ \frac{1}{\sqrt{(x-x_0)^2 + (y-y_0)^2 + (z-z_0 \pm 2nl)^2}} - \frac{1}{\sqrt{(x-x_0)^2 + (y-y_0)^2 + (z+z_0 \pm 2nl)^2}} \right\}$$

8.



$$G(Q, P) = \frac{1}{2\pi} \ln \left(\frac{r}{r^*} \right)$$

$$r = \sqrt{(x-\xi)^2 + (y-\zeta)^2}$$

$$r^* = \sqrt{(x-\xi)^2 + (y+\zeta)^2}$$

$$y=0, \quad G=0$$

$$\frac{\partial G}{\partial n} \Big|_{y=0} = -\frac{\partial G}{\partial y} \Big|_{y=0} = -\frac{\zeta}{\pi r_0^2}$$

$$r_0 = \sqrt{(x-\xi)^2 + \zeta^2}$$

$$u(\xi, \zeta) = - \int_{y=0} f \frac{\partial G}{\partial n} ds \quad \text{where } u=f \text{ on } y=0. \\ s=x$$

$$\Rightarrow u = \frac{1}{\pi} \int_0^\infty \frac{\zeta u_0 dx}{(x-\xi)^2 + \zeta^2} = \frac{u_0}{\pi} \arctan \left(\frac{x-\xi}{\zeta} \right) \Big|_{x=0}^{x=\infty}$$

$$= \frac{u_0}{2} + \frac{u_0}{\pi} \arctan \left(\frac{\xi}{\zeta} \right) \quad \zeta \geq 0, \quad -\infty < \xi < \infty.$$

$$\textcircled{1} \quad (x+2)u_x + 2y u_y = 2u \quad \text{IC: } u(-1, y) = \sqrt{y}$$

$$\frac{dy}{dx} = \frac{2y}{x+2} \quad y = c_1 (x+2)^2 \quad \text{Characteristic}$$

$$\frac{du}{dx} = \frac{2u}{x+2} \quad u = k_1 (x+2)^2 \quad \text{where } k_1 = k_1(c_1)$$

$$\text{on } u(-1, y) = \sqrt{y}$$

$$\sqrt{y} = k_1(c_1) \cdot 1 = k_1(y) \quad \therefore k_1(y) = y^{1/2}$$

$$\therefore u = \frac{\sqrt{y}}{(x+2)} (x+2)^2 = \sqrt{y} (x+2)$$

$$\textcircled{2} \quad x^2 u_x - y^2 u_y = 0 \quad \text{IC: } u(1, y) = F(y)$$

$$\frac{dy}{dx} = \frac{-y^2}{x^2} \quad \therefore \frac{1}{y} + \frac{1}{x} = c$$

$$\frac{xy}{x+y} = c$$

$$\frac{du}{dx} = \frac{0}{x^2} = 0 \quad \therefore u = k(c)$$

$$\text{a) } x=1 \quad F(y) = k\left(\frac{1+y}{y}\right) \quad \therefore k(y) = F\left(\frac{1}{y-1}\right)$$

$$\therefore u = F\left(\frac{xy}{x+y-xy}\right)$$

$$\textcircled{3} \quad \text{b) } u_x + u^2 u_y = 1 \quad \frac{dx}{1} = \frac{dy}{u^2} = \frac{du}{1} \quad x-u = c_1$$

$$3y-u^3 = c_2$$

$$\therefore F(c_1, c_2) = 0 \quad \text{or} \quad F(x-u, 3y-u^3) = 0$$

$$\text{a) } x u_x (u-2y^2) = (u-u_y y) (u-y^2-2x^3) \quad \frac{dx}{x(u-2y^2)} = \frac{dy}{y(u-y^2-2x^3)} = \frac{du}{u(u-y^2)}$$

$$\ln y = \ln u + \ln c_1 \quad y = u c_1$$

$$\frac{dx}{x} [u - c_1^2 u^2 - 2x^3] = \frac{du}{u} (u - 2c_1^2 u^2) = du (1 - 2c_1^2 u)$$

since $u = f(y)$ only
& y is indep of x

$$(u-y^2) \ln x - \frac{2}{3} x^3 = (u-y^2) + c_2$$

$$\therefore (u-y^2) [\ln x - 1] - \frac{2}{3} x^3 = c_2 \quad \therefore F\left(\frac{y}{u}, (u-y^2) [\ln x - 1] - \frac{2}{3} x^3\right) = 0$$

C

$$\frac{dx}{x(u-2y^2)} = \frac{dy}{y(u-y^2-2x^3)} = \frac{du}{u(u-y^2-2x^3)}$$

$$d(\quad) = C \times$$

$$k_1(xu - 2y^2x) + k_2(yu - y^3 - 2x^3y) = k_3(u^2 - uy^2 - 2x^3u)$$

$$y(xu - 2y^2x) \quad (xyu - y^2x - 2x^4y)$$

$$x^2(xu - 2y^2x)$$

$$c_1 y = u$$

$$2x^2(xu - 2y^2x) \rightarrow 2x^3u - 4y^2x^3$$

$$-2y(yu - y^3 - 2x^3y) \rightarrow -2y^2u + 2y^4 + 4x^3y^2$$

$$(u^2 - uy^2 - 2x^3u) \rightarrow u^2 - uy^2 - 2x^3u$$

$$u(u-y) \quad 2y^2(y^2-u)$$

$$2u^2c_1^2$$

$$\frac{(y^2-u)}{c_1 y} \cdot \frac{2y^2(y^2-u)}{c_1^2}$$

$$xy(c_1 - 2y)$$

$$y(u - y^2 - 2x^3)$$

$$u(u - y^2 - 2x^3)$$

$$\frac{2y^2}{u} \cdot \frac{2y^2}{yuy}$$

$$y^2(c_1 - y) - 2yx^3$$

$$\frac{dx}{x(u-2y^2)} = \frac{dy}{y(u-y^2-2x^3)} = \frac{du}{u(u-y^2-2x^3)}$$

$$2x^2(xu - 2y^2x)$$

$$-2y(yu - y^3 - 2x^3y)$$

$$(u^2 - uy^2 - 2x^3u)$$

$$yu^2 - y^3u - 2x^3yu$$

$$u^2 - uy^2 - 2x^3u$$

$$\frac{(2x^2dx - 2ydy + du)u}{u^2 - uy^2 - 2x^3u} = 0$$

$$2y^4 - 3uy^2 + u^2$$

$$2y$$

$$\frac{2x^3}{2x^4u - 2x^4y^2}$$

$$\left(\frac{2x^3}{3} - y^2 + u\right) = C$$

$$x^2u(xu - 2y^2x) \rightarrow x^3u^2 - 2y^2x^3u$$

$$-2y(yu - y^3 - 2x^3y)$$

$$\frac{-2y dy + x du}{(u - y^2)} = \frac{dx}{1}$$

$$\frac{u dx}{x(u - 2y^2)} = \frac{x du}{x(u - y^2 - 2x^3)}$$

$$\int \frac{2x^3 dx}{u - y^2} + \ln(u - y^2) = \ln x + C$$

$$C = \ln\left(\frac{u - y^2}{x}\right) + \int \frac{2x^3 dx}{(u - y^2)}$$

$$\frac{u dx + x du}{2u^2 x - 3xuy^2 + xu(-2x^3)}$$

$$\frac{xu dy + xy du}{2yu^2 - 2xy^2 - 4x^3uy}$$

$$\frac{xu dy + xy du}{xuy(2u - 2y^2 - 4x^3)} = \frac{y u dx - y x du}{y x u (2u - 3y^2 - 2x^3)}$$

$$\frac{xu dy - y u dx + 2xy du}{xuy(y^2 - 2x^3)}$$

$$\text{let } \frac{dx}{x(u - y^2)} = dv$$

$$u = 2x^4$$

$$du = 8x^3$$

$$y(\quad) dx = x(u - 2y^2) dy$$

$$\frac{y(u - y^2 - 2x^3) dx}{x(u - y^2)} = (xu - 2y^2x) dy = \frac{x(u - y^2) dy - xy^2 dy}{y(u - y^2 - 2x^3) xy(u - y^2 - 2x^3)(u - y^2)}$$

$$\frac{dx}{x(u - y^2)} = \frac{dy}{y}$$

$$u_x x(u-2y^2) = (u-u_y y)(u-y^2-2x^3)$$

$$\frac{dx}{x(u-2y^2)} = \frac{dy}{y(u-y^2-2x^3)} = \frac{du}{u(u-y^2-2x^3)}$$

$$\frac{y dx}{xy(u-2y^2)} + \frac{x dy}{xy(u-y^2-2x^3)}$$

$$\frac{2}{3} + \frac{4}{6} = \frac{6}{9} = \frac{2}{3}$$

$$\frac{4}{6} + \frac{4}{6} = \frac{8}{6} = \frac{4}{3}$$

$$\frac{x dx}{u x^2} + \frac{y dy}{-u y^2}$$

$$\frac{y dx + x dy}{xyu - 2xy^3 + xyu + xy^3 + 2x^4y}$$

$$\frac{du}{u(u-y^2-2x^3)}$$

$$\frac{y dx - x dy}{-xy^3 + 2x^4y} = \frac{du}{u(u-y^2-2x^3)}$$

$$\frac{y dx - x dy}{-xy(y^2-2x^3)} = \frac{xy du}{xyu(u-y^2-2x^3)}$$

$$-xy(y^2 + 2x^2)$$

$$\frac{u dx}{xu(u-2y^2)} - \frac{2x du}{xu(u-y^2-2x^3)} = \frac{dy}{y(u-y^2-2x^3)}$$

$$\frac{u dx - 2x du}{xu^2 - 2y^2xu - 2xu^2 + 2xuy^2 + 4x^4u}$$

$$\frac{u dx - x dy}{xu^2 - 2xy^2u - xu^2 + xuy^2 + 2x^4u}$$

$$\frac{u dx - 2x du}{-xu^2 + 4x^4u} =$$

$$\frac{u dx - 2x du}{(u + 4x^3)} = \frac{u dx}{u - 2y^2}$$

$$\frac{u dx - 2x du}{-xu(u - 4x^3)} = \frac{u dx}{ux(u - 2y^2)}$$

$$(u - 2y^2)u dx - 2x($$

Vanduyke - Perturbation Prof
in Fluid Dyn

Q. Erdelyi -

$$\frac{dx}{x(u-y^2)} = \frac{dy}{y(u-y^2-2x^3)} = \frac{du}{u(u-y^2-2x^3)}$$

$$x d(u-y^2) = x d(u-y^2)$$

$$dx(u-y^2-2x^3) = dx dy x(u-y^2)$$

$$dx(u-y^2-2x^3) = du x(u-y^2)$$

$$d[(u-y^2-2x^3)x] = (u-y^2-2x^3)dx + x d(u-y^2-2x^3)$$

$$dy [x(u-y^2)]$$

$$x du - 2xy dy - 6x^3 dx$$

$$x du - 2xy dy - 6x^3 dx$$

$$(u-y^2-2x^3)dx = x d(u-y^2) + (u-y^2)dx$$

$$x du - 2y x dy - 6x^3 dx =$$

$$xu(u-y^2-2x^3) - 2y^2x(u-y^2-2x^3) - 6x^4(u-y^2)$$

$$xu^2 - xu y^2 - 2x^4 u - 2y^2 x u + 2y^4 x + 4y^2 x^4 - 6x^4 u + 6x^4 y^2$$

$$xu^2 - 3xu y^2 + 2y^4 x + 10x^4 y^2 - 8x^4 u$$

$$u = y g \left[-\frac{x^4}{2} + x(u-y^2) \right]$$

$$u_x = y g' \left[\right] \{ -2x^3 + (u-y^2) + u_x x \}$$

$$u_y = g + y g' \left[\right] \{ x(u_y - 2y) \}$$

$$u_x [1 - x y g'] = y g' [-2x^3 + (u-y^2)]$$

$$[u_y - u_y]$$

$$u_y - xyg'u_y = g + yg'(-2xy)$$

$$u_y[1 - xyg'] = yg'[-2x^3 + (u - y^2)] + g$$

$$[yu_y - u] =$$

$$u_x[] = yg'$$

$$[-u + yu_y][1 - xyg'] = yg' + yg'(-2xy) - u[1 - xyg']$$

$$u_x[1 - xyg'] = yg'[-2x^3 + (u - y^2)]$$

$$(u - y^2 - 2x^3) / [u - yu_y] (1 - xyg') = xyg'(-2xy^2 - u)(u - y^2 - 2x^3)$$

$$x(u - 2y^2)u_x(1 - xyg') = xyg'[(u - 2y^2)(-2x^3 + (u - y^2))]$$

$$(u - 2y^2)(u - y^2 - 2x^3)$$

$$u = yg'[-\frac{x''}{2} + x(u - y^2)]$$

$$u_x = yg'[] \{ -2x^3 + (u - y^2) + x(u_x) \}$$

$$u_x[1 - xyg'] = yg' \{ u - y^2 - 2x^3 \}$$

$$u_y = g + yg' \{ x(u_y - 2y) \}$$

$$(u - yu_y)[1 - xyg'] = -yg - xyg'(-2y) + u(1 - xyg')$$

$$= -u + u - xyg'(u - 2y^2)$$

$$(u - y^2 - 2x^3)(u - yu_y)[] = -xyg'(u - 2y^2)(u - y^2 - 2x^3)$$

$$xu_x(u - 2y^2)(1 - yg'x) = xyg'[u - y^2 - 2x^3][u - 2y^2]$$

$$\frac{y dx - x dy}{-xy(y^2 - 2x^3)}$$

$$\frac{2x^2 dx}{2x^3(u-2y^2)} + \frac{du}{u^2 - uy^2 - 2x^3u}$$

$$\frac{2x^2 dx + du - 2y dy}{2x^3u - 4x^3y^2 + u^2 - uy^2 - 2x^3u - 2y^2u + 2y^4 + 4x^3y^2}$$

$$u^2 - 3y^2u + 2y^4$$

$$\frac{2x^2 dx + du - 2y dy}{(u-2y^2)(u-y^2)} = \frac{dx}{x(u-2y^2)}$$

$$2x^3 dx + x(du - 2y dy) = (u - y^2) dx$$

$$2x^3 dx + d[(u - y^2)x]$$

$$2x^4 dx + x(du - 2y dy) - (u - y^2) dx = 0$$

$$2x^2 dx + du - 2y dy$$

$$2x^2(xu - 2y^2x) + (u^2 - uy^2 - 2x^3u) - 2y(yu - y^3 - 2x^3y)$$

$$2x^3u - 4x^3y^2 + u^2 - 2uy^2 - 2x^3u - 2y^2u + 2y^4 + 4x^3y^2$$

$$d(u - y^2) \quad u^2 - 3y^2u + 2y^4$$

$$\frac{2x^2 dx + du - 2y dy}{(u - 2y^2)(u - y^2)} = \frac{dx}{x(u - 2y^2)}$$

$$2x^3 dx + x d(u - y^2) = (u - y^2) dx$$

$$2x^3 dx + d[x(u - y^2)] = 0$$

$$\frac{x^4}{2} + x(u - y^2) = C$$

$$x(u - y^2 - 2x^3) = C$$

$$(u - y^2 - 2x^3) dx = x d(u - y^2)$$

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March 23, 1973

T63.2/31

C. LEVY

1. $(x+2)u_x + 2y u_y = 2u$

I.C.: $u(-1, y) = \sqrt{y}$

$$\frac{dy}{dx} = \frac{2y}{x+2} \Rightarrow y = c_1 (x+2)^2 \quad \text{Characteristic}$$

$$\frac{du}{dx} = \frac{2u}{x+2} \Rightarrow u = k_1 (x+2)^2 \quad \text{where } k_1 = k_1(c_1)$$

Since $u(-1, y) = \sqrt{y}$: $\sqrt{y} = k_1(c_1) \cdot 1 = k_1(y) \therefore k_1(s) = s^{1/2}$

$$u = \frac{\sqrt{y}}{x+2} (x+2)^2 = \sqrt{y} (x+2) \quad (5)$$

2. $x^2 u_x - y^2 u_y = 0$

I.C.: $u(1, y) = F(y)$

$$\frac{dy}{dx} = -\frac{y^2}{x^2} \therefore \frac{1}{y} + \frac{1}{x} = c \quad \text{Characteristic}$$

$$\frac{du}{dx} = \frac{0}{x^2} = 0 \therefore u = k(c)$$

Since $u(1, y) = F(y)$: $F(y) = k\left(\frac{1+y}{y}\right) \therefore k(s) = F\left(\frac{1}{s-1}\right)$

$$u = F\left(\frac{xy}{x+y-xy}\right) \quad (5)$$

3. b $u_x + u^2 u_y = 1$

$$\frac{dx}{1} = \frac{dy}{u^2} = \frac{du}{1} \Rightarrow x - u = c_1$$

$$3y - u^3 = c_2 \quad (5)$$

$$\therefore F(c_1, c_2) = 0 \quad \text{or} \quad F(x-u, 3y-u^3) = 0$$

$$3a \quad u_x \cdot x(u-2y^2) = (u-u_y y)(u-y^2-2x^3)$$

$$\frac{dx}{x(u-2y^2)} = \frac{dy}{y(u-y^2-2x^3)} = \frac{du}{u(u-y^2-2x^3)}$$

$$\Rightarrow \frac{dy}{y} = \frac{du}{u} \quad \text{or} \quad y = C_1 u$$

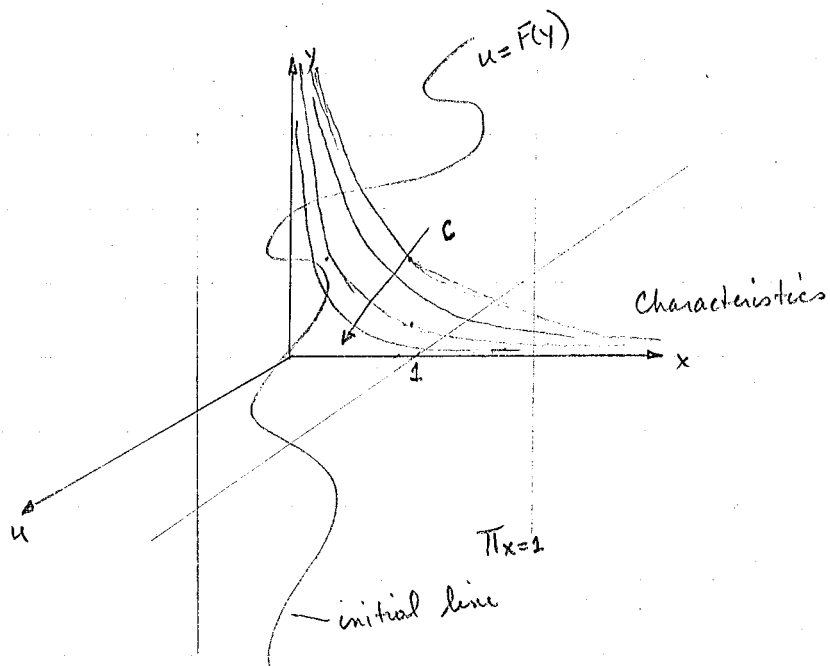
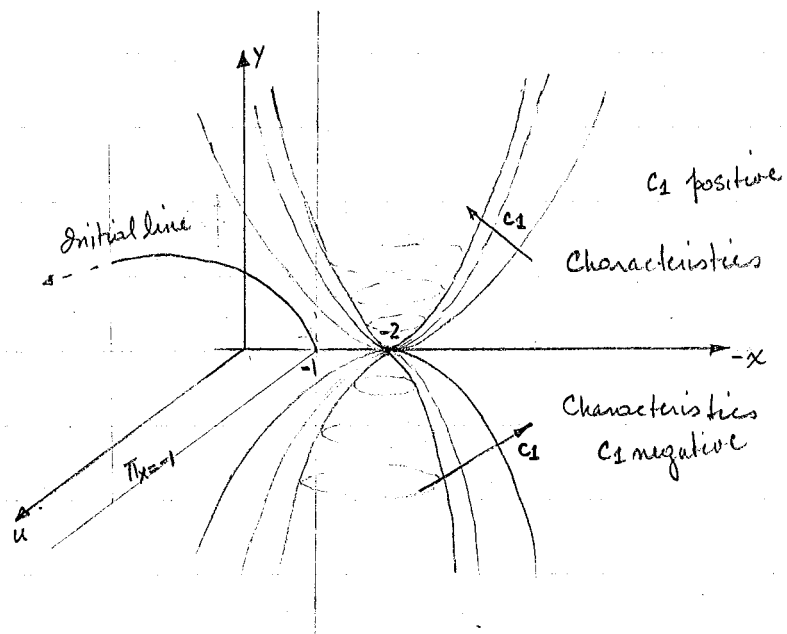
$$\frac{2x^2 dx + du - 2y dy}{(u-2y^2)(u-y^2)} = \frac{dx}{x(u-2y^2)}$$

$$\therefore d\left(\frac{2x^3}{3} + u - y^2\right) = \left(\frac{u-y^2}{x}\right) dx$$

$$\text{or} \quad \frac{2x^3}{3} + (u-y^2) - \int \frac{u-y^2}{x} dx = C_2$$

$$\therefore F(C_1, C_2) = 0 \quad \text{or} \quad F\left(\frac{y}{u}, \frac{2x^3}{3} + (u-y^2) - \int \frac{u-y^2}{x} dx\right) = 0$$

(3)



#2

1. $(x+2)u_x + 2yu_y = 2u$, $u(-1, y) = \sqrt{y}$

$$\frac{dy}{dx} = \frac{2y}{x+2} , \quad \frac{du}{dx} = \frac{2u}{x+2}$$

$$\frac{1}{2} \ln y = \ln(x+2) + \frac{1}{2} \ln k$$

$$\frac{1}{2} \ln u = \ln(x+2) + \ln c$$

$$y = k(x+2)^2$$

$$u = c(x+2)^2$$

where $c = c(k)$

$$= c\left(\frac{y}{(x+2)^2}\right)$$

When $x = -1$ $u = \sqrt{y}$

$$\Rightarrow \sqrt{y} = c\left(\frac{y}{1^2}\right)^{1/2} \Rightarrow c(\alpha) = \sqrt{\alpha}$$

$$\Rightarrow \text{soln. is } u = \left(\frac{y}{(x+2)^2}\right)^{1/2} (x+2)^2$$

$$\underline{u = \sqrt{y} (x+2)}$$

2. $x^2 u_x - y^2 u_y = 0$, $u(1, y) = F(y)$

$$\frac{dy}{dx} = -\frac{y^2}{x^2}$$

$$\frac{du}{dx} = 0 \Rightarrow u = \theta(k)$$

$$\frac{1}{y} = -\frac{1}{x} + 1 + \frac{1}{k}$$

B.C. $\Rightarrow F(y) = \theta(y)$

$$\Rightarrow \underline{u = F\left(\frac{xy}{x+y-xy}\right)}$$

$$3 \text{ a) } x u_x (u - 2y^2) = (u - u_y y)(u - y^2 - 2x^3)$$

$$\text{b) } u_x + u^2 u_y = 1$$

$$\text{b) } dx = \frac{dy}{u^2} = du$$

$$\Rightarrow u = x + \alpha \quad \frac{u^3}{3} = y + \beta$$

$$\underline{F(u-x, \frac{u^3}{3}-y) = 0}$$

$$\text{a) } \frac{dx}{x(u-2y^2)} = \frac{dy}{y(u-y^2-2x^3)} = \frac{du}{u(u-y^2-2x^3)}$$

$$\Rightarrow \frac{dy}{y} = \frac{du}{u} \Rightarrow \underline{y = \alpha u}$$

$$\alpha = \text{const.}$$

$$\frac{dx}{x(u-2y^2)} = \frac{dy(u-2y^2)}{y(u-y^2-2x^3)(u-2y^2)} = \frac{du - 2y dy}{y(u-y^2-2x^3)(u-2y^2)}$$

$$u - y^2 = z \Rightarrow \frac{dx}{x} = \frac{dz}{z - 2x^3} \Rightarrow -2x dx = d\left(\frac{z}{x}\right)$$

$z dx - 2x^3 dx = dz$ $-2x dx = \frac{z^2 dx - x^2 dz}{x^2}$

$$\Rightarrow \underline{-x^2 = \frac{z}{x} - \beta} \Rightarrow \beta = \frac{z+x^3}{x}$$

$$F(y/u, \underline{u - y^2 + x^3}) = 0$$

(15)

Cesar Levy T63.2131

Find the complete integral of

1. $\sqrt{p} + \sqrt{q} - 2x = 0$

2. $u - x + \log(pq) = 0$

3. $p^2 + q^2 - px - qy + \frac{1}{2}xy = 0$

1. $F_p = \frac{1}{2\sqrt{p}} \quad F_q = \frac{1}{2\sqrt{q}} \quad F_u = 0 \quad F_x = -2 \quad F_y = 0$

since $\frac{dq}{dt} = F(F_u, F_y) = 0 \quad q = \alpha$

from differential eq $\sqrt{p} = 2x - \sqrt{\alpha} \quad p = (2x - \sqrt{\alpha})^2$

$\therefore du = (2x - \sqrt{\alpha})^2 dx + \alpha dy$

$u = \frac{1}{6}(2x - \sqrt{\alpha})^3 + \alpha y + \beta$

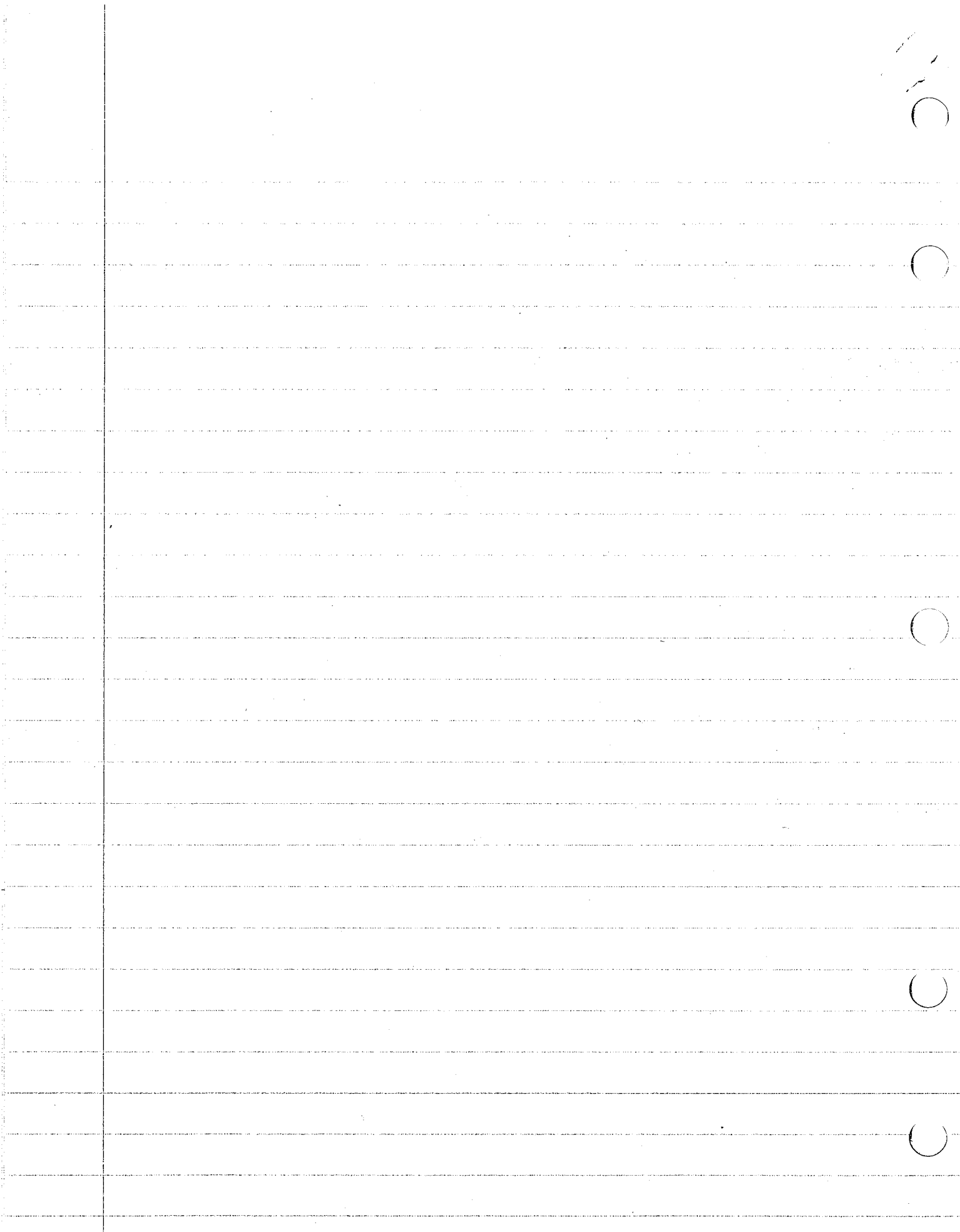
$\boxed{u = \frac{1}{6}(2x - \sqrt{\alpha})^3 + \alpha y + \beta} \quad 5$

2. $F_p = \frac{1}{p} \quad F_q = \frac{1}{q} \quad F_u = 1 \quad F_x = -1 \quad F_y = 0$

$\frac{dx}{1/p} = \frac{dy}{1/q} = \frac{du}{1} = \frac{dp}{1-p} = \frac{dq}{-q}$

this leads to $u = -2\ln q + \alpha$ or $\frac{u-\alpha}{2} = \ln q; q = e^{\frac{\alpha-u}{2}}$

from differential equation $\log p = -\log q + x - u = \frac{u-\alpha}{2} + x - u = \frac{2x - \alpha - u}{2}$



$$\text{or } p = e^{x - (\frac{\alpha+y}{2})}$$

$$\therefore du = e^{x - (\frac{\alpha+y}{2})} dx + e^{\frac{(\alpha-y)}{2}} dy$$

$$= e^{\frac{\alpha-y}{2}} \{ e^{x-\alpha} dx + dy \}$$

$$\text{or } e^{\frac{\alpha-y}{2}} du = e^{x-\alpha} dx + dy$$

$$2e^{\frac{\alpha-y}{2}} = e^{x-\alpha} + y + \beta$$

$$e^{y/2} = \frac{1}{2} e^{\frac{2x-\alpha}{2}} + \frac{1}{2} (y+\beta) e^{y/2}$$

$$\text{or } u = 2 \ln \left[\frac{1}{2} e^{\frac{2x-\alpha}{2}} + \frac{1}{2} (y+\beta) e^{y/2} \right]$$

$$\boxed{u = 2 \ln \left[\frac{1}{2} e^{y/2} \{ e^{x-\alpha} + (y+\beta) \} \right]} \quad 5$$

$$3. \quad F_p = 2p-x \quad F_q = 2q-y \quad F_u = 0 \quad F_x = -p + y/2 \quad F_y = -q + x/2$$

$$\frac{dx}{2p-x} = \frac{dy}{2q-y} = \frac{du}{p^2+q^2-\frac{1}{2}xy} = \frac{2dp}{2p-y} = \frac{2dq}{2q-x}$$

$$\text{one obtains } p+q = \frac{(x+y+\alpha)}{2}$$

using diff eq & substituting for p
gives

$$q = \frac{2y+\alpha}{4} + \frac{\sqrt{2(x-y)^2 - \alpha^2}}{4}$$

$$p = \frac{2x+\alpha}{4} + \frac{\sqrt{2(x-y)^2 - \alpha^2}}{4}$$

$$\therefore du = \frac{2y+\alpha}{4} dy + \frac{2x+\alpha}{4} dx + \frac{1}{4} \sqrt{2R^2 - \alpha^2} dR \quad \text{where } R = (x-y)$$

$$\int \frac{1}{\sqrt{2}} \sqrt{2R^2 - \alpha^2} \cdot \frac{1}{\sqrt{2}} dR = \left\{ \frac{\sqrt{2} R}{2} \sqrt{2R^2 - \alpha^2} - \frac{\alpha^2}{2} \ln (\sqrt{2} R + \sqrt{2R^2 - \alpha^2}) \right\} \frac{1}{\sqrt{2}}$$



$$\therefore u = \beta + \frac{y^2 + x^2 + \alpha(y+x)}{4} + \left\{ \frac{(x-y)}{8} \sqrt{2(x-y)^2 - \alpha^2} - \frac{\alpha^2}{8\sqrt{2}} \ln \left(\sqrt{2}(x-y) + \sqrt{2(x-y)^2 - \alpha^2} \right) \right\}$$

where β & α are integration constants

$$\boxed{u = \frac{y^2 + x^2 + \alpha(x+y)}{4} + \left\{ \frac{(x-y)}{8} \sqrt{2(x-y)^2 - \alpha^2} - \frac{\alpha^2}{8\sqrt{2}} \ln \left(\sqrt{2}(x-y) + \sqrt{2(x-y)^2 - \alpha^2} \right) \right\} + \beta}$$

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$$\sqrt{p} + \sqrt{q} - 2x = 0$$

$$F_p = \frac{1}{2\sqrt{p}}$$

$$F_q = \frac{1}{2\sqrt{q}}$$

$$F_u = 0$$

$$F_x = -2 \quad F_y = 0$$

$$\therefore \frac{dx}{dt} = \frac{1}{2\sqrt{p}}$$

$$\frac{dy}{dt} = \frac{1}{2\sqrt{q}}$$

$$\frac{du}{dt} = \frac{\sqrt{p}}{2} + \frac{\sqrt{q}}{2}$$

$$\frac{dp}{dt} = -(-2)$$

$$\frac{dq}{dt} = 0$$

$$q = \alpha = Q$$

$$\frac{dx}{\frac{1}{2\sqrt{p}}} = \frac{dy}{\frac{1}{2\sqrt{q}}} = \frac{du}{\frac{2}{\sqrt{p} + \sqrt{q}}} = \frac{dp}{2} = \frac{dq}{0}$$

$$\frac{dp}{2} = \frac{dx}{\frac{1}{2\sqrt{p}}}$$

$$(2x - \sqrt{\alpha})^2 = p = P$$

$$du = (2x - \sqrt{\alpha})^2 dx + \alpha dy$$

$$u = \frac{1}{6}(2x - \sqrt{\alpha})^3 + \alpha y + \beta$$

$$\frac{2pdy}{4pq - y^2} = \frac{2ydp}{2py - y^2}$$

$$p^2 + q^2 - px - qy + \frac{1}{2}xy = 0$$

$$\frac{2pdy + 2ydp}{4pq - y^2}$$

$$F_p = 2p - x$$

$$F_q = 2q - y$$

$$F_u = 0$$

$$F_x = -p + \frac{1}{2}y$$

$$F_y = -q + \frac{1}{2}x$$

$$\frac{dx}{dt} = 2p - x$$

$$\frac{dy}{dt} = 2q - y$$

$$\frac{du}{dt} = 2p^2 - px + 2q^2 - qy$$

$$\frac{dp}{dt} = -(-p + \frac{1}{2}y)$$

$$\frac{dq}{dt} = -(-q + \frac{1}{2}x)$$

$$\frac{dx + dy}{2p - x + 2q - y} = \frac{2dp + 2dq}{2p - y + 2q - x}$$

$$\frac{dx}{2p - x} + \frac{dy}{2q - y} = \frac{du}{()} = \frac{2dp}{2p - y}$$

$$\frac{dx + dy}{x + y} = \frac{2dp + 2dq}{2p + 2q + \alpha}$$

$$\frac{pdy}{2pq - y^2} = 2qdp$$

$$\frac{2pdx}{4p^2-2px} - \frac{2qdy}{4q^2-2qy}$$

$$\frac{2xdp}{2px-y} - \frac{2y dq}{2qy-x}$$

$$\frac{2pdx+2xdp}{4p^2-xy} - \frac{2qdy+2y dq}{4q^2-yx}$$

$$u-x + \log(pq) = 0$$

$$F_p = \frac{q}{pq} = \frac{1}{p}$$

$$F_q = \frac{p}{pq} = \frac{1}{q}$$

$$F_u = 1$$

$$F_x = -1 \quad F_y = 0$$

$$dp = -(F_x + F_u p)$$

$$dq = -(F_y + F_u q)$$

$$\frac{dx}{\frac{1}{p}} = \frac{dy}{\frac{1}{q}} = \frac{du}{2} = \frac{dp}{1+p} = \frac{dq}{-q}$$

$$\frac{2d(px) - 2d(qy)}{2(p+q)} = \frac{dx-2dy}{2(p+q)}$$

$$e^{\frac{\alpha-u}{2}} = q$$

$$\frac{u}{2} = -\log q + \alpha$$

$$u-x + \log p + \frac{\alpha-u}{2} = 0$$

$$-2\log q + \alpha - x + \log p + \log q = 0$$

$$u-x + \log p + \frac{\alpha-u}{2} = 0$$

$$\log p + \alpha - x - \log q = 0$$

$$e^{\frac{u+\alpha-2x}{2}} = p = P$$

$$\frac{du-2dp}{2p}$$

$$q dy = -\frac{dq}{q}$$

$$dy = -\frac{dq}{q^2}$$

$$\log p + \frac{u-2x+\alpha}{2} = 0$$

$$2pdx + 2x dp - 2qdy - 2y dq = 2pdx + 2qdx - 4pdy - 4qdy$$

$$y = \frac{1}{q} + c$$

$$p = e^{\frac{\alpha-u}{2}}, \quad q = e^{\frac{\alpha-u}{2}}$$

$$y-c = \frac{1}{q}$$

$$q = \frac{1}{y-c}$$

$$u-x + \log p + \log \frac{1}{y-c} = 0$$

$$u-x + \log \frac{p}{y-c} = 0$$

$$\frac{p}{y-c} = e^{(u-x)}$$

$$p = (y-\alpha) e^{(u-x)}$$

$$q = \frac{1}{y-\alpha}$$

$$du = e^{\frac{2x-u-\alpha}{2}} dx + e^{\frac{\alpha-u}{2}} dy$$

$$du = (y-\alpha) e^{(u-x)} dx + \frac{1}{y-\alpha} dy$$

$$du e^{\frac{\alpha-u}{2}} [e^{x-\alpha} dx + dy]$$

$$du - \frac{1}{y-\alpha} dy = (y-\alpha) e^{(u-x)} dx$$

$$e^{\frac{u-\alpha}{2}} du = e^{x-\alpha} dx + dy$$

$$du = e^{\frac{(u+\alpha-2x)}{2}} dx + e^{\frac{(\alpha-u)}{2}} dy$$

$$2e^{\frac{u-\alpha}{2}} = e^{x-\alpha} + y + \beta$$

$$e^{\frac{(\alpha-u)}{2}} [e^{(u-x)} dx + dy]$$

$$e^{\frac{(u-\alpha)}{2}} du = e^{(u-x)} dx + dy$$

$$\frac{u}{2} = \log(e^{\frac{x-\alpha}{2}} + (y+\beta))$$

$$\frac{dx}{2p-x} = \frac{dy}{2q-y} = \frac{du}{2p^2-px+2q^2-qy} = \frac{2dp}{2p-y} = \frac{2dq}{2q-x}$$

$$2dp - dy = \frac{2dp - dy}{2p-y+y-2q}$$

$$\frac{2dp - dy}{2(p-q)} = \frac{-2dp + dx}{-2q+x+2p-x} = \frac{-dx + 2dq}{x-y}$$

$$\frac{2pdp + 2qdq - du}{2p^2-px+2q^2-qy - 2p^2+px-2q^2+qy} = \frac{-dx + 2dq}{x-y}$$

$$2pdp + 2qdq - du = (p-q)dx + \frac{1}{2}x^2 + \frac{1}{2}y^2$$

$$2pdp$$

$$2dq - dy = dx - 2dp \quad (f')^2 + (g')^2 - xf' - yg' + \frac{1}{2}xy = 0$$

$$2(p+q) - (y+x) = 0 \quad f'(f'-x) + g'(g'-y) = -\frac{1}{2}xy$$

$$p = p(q)$$

$$2p^2 + 2q^2 - 2px - 2qy + xy = 0 \quad (f')^2 g^2 + g'^2 f^2 - xf'g - yg'f + \frac{1}{2}xy = 0$$

$$2p^2 + 2pq - py - px - p\alpha = 0$$

$$2q^2 - 2$$

$$py + p\alpha - 2pq + 2q^2 - px - 2qy + xy = 0$$

$$2q(q-p-y) - p(x-y-\alpha) + xy$$

$$\begin{aligned} f' &= x & g' &= y \\ f &= \frac{x^2}{2} + c & g &= \frac{y^2}{2} + k \\ f' &= 1 & g' &= 1 \\ f &= x + c & g &= y + k \end{aligned}$$

$$\begin{aligned} (y+k)^2 + (x+c)^2 \\ - x(y+k) - y(x+c) + \frac{1}{2}xy = 0 \end{aligned}$$

$$\frac{x+y-\alpha}{2} - p = q$$

$$\left(\frac{x+y-\alpha}{2}\right)^2 = (p+q)^2$$

$$(\quad)^2 = p^2 + q^2 + 2pq$$

$$px + qy + 2pq - \frac{1}{2}xy$$

$$p(x+2q) + qy + \frac{1}{2}xy$$

$$\frac{1 - \left(\frac{x+y-\alpha}{2}\right)^2 + qy + \frac{1}{2}xy}{x+2q} = p$$

$$\frac{x+y-\alpha}{2} + \frac{qy + \frac{1}{2}xy - \left(\frac{x+y-\alpha}{2}\right)^2}{x+2q} = q$$

$$a = \frac{x+y-\alpha}{2}$$

$$a(x+2q) + q(x-y) + \frac{1}{2}xy - a^2 = 2q^2$$

$$2a = x+y-\alpha$$

$$ax + q(x-y+2a) + \frac{1}{2}xy - a^2 = 2q^2$$

$$a^2 = \frac{x^2 + 2xy - 2x\alpha + y^2 - 2y\alpha + \alpha^2}{4}$$

$$2q^2 - ax - q(2x-\alpha) - \frac{1}{2}xy + a^2 = 0$$

$$\frac{1}{2}xy + ax = \frac{x^2 + xy - \alpha x}{2} + \frac{1}{2}xy = \frac{x^2 + 2xy - \alpha x}{2} = \frac{x(x+2y-\alpha)}{2} = p$$

$$2q^2 + b + a^2 - q(2x-\alpha) = 0$$

$$-b + a^2 = \frac{-2x^2 - 4xy + 2x\alpha}{4} + \frac{x^2 + 2xy - 2x\alpha + y^2 - 2y\alpha + \alpha^2}{4}$$

$$\frac{-x^2 - 2xy + y^2 - 2y\alpha + \alpha^2}{4}$$

$$-\frac{1}{4}(x^2 + 2xy - y^2 + 2y\alpha - \alpha^2)$$

$$(y-\alpha+x)(y-\alpha-x)$$

$$-(y-\alpha+x)(y-\alpha+x)$$

$$(2x-\alpha) \pm \sqrt{(2x-\alpha)^2 + 2[x^2 + 2xy - y^2 + 2y\alpha - \alpha^2]}$$

$$\frac{4x^2 - 4x\alpha + \alpha^2 + 2x^2 + 4xy - 2y^2 + 4y\alpha - 2\alpha^2}{4}$$

$$\frac{6x^2 - 4x\alpha + 4xy + 4y\alpha - 2y^2 - \alpha^2}{4}$$

$$(3x - \alpha - y)(2x + \alpha + y)$$

#3. Find complete integrals.

1. $p^2 + q^2 - px - qy + \frac{1}{2}xy = 0$ (1)

$$F_p = 2p - x, F_q = 2q - y, F_u = 0, F_x = -p + y/2, F_y = -q + x/2$$

$$\Rightarrow \frac{dx}{2p-x} = \frac{dy}{2q-y} = \frac{2dp}{2p-y} = \frac{2dq}{2q-x} = \frac{du}{p^2+q^2-\frac{1}{2}xy} \leftarrow \text{using (1)}$$

Since first four denominators linear in p, q, x, y , take linear combination of the four. Coefficients can be chosen to yield:

$$2(dp + dq) - (dx + dy) = 0$$

i.e. $p + q = \frac{1}{2}(x + y + \alpha)$ ($\alpha = \text{constant.}$) (2)

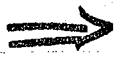
(1) & (2) imply

$$p = \frac{1}{4} \left(2x + \alpha \pm \sqrt{2(x-y)^2 - \alpha^2} \right) = P(x, y)$$

$$q = \frac{1}{4} \left(2y + \alpha \pm \sqrt{2(x-y)^2 - \alpha^2} \right) = Q(x, y)$$

Then $du = P dx + Q dy$

$$\Rightarrow du = \frac{1}{4} \left\{ (2y + \alpha) dy + (2x + \alpha) dx \pm \sqrt{2(x-y)^2 - \alpha^2} d(x-y) \right\}$$



$$u = \beta + \frac{1}{4} \left\{ x^2 + y^2 + \alpha(x+y) + \frac{(x-y)\sqrt{2(x-y)^2 - \alpha^2}}{2} + \frac{\alpha^2}{2\sqrt{2}} \ln \left(\sqrt{2}(x-y) + \sqrt{2(x-y)^2 - \alpha^2} \right) \right\}$$

α & β are the constants of integration.

2. $\sqrt{p} + \sqrt{q} - 2x = 0$

$$F_p = \frac{1}{2\sqrt{p}}, \quad F_q = \frac{1}{2\sqrt{q}}, \quad F_u = 0, \quad F_x = -2, \quad F_y = 0$$

$$2\sqrt{p} dx = 2\sqrt{q} dy = \frac{2 du}{\sqrt{p} + \sqrt{q}} = \frac{dp}{2} = \frac{dq}{0}$$

Last $\Rightarrow q = \alpha = \text{const} = \Phi(x, y)$

Eqn $\Rightarrow \sqrt{p} = 2x - \sqrt{\alpha} \Rightarrow p = (2x - \sqrt{\alpha})^2 = P(x, y)$

$$\Rightarrow du = P dx + \Phi dy = (2x - \sqrt{\alpha})^2 dx + \alpha dy$$

$$\Rightarrow u = \frac{1}{6} (2x - \sqrt{\alpha})^3 + \alpha y + \beta$$

3.

$$u - x + \log p + \log q = 0 \quad (I)$$

$$F_p = \frac{1}{p}, \quad F_q = \frac{1}{q}, \quad F_u = 1, \quad F_x = -1, \quad F_y = 0$$

$$p dx = q dy = \frac{du}{2} = \frac{dp}{1-p} = \frac{dq}{-q}$$

Many choices for first integral - use du & dq since soln.

contains $\ln(q)$ & no p - $\ln q$ can be eliminated from (I)

$$\ln q = -\frac{1}{2}(u - \alpha)$$

$$(I) \Rightarrow q = e^{\frac{1}{2}(\alpha - u)} \quad \& \quad p = e^{x - \frac{1}{2}(u + \alpha)}$$

$$du = e^{x - \frac{1}{2}(u + \alpha)} dx + e^{\frac{1}{2}(\alpha - u)} dy$$

$$2e^{u/2} = e^{x - \alpha/2} + ye^{\alpha/2} + 2\beta$$

$$u = 2 \ln \left\{ \frac{1}{2}(e^{x - \alpha/2} + ye^{\alpha/2}) + \beta \right\}$$

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C. Henry T63.2131

Notation: $\begin{pmatrix} u \\ v \end{pmatrix}_{,x} = \underline{u}_{,x}$ $\begin{pmatrix} u \\ v \end{pmatrix}_{,t} = \underline{u}_{,t}$

1. $\begin{pmatrix} 1 & 1 \\ 3 & -2 \end{pmatrix} \underline{u}_{,x} + \begin{pmatrix} 2 & 3 \\ 1 & -1 \end{pmatrix} \underline{u}_{,t} = \begin{pmatrix} u-v \\ 2v \end{pmatrix}$

$$\det |A - \mu B| = -5(\mu^2 - 3\mu + 1) = 0 \quad \mu^{(1)} = 2.618 \quad \mu^{(2)} = .382 \quad \mu^{(1)} \neq \mu^{(2)}$$

Since eigenvalues are real system is totally hyperbolic ✓

for $\mu^{(1)}$ the left $\bar{E}\bar{V} = (1.6175 \quad -1)$ for $\mu^{(2)}$ the left $\bar{E}\bar{V} = (1 \quad 1.6175)$

$\beta_1^{(1)}, \beta_2^{(1)}$ for $\mu^{(1)}$ are $(2.235 \quad 5.8525)$

$\beta_1^{(2)}, \beta_2^{(2)}$ for $\mu^{(2)}$ are $(3.6175 \quad 1.3825)$

$$\hat{u}^{(1)} = \beta_1^{(1)} u + \beta_2^{(1)} v = 2.235u + 5.8525v \quad D_1 = 2.618 \frac{\partial}{\partial x} + \frac{\partial}{\partial t}$$

$$\hat{c}^{(1)} = \lambda_1^{(1)} c_1 + \lambda_2^{(1)} c_2 = 1.6175u - 3.6175v$$

$$\hat{u}^{(2)} = \beta_1^{(2)} u + \beta_2^{(2)} v = 3.6175u + 1.3825v \quad D_2 = .382 \frac{\partial}{\partial x} + \frac{\partial}{\partial t}$$

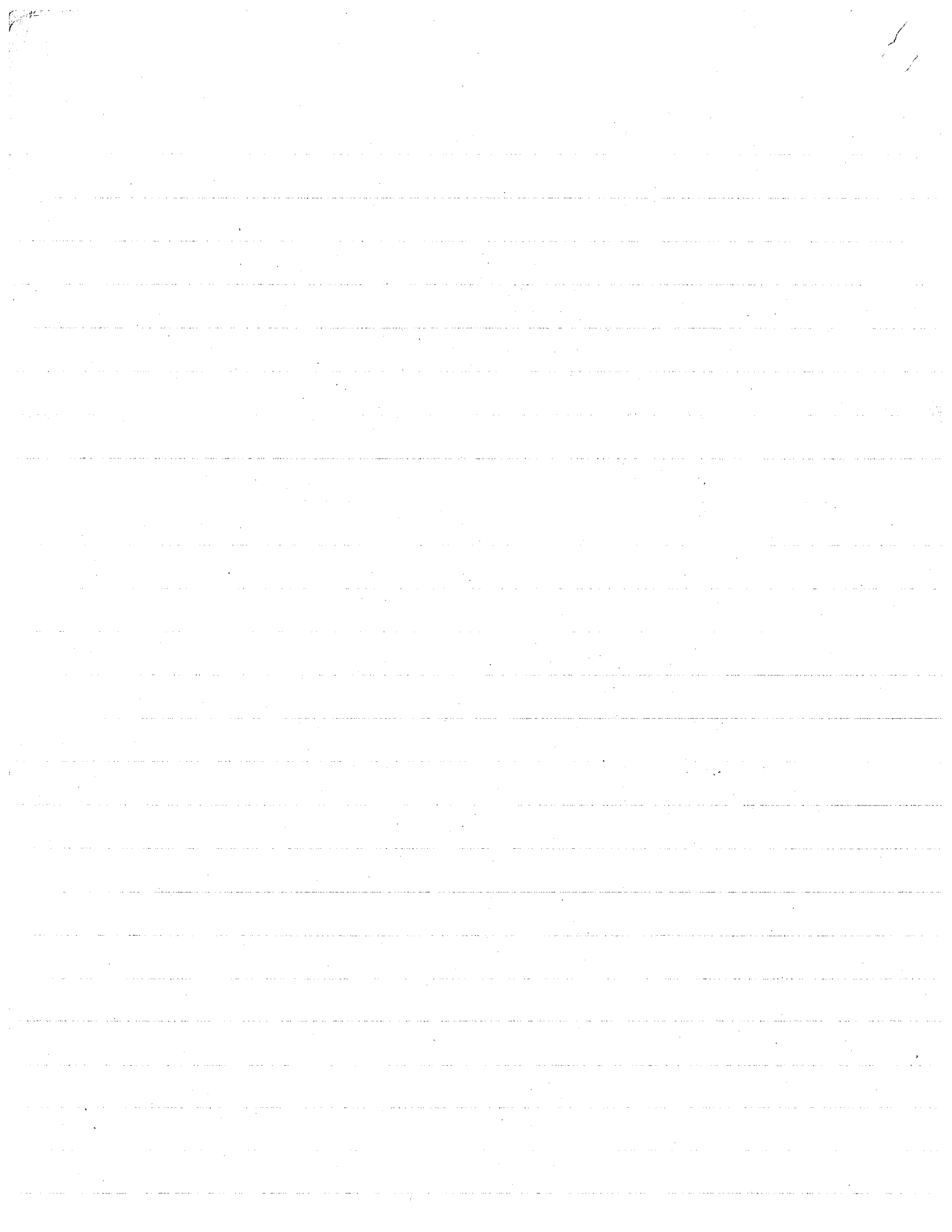
$$\hat{c}^{(2)} = \lambda_1^{(2)} c_1 + \lambda_2^{(2)} c_2 = u + 2.235v$$

Characteristics: $\frac{dt}{dx} = \frac{1}{2.618} \Rightarrow t - \frac{x}{2.618} = \alpha \quad \frac{dt}{dx} = \frac{1}{.382} \Rightarrow t - \frac{x}{.382} = \beta$

2. $\begin{pmatrix} p & u \\ \rho u & c^2 \end{pmatrix} \begin{pmatrix} u \\ p \end{pmatrix}_x + \begin{pmatrix} 0 & 1 \\ p & 0 \end{pmatrix} \begin{pmatrix} u \\ p \end{pmatrix}_t = \begin{pmatrix} -\frac{2pu}{x} \\ 0 \end{pmatrix}$

$$\det |A - \mu B| = p[c^2 - (u - \mu)^2] = 0 \quad \mu^{(1)} = u - c \quad \mu^{(2)} = u + c \quad \mu^{(1)} \neq \mu^{(2)}$$

Since eigenvalues are real system is totally hyperbolic ✓



?

$$? \mathcal{L} = (\pm c, 1)$$

for $\mu^{(1)}$ the left $\vec{EV} = (c - \rho)$ for $\mu^{(2)}$ the left $\vec{EV} = (c + \rho)$

$\beta_1^{(1)}, \beta_2^{(1)}$ for $\mu^{(1)}$ are $(-\rho^2, c)$

$\beta_1^{(2)}, \beta_2^{(2)}$ for $\mu^{(2)}$ are (ρ^2, c)

3

$$\hat{u}^{(1)} = \beta_1^{(1)} u + \beta_2^{(1)} \rho = \rho(c - \rho u)$$

$$D_1 = (u - c) \frac{\partial}{\partial x} + \frac{\partial}{\partial t}$$

$$\hat{c}^{(1)} = \lambda_1^{(1)} c_1 + \lambda_2^{(1)} c_2 + (D_1 \beta_1^{(1)}) u + (D_1 \beta_2^{(1)}) \rho = -\frac{2\rho u c}{x} + \left\{ \left[(u - c) \frac{\partial}{\partial x} + \frac{\partial}{\partial t} \right] (-\rho^2) \right\} u \text{ if } c \text{ is a const.}$$

$$\hat{u}^{(2)} = \beta_1^{(2)} u + \beta_2^{(2)} \rho = \rho(c + \rho u)$$

$$D_2 = (u + c) \frac{\partial}{\partial x} + \frac{\partial}{\partial t}$$

$$\hat{c}^{(2)} = \lambda_1^{(2)} c_1 + \lambda_2^{(2)} c_2 + (D_2 \beta_1^{(2)}) u + (D_2 \beta_2^{(2)}) \rho = -\frac{2\rho u c}{x} + \left\{ \left[(u + c) \frac{\partial}{\partial x} + \frac{\partial}{\partial t} \right] \rho^2 \right\} u \text{ if } c \text{ is a const.}$$

if c is not const add $\left\{ \left[(u \mp c) \frac{\partial}{\partial t} + \frac{\partial}{\partial t} \right] c \right\} \rho$ to $\hat{c}^{(1)}$ & $\hat{c}^{(2)}$ respectively

Characteristic $\frac{dt}{dx} = \frac{1}{u+c}$; $\frac{dt}{dx} = \frac{1}{u-c}$

$$3. \begin{pmatrix} x+y & 0 \\ 0 & x-y \end{pmatrix} \underline{u}_x + \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \underline{u}_y = \underline{0}$$

$$\det |A - \mu B| = (x+y)(x-y) - \mu^2 = 0$$

$\mu^{(1,2)} = \pm \sqrt{x^2 - y^2}$ totally hyperbolic for $x^2 > y^2$
elliptic if $x^2 < y^2$

for $\mu^{(1)}$ the left $\vec{EV} = (x-y, \sqrt{x^2 - y^2})$ for $\mu^{(2)}$ the left $\vec{EV} = (x-y, -\sqrt{x^2 - y^2})$

$\beta_1^{(1)}, \beta_2^{(1)}$ for $\mu^{(1)}$ are $(\sqrt{x^2 - y^2}, x-y)$

$\beta_1^{(2)}, \beta_2^{(2)}$ for $\mu^{(2)}$ are $(-\sqrt{x^2 - y^2}, x-y)$

$$\text{let } \sqrt{} = \sqrt{x^2 - y^2}$$

$$\hat{u}^{(1)} = \beta_1^{(1)} u + \beta_2^{(1)} v = \sqrt{x^2 - y^2} u + (x-y)v$$

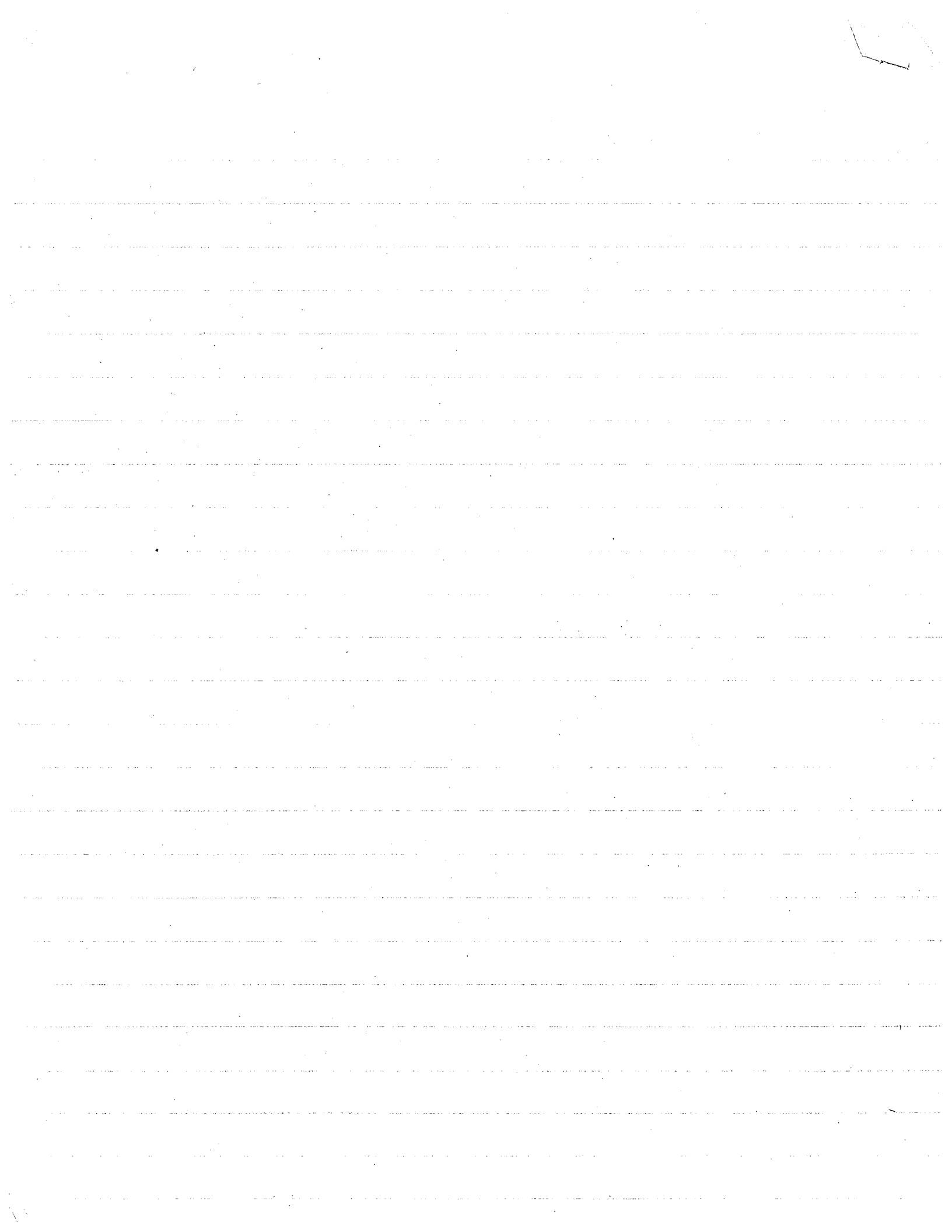
$$D_1 = \sqrt{x^2 - y^2} \frac{\partial}{\partial x} + \frac{\partial}{\partial y}$$

$$\hat{c}^{(1)} = (D_1 \beta_1^{(1)}) u + (D_1 \beta_2^{(1)}) v = \left\{ \left[\sqrt{} \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right] \sqrt{} \right\} u + \left\{ \left[\sqrt{} \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right] (x-y) \right\} v$$

$$\hat{u}^{(2)} = \beta_1^{(2)} u + \beta_2^{(2)} v = -\sqrt{x^2 - y^2} u + (x-y)v$$

$$D_2 = -\sqrt{x^2 - y^2} \frac{\partial}{\partial x} + \frac{\partial}{\partial y}$$

$$\hat{c}^{(2)} = (D_2 \beta_1^{(2)}) u + (D_2 \beta_2^{(2)}) v = \left\{ \left[-\sqrt{} \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right] (-\sqrt{}) \right\} u + \left\{ \left[-\sqrt{} \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right] (x-y) \right\} v$$



the characteristics are $\frac{dy}{dx} = \pm \frac{1}{\sqrt{1-u^2}}$

$$4. \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix} \underline{u}_x + \begin{pmatrix} 1 & 0 \\ 2 & -1 \end{pmatrix} \underline{u}_y = \begin{pmatrix} -4 \\ 1-u^2 \end{pmatrix}$$

$\det |A - \mu B| = (1-\mu)\mu - 2\mu = 0$ $\mu = 0, -1$ ^{(1), (2)} Since EV are real system is totally hyperbolic

for $\mu^{(1)}$ the left EV = $(0, 1)$ for $\mu^{(2)}$ the left EV = $(1, -1)$

for $\mu^{(1)}$ $\beta_1^{(1)}, \beta_2^{(1)}$ are $(2, -1)$

$\mu^{(2)}$ $\beta_1^{(2)}, \beta_2^{(2)}$ are $(-1, 1)$

$$\hat{u}^{(1)} = 2u - v$$

$$D_1 = \frac{\partial}{\partial y}$$

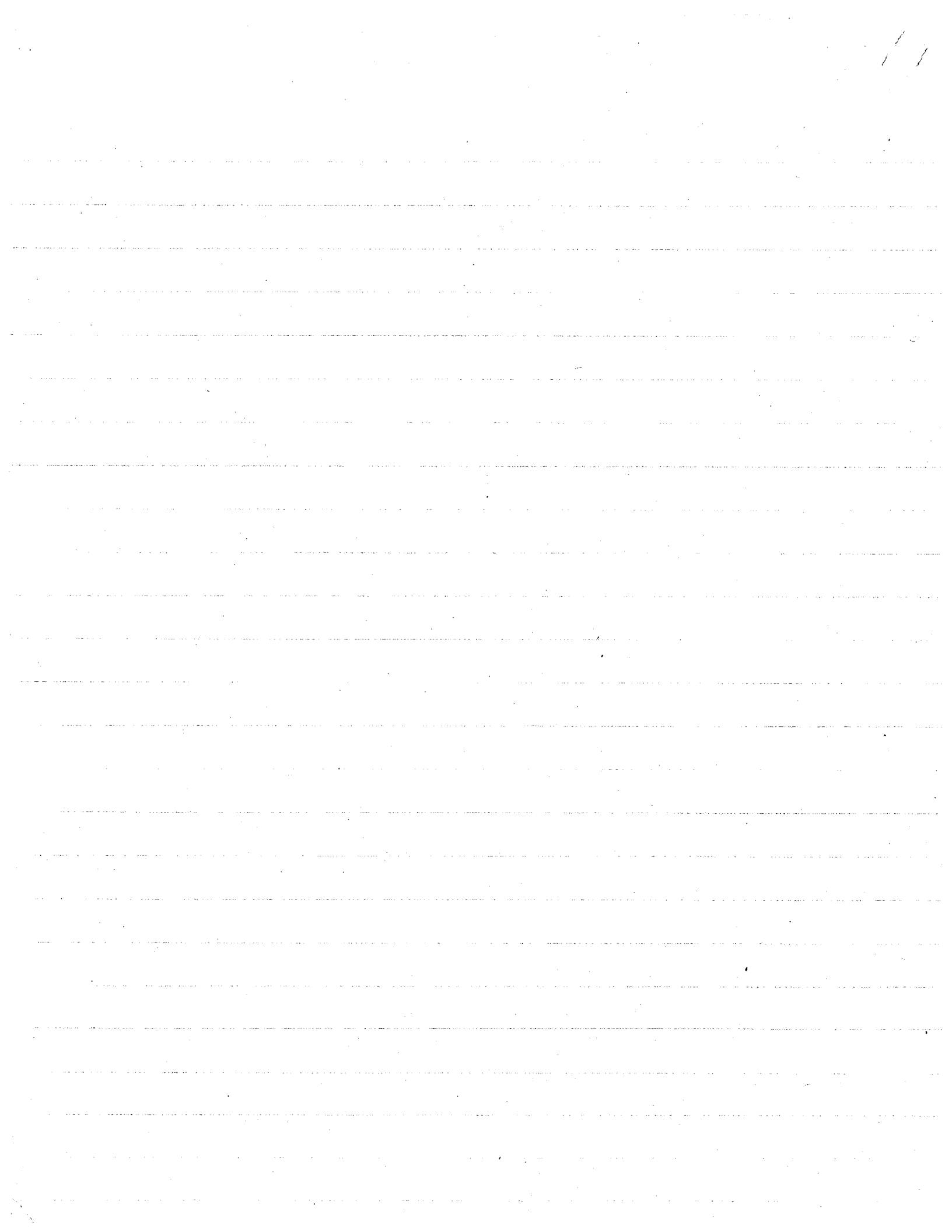
$$\hat{c}^{(1)} = 1 - u^2 \text{ since } D_1 \beta_i^{(1)} = 0$$

$$\hat{u}^{(2)} = -u + v$$

$$D_2 = -\frac{\partial}{\partial x} + \frac{\partial}{\partial y}$$

$$\hat{c}^{(2)} = (u^2 - u - 1)$$

5



$$cu_y - cv_t + u_t - c^2 u_x = 0$$

$$u_t + cu_x - c(v_t + cv_x) = 0$$

$$-cu_x + cv_t + u_t - c^2 v_x = 0$$

$$u_t - cu_x + c(v_t - cv_x) = 0$$

$$\frac{d}{ds} = \frac{\partial}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial}{\partial t} \frac{\partial t}{\partial s}$$

$$\frac{\partial t}{\partial s} = 1 \quad \frac{\partial x}{\partial s} = m \quad \left(\frac{dt}{dx} = \right)$$

$$x = ms + f(t)$$

$$\frac{dx}{ds} = \frac{\partial x}{\partial s} \frac{\partial s}{\partial t} + \frac{\partial x}{\partial t} \quad t = \frac{x}{m} + a$$

$$\frac{dt}{dx} = \frac{1}{m} \quad t = mx + a$$

$$\begin{pmatrix} 1 & 1 \\ 3 & -2 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix}_{,x} + \begin{pmatrix} 2 & 3 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix}_{,t} = \begin{pmatrix} 1 & -1 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} u-v \\ 2v \end{pmatrix} = \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

$$|A - \mu B| = \begin{vmatrix} 1-2\mu & 1-3\mu \\ 3-\mu & \mu-2 \end{vmatrix} = \mu - 2\mu^2 - 2 + 4\mu - 3 + 9\mu + \mu - 3\mu^2$$

$$= -5(\mu^2 - 3\mu + 1) = 0 \quad \mu = \frac{3 \pm \sqrt{9-4}}{2}$$

$$\mu = \frac{3 \pm \sqrt{5}}{2} = \frac{3 \pm 2.236}{2} = 2.618, .382$$

$$\mu_1 = 2.618 \quad \begin{pmatrix} -4.236 & -6.851 \\ .382 & .618 \end{pmatrix} \quad .382 \sqrt{\frac{1.6175}{.382}}$$

$$\bar{E}V_1 = \begin{pmatrix} 1.6175 & -1 \end{pmatrix}$$

$$\mu_2 = .382 \quad \begin{pmatrix} .236 & -.146 \\ 2.618 & -1.618 \end{pmatrix} \quad .146 \sqrt{\frac{1.6175}{.236}}$$

$$\bar{E}V_2 = \begin{pmatrix} 1 & 1.6175 \end{pmatrix}$$

$$\begin{pmatrix} 1.6175 & -1 \end{pmatrix} \begin{pmatrix} 2 & 3 \\ 1 & -1 \end{pmatrix} = \begin{pmatrix} 2.235 & 5.8525 \end{pmatrix} = \beta_1^{(1)}, \beta_2^{(1)} \text{ for } \mu_1$$

$$\begin{pmatrix} 1 & 1.6175 \end{pmatrix} \begin{pmatrix} 2 & 3 \\ 1 & -1 \end{pmatrix} = \begin{pmatrix} 3.6175 & 1.3825 \end{pmatrix} = \beta_1^{(2)}, \beta_2^{(2)} \text{ for } \mu_2$$

$$\hat{u}^{(1)} = \beta_1^{(1)} u + \beta_2^{(1)} v = 2.235u + 5.8525v \quad D_1 = 2.618 \frac{\partial}{\partial x} + \frac{\partial}{\partial t}$$

$$\hat{c} = \lambda_1^{(1)} c_1 + \lambda_2^{(2)} c_2 + (D\beta_1)u + (D\beta_2)v = 1.6175(u-v) - 2v + \left[\left(2.618 \frac{\partial}{\partial x} + \frac{\partial}{\partial t} \right) 2.235 \right] u + \left[\left(2.618 \frac{\partial}{\partial x} + \frac{\partial}{\partial t} \right) 5.8525 \right] v$$

since β is not a fun. of x or t

$$\therefore \hat{c}_1 = 1.6175(u-v) - 2v \quad D_1 = 2.618 \frac{\partial}{\partial x} + \frac{\partial}{\partial t} \quad \hat{u}^{(1)} = 2.235u + 5.8525v$$

$$= 1.6175u - 3.6175v$$

$$\hat{u}^{(2)} = \beta_1^{(2)} u + \beta_2^{(2)} v = 3.6175u + 1.3825v$$

$$D_2 = .382 \frac{\partial}{\partial x} + \frac{\partial}{\partial t}$$

$$\hat{c}_2 = \lambda_1^{(2)} c_1 + \lambda_2^{(2)} c_2 = (u-v) + 3.235v = u + 2.235v$$

$$\begin{pmatrix} p & u \\ \rho u & c^2 \end{pmatrix} \begin{pmatrix} u \\ p \end{pmatrix}_x + \begin{pmatrix} 0 & 1 \\ p & 0 \end{pmatrix} \begin{pmatrix} u \\ p \end{pmatrix}_t = \begin{pmatrix} -2pu & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} u \\ p \end{pmatrix}$$

$$\begin{vmatrix} p & u-\mu \\ \rho u - \rho\mu & c^2 \end{vmatrix} = 0 \quad \rho c^2 - (u-\mu)^2 \rho = 0 \quad (u-\mu)^2 = c^2$$

$$\mu = u-c \quad \mu = u+c$$

totally hyperbolic

$$\mu = u-c$$

$$\begin{pmatrix} p & c \\ \rho c & c^2 \end{pmatrix} \rightarrow \begin{pmatrix} p & c \\ 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} c & -p \end{pmatrix} \text{ should be } \begin{pmatrix} c & \pm 1 \end{pmatrix} \text{ (normal form)}$$

$$\mu = u+c$$

$$\begin{pmatrix} p & -c \\ -\rho c & c^2 \end{pmatrix}$$

$$\begin{pmatrix} c & p \end{pmatrix}$$

$$\begin{pmatrix} c & -p \end{pmatrix} \begin{pmatrix} 0 & 1 \\ p & 0 \end{pmatrix} = \begin{pmatrix} -p^2 & c \end{pmatrix} = \beta_1^{(1)} \beta_2^{(1)} \int_{u_1} u-c$$

$$\begin{pmatrix} c & p \end{pmatrix} \begin{pmatrix} 0 & 1 \\ p & 0 \end{pmatrix} = \begin{pmatrix} p^2 & c \end{pmatrix} = \beta_1^{(2)} \beta_2^{(2)} \int_{u_1} u+c$$

$$\hat{u}_1^{(1)} = \beta_1^{(1)} u + \beta_2^{(1)} p = -p^2 u + cp$$

$$D_1 = (u-c) \frac{\partial}{\partial x} + \frac{\partial}{\partial t}$$

$$\hat{c}_1^{(1)} = \lambda_1^{(1)} c_1 + \lambda_2^{(1)} c_2 + (D\beta_1)u + (D\beta_2)p = c \left(-\frac{2pu}{x} \right) + \left\{ \left[(u-c) \frac{\partial}{\partial x} + \frac{\partial}{\partial t} \right] (-p^2) \right\} u + \left\{ \left[(u-c) \frac{\partial}{\partial x} + \frac{\partial}{\partial t} \right] c \right\} p$$

$$\hat{u}_2^{(2)} = \beta_1^{(2)} u + \beta_2^{(2)} p = p^2 u + cp$$

$$D_2 = (u+c) \frac{\partial}{\partial x} + \frac{\partial}{\partial t}$$

$$\hat{c}_2^{(2)} = c \left(-\frac{2pu}{x} \right) + \left\{ \left[(u+c) \frac{\partial}{\partial x} + \frac{\partial}{\partial t} \right] p^2 \right\} u + \left\{ \left[(u+c) \frac{\partial}{\partial x} + \frac{\partial}{\partial t} \right] c \right\} p$$

$$\begin{pmatrix} x+y & 0 \\ 0 & x-y \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix}_x + \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix}_y = 0$$

$$|A - \mu B| = \begin{vmatrix} x+y & -\mu \\ -\mu & x-y \end{vmatrix} \quad (x+y)(x-y) - \mu^2 = 0 \quad \mu = \pm \sqrt{x^2 - y^2} \quad \begin{array}{l} \text{totally hyperb if } x^2 > y^2 \\ \text{elliptic if } y^2 > x^2 \end{array}$$

$$\mu_1 = +\sqrt{x^2 - y^2} \quad (x-y \quad \sqrt{}) \begin{pmatrix} x+y & -\sqrt{} \\ -\sqrt{} & x-y \end{pmatrix} = \begin{pmatrix} 0 & 0 \end{pmatrix}$$

$$\bar{E}V_1 = (x-y \quad \sqrt{x^2 - y^2})$$

$$\mu_2 = -\sqrt{x^2 - y^2} \quad \begin{pmatrix} x+y & \sqrt{} \\ \sqrt{} & x-y \end{pmatrix} \quad \bar{E}V_2 = (x-y \quad -\sqrt{x^2 - y^2})$$

$$\mu_1 \quad (x-y \quad \sqrt{}) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = (\sqrt{} \quad x-y) \quad \beta_1^{(1)}, \beta_2^{(1)}$$

$$\mu_2 \quad (x-y \quad -\sqrt{}) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = (-\sqrt{} \quad x-y) \quad \beta_1^{(2)}, \beta_2^{(2)}$$

$$\hat{u}^{(1)} = \beta_1^{(1)} u + \beta_2^{(1)} v = \sqrt{x^2 - y^2} u + (x-y) v$$

$$D_1 = \sqrt{x^2 - y^2} \frac{\partial}{\partial x} + \frac{\partial}{\partial y}$$

$$\hat{u}^{(2)} = \beta_1^{(2)} u + \beta_2^{(2)} v = -\sqrt{x^2 - y^2} u + (x-y) v$$

$$D_2 = -\sqrt{x^2 - y^2} \frac{\partial}{\partial x} + \frac{\partial}{\partial y}$$

$$\hat{c}^{(1)} = \cancel{\lambda_1^{(1)} c_1} + \cancel{\lambda_2^{(1)} c_2} + (D_1 \beta_1) u + (D_1 \beta_2) v = \left\{ \left[\sqrt{x^2 - y^2} \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right] \sqrt{x^2 - y^2} \right\} u + \left\{ \left[\sqrt{x^2 - y^2} \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right] (x-y) \right\} v$$

$$\hat{c}^{(2)} = (D_1 \beta_1) u + (D_1 \beta_2) v = \left\{ \left[-\sqrt{x^2 - y^2} \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right] \sqrt{x^2 - y^2} \right\} u + \left\{ \left[-\sqrt{x^2 - y^2} \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right] (x-y) \right\} v$$

$$\begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix}_x + \begin{pmatrix} 1 & 0 \\ 2 & -1 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix}_y = \begin{pmatrix} -u \\ 1 - u^2 \end{pmatrix}$$

$$|A - \mu B| = \begin{vmatrix} 1-\mu & -1 \\ -2\mu & +\mu \end{vmatrix} = (1-\mu)\mu - 2\mu = 0 \quad -\mu^2 - \mu = 0 \quad \mu = 0 \text{ or } \mu = -1$$

$$\mu=0 \quad \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix} \quad (0 \quad -1) = \bar{E}V_1$$

$$\mu=-1 \quad \begin{pmatrix} 2 & -1 \\ 2 & -1 \end{pmatrix} \quad (1 \quad -1) = \bar{E}V_2$$

$$\mu=0 \quad (0 \quad 1) \begin{pmatrix} 1 & 0 \\ 2 & -1 \end{pmatrix} \quad (2 \quad -1) \quad \beta_1^{(1)} \beta_2^{(1)}$$

$$\mu=-1 \quad (1 \quad -1) \begin{pmatrix} 1 & 0 \\ 2 & -1 \end{pmatrix} \quad (-1 \quad 1) \quad \beta_1^{(2)} \beta_2^{(2)}$$

$$\hat{u}^{(1)} = \beta_1^{(1)} u + \beta_2^{(1)} v = 2u - v$$

$$D_1 = \frac{\partial}{\partial y}$$

$$\hat{u}^{(2)} = \beta_1^{(2)} u + \beta_2^{(2)} v = -u + v$$

$$D_2 = -\frac{\partial}{\partial x} + \frac{\partial}{\partial y}$$

$$\hat{c}^{(1)} = (D_1 \beta_1^{(1)}) u + (D_1 \beta_2^{(1)}) v + \lambda_1^{(1)} c_1 + \lambda_2^{(1)} c_2 = (1 - u^2)$$

$$\hat{c}^{(2)} = \quad \quad \quad + \lambda_1^{(2)} c_1 + \lambda_2^{(2)} c_2 = -u + 1 - u^2 = (-1 - u + u^2)$$

$$-u - 1 + u^2$$

H.W. Look at $W_{tt} = c^2(w_x) W_{xx}$

Change variables to put it into a system of 2 first order p.d.e.

Find characteristics & Riemann Invariants. Suggest method if $c = c(w_x, \epsilon x)$

Let $W_t = u$ $W_x = v$ then $W_{tx} = W_{xt}$ or $u_x - v_t = 0$ ①

$$W_{tt} - c^2(w_x) W_{xx} = 0 \Rightarrow u_t - c^2(v) v_x = 0$$

then
$$\begin{pmatrix} 1 & 0 \\ 0 & -c^2(v) \end{pmatrix} \begin{pmatrix} u_x \\ v_x \end{pmatrix} + \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} u_t \\ v_t \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

to find EV

$$\det |A - \mu B| = 0 \quad \det \begin{vmatrix} 1 & \mu \\ -\mu & -c^2(v) \end{vmatrix} = 0 \quad \text{or} \quad \mu = \pm c(v)$$

the EV are

for $\mu_1 = +c(v)$ on C_+ $(c(v) \ 1) \begin{pmatrix} 1 & c(v) \\ -c(v) & -c^2(v) \end{pmatrix} = (0 \ 0)$ $(c(v) \ 1) \quad \beta_1^{(1)} = 1, \beta_2^{(1)} = -c(v)$

for $\mu_2 = -c(v)$ on C_- $(-c(v) \ 1) \begin{pmatrix} 1 & -c(v) \\ c(v) & -c^2(v) \end{pmatrix} = (0 \ 0)$ $(-c(v) \ 1) \quad \beta_1^{(2)} = +1, \beta_2^{(2)} = +c(v)$

$\therefore D_1 = c(v) \frac{\partial}{\partial x} + \frac{\partial}{\partial t} \quad \hat{u}^{(1)} = u + cv \quad \text{since } c \neq c(x, t) \text{ then } \hat{c}^{(1)} = 0$

$D_2 = -c(v) \frac{\partial}{\partial x} + \frac{\partial}{\partial t} \quad \hat{u}^{(2)} = u + cv \quad \text{since } c \neq c(x, t) \text{ then } \hat{c}^{(2)} = 0$

or: $D_1 u - c D_1 v = 0$ on C_+
 $D_2 u + c D_2 v = 0$ on C_-

since $c = c(v)$ let $L(v) = \int_{v_0}^v c(z) dz$ where $v_0 = \text{const} \therefore DL(v) = c(v) Dv$

$\therefore$ on C_+ $\left. \begin{aligned} D_1 [u - L(v)] &= 0 \\ D_2 [u + L(v)] &= 0 \end{aligned} \right\} \begin{aligned} \text{on } C^+ \text{ let the const be } r \\ \text{on } C^- \text{ let the const be } s \end{aligned}$

$\therefore \begin{aligned} u - L(v) &= r & \text{on } C^+ \\ u + L(v) &= s & \text{on } C^- \end{aligned}$

In the case where $c = c(w_x, \epsilon x)$ we do the same as before i.e. $W_t = u$ $W_x = v$

then $u_x - v_t = 0$

& $u_t - c^2(v, \epsilon x) v_x = 0$ where $\epsilon x = \epsilon x$

again we write in matrix notation $A \underline{U}_x + B \underline{U}_t = 0$
and solve. Everything remains the same

i.e.

$$D_1 = c(v, \xi) \frac{\partial}{\partial x} + \frac{\partial}{\partial t}$$

$$\left. \begin{aligned} \hat{u}^{(1)} &= u - cv \\ \hat{u}^{(2)} &= u + cv \end{aligned} \right\} \text{ but } \hat{c}^{(1)} = D_1[-c(v, \xi)]v$$

$$D_2 = -c(v, \xi) \frac{\partial}{\partial x} + \frac{\partial}{\partial t}$$

$$\hat{c}^{(2)} = D_2[+c(v, \xi)]v$$

we can also write this as

$$D_1 u - c D_1 v = 0$$

$$D_2 u + c D_2 v = 0$$

now since $c = c(v, \xi)$ write the Taylor expansion about $\xi = 0$

$$\therefore c(v, \xi) = c(v, 0) + \frac{\partial c}{\partial \xi}(v, 0)\xi + O(\xi^2) \text{ terms; since } \xi \text{ is slowly varying}$$

neglect the terms of order ξ^2 or higher. Note that $\frac{d\xi}{dx} = \epsilon$ as small number.

now $c(v, 0)$ & $\frac{\partial c}{\partial \xi}(v, 0)$ are fns of v only

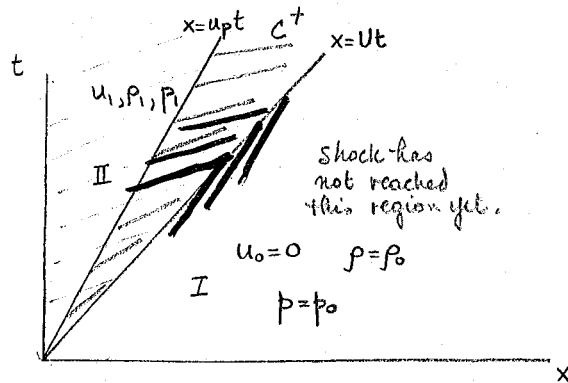
$$\therefore \text{ let } L_0(v) = \int_{v_0}^v c(z, 0) dz \quad \& \quad L_1(v) = \int_{v_0}^v \frac{\partial c}{\partial \xi}(z, 0) dz$$

then $D\{L_0 + \xi L_1\} = c(v, \xi) Dv$ for slowly varying ξ

$$\therefore u + [L_0 + \xi L_1](v) = s \text{ on } C^-$$

$$u - [L_0 + \xi L_1](v) = r \text{ on } C^+$$

Given: Ahead of shock $u=0$ $p=p_0$ $\rho=\rho_0$. The piston starts instantaneously from rest. $u_p > 0$ $u_p = \text{const.}$ Find U and the rest of unknowns behind shock and draw (t, x) diagram explaining solution.



in region 2 the velocity $u_1 = u_p < U$. This is due to the fact that the shock has passed this region and the velocity there is subsonic. By subsonic theory the data at a pt depends on the data at the piston i.e. $u_1 = u_p$.

from $(1-\mu^2)(U-u_0)^2 - (u_1-u_0)(U-u_0) = (1-\mu^2)c_0^2$

we find $U = u_p \left\{ \frac{1}{2(1-\mu^2)} + \sqrt{\left[\frac{1}{2(1-\mu^2)} \right]^2 + \left(\frac{c_0}{u_p} \right)^2} \right\}$

using $\rho_0(u_0 - U) = \rho_1(u_1 - U)$

we find $\rho_1 = \frac{\rho_0}{1 - u_p/U}$ where $U/u_p = \frac{1}{2(1-\mu^2)} \left\{ 1 + \sqrt{1 + \left(\frac{2c_0(1-\mu^2)}{u_p} \right)^2} \right\}$

using $m u_0 + p_0 = m u_1 + p_1$

we find $p_1 = p_0 - m u_1 = p_0 + \rho_0 u_p U = p_0 + \frac{\rho_0 u_p^2}{2(1-\mu^2)} \left\{ 1 + \sqrt{1 + \left(\frac{2c_0(1-\mu^2)}{u_p} \right)^2} \right\}$

note. I, II are simple wave regions since u, p, ρ are constant.

1. When $u_p = u_p(t)$ we had shown previously that the characteristics will intersect only when the piston accelerates in positive direction i.e. when $u_p'(t) > 0$
- ② If $u_p' > 0 \forall t$ then we would have compression waves and shock analysis would go through in same manner, i.e. where $c_0, u_p, U, u_0, u_1, p_1, p_0, \rho_1, \rho_0$ were written as constants they now become time dependent.
- ③ If $u_p' < 0 \forall t$ then we have rarefaction waves and no shock will form.
- ④ If $u_p = u_p(t)$ is such that $u_p'(t) > 0 \forall t < T_1$ and $u_p'(t) < 0 \forall t > T_1$

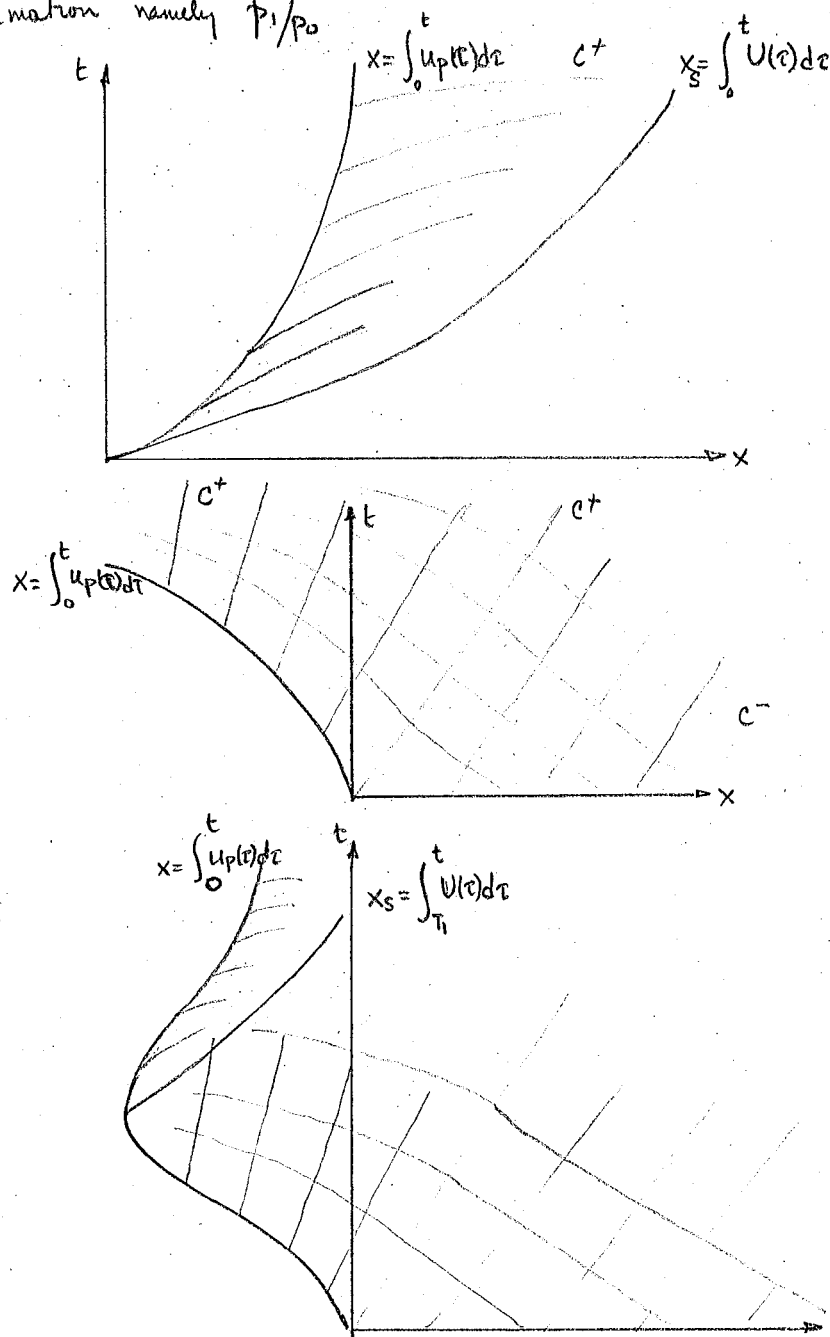
Then we can use the results of (a) to find out where shock occurred and all pertinent data.

If $u_p'(t) < 0 \quad \forall t < T_1$ and $u_p'(t) > 0 \quad \forall t > T_1$ then @ $t = T_1^+$
 where $u_p'(t) = 0^+$ is when first characteristic of converging nature
 will meet last characteristic of diverging nature, i.e. a rarefaction wave
 will intersect a compression wave.

Behind the shock all the values will be a fun of time and position (can be param wrt t)

Before " " " " " " " " " " " "

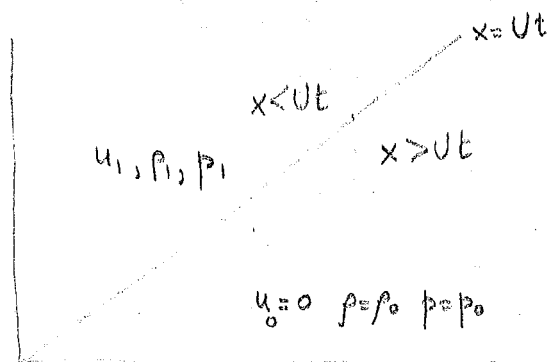
The shock strength can be defined by the pressure change due to shock formation namely p_1/p_0



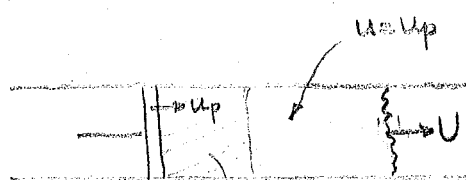
Ahead of the shock $u=0$ $\rho=\rho_0$ $p=p_0$

Piston starts instantaneously from rest $u_p > 0$ $u_p = \text{const}$

Find U & rest of unknowns behind shock & draw (t, x) diag explaining sol. look at case $u_p = u_p(t)$



make assumption that $u_1 = u_p$



if $u > u_p$ but $u < U$
then $\exists$ a time t_{oo} such that
 $p=0 \Rightarrow$ rarefaction waves this
is impossible. if $u < u_p$

that implies that piston will catch up the slower moving gas.

$$(U-u_0)^2 = c_0^2 + \frac{(u_1-u_0)^2}{1-\mu^2}$$

$$U = u_0 \pm \sqrt{c_0^2 + \frac{(u_1-u_0)^2}{1-\mu^2}} \quad u_0=0 \quad \therefore U = \sqrt{c_0^2 + \frac{u_p^2}{1-\mu^2}}$$

$$\mu^2 U^2 + (1-\mu^2)c_0^2 = \mu^2(u_1-U)^2$$

$$\mu^2 U^2 + (1-\mu^2)c_0^2 = -U(u_1-U) = +U^2 - Uu_1$$

$$U^2(\mu^2-1) + (1-\mu^2)c_0^2 + Uu_1 = 0$$

$$U^2 = \frac{u_1}{1-\mu^2} U \quad (1-\mu^2)c_0^2 =$$

$$U = \frac{u_p}{2(1-\mu^2)} + \sqrt{\frac{u_1^2}{4(1-\mu^2)^2} + c_0^2}$$

$$\mu^2(u_0-U)^2 + (1-\mu^2)c_0^2 = \mu^2(u_1-U)^2 + (1-\mu^2)c_1^2 = (u_0-U)(u_1-U)$$

$$(1-\mu^2)(U-u_0)^2 + (1-\mu^2)c_0^2 - (U-u_0)(u_1-U) = (U-u_0)^2$$

$$(1-\mu^2)(U-u_0)^2 = (1-\mu^2)c_0^2 + (U-u_0) \left[\frac{(U-u_0) + (u_1-U)}{(u_1-u_0)(U-u_0)} \right]$$

$$\rho_0(u_0 - U) = \rho_1(u_1 - U)$$

$$\frac{-\rho_0 U}{u_p - U} = \rho_1$$

$$\rho_1 = \frac{\rho_0 U}{U - u_p} = \frac{\rho_0}{1 - u_p/U} \quad \text{where}$$

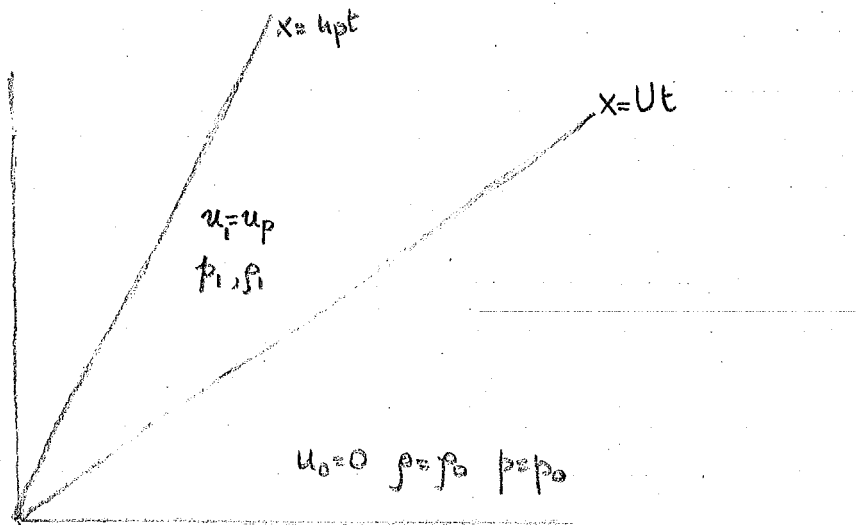
$$\frac{U}{u_p} = \frac{1}{2(1-\mu^2)} + \sqrt{\left(\frac{c_0}{u_p}\right)^2 + \frac{1}{4}\left(\frac{1}{1-\mu^2}\right)^2}$$

$$mu_0 - mu_1 + p_0 = p_1$$

$$m(u_0 - u_1) + p_0 = p_1$$

$$m = \rho_0 u_0 = \rho_0(u_0 - U) = -\rho_0 U$$

$$\therefore p_1 = p_0 - mu_1 = p_0 + \rho_0 u_p U = p_0 + \rho_0 u_p \left[\frac{u_p}{2(1-\mu^2)} + u_p \sqrt{\left(\frac{c_0}{u_p}\right)^2 + \frac{1}{4}\left(\frac{1}{1-\mu^2}\right)^2} \right]$$



Since $(1-\mu^2)(U-u_0)^2 - (u_1-u_0)(U-u_0) = (1-\mu^2)c_0^2$

then by $u_0=0$ $u_1=u_p$

$$U = \frac{u_p}{2(1-\mu^2)} + \sqrt{\left[\frac{u_p}{2(1-\mu^2)}\right]^2 + c_0^2}$$

Since $p_0(u_0-U) = p_1(u_p-U)$ then

$$p_1 = \frac{p_0}{1 - u_p/U} \quad \text{where} \quad \frac{U}{u_p} = \frac{1}{2(1-\mu^2)} + \sqrt{\left[\frac{1}{2(1-\mu^2)}\right]^2 + \left(\frac{c_0}{u_p}\right)^2}$$

also $mu_0 = mu_1 + p_0 = p_1$ then

$$p_1 = p_0 + p_0 u_p U = p_0 + p_0 \left\{ \frac{u_p^2}{2(1-\mu^2)} + u_p^2 \sqrt{\left[\frac{1}{2(1-\mu^2)}\right]^2 + \left(\frac{c_0}{u_p}\right)^2} \right\}$$

$$\begin{pmatrix} 1/c_0 & 1 \\ 1 & c_0 \end{pmatrix} \begin{pmatrix} [u_{tt}] \\ [u_t] \end{pmatrix} = \begin{pmatrix} [U_x^\circ] \\ c_0^2 [V_x^\circ] + 2c_0 c_y [v_t v_x] + \psi_u [u_t] \end{pmatrix}$$

$$\frac{1}{\sigma} = \frac{1}{\sigma_0} e^{-\int_0^x \Omega(s) ds}$$

$$c_0 [U_x^\circ]$$

$$\begin{aligned} P_x &= K_A A_x + K_x \\ P_t &= K_A A_t \end{aligned}$$

$$0 = c_0 [U_x^\circ] - c_0^2 [V_x^\circ] + 2c_0 c_y [v_t v_x] - \psi_u [u_t]$$

$$\frac{dK}{dA} A_x$$

$$[u_{tt}] = -c_0(x) [v_t] = \sigma(x)$$

$$[u_t]_x$$

$$[u_{xt}] = [U_x^\circ] - [T_{yx} u_{tt}]$$

$$P_x = \frac{P_t A_x + K_x}{A_t}$$

$$[U_x^\circ] = v_{tt} + T_x u_{tt} = [u_{xt}] + [T_x u_{tt}]$$

$$[U_x^\circ]_x = [u_t]_x + [T_x u_{tt}]$$

$$\frac{1}{\sigma} = \frac{\sigma_y}{[u_t]_x} = \sigma(x)$$

$$\frac{1}{\sigma} = \frac{A \sigma}{\sigma_L}$$

$$u_{tt} - c^2 v_{xt} - c_v^2 v_t v_x = \psi_u u_t$$

$$[u_t]_x = [u_{xt}] -$$

$$[U_x^\circ] = [u_{xt}] - [T_{yx} u_{tt}]$$

$$[V_x^\circ] = [v_{xt}] - [T_{yx} v_{tt}]$$

$$v_{xt} = u_{xv}$$

$$y = -\sigma_L A \sigma + \int A \sigma_L$$

$$y' = -A + \frac{\sigma_L'}{\sigma_L^2} \int A \sigma_L$$

$$[u_t]_x = \left(\frac{\sigma}{-c_0} \right)_x$$

$$\sigma_L' - \sigma_L^2 \Omega = 0$$

$$\sigma_L' = \sigma_L^2 \Omega$$

$$\sigma_L$$

$$y = \frac{\sigma_L'}{\sigma_L^2} \int A \sigma_L$$

$$-\Omega y = \frac{\sigma_L'}{\sigma_L^2} \int A \sigma_L$$

$$\frac{d}{dx} \int_x^\infty f(z) dz = f(x)$$

the set to Riccati eq gave

$$Q(x) = \exp \int_x^\infty \Omega(r) dr \quad Q_0 = \frac{1}{\mu_{\infty}}$$

$$\text{Lunar set } A \equiv 0 \Rightarrow Q(x) = Q_0 \exp \left(- \int_x^\infty \Omega(r) dr \right)$$

$$\frac{dQ(x)}{dx} \Big|_{x=0} = \left[1 - Q_0 \int_x^\infty A(r) \exp \left(- \int_r^\infty \Omega(s) ds \right) dr \right] \exp \left(- \int_x^\infty \Omega(r) dr \right) Q_0$$

$$\frac{(\text{denom}) (\mu_{\infty}) + \mu_{\infty} (Q_0 A(x) \exp \left(- \int_x^\infty \Omega(s) ds \right))}{1 - Q_0 \int_x^\infty A(r) \exp \left(- \int_r^\infty \Omega(s) ds \right) dr}$$

$$\left| Q_0 \int_x^\infty A(r) \exp \left(- \int_r^\infty \Omega(s) ds \right) dr \right| < \epsilon$$

$$\left| \int_x^\infty A(r) \exp \left(- \int_r^\infty \Omega(s) ds \right) dr \right| \geq |Q_0| \int_x^\infty |A(r)|$$

$$A(x) \exp \left(- \int_x^\infty \Omega(s) ds \right) = 0$$

Assume Q solves

$$Q' + Q(x)Q = 0$$

non-linear

$$Q' + Q(x)Q = A(x)^2$$

Suppose $Q(r)$ solves

then Q satisfies Riccati eq

is straightforward to prove

$$\Omega(x) Q = A(x)^2$$

$$Q = \frac{A(x)}{\Omega(x)}$$

$$A(x)$$

$$Q(x) = \frac{1 - \int_x^\infty A(r) Q(r) dr}{Q(x)}$$

$$\left| \frac{Q(x)}{Q(x)} - 1 \right| = \left| \frac{1 - \int_x^\infty A(r) Q(r) dr}{1} \right| < \epsilon$$

$$\left| \frac{1 - \int_x^\infty A(r) Q(r) dr}{\int_x^\infty A(r) Q(r) dr} \right| < \epsilon$$

1. Given: $v(x) = \frac{v_L(x)}{1 - \int_0^x A(r) v_L(r) dr}$ and $v_L(x) = v(0) \exp\left(-\int_0^x \Omega(s) ds\right)$

For $0 \leq x \leq y$ under what conditions is $v_L(x)$ a good approx to $v(x)$

we want the conditions $\Rightarrow \left| \frac{v(x)}{v_L(x)} - 1 \right| < \epsilon$ for $\epsilon > 0$ but small.

$$\left| \frac{v(x)}{v_L(x)} - 1 \right| = \left| \frac{1}{1 - \int_0^x A(r) v_L(r) dr} - 1 \right| = \left| \frac{\int_0^x A(r) v_L(r) dr}{1 - \int_0^x A(r) v_L(r) dr} \right| < \epsilon$$

$$\left| \int_0^x A(r) v_L(r) dr \right| < \epsilon \left| 1 - \int_0^x A(r) v_L(r) dr \right| \leq \epsilon + \epsilon \left| \int_0^x A(r) v_L(r) dr \right|$$

or $\left| \int_0^x A(r) v_L(r) dr \right| \leq \frac{\epsilon}{1-\epsilon} \quad \forall x \in [0, y]$

In other words, if we were given $v_L(x)$, then $\forall A(x)$ $\Rightarrow$ the integral condition is satisfied then v/v_L approximates 1 to a tolerance of ϵ .

2. $A_t + (Au)_x = 0$ propagating into $A = A_0(x) \quad u = 0$
 $A(u_t + uu_x) + p_x = -\nu u$
 $p = K(A, x)$

$$\left. \begin{aligned} p_t &= K_A A_t + K_x x_t \\ p_x &= K_A A_x + K_x \end{aligned} \right\} \quad p_t + u p_x = -K_A A u_x + K_x (u + x_t)$$

Since x, t are independent variables $x_t = 0$

$$\therefore \quad \begin{aligned} p_t + u p_x + K_A A u_x &= u K_x \\ u_t + u u_x + p_x/A &= -\nu u/A \end{aligned} \quad (1)$$

Define $G(x, \alpha) = g(x, t)$

where $G_{,x} = g_{,x} + g_{,t} T_{,x}$ and $t = T(x, \alpha)$ is the arrival time

then we can rewrite (1) as

$$\begin{aligned} p_t (1 - u T_x) - K_A A T_x u_t &= u K_x - K_A A u_x - u p_x \\ p_t \left(-\frac{T_x}{A}\right) + (1 - u T_x) u_t &= -\frac{\nu u}{A} - \frac{p_x}{A} - u u_x \end{aligned}$$

taking jumps and noting the right hand side of eqs. to be continuous

$$\begin{pmatrix} 1 - uT_x & -K_A A T_x \\ -\frac{1}{A} T_x & 1 - uT_x \end{pmatrix} \begin{pmatrix} [p_t] \\ [u_t] \end{pmatrix} = 0 \quad (2)$$

$$\text{and } (1 - uT_x)^2 + K_A T_x^2 = 0 \quad \text{or } (1 - uT_x) = \pm \sqrt{K_A} T_x$$

$$\text{and } T_x = \frac{1}{u \pm \sqrt{K_A}} ; \quad \text{take } T_x = \frac{1}{u + \sqrt{K_A}} ; \text{ ahead of front } T_x = \frac{1}{\sqrt{K_A}}$$

from (2) one obtains that $[u_t] = \frac{1}{A_0 \sqrt{K_A}} [p_t]$ strength of acceleration front.

now differentiating (1) wrt t and taking jumps gives

$$\begin{pmatrix} 1 - uT_x & -K_A A T_x \\ -\frac{1}{A} T_x & 1 - uT_x \end{pmatrix} \begin{pmatrix} [p_{tt}] \\ [u_{tt}] \end{pmatrix} = \begin{pmatrix} -[u_t p_x] - [u p_x'] - [(K_{AA} A + K_A) A_t u_x] - [K_A A u_x'] + [K_x u_t] + [u K_{xt}] \\ -[u_t u_x] - [u u_x'] - [p_x' / A] + [p_x A_t / A^2] - [\frac{\nu u_t}{A}] + [\frac{\nu u A_t}{A^2}] \end{pmatrix} \quad (3)$$

multiply 1st eq by $\frac{1}{A_0 \sqrt{K_A}}$ and evaluate @ head of front ($u=0, A=A_0(x)$) making use of

$$\frac{A_t}{A} (p_x / A + \frac{\nu u}{A}) = \left(\frac{A_t}{A} \right)_x (u_t + u u_x) \quad \text{and} \quad u_t (K_x - p_x) = - (u_t K_A A_x). \quad \text{Then (3) leads to}$$

$$0 = \frac{1}{A_0 \sqrt{K_A}} \left\{ [u_t K_A A_0'] - [K_A A_0 u_x'] - [(K_{AA} A_0^2 + K_A A_0) u_x^2] \right\} + [p_x' / A_0] - [\frac{\nu u_t}{A_0}]$$

$$\text{but } [u_x'] = [u_t]_x - T_x [u_t]_t \stackrel{\circ}{=} \quad \text{and } [u_x^2] = [u_x']^2 - 2 T_x [u_x u_t] + T_x^2 [u_t^2] \\ = -T_x^2 [u_t]^2 + 2 T_x [u_t] u_t \stackrel{\circ}{=} -T_x^2 [u_t]^2 = -\frac{1}{K_A} [u_t]^2$$

$$\text{also } [p_x'] = [p_t]_x - T_x [p_t]_t \stackrel{\circ}{=} (A_0 \sqrt{K_A} [u_t])_x$$

$$\text{Thus } 0 = K_A^2 A_0' [u_t] - K_A^2 A_0 [u_t]_x + (K_{AA} A_0^2 + K_A A_0) [u_t]^2 - A_0 K_A \sqrt{K_A} \left\{ \frac{1}{A_0} \left((A_0 \sqrt{K_A} [u_t])_x + \nu [u_t] \right) \right\}$$

and one obtains the Riccati eq

$$-2 K_A^2 A_0 [u_t]_x - \left(\frac{A_0 K_A (K_A)'}{2} + K_A \sqrt{K_A} \nu \right) [u_t] + (K_{AA} A_0^2 + K_A A_0) [u_t]^2 = 0$$

$$\text{or } [u_t]_x + \left(\frac{(K_A)'}{4 K_A} + \frac{\nu \sqrt{K_A}}{2 K_A A_0} \right) [u_t] - \left(\frac{K_{AA} A_0}{2 K_A^2} + \frac{1}{2 K_A} \right) [u_t]^2 = 0$$

Let $\Omega(x) = Lr^{-1} + Ls^{-1}$ where $Lr = \frac{4K_A}{(K_A)'}$ $Ls = \frac{2K_A A_0}{\sqrt{K_A}}$

$$A(x) = \left(\frac{K_{AA} A_0 + K_A}{2K_A^2} \right)$$

$$[u_t]^x = \frac{[u_t]^0 \exp\left(-\int_0^x \Omega(s) ds\right)}{1 - [u_t]^0 \left\{ \int_0^x A(r) \exp\left(-\int_0^r \Omega(s) ds\right) dr \right\}}$$

where $[u_t]^x$ is the strength at position x , and $[u_t]^0$ is the strength @ $x=0$.



* P



$$A_t + (Au)_x = 0 \rightarrow A_t + Au_x + A_x u = 0 \Rightarrow A_t + uA_x = -Au_x$$

$$A(u_t + uu_x) + p_x = -\gamma u$$

$$p = K(A, x)$$

$$p_t = K_A A_t + K_x x_t \stackrel{0}{=} 0$$

$$p_x = K_A A_x + K_x \rightarrow up_x + p_t = K_A [A_t + uA_x] + uK_x$$

$$p_t + up_x + K_A A u_x = uK_x$$

$$u_t + uu_x + p_x/A = -\frac{\gamma u}{A}$$

now make change of variables to (x, α) i.e. for any $G(x, \alpha) = g(x, t)$

$$\text{then } G_{,x} = g_x + g_t t_x$$

$$t_x = \frac{\partial}{\partial x} (T(x, \alpha)) = T_x$$

Change all x deriv of g to x deriv of G

$$\therefore g_x = G_x - g_t T_x$$

$$p_t + u p_x - u p_t T_x + K_A A u_x - K_A A T_x u_t = u K_x$$

$$u_t + u u_x - u u_t T_x + \frac{1}{A} (p_x - p_t T_x) = -\frac{\gamma u}{A}$$

$$\text{or } p_t (1 - u T_x) + u_t (-K_A A T_x) = u(K_x - p_x) - K_A A u_x$$

$$p_t (-\frac{T_x}{A}) + u_t (1 - u T_x) = -u(\frac{\gamma}{A} + u_x) - \frac{p_x}{A}$$

now take jumps

$$\text{Characteristic Condition } \begin{pmatrix} 1 - u T_x & -K_A A T_x \\ -T_x/A & 1 - u T_x \end{pmatrix} \begin{pmatrix} [p_t] \\ [u_t] \end{pmatrix} = 0$$

since all are const wrt x

this gives rise to $T_x = \frac{1}{u \pm \sqrt{K_A}}$ as the EV of the matrix; take $+\sqrt{}$ for wave to right

now differentiate original eq wrt t and transform to (x, α) coord.

$$\begin{cases} 1 - u T_x = \frac{\sqrt{K_A}}{u + \sqrt{K_A}} & \frac{\sqrt{K_A}}{u + \sqrt{K_A}} [p_t] - \frac{K_A A}{u + \sqrt{K_A}} [u_t] = 0 \\ \text{or } [u_t] = \frac{1}{A \sqrt{K_A}} [p_t] \end{cases} \text{ strength of the acceleration front.}$$

$$p_{tt} + u_t p_x + u p_{xt} + K_{At} A u_x + K_A A_t u_x + K_A A u_{xt} = u_t K_x + u K_{xt}$$

$$u_{tt} + u_t u_x + u u_{xt} + p_{xt}/A - \frac{p_x}{A^2} A_t = -\frac{\gamma u_t}{A} + \frac{\gamma u}{A^2} A_t$$

$$p_{tt} - u T_x p_{tt} - K_A A T_x u_{tt} = -u_t p_x - u p_x' - K_{At} A u_x - K_A A_t u_x - K_A A u_x' + u_t K_x + u K_x'$$

$$u_{tt} - u T_x u_{tt} - \frac{T_x}{A} p_{tt} = -u_t u_x - u u_x' - \frac{p_x}{A} + \frac{p_x}{A^2} A_t - \frac{\gamma u_t}{A} + \frac{\gamma u}{A^2} A_t$$

$$\begin{matrix} 1 \\ 2 \end{matrix} \begin{pmatrix} 1 - uT_x & -K_A A T_x \\ -T_x/A & 1 - uT_x \end{pmatrix} \begin{pmatrix} [p_t] \\ [u_t] \end{pmatrix} = \begin{pmatrix} -[u_t p_x] - u[P_x^*] - (K_{AA}A + K_A)[A_t u_x] - K_A A [U_x^*] + K_x [u_t] + u[K_x t] \\ -[u_t u_x] - u[U_x^*] - \frac{1}{A} [P_x^*] + \frac{1}{A^2} [p_x A_t] - \frac{\gamma}{A} [u_t] + \frac{\gamma u}{A^2} A_t \end{pmatrix}$$

mult 1 by $\frac{1}{A\sqrt{K_A}} \therefore$

$$0 = \frac{1}{A\sqrt{K_A}} \left\{ -[u_t p_x] - [u P_x^*] - [(K_{AA}A + K_A) A_t u_x] - [K_A A U_x^*] + [K_x u_t] + [u K_x t] - [u_t u_x] - [u U_x^*] - [P_x^*/A] + [\frac{1}{A^2} p_x A_t] - [\frac{\gamma}{A} u_t] + [\frac{\gamma u}{A^2} A_t] \right\}$$

$$[u_t p_x] = [u_t (p_x - T_x p_t)] = [u_t p_x] - T_x [u_t p_t]$$

note also $\frac{A_t}{A} (p_x/A + \frac{\gamma u}{A}) = -\frac{A_t}{A} (u_t + u u_x) \quad \& \quad A_t = -(Au)_x$

$$p_x = -\gamma u - A(u_t + u u_x)$$

$$\therefore \left[\frac{A_t}{A} (p_x/A + \frac{\gamma u}{A}) \right] = \left[\frac{(Au)_x}{A} (u_t + u u_x) \right] = \left[\frac{(Au)_x u_t}{A} \right] = [u_x u_t] + \left[\frac{u A_x u_t}{A} \right]$$

$$\therefore -[u_t u_x] + \left[\frac{1}{A^2} p_x A_t \right] + \left[\frac{\gamma u A_t}{A^2} \right] = \left[\frac{u A_x u_t}{A} \right]$$

$$A_t u_x = -(Au)_x u_x = -(A u_x^2 + u A_x u_x)$$

$$[u_t (K_x - p_x)] = -[u_t K_A A_x]$$

$$0 = \frac{1}{A\sqrt{K_A}} \left\{ [u_t K_A A_x] - [u P_x^*] - [K_A A U_x^*] + [u (Au)_x K_{Ax}] - [(K_{AA}A + K_A)(Au)_x u_x] + \left[\frac{u A_x u_t}{A} \right] - [u U_x^*] - [P_x^*/A] - \left[\frac{\gamma}{A} u_t \right] \right\}$$

$$\frac{(K_A)_x}{K_A}$$

Evaluated in front of front

$$0 = \frac{1}{A_0 \sqrt{K_A}} \left\{ K_A A_0' [u_t] - K_A A_0 [u_t]_x - [(K_{AA} A_0^2 + K_A A_0) u_x^2]^* \right\} \\ - \frac{1}{A_0} \left(A_0 \sqrt{K_A} [u_t] \right)_x - \frac{\nu}{A_0} [u_t]$$

$$[u_x^2]^* = -T_x [u_t]^2 = -\frac{1}{K_A} [u_t]^2 \quad \text{since } [u_x] = -[u_x]^2 + 2[u_x] u_{x+} \rightarrow 0 \text{ since } u=0 \text{ at wave front}$$

$$\left\{ K_A A_0' [u_t] - K_A A_0 [u_t]_x + (K_{AA} A_0^2 + K_A A_0) \frac{1}{K_A} [u_t]^2 \right\} \\ - \sqrt{K_A} (A_0 \sqrt{K_A} [u_t])_x - \sqrt{K_A} \nu [u_t] = 0$$

$$\cancel{(K_{AA} A_0^2 - \sqrt{K_A} \nu) [u_t]} \quad A_0' \sqrt{K_A} [u_t] + A_0 (\sqrt{K_A})_x [u_t] + A_0 \sqrt{K_A} [u_t]_x \\ \frac{1}{2\sqrt{K_A}} \frac{K_{AA} A_0' + K_{AX}}{A_0 \sqrt{K_A} [u_t]} \frac{(K_A)_x}{2\sqrt{K_A}}$$

$$\cancel{K_A^2 A_0' [u_t]} - \cancel{K_A^2 A_0 [u_t]_x} + (K_{AA} A_0^2 + K_A A_0) [u_t]^2 - \cancel{A_0' K_A^2 [u_t]} \\ - \frac{A_0 K_A}{2} (K_{AA} A_0' + K_{AX}) [u_t] - A_0 K_A^2 [u_t]_x - \sqrt{K_A} K_A \nu [u_t] = 0$$

$$- 2 K_A^2 A_0 [u_t]_x + \left[\frac{A_0 K_A}{2} (K_{AA} A_0' + K_{AX}) + K_A^{\frac{3}{2}} \nu \right] [u_t] + (K_{AA} A_0^2 + K_A A_0) [u_t]^2 = 0 \\ \frac{[u_t]_x}{[u_t]^2} + \left[\frac{A_0 K_A (K_{AA} A_0' + K_{AX}) + 2 K_A^{\frac{3}{2}} \nu}{4 K_A^2 A_0} \right] \frac{1}{[u_t]} - \frac{(K_{AA} A_0^2 + K_A A_0)}{2 K_A^2 A_0} = 0$$

$$\Omega(x) = \left(\frac{K_{AA} A_0' + K_{AX}}{4 K_A} \right) + \frac{\nu}{2 K_A^{\frac{3}{2}} A_0} = \frac{(K_A)_x}{4 K_A} + \frac{\nu}{2 K_A^{\frac{3}{2}} A_0}$$

$$L_r = \frac{4 K_A}{(K_A)_x} \quad L_g = \frac{2 K_A^{\frac{3}{2}} A_0}{\nu}$$

$$A(x) = - \left(\frac{K_{AA} A_0^2 + K_A A_0}{2 K_A^2 A_0} \right)$$

$$\text{Solution is } [u_t] = \frac{[u_t]_0 \exp \left(\int_0^x \Omega(s) ds \right)}{1 - [u_t]_0 \int_0^x A(r) \exp \left(\int_0^r \Omega(s) ds \right) dr}$$

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$$\bar{u}_t - c^2(\bar{x}) \bar{v}_x = 0$$

(1)

$$\bar{v}_t - \bar{u}_x = 0 \quad \text{with} \quad u(0, \frac{\bar{t}\bar{c}}{L_s}) = f(\frac{\bar{t}}{\tau_p})$$

$$\omega = \frac{L_s}{\tau_p c} \gg \quad \text{or} \quad \frac{L_s}{c} \gg \tau_p$$

i.e. $\min(\frac{L_s}{c}) \gg \tau_p \quad x \in [0, y]$; suppose this occurs @ $x = x^*$

then let $L_s(x^*) = L^0$ & $c(x^*) = c_0$

then $\min L_s \leq L^0$ and $\max c \geq c_0$

$\therefore \frac{L^0}{c_0} \gg \frac{\min L_s}{\max c}$; take as condition on ω to be

$$\frac{\min L_s}{\max c} = \frac{L}{c} \gg \tau_p.$$

Normalize wrt L and non dim $(\bar{x}, \bar{t})$ wrt $(L, \bar{c})$

let $u = \bar{u}/u_0$, $v = \bar{v}/u_0$, $t = \bar{t}\bar{c}/L$, $x = \bar{x}/L$

then (1) becomes

$$u_t - \frac{c^2(x, L)}{c^2} v_x = 0$$

$$v_t - u_x = 0 \quad \text{with} \quad u(0, t) = f(\omega t)$$

or

$$\begin{pmatrix} u \\ v \end{pmatrix}_t + \begin{pmatrix} 0 & -\delta^2 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix}_x = 0 \quad \text{where} \quad \delta(x) = \frac{c(x, L)}{c}$$

Characteristic Condition leads to $2 \pm V: \pm \delta$ pick $+\delta$

the right EV becomes $\underline{r} = \begin{pmatrix} 1 \\ -1/\delta \end{pmatrix}$

the left EV becomes $\underline{l} = \begin{pmatrix} 1 & -\delta \end{pmatrix}$

the characteristic $\frac{dt}{dx} = \frac{1}{\delta(x)}$ and $x = t - \int_0^x \frac{ds}{\delta(s)} \quad \therefore \beta = \omega \alpha$

the solution to this problem is $U^{(0)}(x) = \underline{r} \underline{\sigma}_L$ where

σ_L solves $\sigma_L' + \Omega \sigma_L = 0$ & $\Omega = \frac{L \cdot x}{L \cdot x'} = \frac{-dc/dx}{2c}$

$$\therefore \sigma_L(x) = \sigma(0) \exp\left(-\int_0^x \frac{dc}{2c}\right) = f(\beta) \exp\left[\frac{1}{2} \ln c(x) - \frac{1}{2} \ln c(0)\right] = f(\beta) \left\{\frac{c(x)}{c(0)}\right\}^{1/2}$$

Let $\delta = c(x)/c(0)$

$$\therefore \tilde{U}^{(0)} = f(\beta) \delta^{1/2} \begin{pmatrix} 1 \\ -1/\delta \end{pmatrix} = \begin{pmatrix} U^0 \\ V^0 \end{pmatrix}$$

rewriting the equations we find

self adjoint

$$\left. \begin{aligned} U_\beta + \delta V_\beta &= \frac{\delta^2}{\omega} V_x \\ U_\beta + \delta V_\beta &= \frac{\delta}{\omega} U_x \\ \frac{\delta}{\omega} U_x &= \frac{\delta^2}{\omega} V_x \end{aligned} \right\} = \begin{cases} U^{(n+1)} + \delta V^{(n+1)} = \frac{\delta^2}{\omega} V_x^{(n)} \\ U^{(n+1)} + \delta V^{(n+1)} = \frac{\delta}{\omega} U_x^{(n)} \\ U_x^{(n)} = \delta V_x^{(n)} \end{cases}$$

one finds that

$$U^{(1)} + \delta V^{(1)} = \frac{\delta^2}{\omega} V_x^{(0)}$$

$$U^{(1)} + \delta V^{(1)} = \frac{\delta}{\omega} U_x^{(0)} = \frac{\delta}{\omega} \frac{d}{dx} (f(\beta) \delta^{1/2}) = \frac{\delta}{\omega} f(\beta) \delta^{1/2} \frac{\delta_x}{2\delta}$$

$$U_x^{(1)} = \delta V_x^{(1)}$$

then

$$U^{(1)} + \delta V^{(1)} = \frac{\delta_x}{2\omega} f(\beta) \delta^{1/2}$$

$$\& U_x^{(1)} = \delta V_x^{(1)}$$

$$\Rightarrow \left. \begin{aligned} U^{(1)} - \frac{2\delta}{\delta_x} U_x^{(1)} &= Z(x) - \frac{\delta}{\delta_x} \frac{d}{dx} Z(x) \\ \& U_x^{(1)} &= \delta V_x^{(1)} \end{aligned} \right\} \Rightarrow$$

where $Z(x) = \frac{\delta_x}{2\omega} f(\beta) \delta^{1/2}$

$$U^{(1)} = Z(x) + \text{const} \quad \text{where } U^{(1)}(0) = 0 \quad \therefore \text{const} = -Z(0)$$

$$\therefore U^{(1)} = Z(x) - Z(0)$$

and
$$V^{(1)} = \frac{1}{\omega} f(\beta) \delta^{1/2} \frac{\delta_x}{2\delta} - \frac{U^{(1)}}{\delta} = \frac{1}{\delta} \{Z(x) - Z(0) + Z(0)\} = \frac{Z(0)}{\delta}$$

$$\therefore \tilde{U}^{(1)} = Z(x) \begin{pmatrix} 1 \\ 0 \end{pmatrix} - Z(0) \begin{pmatrix} 1 \\ -1/\delta \end{pmatrix} \quad \& \quad Z(x) = \frac{\delta_x}{2\omega} f(\beta) \delta^{1/2}$$

$$\therefore \tilde{u} = \tilde{U}^{(0)} + \frac{h_1(\beta)}{\omega} U^{(1)}$$

$$\bar{u}_t - c^2(x) \bar{v}_x = 0$$

$$\bar{v}_t - \bar{u}_x = 0 \quad \text{with } u(0, \bar{t}) = f(\omega \bar{t})$$

(1)

$$\omega = \frac{L_s}{\tau_p c} \gg 1 \quad \text{or} \quad \frac{L_s}{c} \gg \tau_p$$

i.e. $\min(\frac{L_s}{c}) \gg \tau_p \quad x \in [0, y]$; suppose this occurs @ $x = x^*$

then let $L_s(x^*) = L^0$ & $c(x^*) = c_0$

then $\min L_s \leq L^0$ and $\max c \geq c_0$

$\therefore \frac{L^0}{c_0} \geq \frac{\min L_s}{\max c}$; take as condition on ω to be

$$\frac{\min L_s}{\max c} = \frac{L_s}{c} \gg \tau_p.$$

normalize wrt L_s and non dim (x, t) wrt $(L_s \& \bar{c})$

$$\text{let } u = \bar{u}/u_0 \quad v = \bar{v}/u_0 \quad t = \bar{t} \bar{c}/L_s \quad x = \bar{x}/L_s$$

Then (1) becomes

$$u_t - \frac{c^2(x L_s)}{\bar{c}^2} v_x = 0$$

$$v_t - u_x = 0 \quad \text{with } u(0, \frac{L_s}{\bar{c}} t) = f(\frac{L_s}{\bar{c}^2 \tau_p} t)$$

$$\text{or} \quad \begin{pmatrix} u \\ v \end{pmatrix}_t + \begin{pmatrix} 0 & -c^2/\bar{c}^2 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix}_x = 0 \quad \text{where } c = c(x L_s)$$

Characteristic condition leads to 2 EV: $\pm c/\bar{c}$ pick $c/\bar{c}$

then

$$\alpha = t - \int_0^x \frac{\bar{c} d\bar{s}}{c(\bar{s} L_s)} \quad \& \quad \beta = \omega \left(t - \int_0^x \frac{\bar{c} d\bar{s}}{c(\bar{s} L_s)} \right)$$

$$\text{the right EV becomes } \underline{\Gamma} = \begin{pmatrix} 1 \\ -\bar{c}/c \end{pmatrix}$$

$$\text{the left EV becomes } \underline{\ell} = \begin{pmatrix} 1 & -c/\bar{c} \end{pmatrix}$$

$$\Omega = \frac{\underline{\ell} \cdot \underline{\Gamma}'}{\underline{\ell} \cdot \underline{\ell}} = \frac{(1 \quad -c/\bar{c}) \begin{pmatrix} 0 \\ \frac{\bar{c} c'}{\bar{c}^2} L_s \end{pmatrix}}{(1 \quad -c/\bar{c}) \begin{pmatrix} 1 \\ -\bar{c}/c \end{pmatrix}} = \frac{-\frac{c'}{2\bar{c}} L_s}{L_s} = -\frac{c'}{2\bar{c}}$$

$$\text{where } L_s = -\frac{2\bar{c}}{c'}$$

$$\text{and } \underline{\Gamma}'(x) + \Omega(x) \underline{\Gamma}(x) = 0$$

$$U^{(0)} - \frac{2\gamma}{\gamma_x} U_x^{(0)} = 0 \quad \therefore U_x^{(0)} = U^{(0)} \frac{\gamma_x}{2\gamma} = f(\beta) \delta^{1/2} \frac{\gamma_x}{2\gamma}$$

$$U^{(1)} + \gamma V^{(1)} = \frac{\gamma_x}{\omega} f(\beta) \delta^{1/2} \frac{\gamma_x}{2\gamma} = \frac{\gamma_x}{2\omega} f(\beta) \delta^{1/2}$$

$$U^{(1)} + \gamma V^{(1)} = \frac{\gamma_x}{2\omega} f(\beta) \delta^{1/2}$$

$$\text{d } U_x^{(1)} = \gamma V_x^{(1)}$$

$$U_x^{(1)} + \gamma_x V^{(1)} + \gamma V_x^{(1)} = \frac{d}{dx} \left\{ \frac{\gamma_x}{2\omega} f(\beta) \delta^{1/2} \right\}$$

$$2U_x^{(1)} + \gamma_x V^{(1)} = \frac{d}{dx} \left\{ \frac{\gamma_x}{2\omega} f(\beta) \delta^{1/2} \right\}$$

$$\gamma V^{(1)} = -\frac{2U_x^{(1)}}{\gamma_x} + \frac{\gamma}{\gamma_x} \frac{d}{dx} \left\{ \frac{\gamma_x}{2\omega} f(\beta) \delta^{1/2} \right\}$$

$$U^{(1)} - \frac{2\gamma}{\gamma_x} U_x^{(1)} + \frac{\gamma}{\gamma_x} \frac{d}{dx} \left\{ \frac{\gamma_x}{2\omega} f(\beta) \delta^{1/2} \right\} = \frac{\gamma_x}{2\omega} f(\beta) \delta^{1/2}$$

$$\text{with } U^{(1)}(0) = 0 \quad \frac{\gamma}{\gamma_x} \frac{d}{dx} Z(x) = Z(x)$$

$$U^{(1)} - \frac{2\gamma}{\gamma_x} U_x^{(1)} = Z(x) - \frac{\gamma}{\gamma_x} \frac{d}{dx} Z(x)$$

$$\text{let } U^{(1)} = Z(x) + C \quad U^{(1)} = Z(x) - Z(0)$$

$$U^{(1)} + \gamma V^{(1)} = \frac{\gamma_x}{\omega} f(\beta) \delta^{1/2} \frac{\gamma_x}{2\gamma} = \frac{U^{(1)}}{\gamma}$$

$$V^{(1)} = \frac{Z(x)}{\gamma} - \frac{U^{(1)}}{\gamma} = \frac{1}{\gamma} (Z - Z + Z_0)$$

$$\therefore U^{(1)} = \begin{pmatrix} Z(x) - Z(0) \\ Z(0) \end{pmatrix} = Z(x) \begin{pmatrix} 1 \\ 0 \end{pmatrix} - \begin{pmatrix} 1 \\ -\gamma \end{pmatrix} Z(0)$$

$$\therefore U^0 = \gamma(x) a_\mu(x) = f(\beta) \left(\frac{1}{c} \right) \exp \left(- \int_0^x \frac{1}{L(x)} dx \right)$$

$$U^0 = f(\beta) \left(-\frac{1}{c} \right) \exp \left(+ \int_0^x \frac{dc}{2c} \right) = f(\beta) \left(-\frac{1}{y} \right) \delta y$$

$$= f(\beta) \left(-\frac{1}{\gamma}\right) \delta^{\frac{1}{2}} \quad \text{where } \gamma = c/c \quad \& \quad \delta = c/c(0)$$

$$\frac{1}{2} \delta^{-1/2} \cdot \frac{C' L_s}{C(0)}$$

$$(C_0 I - A_0) \underline{U}^{(n+1)} = \underline{B_0} \underline{U}^{(n)} - \underline{A_0} \underline{U}_x^n$$

$$\left[\begin{pmatrix} \gamma & 0 \\ 0 & \gamma \end{pmatrix} - \begin{pmatrix} 0 & -\gamma^2 \\ 1 & 0 \end{pmatrix} \right] = \begin{pmatrix} \gamma & \gamma^2 \\ 1 & \gamma \end{pmatrix} \sim U^{(2)} = -\gamma \begin{pmatrix} 0 & -\gamma^2 \\ -1 & 0 \end{pmatrix} \sim U^\dagger$$

$$d \quad \ell A_0 U_x^{n+1} = 0$$

$$U_x^{(0)} = \frac{d}{dx} f(\beta) \left[\delta^{\frac{1}{2}} \begin{pmatrix} 1 \\ -\frac{1}{8} \end{pmatrix} \right] + f(\beta) \left[\frac{d}{dx} \delta^{\frac{1}{2}} \right] \begin{pmatrix} 1 \\ -\frac{1}{8} \end{pmatrix} + f(\beta) \delta^{\frac{1}{2}} \frac{d}{dx} \begin{pmatrix} 1 \\ -\frac{1}{8} \end{pmatrix}$$

$$= \cancel{\frac{d}{d\beta}} f'(\beta) \left(-\frac{\omega}{\delta} \right) \delta^{\frac{1}{2}} \begin{pmatrix} 1 \\ -\frac{1}{8} \end{pmatrix} + f(\beta) \frac{\delta^{-\frac{1}{2}}}{2} c' \underline{L} \begin{pmatrix} 1 \\ -\frac{1}{8} \end{pmatrix} + f(\beta) \delta^{\frac{1}{2}} \begin{pmatrix} 0 \\ \frac{d\delta/dx}{\delta^2} \end{pmatrix}$$

$$U_x^{(0)} = U^{(0)} \frac{\delta x}{2\delta}$$

$$(1 - \delta^2) \begin{pmatrix} 0 & -\delta^2 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} \delta & \\ & -\delta \end{pmatrix} (\delta \quad -\delta^2)$$

(0)
u x

$$U^{(0)} = f(\beta) \delta^{1/2}$$

$$U_x^{(0)} = \delta^{1/2} f'(\beta) \beta_x + f(\beta) \frac{1}{2} \delta^{-1/2} \delta_x$$

$$U = U_0 \left(\frac{c}{c_0} \right)^{1/2} f(\beta) \left(-\frac{1}{\delta} \right) \delta^{1/2}$$

$$U^{(0)}$$

$$45. (c_0 I - A_0) \underline{U}_\beta = \frac{c_0}{w} A_0 \underline{U}_x$$

$$\frac{U}{U_x} = \frac{12\gamma}{\omega x} \quad \text{where } C_0 = \gamma(x) \quad \frac{U}{U_0} = \left[\frac{\gamma(x)}{\gamma(0)} \right]^{\frac{1}{2}} \begin{pmatrix} \gamma + \gamma^2 \\ \gamma \end{pmatrix} \begin{pmatrix} U_\beta \\ V_\beta \end{pmatrix} = -\frac{\gamma}{\omega} \begin{pmatrix} 0 & -\gamma^2 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} U_x \\ V_x \end{pmatrix}$$

$$U = \frac{U_x^2 + U_y^2}{2} = \frac{1}{2} \omega^2 r^2$$

$$U_\beta + \gamma \dot{V}_\beta = \frac{\gamma}{w} U_x$$

$$V = -2U_x$$

with Camp

$$\gamma/\omega U_x = \gamma^2/\omega V_x$$

$$U_x + \gamma_x V + \gamma V_x = 0$$

$$U^{n+1} + \gamma V^{n+1}$$

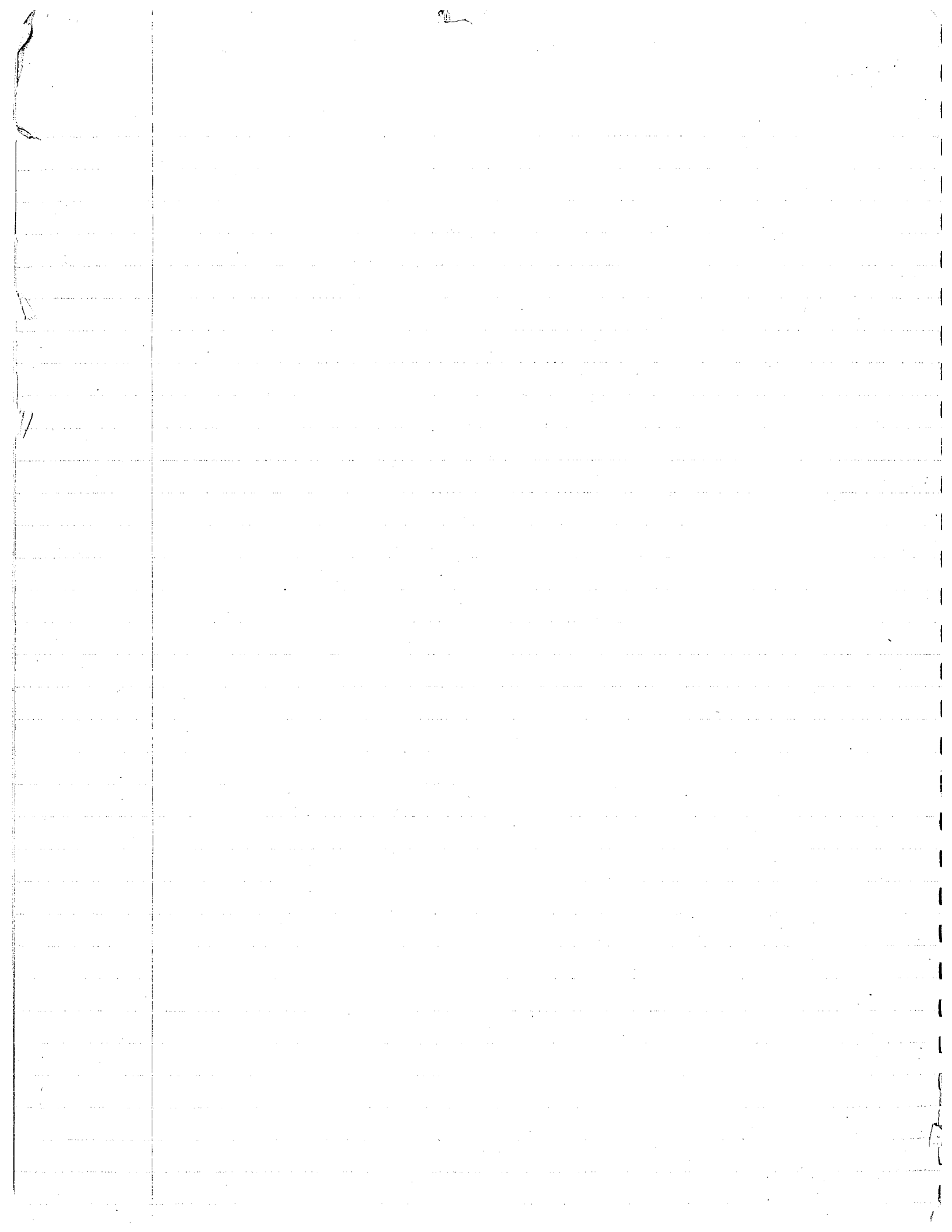
$$\frac{\delta^2}{\delta^2} \quad \frac{V^n}{V^n}$$

$$B \quad U^m \quad \gamma \quad V^m \quad X^m$$

$$2U_x + \gamma_x V = 0$$

$$U^{n+1} + \gamma V^{n+1}$$

U^m
X



Given:
$$\left. \begin{aligned} u_t - c^2(v) v_x &= -2u - Bu^2 \\ v_t - u_x &= 0 \end{aligned} \right\} (1)$$

And suppose we have non-dim equations with respect to $|\Omega|^{-1}$; we can now rewrite the eqns for $u(x, t) = \underline{u}(x, \beta)$ with respect to arrival time $t = T(x, \beta)$

$\therefore$ (1) becomes

$$\left[\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - T_x \begin{pmatrix} 0 & -c^2 \\ -1 & 0 \end{pmatrix} \right] \underline{u}_\beta = \left[\begin{pmatrix} -2u - Bu^2 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 & -c^2 \\ -1 & 0 \end{pmatrix} \underline{u}_x \right] T_\beta \quad (2)$$

Let $U(x, \beta) = \frac{1}{\omega} \sum \omega^{-n} U^{(n)}(x, \beta)$

Let $T = \int_0^x \frac{ds}{c(u, s)} = \frac{1}{\omega} \sum \omega^{-n} T^{(n)}(x, \beta)$ where $T_x = \frac{1}{c(u, x)} = \frac{1}{EV \text{ of } A}$

$$\begin{aligned} & \left[\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \left(\frac{1}{c(u)} + \frac{1}{\omega} \sum \omega^{-n} T_x^{(n)} \right) \begin{pmatrix} 0 & -[c(u)^2 + 2c_v(u)v + c_v^2 v^2 + \dots] \\ -1 & 0 \end{pmatrix} \right] \sum \omega^{-n} \underline{u}_{\beta}^{(n)}(x, \beta) \\ &= \left[\begin{pmatrix} -2 \frac{1}{\omega} \sum \omega^{-n} U^{(n)} - B \left\{ \frac{1}{\omega} \sum \omega^{-n} U^{(n)} \right\}^2 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 & -[c(u)^2 + 2c_v(u)v + c_v^2 v^2 + \dots] \\ -1 & 0 \end{pmatrix} \frac{1}{\omega} \sum \omega^{-n} \underline{u}_x^{(n)} \right] \quad (3) \end{aligned}$$

but $c(v) = c(u) + c_v(u)v + \dots$, $c(u) = 1$, $c_v(u) = \text{const}$

for $O\left(\frac{1}{\omega}\right)$ equation let $n=0$; thus we obtain

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \underline{u}_\beta^{(0)} = \left[\begin{pmatrix} -2 \frac{1}{\omega} U^{(0)} \\ 0 \end{pmatrix} - \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} \frac{1}{\omega} \underline{u}_x^{(0)} \right] \quad (4)$$

and $T_x^{(0)} = -\frac{c_v(u)}{c(u)} v = -c_v(u) v = \begin{pmatrix} 0 & -c_v \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix}$

we found $\underline{u}^{(0)} = \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \end{pmatrix} f(\beta) e^{-x}$ and thus $T_x^{(0)} = -\begin{pmatrix} 0 & -c_v \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix} f(\beta) e^{-x} \quad (*)$

for $O\left(\frac{1}{\omega^2}\right)$ equation

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \frac{1}{\omega} \underline{u}_\beta^{(1)} - \begin{bmatrix} 0 & -2c_v v^{(0)} \\ 0 & 0 \end{bmatrix} \frac{1}{\omega} \underline{u}_\beta^{(0)} + \frac{1}{\omega} T_x^{(0)} \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} \underline{u}_\beta^{(0)} = \left[\begin{pmatrix} -2 \frac{1}{\omega^2} U^{(1)} - B \frac{1}{\omega^2} U^{(0)^2} \\ 0 \end{pmatrix} - \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} \frac{1}{\omega^2} \underline{u}_x^{(1)} - \frac{1}{\omega^2} \begin{pmatrix} 0 & -2c_v v^{(0)} \\ 0 & 0 \end{pmatrix} \underline{u}_x^{(0)} \right] \quad (5)$$

$$\frac{1}{\omega} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} U_{\beta}^{(1)} - \frac{1}{\omega} \begin{bmatrix} 0 & +2c_v f(\beta) e^{-x} \\ 0 & 0 \end{bmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix} f'(\beta) e^{-x} + \frac{1}{\omega} \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} (-c_v f(\beta) e^{-x}) \begin{pmatrix} 1 \\ -1 \end{pmatrix} f'(\beta) e^{-x} = \text{left hand side of eq (5)}$$

$$= \frac{1}{\omega} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} U_{\beta}^{(1)} - \frac{1}{\omega} c_v f(\beta) f'(\beta) e^{-2x} \begin{pmatrix} -1 \\ -1 \end{pmatrix} = 0 \quad \begin{matrix} (6a) \\ (6b) \end{matrix}$$

the left hand side of (5) gives

$$l(x) \begin{bmatrix} -2U^{(1)} + V_x^{(1)} + (2c_v - B) f^2(\beta) e^{-2x} \\ U_x^{(1)} \end{bmatrix} = 0 \quad (7)$$

after multiplication by a left EV of A.

$$\text{Using } U_{\beta}^{(1)} + V_{\beta}^{(1)} = -c_v f(\beta) f'(\beta) e^{-2x}$$

$$\text{one obtains } U^{(1)} + V^{(1)} = -c_v e^{-2x} f^2(\beta) + g(x) \quad (8)$$

$$\text{but } U(x, 0) = 0 \Rightarrow g(x) = 0 \text{ since } f(0) = 0$$

Using (8) into (7) gives

$$\begin{pmatrix} 1 & -1 \end{pmatrix} \begin{bmatrix} 2V^{(1)} + 2c_v f^2(\beta) e^{-2x} + V_x^{(1)} + (2c_v - B) f^2(\beta) e^{-2x} \\ + 2c_v f^2(\beta) e^{-2x} - V_x^{(1)} \end{bmatrix} = 0$$

and the transport equation is of the form,

$$V_x^{(1)} + \frac{2 \cdot 1}{1 - (-1)} V^{(1)} + f^2(\beta) e^{-2x} \left\{ \frac{2c_v + 2c_v - B - 2c_v}{2} \right\} = 0$$

or

$$V_x^{(1)} + V^{(1)} = -\left[\frac{2c_v - B}{2}\right] f^2(\beta) e^{-2x} \quad (9)$$

thus (9) yields

$$V^{(1)} = f^2(\beta) \left[\frac{2c_v - B}{2}\right] e^{-2x} \quad (10)$$

$$\text{put (10) into (8) giving } U^{(1)} = [1 - e^{-2x}] f^2(\beta) \left[\frac{4c_v - B}{2}\right] \text{ with } U^{(1)}(0, t) = 0 \quad (11)$$

$$\therefore \underline{U}^{(1)} = \begin{pmatrix} -1 \\ 1 \end{pmatrix} V^{(1)} + \begin{pmatrix} -1 \\ 0 \end{pmatrix} c_v e^{-2x} f^2(\beta) + f^2(\beta) \frac{4c_v - B}{2} \quad (12)$$

$$T_x = \frac{1}{c(\alpha)} = \frac{1}{\omega} \sum \omega^{-n} T_x^{(n)}(x, \beta) = -\frac{c_v(0)}{c^2(0)} V + \left\{ \frac{2c_v^2(0)}{c^3(0)} - \frac{c_{vv}(0)}{c^2(0)} \right\} V^2$$

$$T_x^{(1)} = -\frac{c_v(0)}{c^2(0)} V^{(1)} \quad T_x^{(1)} = -c_v V^{(1)} + \left\{ 2c_v^2(0) - c_{vv}(0) \right\} V^2(0)$$

$$T^{(1)} = \int_0^x -c_v V^{(1)} dx + \int_0^x \left\{ 2c_v^2(0) - c_{vv}(0) \right\} V^2(0) dx$$

where $V^{(1)}$ is given by (10) and $V^{(0)}$ is given by (*)

