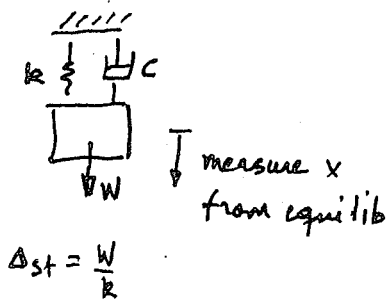
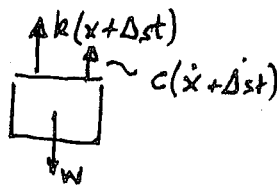




$F = c\dot{x}$ in direction opposite to motion $[c] = \frac{\text{lb} \cdot \text{sec}}{\text{ft}} = \frac{\text{N} \cdot \text{s}}{\text{m}}$



$$\Sigma F = W - k(x + \Delta_{st}) - c(\dot{x} + \Delta_{st}) = -kx - c\dot{x} = m\ddot{x}$$

$$m\ddot{x} + c\dot{x} + kx = 0$$

$$C e^{st} (ms^2 + cs + k) = 0 \Rightarrow s = \frac{-c \pm \sqrt{c^2 - 4mk}}{2m}$$

Case I $k^2 - 4mk > 0$

$$s_1 = \frac{-c + \sqrt{c^2 - 4mk}}{2m} < 0$$

$$s_2 = \frac{-c - \sqrt{c^2 - 4mk}}{2m} < 0$$

$$x(t) = C_1 e^{s_1 t} + C_2 e^{s_2 t}$$

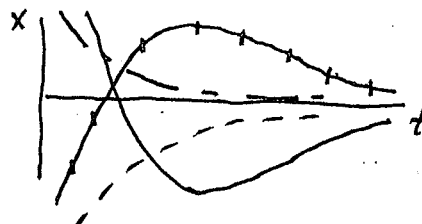
dying exponentials

solution is APERIODIC (no oscillatory behavior)

$$x(t=0) = x_0 = C_1 + C_2$$

$$\dot{x}(t=0) = v_0 = C_1 s_1 + C_2 s_2$$

get C_1 & C_2 from here



can be any one of these depending on Initial Conditions (IC)

This is called the overdamped case

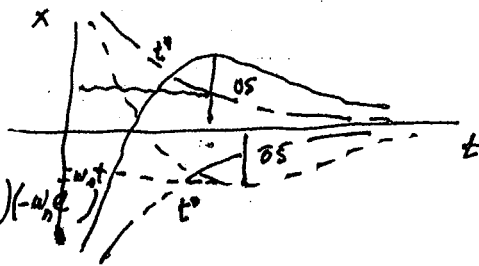
Case II $c^2 - 4mk = 0$ or $c = \sqrt{4mk} = 2\sqrt{mk} = 2\sqrt{m^2 \cdot \frac{k}{m}} = 2m\omega_n$ This value of $c = c_{crit}$

$$c_{crit} = \text{critical damping constant}; s_1 = s_2 = -\frac{c}{2m} = -\frac{c_{crit}}{2m} = -\frac{2m\omega_n}{2m} = -\omega_n$$

$$\therefore x(t) = C_1 e^{-\omega_n t} + C_2 t e^{-\omega_n t} = (C_1 + C_2 t) e^{-\omega_n t}$$

dying exponentials

solution is APERIODIC



$$x(t=0) = x_0 = C_1$$

$$\dot{x}(t) = C_2 e^{-\omega_n t} + (C_1 + C_2 t)(-\omega_n e^{-\omega_n t})$$

$$\dot{x}(t=0) = C_2 - \omega_n C_1 = v_0$$

$$\therefore C_2 = v_0 + \omega_n x_0$$

can be any one of these 4 depending on ICS.

$$C_2 - \omega_n (C_1 + C_2 t^*) = 0$$

$$\text{or } C_2 - \omega_n C_1 = \omega_n C_2 t^* \quad t^* = \frac{1}{\omega_n} = \frac{C_1}{C_2}$$

$$x(t^*) = 0.5 = (C_1 + C_2 t^*) e^{-\omega_n t^*}$$

This is called the critically damped case