

$$\frac{2\pi f_f}{60} = 840 \text{ rpm} \times \frac{2\pi \text{ rad}}{1 \text{ rev}} \times \frac{1 \text{ min}}{60 \text{ sec}} = 28\pi \frac{\text{rad}}{\text{s}} = 87.96 \frac{\text{rad}}{\text{s}}$$

rpm $\rightarrow \frac{\text{rad}}{\text{s}}$

$$e\omega/2 = 3 \text{ lb-in}; \times 2 = 6 \text{ lb-in} = e\omega_0; m\omega = 200 \text{ lb}$$

when $x=0$ rotating mass form Δ of 90° to horizontal $x_p = \sum_{ss, RV} \sin(\omega_f t - \psi)$

$$\therefore \omega_f t - \psi = 0 \quad \& \quad \psi = 90^\circ \quad \tan \psi = \infty = \frac{2\zeta r}{1-r^2} \Rightarrow r=1 \quad \text{hence } \omega_f = \omega_n = 87.96 \frac{\text{rad}}{\text{s}}$$

$$\text{when } \omega_f = \omega_n \quad \sum_{ss, RV} = 0.75 \text{ in} = \frac{m_0 e}{m} \frac{r^2}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}} = \frac{\omega_0 e}{W} \frac{r^2}{2\zeta/1} = \frac{6 \text{ lb-in}}{200 \text{ lb}} \cdot \frac{1}{2\zeta}$$

$$\text{now } \zeta = \frac{6}{200} \cdot \frac{1}{2(0.75)} = 0.02$$

$$\omega_n = 87.96 = \sqrt{\frac{k}{m}} \quad m = \frac{W}{g} = \frac{200}{32.2} \quad \& \quad k = m\omega_n^2$$

$$F_{\text{trans, max, RV}} = \frac{m_0 e k \sqrt{1 + (2\zeta r)^2}}{m \sqrt{(1-r^2)^2 + (2\zeta r)^2}}$$

for 2nd part $f_f = 1260 \text{ rpm} \Rightarrow \omega_f = 1.5(87.96) = 131.94 \frac{\text{rad}}{\text{s}} \Rightarrow r = \frac{\omega_f}{\omega_n} = \frac{131.94}{87.96} = 1.5$

everything else not change $\omega_0 e = 6 \text{ lb-in}$ $W = 200 \text{ lb}$ $\zeta = 0.02$

$$\sum_{ss, RV} = \frac{\omega_0 e}{W} \frac{r^2}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}} \quad \text{and } \psi = \tan^{-1}\left(\frac{2\zeta r}{1-r^2}\right) \quad \text{since } \omega_f t \text{ represents angle rot. mass makes with horiz}$$