

HW #1

12-11, 15, 24, 25 in 6 pgs

Friction.

Ch 12

(11)

For Normal driver:

$$\text{Initial velocity} = 44 \text{ ft/s}$$

$$\text{acceleration} = -2 \text{ ft/s}^2$$

Using: $v^2 = u^2 + 2as$

where v = final velocity.

u = Initial velocity.

s = displacement.

$$0 = 44^2 - 2s$$

$$s = \frac{44^2}{2} = 484 \text{ ft}$$

Now the driver also has a delay reaction time of 0.75 secs.

So Using: $s = ut$ where u = Initial velocity

$$s = 44(0.75)$$

t = time

$$s = 33 \text{ ft}$$

∴ The shortest stopping distance needed = $484 + 33$

$$= \underline{\underline{517 \text{ ft}}}$$

(15)

$$s = (t^3 - 9t^2 + 15t) \text{ ft}$$

at $t = 6 \text{ s}$.

$$\begin{aligned} s &= 6^3 - 9(6)^2 + 15(6) = 216 - 324 + 90 \\ &= \underline{-18 \text{ ft}} \quad \checkmark \end{aligned}$$

$$s = t^3 - 9t^2 + 15t$$

$$\frac{ds}{dt} = v = 3t^2 - 18t + 15$$

Now particle stops when $3t^2 - 18t + 15 = 0$
 $(3t - 3)(t - 5) = 0$

$$t = 1 \text{ s}, t = 5 \text{ s.} \quad \checkmark$$

at $t = 1 \text{ s}$

$$s = 1 - 9 + 15 = 7 \text{ ft}$$

at $t = 5 \text{ s}$

$$s = 125 - 225 + 75 = -25 \text{ ft}$$

Distance travelled so far is $7 + 32 = 39 \text{ ft}$
 $(7 - (-25))$ \checkmark

at $t = 6 \text{ s}$

$$s = -18 \text{ ft}$$

So total distance travelled = $39 + 7 = 46 \text{ ft}$
 $(-18 - (-25))$ \checkmark

For the drunken driver :

$$\text{Initial velocity, } u = 44 \text{ ft/s}$$

$$\text{acceleration, } a = -2 \text{ ft/s}^2$$

Using $v^2 = u^2 + 2as$

$$0 = 44^2 - 4s$$

$$s = 484 \text{ ft}$$

But the delay time for the drunken driver = 3 secs.

using $s = ut$ where $u = \text{initial velocity}$
 $t = \text{time}$

$$s = 44(3) = 132 \text{ ft.}$$

$$\begin{aligned}\therefore \text{The shortest stopping distance} &= 484 + 132 \\ &= \underline{\underline{616 \text{ ft}}}\end{aligned}$$

(24) For Car A :

$$u = 0 \text{ ft/s}$$

$$a = 6 \text{ ft/s}^2$$

$$V = 80 \text{ ft/s}$$

Using $v^2 = u^2 + 2as$

$$6400 = 12s \Rightarrow s = 533\frac{1}{3} \text{ ft}$$

Using $v = u + at \Rightarrow 80 = 6t \Rightarrow t = 13\frac{1}{3} \text{ sec.}$

(t during which car accelerates)

For Car B : (car B also is moving during this time)

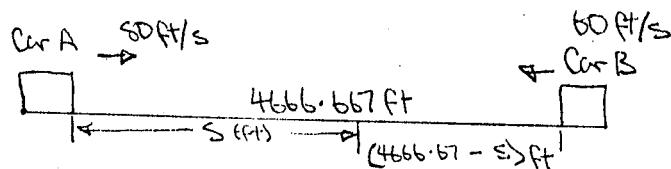
$$\text{at } t = 13\frac{1}{3} \text{ sec.}$$

Using $s = ut$

$$s = 60 (13\frac{1}{3}) = 800 \text{ ft.}$$

Now Car A is travelling at a constant velocity of 80 ft/s and Car B at 60 ft/s with a distance of

$$6000 - 800 - 533\frac{1}{3} = 4666.667 \text{ ft between them.}$$



Using $s = ut$

For Car A:

$$S = 80t \quad \dots \quad (1)$$

For Car B:

$$4666.667 - S = 60t \quad \dots \quad (2)$$

Sub. $80t$ for S in (2):

$$4666.667 - 80t = 60t$$

$$140t = 4666.667$$

$$t = 33.33 \text{ secs.}$$

For Car A, $S = 80(33.33) = 2666 \frac{2}{3} \text{ ft.}$

Hence Car A will travel a distance of 3200 ft in a time of $46 \frac{2}{3} \text{ secs}$ when it encounters Car B.

(25)

$$a = (2 - v^2/500) \text{ ft/s}^2$$

For max speed, $a=0$

$$2 - v^2/500 = 0$$

$$v^2 = 1000$$

$$v = \sqrt{1000} = \underline{31.6 \text{ ft/s}}$$

$$a = 2 - v^2/500$$

$$v \frac{dv}{ds} = 2 - v^2/500$$

$$v dv = (2 - v^2/500) ds$$

$$\frac{v}{2 - v^2/500} dv = ds$$

$$s = \int \frac{500v}{1000 - v^2} dv = -250 \ln(1000 - v^2) + C$$

$$\text{when } s=0, v=0$$

$$0 = -250 \ln(1000) + C$$

$$C = 250 \ln(1000)$$

$$s = -250 \ln(1000 - v^2) + 250 \ln(1000)$$

$$\text{when } v = 8 \text{ ft/s}$$

$$s = -250 \ln(936) + 250 \ln(1000) = 1726.9 - 1710.4$$

$$s = \underline{16.5 \text{ ft}}$$

RESF 246.06

SOLUTION HW #2

12-57, 66, 75, 81 in 8 PAGES

Homework Problems

Ch 12

$$57) \quad \vec{r}_A = \{4.5t\hat{i} + 13.5t(2-t)\hat{j}\} \text{ m}$$

$$\vec{r}_B = \{4.5(t^2 - 2t + 2)\hat{i} + (4.5t - 9)\hat{j}\} \text{ m}$$

For Particles to collide: $r_{Ax} = r_{Bx}$ $r_{Ay} = r_{By}$

$$4.5t = 4.5(t^2 - 2t + 2)$$

$$4.5(t^2 - 3t + 2) = 0$$

$$4.5(t-2)(t-1) = 0$$

$$(t-2)(t-1) = 0$$

$$t=2, t=1$$



$$13.5t(2-t) = 4.5t - 9$$

$$-13.5t^2 + 27t = 4.5t - 9$$

$$13.5t^2 - 22.5t - 9 = 0$$

$$4.5(3t^2 - 5t - 2) = 0$$

$$4.5(3t+1)(t-2) = 0$$

$$t=2, t=-\frac{1}{3}$$



Particles will collide at $t=2$ secs.



The Position vector for the pt. of collision is

$$\vec{r}_C = \{9\hat{i}\}$$



The collision will take place at $(9 \text{ m}, 0)$

$$\bar{V}_a = \frac{d\bar{r}_a}{dt} = \{4.5\hat{i} + (-27t + 27)\hat{j}\} \text{ m/s}$$

$$\bar{V}_b = \frac{d\bar{r}_b}{dt} = \{4.5(2t - 2)\hat{i} + 4.5\hat{j}\} \text{ m/s}$$

Just before collision:

$$\bar{V}_a = \{4.5\hat{i} + (-27)\hat{j}\} \text{ m/s}$$

$$|\bar{V}_a| = \sqrt{(4.5)^2 + (-27)^2} = \sqrt{749.25} = 27.37 \text{ m/s}$$

$$\bar{V}_b = \{9\hat{i} + 4.5\hat{j}\} \text{ m/s}$$

$$|\bar{V}_b| = \sqrt{(9)^2 + (4.5)^2} = \sqrt{101.25} = 10.06 \text{ m/s}$$

$$(2) \div (1)$$

$$\frac{V_A \sin \theta}{V_A \cos \theta} = \frac{11.725}{16} \Rightarrow \tan \theta = 0.733$$

$$\theta = \tan^{-1} 0.733 = 36.2^\circ$$

✓

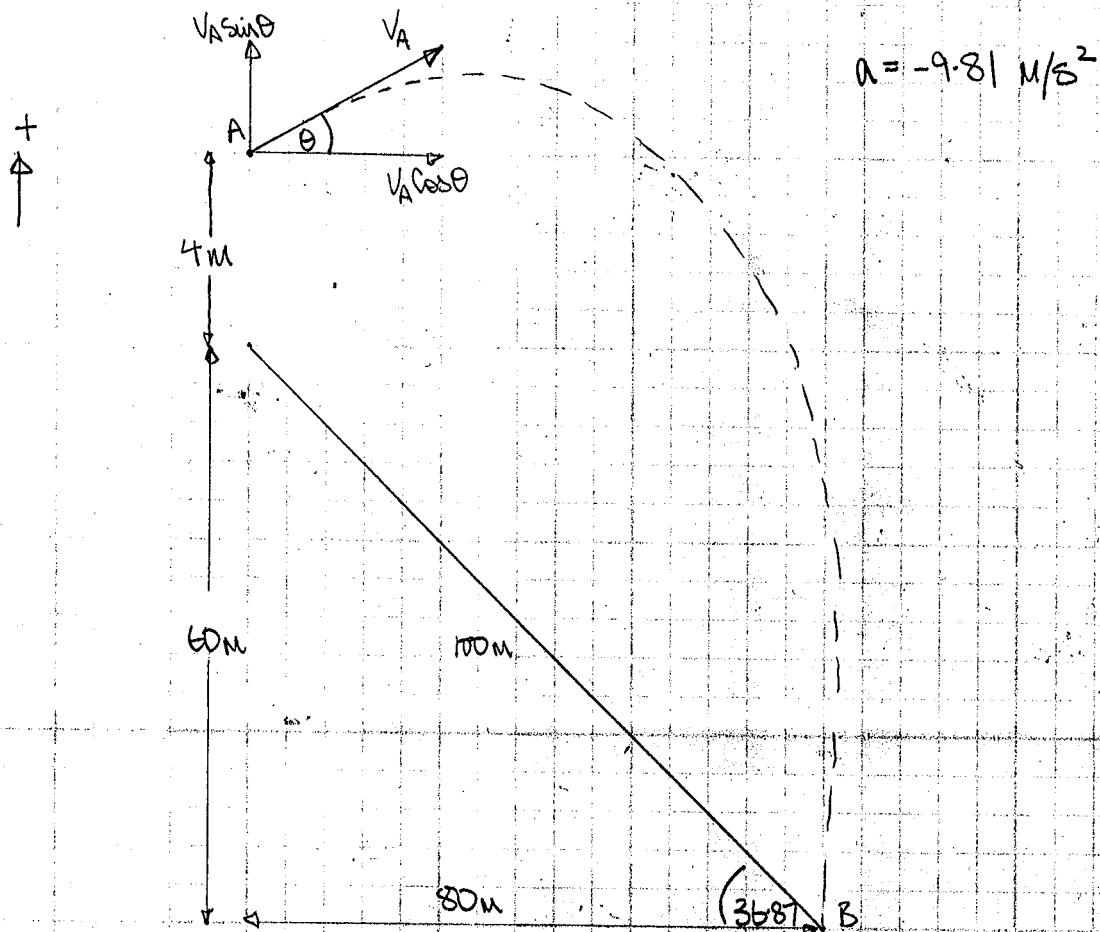
$$V_A \cos \theta = 16$$

$$V_A = \frac{16}{\cos \theta} = \frac{16}{0.807}$$

$$u = 19.8 \text{ m/s}$$

✓

(66)



For Horizontal Motion:

$$v_A \cos \theta = \frac{80}{5} = 16 \frac{\text{m}}{\text{s}} \quad \text{--- (1)}$$

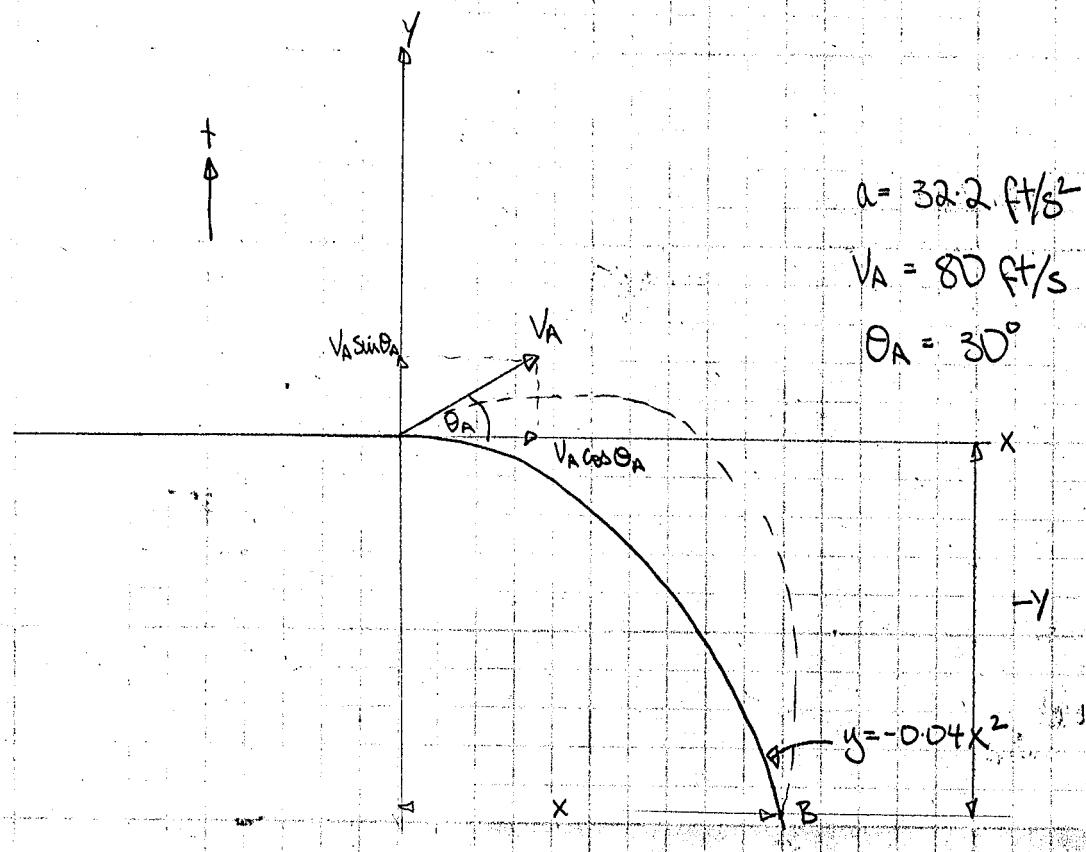
For Vertical Motion:

Using: $s = v_0 t + \frac{1}{2} a t^2$

$$-64 = 5v_A \sin \theta - \frac{1}{2}(25)(9.81)$$

$$v_A \sin \theta = 11.725 \frac{\text{m}}{\text{s}} \quad \text{--- (2)}$$

(75)



For Vertical Motion: Using $s = vt + \frac{1}{2}at^2$

$$-Y = V_A \sin \theta_A t - \frac{1}{2}(32.2) t^2$$

$$-Y = 40t - 16.1t^2 \quad \text{--- (1)} \checkmark$$

For Horizontal Motion:

$$X = V_A \cos \theta_A t = 80(0.866)t$$

$$X = 69.28t \quad \checkmark$$

$$t = \frac{X}{69.28} \quad \text{--- (2)}$$

Sub. (2) in (1):

$$-Y = \frac{40X}{69.28} - 16.1\left(\frac{X}{69.28}\right)^2 \quad \checkmark$$

$$-Y = 0.577X - 3.35 \times 10^{-3} X^2 \quad \dots \quad (3)$$

$$y = -0.04X^2 \quad (\text{eqn of parabola given})$$

$$0.04X^2 = 0.577X - 3.35 \times 10^{-3} X^2$$

$$4.335 \times 10^{-2} X^2 = 0.577X$$

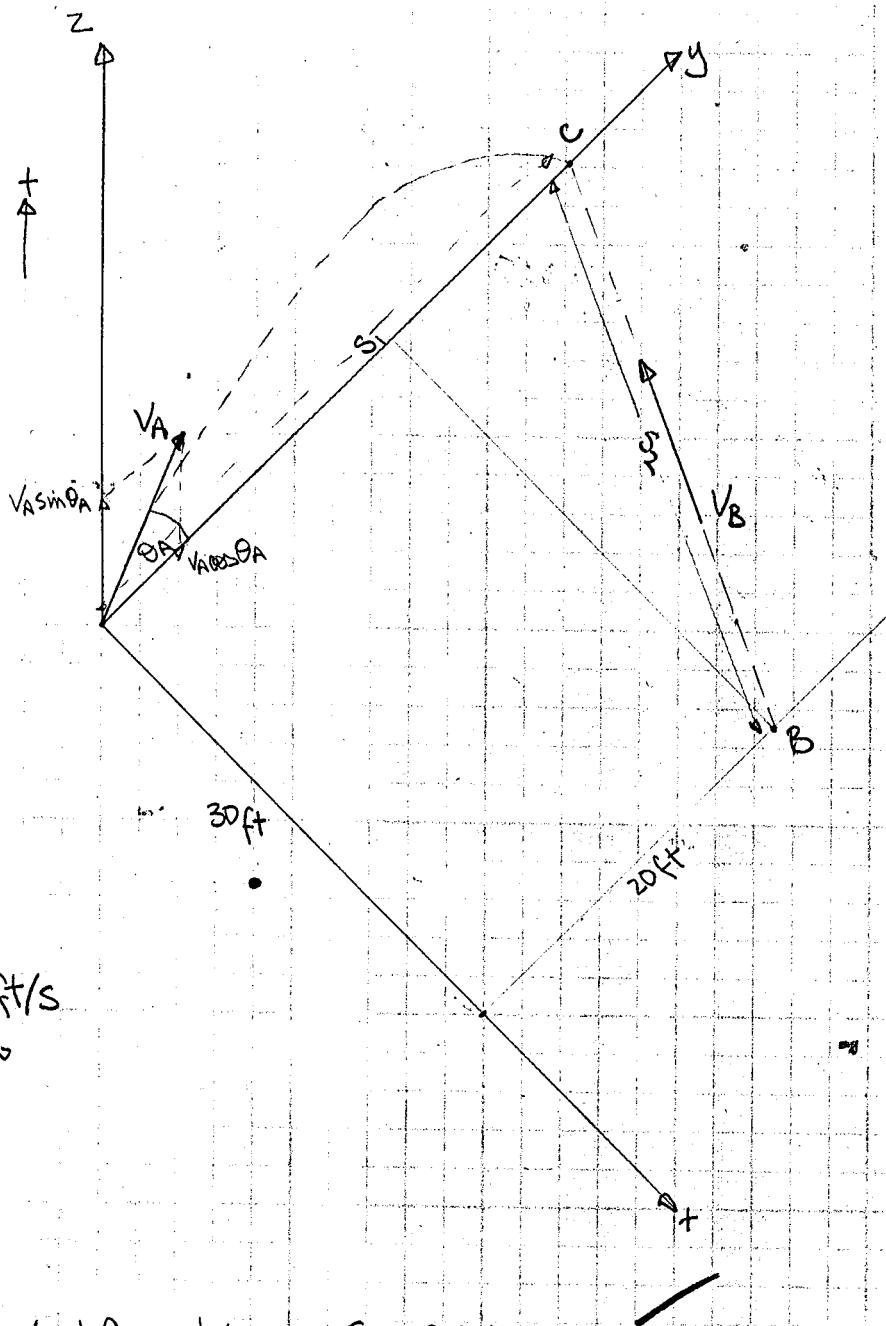
$$4.335 \times 10^{-2} X = 0.577$$

$$X = \frac{0.577}{4.335 \times 10^{-2}} = 13.3 \text{ ft}$$

also the trivial solution
 $X=0$ also solves
eqn.

$$y = -0.04X^2 = -0.04(13.3)^2 = -7.1 \text{ ft}$$

(81)



$$V_A = 50 \text{ ft/s}$$

$$\theta_A = 60^\circ$$

For Horizontal Motion :

$$S_1 = 25t_1$$

For Vertical Motion :

$$\text{Using } S = \frac{1}{2}at_1^2$$

$$0 = V_A \sin \theta_A t_1 + \frac{1}{2}(32.2)t_1^2$$

$$0 = 43.3t_1 - 16.1t_1^2$$

$$16.1t_1^2 = 43.3t_1$$

$$16.1t_1 = 43.3$$

$$t_1 = \frac{43.3}{16.1} = 2.69 \text{ secs. and } t=0 \text{ solve the eqn.; } t=2.69 \text{ sec solves problem}$$

$$S_1 = 25(2.69) = 67.24 \text{ ft}$$

$$S_2^2 = (67.24 - 20)^2 + 30^2$$

$$S_2 = \sqrt{2231.24 + 900} = \sqrt{3131.24} = 55.96 \text{ ft}$$

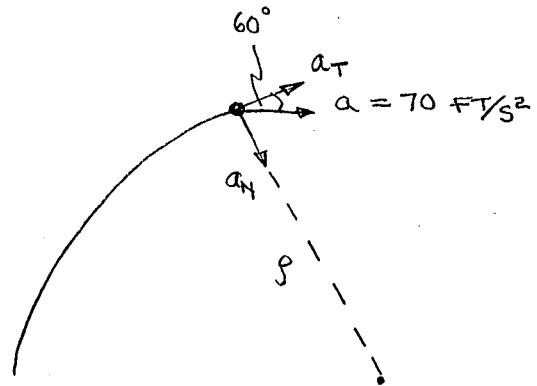
$$V_B = \frac{S_2}{t_1} = \frac{55.96}{2.69} = 20.8 \text{ ft/s}$$

HW #3 in 6 pages

12 - 85, 88, 94, 108, 117, 126

DYNAMICS HOME WORK #3

12-85



GIVEN

$$\text{VELOCITY } (v) = 400 \text{ FT/S}$$

$$\text{ACCELERATION } (a) = 70 \text{ FT/S}^2$$

$$\Rightarrow a_T = 70 \cos 60^\circ$$

$$\underline{a_T = 35 \text{ FT/S}^2}$$

FROM

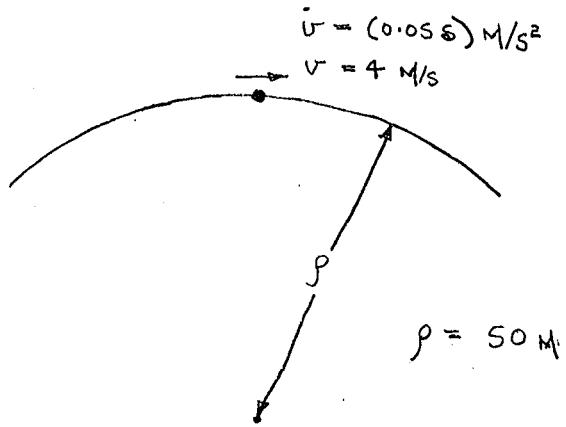
$$\frac{v^2}{\rho} = a_n$$

$$\Rightarrow (70 \sin 60^\circ) = \frac{400^2}{\rho}$$

$$\rho = \frac{400^2}{(70 \sin 60^\circ)}$$

$$\underline{\rho = 2639 \text{ FT}}$$

12-88



GIVEN

$$\dot{v} = a_T = 0.05 \text{ s}$$

$$\text{BUT } a ds = v dv$$

$$0.05 s ds = v dv$$

$$\Rightarrow \int_4^r v dv = \int_0^s 0.05 s ds$$

$$\frac{1}{2} v^2 \Big|_4^r = \frac{0.05 s^2}{2}$$

$$\frac{1}{2} v^2 - 16 = \frac{0.05 s^2}{2}$$

$$v = \sqrt{0.05 s^2 + 16}$$

WHEN $s = 10 \text{ m}$

$$v = 4.58 \text{ m/s}$$

$$\text{FROM } a_n = \frac{v^2}{r}$$

$$\Rightarrow a_n = \frac{0.05 s^2 + 16}{50}$$

WHEN $s = 10 \text{ m}$

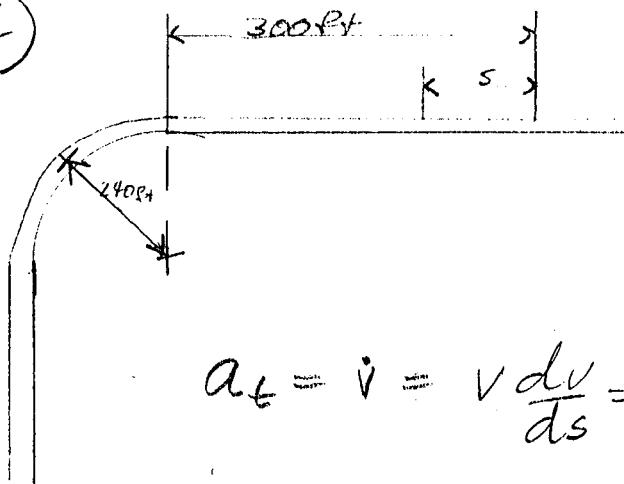
$$a_n = 0.42 \text{ m/s}^2$$

$$\text{AND } a_T = 0.05(10) \\ = 0.5 \text{ m/s}^2$$

$$a = \sqrt{0.5^2 + 0.42^2}$$

$$a = 0.653 \text{ m/s}^2$$

?) 94)



$$V_0 = 0 \text{ at } s = 0$$

$$\dot{V} = (0.05t^2) \text{ ft/s}^2 \quad t > 0$$

Determine magnitude of velocity and acceleration for $t = 18 \text{ s}$

$$a_t = i = v \frac{dv}{ds} = \cancel{\frac{ds}{dt}} \frac{dv}{\cancel{ds}}$$

$$0.05t^2 = \frac{dv}{dt}$$

$$\int 0.05t^2 dt = \int dv$$

$$\frac{0.05t^3}{3} = v \quad /_{t=18}$$

$$|V| = 97.2 \text{ ft/s} \quad \checkmark$$

$$\frac{0.05t^3}{3} = \frac{ds}{dt}$$

$$\int \frac{0.05t^3}{3} dt = \int ds$$

$$\frac{0.05t^4}{12} = s \quad /_{t=18}$$

$$s = 437.40 \text{ ft} \quad \checkmark$$

IMPORTANT!!
MUST BE
STATED

location of vehicle
length of curve

$$\vec{a} = \dot{v} \vec{v}_T + \frac{v^2}{r} \vec{v}_n$$

$$\vec{a} = (0.05t^2) \vec{v}_T + \frac{(97.2)^2}{240} \vec{v}_n = [16.2 \vec{v}_T + 39.37 \vec{v}_n] \text{ ft/s}^2 \quad \checkmark$$

$$|a| = 42.57 \text{ ft/s}^2 \quad |V| = 97.2 \text{ ft/s}$$

excellent

12-108

GIVEN

$$\dot{\theta} = \frac{d\theta}{dt} = 0.8 \text{ RAD/S}$$

$$\ddot{\theta} = -0.2 \text{ RAD/S}^2$$

AND $r = 0.75 \cos \theta + 2 \quad (\text{FT.})$

$$\Rightarrow \dot{r} = -0.75 \dot{\theta} \sin \theta$$

AND $\ddot{r} = -0.75 \dot{\theta} \cos \theta \cdot \dot{\theta} - 0.75 \ddot{\theta} \sin \theta$

$$\ddot{r} = -0.75 \dot{\theta}^2 \cos \theta - 0.75 \ddot{\theta} \sin \theta$$

\Rightarrow RADIAL COMP OF VELOCITY $v_r = \dot{r}$

WHEN $\theta = \pi/8$

$$v_r = -0.75(0.8) \sin(\pi/8)$$

$$v_r = -0.23 \text{ FT/S}$$

TRANSVERSE COMP OF VELOCITY v_θ

$$v_\theta = r \dot{\theta}$$

$$= (0.75 \cos \theta + 2) 0.8$$

WHEN $\theta = \pi/8$

$$v_\theta = (0.75 \cos(\pi/8) + 2) 0.8$$

$$v_\theta = 2.15 \text{ FT/S}$$

AND

$$a_r = \ddot{r} - r \dot{\theta}^2$$

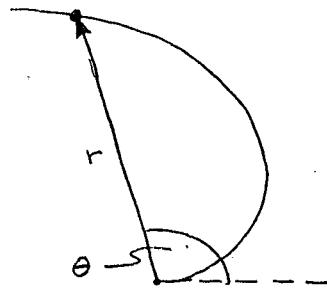
$$= (-0.75(0.8)^2 \cos(\pi/8) - 0.75(-0.2) \sin(\pi/8))$$

$$- (0.75 \cos(\pi/8) + 2)(0.8^2)$$

$$a_r = -2.11 \text{ FT/S}^2$$

$$\begin{aligned}
 a_\theta &= r\ddot{\theta} + 2\dot{r}\dot{\theta} \\
 &= (0.75 \cos(\pi/8) + 2)(-0.2) + 2(-0.75(0.8) \sin(\pi/8))(0.8) \\
 a_\theta &= -0.91 \text{ FT/S}^2 \quad \checkmark
 \end{aligned}$$

12-117



GIVEN

$$r = a\theta$$

RATE OF ANGULAR ROTATION = $\dot{\theta}$ (CONSTANT)

\Rightarrow " " " ACCELERATION = $\ddot{\theta} = 0$

$$\dot{r} = a\dot{\theta}$$

$$\text{AND } \ddot{r} = a\ddot{\theta}$$

$$\Rightarrow \ddot{r} = 0$$

$$v_r = \dot{r}$$

$$\underline{v_r = a\dot{\theta}}$$

$$v_\theta = r\dot{\theta}$$

$$\underline{v_\theta = a\theta\dot{\theta}}$$

$$\Rightarrow a_r = \cancel{r^2} - r\dot{\theta}^2$$

$$\underline{a_r = -r\dot{\theta}^2 = -a\theta\dot{\theta}^2}$$

$$a_\theta = \cancel{r\ddot{\theta}^2} + 2\dot{r}\dot{\theta}$$

$$\underline{a_\theta = 2a\dot{\theta}^2}$$

$$\text{ACCELERATION } \ddot{\mathbf{a}} = (\ddot{r} - r\dot{\theta}^2) \mathbf{u}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta}) \mathbf{u}_\theta + \ddot{z} \mathbf{u}_z$$

$$\text{OR } \ddot{\mathbf{a}} = \ddot{r} \mathbf{u}_r - r\ddot{\theta}^2 \mathbf{u}_r + r\ddot{\theta} \mathbf{u}_\theta + 2\dot{r}\dot{\theta} \mathbf{u}_\theta + \ddot{z} \mathbf{u}_z$$

$$\frac{d\ddot{\mathbf{a}}}{dt} = \frac{d(\ddot{r} \mathbf{u}_r)}{dt} - \frac{d(r\ddot{\theta}^2 \mathbf{u}_r)}{dt} + \frac{d(r\ddot{\theta} \mathbf{u}_\theta)}{dt} + \frac{d(2\dot{r}\dot{\theta} \mathbf{u}_\theta)}{dt} + \frac{d(\ddot{z} \mathbf{u}_z)}{dt}$$

$$= \ddot{r} \mathbf{u}_r + \ddot{r} \dot{\mathbf{u}}_r - \left\{ \left[\frac{d(r\ddot{\theta}^2)}{dt} \right] \mathbf{u}_r + r\ddot{\theta}^2 \dot{\mathbf{u}}_r \right\} \\ + \left[\frac{d}{dt} (r\ddot{\theta}) \right] \mathbf{u}_\theta + r\ddot{\theta} \dot{\mathbf{u}}_\theta + \left[\frac{d(2\dot{r}\dot{\theta})}{dt} \right] \mathbf{u}_\theta \\ + 2\dot{r}\dot{\theta} \dot{\mathbf{u}}_\theta + \ddot{z} \mathbf{u}_z$$

$$= \ddot{r} \mathbf{u}_r + \ddot{r} \dot{\mathbf{u}}_r - (2r\dot{\theta}\ddot{\theta} + \dot{r}\dot{\theta}^2) \mathbf{u}_r - r\ddot{\theta}^2 \dot{\mathbf{u}}_r + (r\ddot{\theta} + \dot{r}\ddot{\theta}) \mathbf{u}_\theta \\ + r\ddot{\theta} \dot{\mathbf{u}}_\theta + (2\dot{r}\ddot{\theta} + 2\ddot{r}\dot{\theta}) \mathbf{u}_\theta - 2\dot{r}\dot{\theta}^2 \mathbf{u}_r + \ddot{z} \mathbf{u}_z$$

$$\text{BUT } \dot{\mathbf{u}}_\theta = -\dot{\theta} \mathbf{u}_r -$$

$$\text{AND } \dot{\mathbf{u}}_r = \dot{\theta} \mathbf{u}_\theta -$$

SUBSTITUTING

$$\ddot{\mathbf{a}} = \ddot{r} \mathbf{u}_r + \ddot{r} \dot{\mathbf{u}}_\theta - (2r\dot{\theta}\ddot{\theta} + \dot{r}\dot{\theta}^2) \mathbf{u}_r + r\ddot{\theta}^3 \mathbf{u}_\theta \\ + (r\ddot{\theta} + \dot{r}\ddot{\theta}) \mathbf{u}_\theta - r\ddot{\theta} \dot{\mathbf{u}}_r + (2\dot{r}\ddot{\theta} + 2\ddot{r}\dot{\theta}) \mathbf{u}_\theta \\ - 2\dot{r}\dot{\theta}^2 \mathbf{u}_r + \ddot{z} \mathbf{u}_z$$

$$= (\ddot{r} - 2r\dot{\theta}\ddot{\theta} - \dot{r}\dot{\theta}^2 - r\ddot{\theta}\dot{\theta} - 2\dot{r}\dot{\theta}^2) \mathbf{u}_r \\ + (\ddot{r}\dot{\theta} + r\dot{\theta}^3 + r\ddot{\theta} + \dot{r}\ddot{\theta} + 2\dot{r}\dot{\theta} + 2\ddot{r}\dot{\theta}) \mathbf{u}_\theta$$

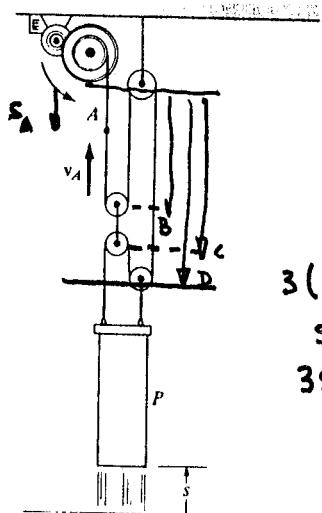
$$\ddot{\mathbf{a}} = (\ddot{r} - 3r\dot{\theta}\ddot{\theta} - 3\dot{r}\dot{\theta}^2) \mathbf{u}_r + (3\dot{r}\ddot{\theta} + 3\ddot{r}\dot{\theta} + r\dot{\theta}^3 + r\ddot{\theta}) \mathbf{u}_\theta$$

SOLN TO HW #4 in 2 pgs

12-131, 135, 140, 149, 150, 155

Ch 12 - Kinematics of a Particle

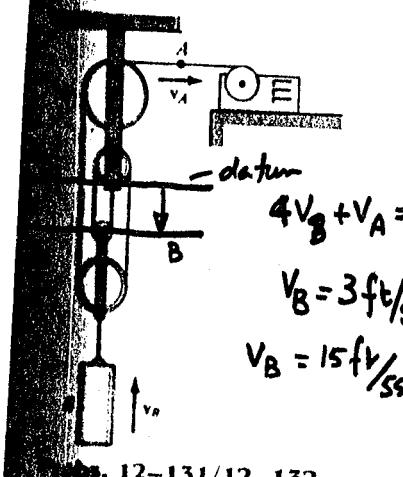
12-135. The pipe P is being lifted using the cable and pulley system shown. If point A on the cable is being drawn toward the drum with a speed of 2 m/s, determine the speed of the pipe.



Probs. 12-135/12-136

$$\begin{aligned} 3(s_D - s_C) + s_C + s_B + s_B - s_A &= 0 \\ s_C - s_B &= c_2 \\ 3s_D - 2s_C + 2s_B - s_A &= c_1 \\ 3s_D + c_2 - s_A &= c_1 \\ 3v_D - v_A &= 0 \\ 3v_D - (-2) &= 0 \\ v_D &= -\frac{2}{3} \text{ m/s} \end{aligned}$$

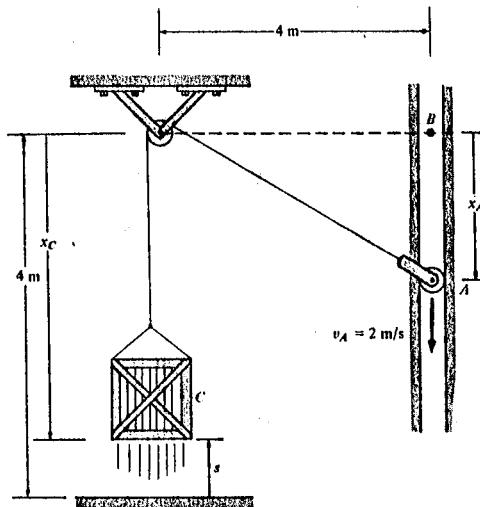
31. Determine the constant speed at which the cable at A must be drawn in by the motor in order to hoist the load at B 15 ft/s.



Probs. 12-131/12-132

or as done in class

*12-140. The crate C is being lifted by moving the roller at A downward with a constant speed of $v_A = 2 \text{ m/s}$ along the guide. Determine the velocity and acceleration of the crate at the instant $s = 1 \text{ m}$. When the roller is at B , the crate rests on the ground. Neglect the size of the pulley in the calculation. Hint: Relate the coordinates x_C and x_A using the problem geometry, then take the first and second time derivatives.



Prob. 12-140

SOLN

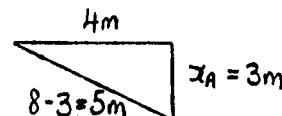


$$\begin{aligned} x_C + \sqrt{x_A^2 + 4^2} &= l \\ \dot{x}_C + \frac{1}{2}(x_A^2 + 16)^{-\frac{1}{2}}(2x_A)\dot{x}_A &= 0 \\ \ddot{x}_C - \frac{1}{4}(x_A^2 + 16)^{-\frac{3}{2}}(4x_A^2)\dot{x}_A^2 &+ (x_A^2 + 16)^{-\frac{1}{2}}(\ddot{x}_A)^2 + (x_A^2 + 16)^{-\frac{3}{2}}x_A\ddot{x}_A = 0 \end{aligned}$$

When $s = 1 \text{ m}$, $x_C = 3 \text{ m}$

$$v_A = \dot{x}_A = 2 \text{ m/s}$$

$$a_A = \ddot{x}_A = 0$$



Thus,

$$v_C + (3^2 + 16)^{-\frac{1}{2}}(3)(2) = 0$$

$$v_C = -1.2 \text{ m/s} = \underline{1.2 \text{ m/s} \uparrow}$$

$$\begin{aligned} a_C - (3^2 + 16)^{-\frac{3}{2}}(3)^2(2)^2 + (3^2 + 16)^{-\frac{1}{2}}(2)^2 &+ 0 = 0 \\ a_C = -0.512 \text{ m/s}^2 = \underline{0.512 \text{ m/s}^2 \uparrow} \end{aligned}$$

12-149. Two boats leave the shore at the same time and travel in the directions shown. If $v_A = 20 \text{ ft/s}$ and $v_B = 15 \text{ ft/s}$, determine the speed of boat A with respect to boat B. How long after leaving the shore will the boats be 800 ft apart?

$$\begin{aligned} \bar{v}_A &= v_A (-\sin 30^\circ \hat{i} + \cos 30^\circ \hat{j}) \\ \bar{v}_B &= v_B (\sin 45^\circ \hat{i} + \cos 45^\circ \hat{j}) \\ \bar{v}_{A/B} &= \bar{v}_B - \bar{v}_A = (v_B \cos 45^\circ + v_A \sin 30^\circ) \hat{i} + (v_A \cos 30^\circ - v_B \sin 45^\circ) \hat{j} \\ &= 21.67 \hat{i} + 67.139 \hat{j} \\ \bar{r}_{A/B} &= -20.6066 t \hat{i} + 67.139 t \hat{j} \\ |\bar{r}_{A/B}| &= 21.67 t = 800 \text{ ft} \quad t = 36.92 \text{ sec} \end{aligned}$$

Probs. 12-149/12-150

12-150. Each boat begins from rest at point O and heads in the direction shown at the same instant. If A has an acceleration of $a_A = 2 \text{ ft/s}^2$, and B has an acceleration of $a_B = 3 \text{ ft/s}^2$, determine the speed of boat A with respect to boat B at the instant they become 800 ft apart. How long will this take?

$$\begin{aligned} \bar{r}_A &= t^2 (-\sin 30 \hat{i} + \cos 30 \hat{j}) \\ \bar{r}_B &= \frac{3}{2} t^2 (\sin 45 \hat{i} + \cos 45 \hat{j}) \\ \bar{r}_{A/B} &= -1.56066 t^2 \hat{i} + .1946 t^2 \hat{j} \\ |\bar{r}_{A/B}| &= 1.57275 t^2 = |\bar{r}_A - \bar{r}_B| \\ \therefore t &= 22.5536 \text{ sec} \\ \bar{v}_A &= 2t (-\sin 30 \hat{i} + \cos 30 \hat{j}) \\ \bar{v}_B &= 3t (\sin 45 \hat{i} + \cos 45 \hat{j}) \\ \therefore |\bar{v}_{A/B}| &= -3.121 t \hat{i} - .38927 t \hat{j} = |\bar{v}_A - \bar{v}_B| \\ &= 70.39 \hat{i} - 8.78 \hat{j} = 70.94 \text{ ft/sec} \end{aligned}$$

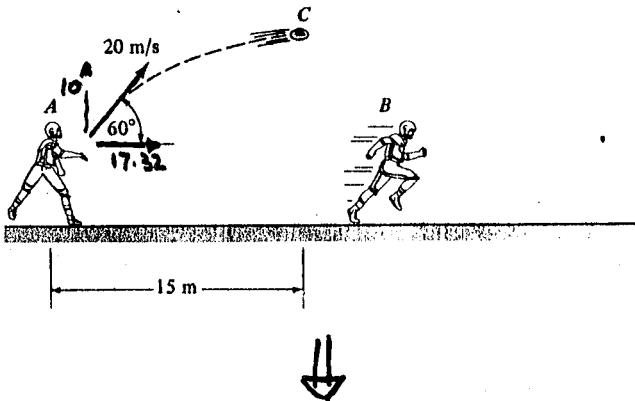
Note here constant acceleration a_A & a_B
initial velocity \bar{v}_A & \bar{v}_B

$$\bar{v}_A = a_A t \cdot \bar{u}_A \quad \bar{v}_B = a_B t \cdot \bar{u}_B$$

$$\bar{r}_A = a_A t^2 \frac{1}{2} \bar{u}_A \quad \bar{r}_B = a_B t^2 \frac{1}{2} \bar{u}_B$$

\bar{u}_A & \bar{u}_B are unit vectors in direction
of motion: given in () above.

12-155. At a given instant the football player at A throws a football C with a velocity of 20 m/s in the direction shown. Determine the constant speed at which the player at B must run so that he can catch the football at the same elevation at which it was thrown. Also calculate the relative velocity and relative acceleration of the football with respect to B at the instant the catch is made. Player B is 15 m away from A when A starts to throw the football.



Ball :

$$\begin{aligned} \rightarrow S_c &= 20 \cos 60^\circ t \\ \uparrow -20 \sin 60^\circ &= 20 \sin 60^\circ - 9.81 t \\ t &= 3.53 \text{ s} \\ S_c &= 35.31 \text{ m} \end{aligned}$$

Player B :

$$S_B = V_B t$$

$$\begin{aligned} \text{Require,} \\ 35.31 &= 15 + V_B (3.53) \\ V_B &= 5.75 \text{ m/s} \end{aligned}$$

At the time of the catch

$$\begin{aligned} (V_c)_x &= 20 \cos 60^\circ = 10 \text{ m/s} \\ (V_c)_y &= 20 \sin 60^\circ = 17.32 \text{ m/s} \end{aligned}$$

$$\bar{V}_c = \bar{V}_B + \bar{V}_{c/B}$$

$$10 \hat{i} - 17.32 \hat{j} = 5.75 \hat{i} + (V_{c/B})_x \hat{i} + (V_{c/B})_y \hat{j}$$

$$\rightarrow 10 = 5.75 + (V_{c/B})_x$$

$$\uparrow -17.32 = (V_{c/B})_y$$

$$(V_{c/B})_x = 4.25 \text{ m/s} \rightarrow$$

$$(V_{c/B})_y = 17.32 \text{ m/s} \downarrow$$

$$V_{c/B} = \sqrt{(4.25)^2 + (17.32)^2} = 17.8 \text{ m/s}$$

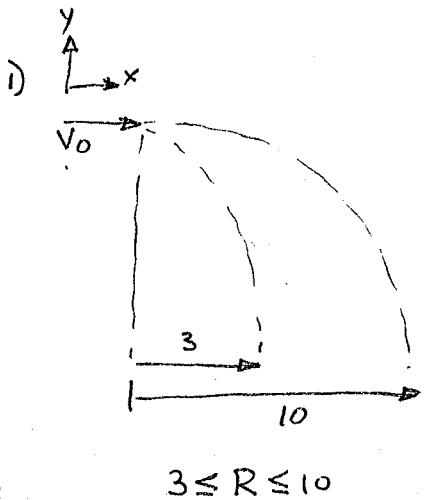
$$\theta = \tan^{-1} \left(\frac{17.32}{4.25} \right) = 76.2^\circ \quad \searrow \theta$$

$$\bar{a}_c = \bar{a}_B + \bar{a}_{c/B}$$

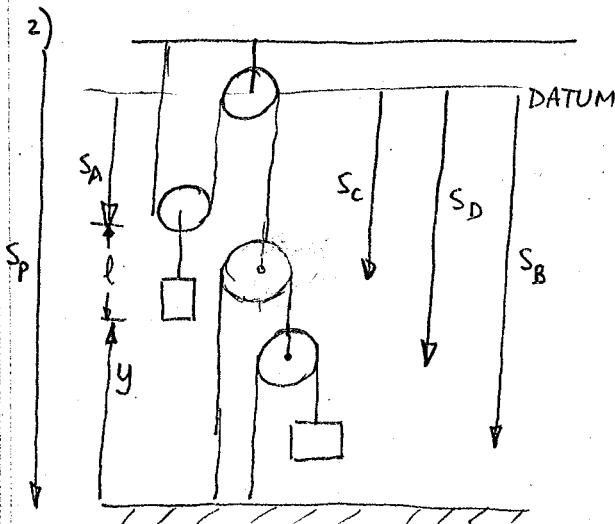
$$-9.81 \hat{j} = 0 + \bar{a}_{c/B}$$

$$a_{c/B} = 9.81 \text{ m/s}^2 \downarrow$$

EXAM #1



$$3.47 \text{ ft/s} \leq V_{0x} \leq 11.58 \text{ ft/s}$$



$$2S_A + S_C = C_1 \Rightarrow 2\dot{V}_A + \dot{V}_C = 0$$

$$(S_P - S_C) + (S_D - S_C) = C_2 \Rightarrow \dot{V}_D = 2\dot{V}_C$$

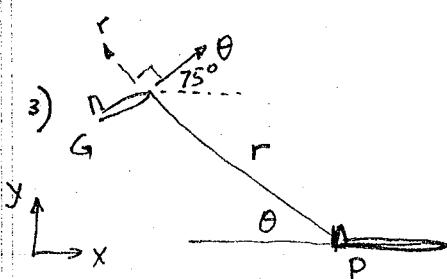
$$(S_P - S_D) + (S_B - S_D) = C_3 \Rightarrow \dot{V}_B = 2\dot{V}_D$$

$$S_A + l + y = S_P \Rightarrow \ddot{V}_A = -\ddot{y}$$

$$y = \frac{t^2}{4} \Rightarrow \ddot{y} = \frac{1}{2} \text{ m/s}^2 \quad \ddot{V}_A = a_A = -\frac{1}{2} \text{ m/s}^2$$

$$a_B = 2a_D = 2(2a_C) = 2(2(-2a_A)) = -8a_A$$

$$= -8\left(-\frac{1}{2}\right) = 4 \text{ m/s}^2$$



Given

$$\bar{V}_G = \bar{V}_P + \bar{V}_{G/P}$$

$$\bar{V}_P = 200 \text{ km/hr} \quad \bar{l} =$$

$$r = 60 \text{ m} = \text{const} \Rightarrow \dot{r} = \ddot{r} = 0$$

$$\theta = 15^\circ \quad \dot{\theta} = 5^\circ/\text{sec} = 0.0873 \text{ rad/sec}$$

$$\ddot{\theta} = 0$$

$$(V_{G/P})_r = \dot{r} = 0 \quad (V_{G/P})_\theta = r\dot{\theta} = 60(0.0873) = 5.24 \text{ m/s} \quad \bar{V}_{G/P} = (\bar{V}_{G/P})_\theta = 5.24 \bar{u}_\theta$$

θ direction is 75° to horizontal $\therefore \bar{u}_\theta = \bar{l} \cos 75^\circ + \bar{j} \sin 75^\circ$

$$\bar{V}_G = 55.56 \bar{i} + 5.24 \cos 75^\circ \bar{l} + 5.24 \sin 75^\circ \bar{j} = 56.92 \bar{i} + 5.06 \bar{j} \text{ m/s}$$

$|\bar{V}_G| = 57.14 \text{ m/s}$

$$\bar{a}_G = \bar{a}_P + \bar{a}_{G/P} \quad \bar{a}_P = \bar{0} \quad (\text{constant vel})$$

$$(a_{G/P})_r = \ddot{r} - r\dot{\theta}^2 = 0 - 60(0.0873)^2 = -4.57 \text{ m/s}^2$$

$$(a_{G/P})_\theta = r\ddot{\theta} + 2\dot{r}\dot{\theta} = 0 - 0 = 0$$

$$\bar{a}_G = (a_{G/P})_r = -4.57 \bar{u}_r \quad |\bar{a}_G| = 4.57 \text{ m/s}^2$$

3b.) Given $\dot{r} = 2 \text{ m/s} \Rightarrow \ddot{r} = 0$ $\bar{a}_P = 5 \text{ km/hr/s} \bar{t} = 1.389 \text{ m/s}^2 \bar{t}$
 $\theta = \text{const} \Rightarrow \dot{\theta} = \ddot{\theta} = 0$

$$\bar{a}_G = \bar{a}_P + \bar{a}_{G/P}$$

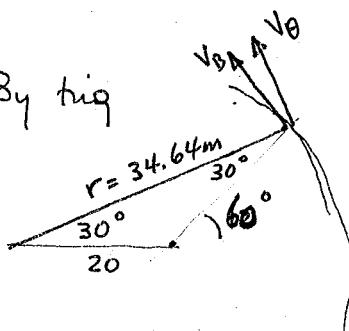
$$(a_{G/P})_r = \ddot{r} - r\dot{\theta}^2 = 0 \quad (a_{G/P})_\theta = r\ddot{\theta} + 2\dot{r}\dot{\theta} = 0$$

$$\therefore \bar{a}_G = \bar{a}_P = 1.389 \text{ m/s}^2 \bar{t} \quad |\bar{a}_G| = 1.389 \text{ m/s}^2$$

Note: the info given was about the relative change in r between the glider & the plane

Note that 3a) could have also been solved using n, t coordinates where t is in θ direction n in $-r$ direction

4) By trig



$$r = 2(20 \cos 30^\circ) = 40 \cos \theta$$

$$\dot{r} = -40 \sin \theta \dot{\theta}$$

$$\ddot{r} = -40 \cos \theta \dot{\theta}^2 - 40 \sin \theta \ddot{\theta}$$

$$V = 30 \text{ m/s} = \sqrt{V_r^2 + V_\theta^2} = \sqrt{\dot{r}^2 + (r\dot{\theta})^2}$$

$$= \sqrt{(-40 \sin \theta)^2 \dot{\theta}^2 + (40 \cos \theta)^2 \ddot{\theta}^2}$$

$$30 = 40 \dot{\theta} \Rightarrow \dot{\theta} = .75 \text{ rad/s}$$

also $V_B \cos 30^\circ = V_\theta = r\dot{\theta}$

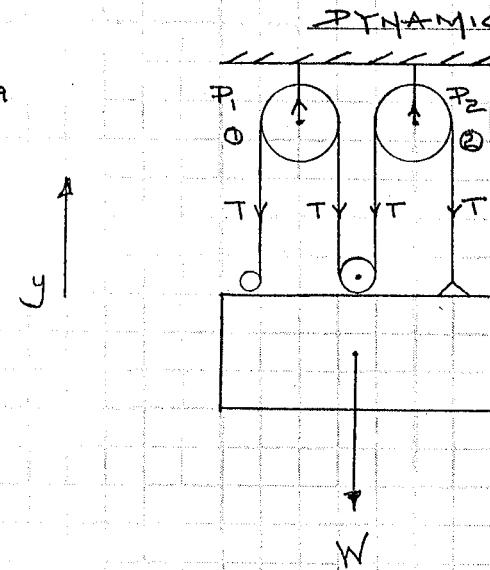
$$30 \cos 30^\circ = 40 \cos 30^\circ \dot{\theta} \Rightarrow \dot{\theta} = .75 \text{ rad/s}$$

HW #5

13-19, 25, 32, 38 in 5 pages

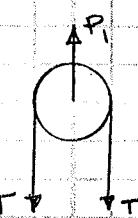


13-19



TENSION IN STRING IS
CONSTANT

FREE BODY OF PULLEY ①



$$\Sigma F_y = P_1 - T - T = 0$$

$$P_1 = 2T$$

FREE BODY OF ② REVEALS
THE SAME IE.

$$P_2 = 2T$$

∴ NET FORCE ACTING ON ELEVATOR

$$F_N = 4T - W$$

$$\text{BUT } F_N = M_E a_E$$

WHERE M_E = MASS OF ELEVATOR

a_E = ACC. " "

$$a_E = \frac{4T - W}{M_E}$$

$$\text{BUT } v_E^2 = v_{E_0}^2 + 2a_E s_E$$

GIVEN

$$v_{E_0} = 0 \text{ m/s}$$

$$v_E = \frac{(4T - W)}{2M_E}$$

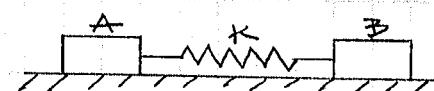
$$v_E = 3.62 \text{ m/s}$$



Florida International University
The State University of Florida at Miami

College of Engineering & Applied Sciences

13-25



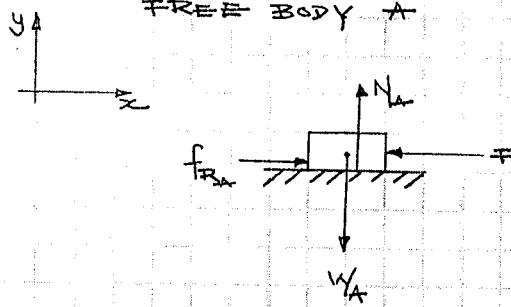
GIVEN $W_A = 8 \text{ lb}$

$W_B = 6 \text{ lb}$

SPRING CONSTANT $K = 20 \text{ lb/ft}$

COMPRESSED DISTANCE = 0.2 FT

FREE BODY A



F IS FORCE EXERTED BY SPRING

$$F = Kx$$

⇒ NET FORCE ACTING ON A

$$F_{\text{net}} = f_{\text{FA}} - F$$

$$f_{\text{FA}} = \mu N$$

$$\text{BUT } F_{\text{net}} = m_A a_A$$

$$\Rightarrow m_A a_A = \mu N_A - Kx$$

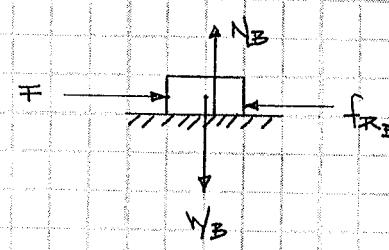
$$a_A = \frac{\mu N_A - Kx}{m_A}$$

$$m_A = \frac{8 \text{ lb}}{32.2 \text{ ft/s}^2}$$

$$\mu = 0.2$$

$$a_A = -9.66 \text{ ft/s}^2$$

FREE BODY B



NET FORCE ACTING ON B

$$F_{\text{net}} = F - f_{\text{FB}}$$

$$a_B = \frac{Kx - \mu N_B}{m_B}$$

$$a_B = 15.03 \text{ ft/s}^2$$



$$\int_0^t dt = \int_0^s \frac{ds}{(v_0 - ks/m)}$$

$$\text{LET } u = v_0 - \frac{ks}{m}$$

$$du = -\frac{k}{m} ds$$

$$-\frac{m}{k} du = ds$$

$$\Rightarrow t = -\frac{m}{k} \ln \left(v_0 - \frac{ks}{m} \right) \Big|_0^s$$

$$\text{BUT } s = \frac{1}{2K} m v_0$$

$$\Rightarrow t = -\frac{m}{k} \ln \left(v_0 - \frac{1}{2K} m v_0 \left(\frac{k}{m} \right) \right) + \frac{m}{k} \ln v_0$$

$$= -\frac{m}{k} \ln \left(\frac{1}{2} v_0 \right) + \frac{m}{k} \ln v_0$$

$$= \frac{m}{k} \left(\ln \frac{1}{2} v_0 + \ln v_0 \right)$$

$$= \frac{m}{k} \left(\ln \left(\frac{v_0}{2} \right) \right)$$

$$t = \frac{m}{k} \ln 2 \text{ SECS} \quad \checkmark$$

$$\text{also } m \frac{dv}{dt} = -kv$$

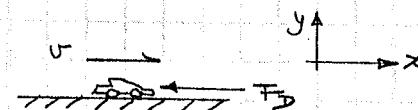
$$\therefore \frac{mdv}{-kv} = dt$$

$$\frac{m}{k} - \ln v \Big|_{v_0}^{kv_0} = t$$

$$\frac{m}{k} \ln 2 = t$$



13.32



F_D = DRAG RESISTANCE OF WIND

$$F_D = -Kv$$

INITIAL VELOCITY = v_0

FINAL VELOCITY = $\frac{1}{2}v_0$

MASS OF CAR = m

$$\Rightarrow ma = -Kv$$

$$\text{BUT } ads = v \, dv$$

$$a = -\frac{Kv}{m}$$

$$\Rightarrow ds = \frac{-mv}{K} \, dv$$

$$s = \int_{v_0}^{\frac{1}{2}v_0} -\frac{m}{K} \, dv = -\frac{mv}{K} \Big|_{v_0}^{\frac{1}{2}v_0}$$

$$s = \frac{1}{2} \frac{mv_0}{K} \quad (\text{m, ft, km, ?})$$

AND

$$s = -\frac{mv}{K} + C$$

$$\text{WHEN } s = 0, v = v_0$$

$$\Rightarrow 0 = -\frac{mv_0}{K} + C$$

$$C = \frac{mv_0}{K}$$

$$\text{Now } s = -\frac{mv}{K} + \frac{mv_0}{K}$$

$$\text{BUT } v = \frac{ds}{dt}$$

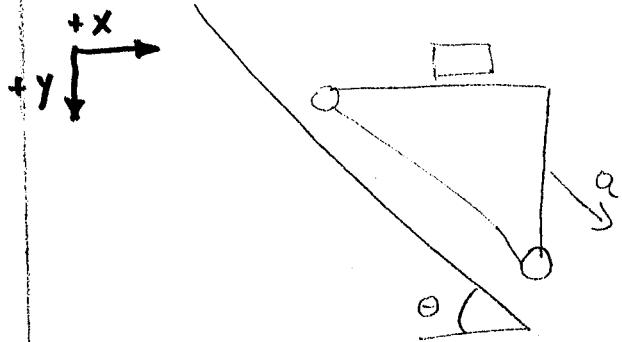
$$s = -\frac{mds}{Kdt} + \frac{mv_0}{K}$$

$$\frac{m}{K} \frac{ds}{dt} = \frac{mv_0}{K} - s$$

$$\frac{ds}{dt} = v_0 - \frac{Ks}{m}$$

$$dt = \frac{ds}{v_0 - \frac{Ks}{m}}$$

13-38



$$m = 10 \text{ kg}$$

$$\mu_s = 0.3$$

$$a = 6 \text{ m/s}^2$$

$$\downarrow mg$$

$$\rightarrow \mu_s N$$

$$\uparrow N$$

FBD for box

For no slip cart & box have same a

$$\rightarrow \sum F_x = ma$$

$$+\downarrow \sum F_y = may$$

$$\mu_s N = ma \cos \theta$$

$$mg - N = ma \sin \theta$$

$$mg - \left(\frac{ma \cos \theta}{\mu_s} \right) = ma \sin \theta$$

$$g \mu_s = (\cos \theta + \mu_s \sin \theta) a$$

$$9.81 (0.3) = \cos \theta + 0.3 (\sin \theta) (6)$$

$$2.943 = \cos \theta + 1.8 \sin \theta$$

$$-2.943 + \cos \theta + 1.8 \sin \theta = 0$$

$$\boxed{\theta = 78.7^\circ}$$

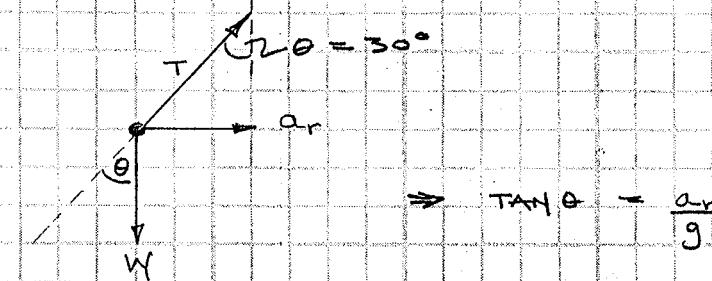
SOLN TO HW #6

13-48, 64, 66, 77, 90 in 6 pages



13-48

FREE BODY OF PLANE



BUT

$$a_r = \frac{v^2}{r}$$



$$5.66 = \frac{v^2}{r}$$

$\theta = 30^\circ$

$$r = 8 + 4 \sin 30^\circ$$
$$= 10 \text{ m}$$

$$v = 7.52 \text{ m/s}$$

MAT WEIGHTS 50 kg

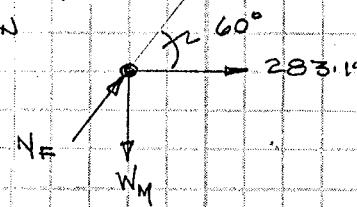


FORCE TOWARD CENTER $F_c = m a_r$

$$= 50 (5.66) = 283.19$$

FREE BODY

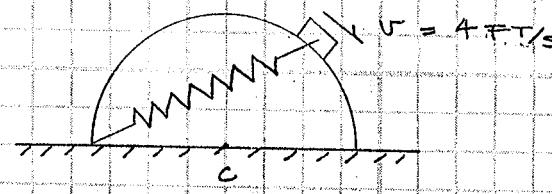
OF MAN



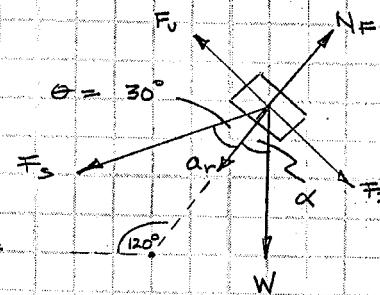
$$\cos 60^\circ = \frac{283.19}{N_F}$$

$$N_F = 566.4 \text{ N}$$

1349 in SW 11, 20
1349 in SW 11, 20



FREE BODY OF BLOCK

 F_u = SPRING'S FORCECOMPONENT ACTING $\theta = 30^\circ$
UP CURVE, F_D = WEIGHT COMPONENT
ACTING DOWN CURVE

$v = 4 \text{ FT/S}$

 F_s = FORCE DUE TO SPRING a_r = ACCELERATION TOWARD CENTER. W = WEIGHT OF BLOCK

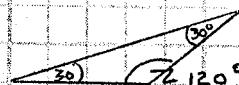
$a_r = \frac{v^2}{r} = \frac{4^2}{5}$

$a_r = 3.33 \text{ FT/S}^2$

$\pi r \theta = 30^\circ \text{ LENGTH OF SPRING}$

$L = \sqrt{9 + 9 - 18 \cos 120^\circ}$

$L = 5.20$

STRETCHED DISTANCE x GIVEN BY

$x = 5.20 - x_0, x_0 = 3\pi r$

$x = 2.20 \text{ ft}$

$$\Rightarrow F_s = kx \\ = 2(2.20)$$

$F_s = 4.40 \text{ lb}$

$\Rightarrow \sum F_y - Ma_r = -N_F + W \cos \alpha + F_s \cos \theta$

$N_F = -\frac{5}{32.2}(5.33) + 4.4 \cos 30^\circ + 5 \cos 30^\circ$

$N_F = 7.31 \text{ lb}$

NET FORCE ACTING DOWN CURVE

$$\begin{aligned} \sum F_x &= F_D - F_u = ma_f \\ &= W \sin \alpha - F_s \sin \theta \\ &= 5 \sin 30^\circ - 4.4 \sin 30^\circ \end{aligned}$$

$(m = \frac{5}{32.2} \text{ SLUGS})$

$\Rightarrow ma_f = 0.316$

$a_f = 1.93 \text{ FT/S}^2$

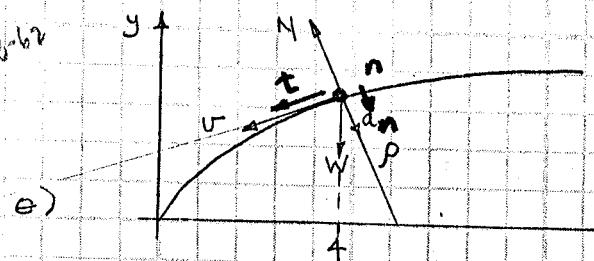


15-66

$$\text{Now } |\alpha| = \sqrt{\alpha_x^2 + \alpha_y^2} = \sqrt{1.93^2 + 5.33^2}$$

$$|\alpha| = 5.67 \text{ FT/S}^2$$

Wn 13-62



GIVEN $v = 4 \text{ M/S}$

MASS (m) = 80KG

$$y = 3(1 - e^{-x/2})$$

$$\Rightarrow \frac{dy}{dx} = \frac{3}{2} e^{-x/2}$$

$$\frac{d^2y}{dx^2} = -\frac{3}{4} e^{-x/2}$$

$$\text{WHEN } N \quad x = 4$$

$$\frac{dy}{dx} = \frac{3}{2} e^{-2} \\ = 0.203$$

$$\Rightarrow \tan \theta = 0.203$$

$$\theta = 11.48^\circ$$

$$\Rightarrow \text{ACCELERATION } a_\theta = g \sin \theta \text{ from } w \sin \theta = m a_\theta$$

$$= 9.81 \sin 11.48^\circ$$

$$a_\theta = 1.95 \text{ M/S}^2$$

$$\rho = \left[1 + \left(\frac{dy}{dx} \right)^2 \right]^{3/2}$$

$$\frac{d^2y}{dx^2}$$

$$\rho = \frac{-2 \left[1 + (0.203)^2 \right]^{3/2}}{(0.203)}$$

$$\rho = 10.47 \text{ M}$$

$$\Rightarrow a_n = \frac{v^2}{\rho} = \frac{16}{10.47}$$

$$a_n = 1.53 \text{ M/S}^2$$

\Rightarrow FORCE TOWARD CENTER



Florida International University
The State University of Florida at Miami

College of Engineering & Applied Sciences

$$\text{WHEN } \dot{\theta} = 2/30 \text{ rad/s}$$

$$\Rightarrow r = -600(\ddot{\theta} + \frac{4}{900})$$

(WHEN $\dot{\theta} = 0$)

$$\Rightarrow \ddot{\theta} = -\left(0 \times r\right) - 1200(0)^2 \frac{2}{30}$$

$$(1200)^2 \dot{\theta}$$

$$\ddot{\theta} = 0 \text{ rad/s}$$

$$\Rightarrow a_r = r - r(\dot{\theta})^2$$

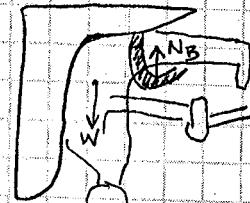
$$= -2.667 - 1200\left(\frac{2}{30}\right)^2$$

$$a_r = -8.00 \text{ ft/s}^2$$

r IS FORCE TOWARD CENTER

$$F_p = \frac{150}{32.2} (-8.00)$$

$$= -37.27 \text{ lb}$$



$$\Rightarrow N_B - W = F_p = m a_r$$

$$N_B = W + F_p$$

$$= 150 - 37.27$$

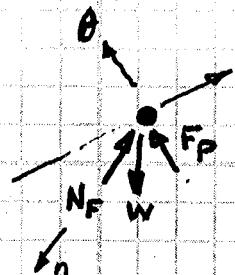
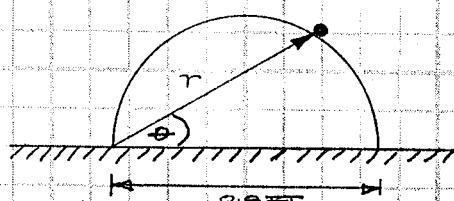
$$N_B = 113 \text{ lb}$$



Florida International University
The State University of Florida at Miami

College of Engineering & Applied Sciences

15-77



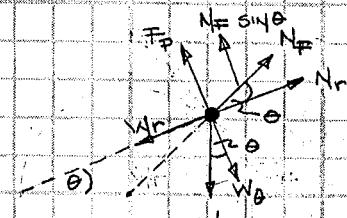
$$r = 0.8 \cos \theta$$

$$\dot{r} = -0.8 \sin \theta \cdot \dot{\theta}$$

$$\ddot{r} = -(0.8 \sin \theta) \ddot{\theta} + (-0.8 \cos \theta) \dot{\theta}^2$$

$$\ddot{r} = -0.8 (\ddot{\theta} \sin \theta + \dot{\theta}^2 \cos \theta)$$

FREE BODY OF PARTICLE



N_r - comp of N_F in r dir

W_r - comp of W in r dir

W_θ - comp of W in θ dir

F_P is in θ dir

$$\Rightarrow \sum F_r = N_r - W_r = m a_r$$

$$N_F \cos 30^\circ - W \sin \theta = m a_r$$

$$0.866 N_F - 0.25 = \frac{0.5}{32.2} a_r \quad \text{①}$$

$$\sum F_\theta = F_P + N_F \sin \theta - W_\theta = m a_\theta$$

$$F_P = m a_\theta + W \cos \theta - N_F \sin \theta \quad \text{②}$$

$$a_\theta = \ddot{r} \dot{\theta} + r \ddot{\theta}$$

$$= 0.8 \cos(30^\circ) 0.8 + 2(-0.8)(0.4)(\sin 30^\circ)(0.4)$$

$$a_\theta = 0.4263 \text{ ft/s}^2$$

$$\text{AND } a_r = \dot{r} - r \dot{\theta}^2$$

$$= -0.8 (0.8 \sin 30^\circ + 0.4^2 \cos 30^\circ)$$

$$(2 \pi)^2 - 0.542 \text{ ft/s}^2$$



Florida International University
The State University of Florida at Miami

College of Engineering & Applied Sciences

$$F_N = m a_n$$

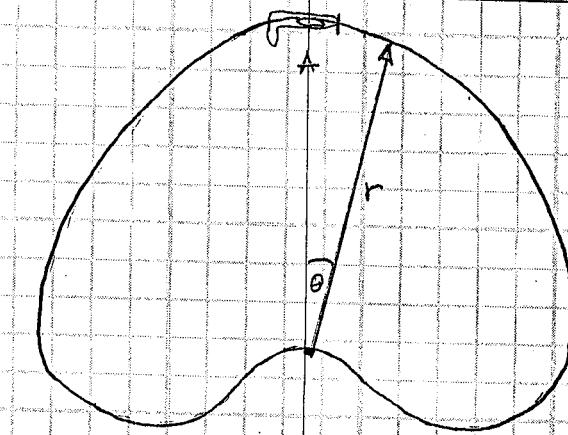
$$= 80 (1.53)$$

$$\Sigma F_n = W \cos \theta - N = m a_n = F_N$$

$$\Rightarrow \text{NORMAL FORCE} = W \cos 11.48^\circ - 122.3$$

$$= 64.7 \text{ N}$$

13-90



$$r = 600(1 + \cos \theta) \text{ ft}$$

$$\text{AT } A \quad v_p = 80 \text{ ft/s}$$

$$\dot{r} = -600 \sin \theta \dot{\theta}$$

$$\ddot{r} = (-600 \sin \theta) \ddot{\theta} - \dot{\theta}^2 600 \cos \theta$$

$$\ddot{r} = -600(\ddot{\theta} + \dot{\theta}^2 \cos \theta)$$

$$\text{VELOCITY} \quad v_p = r \dot{\theta}$$

$$\Rightarrow 80 = r(\theta = 0) \dot{\theta}$$

$$\dot{\theta} = \frac{80}{1200}$$

$$\dot{\theta} = \frac{2}{30} \text{ rad/s}$$

$$\text{SINCE} \quad v_r = \sqrt{(r \dot{\theta})^2 + (r \dot{\theta})^2}$$

$$\Rightarrow v_r = \frac{1}{2} \sqrt{(r \dot{\theta})^2 + (r \dot{\theta})^2} (\dot{r} \dot{\theta} + r \ddot{\theta} \dot{\theta} + r \dot{\theta} \ddot{\theta} + \dot{r} \dot{\theta} \dot{\theta})$$

$$\text{BUT} \quad \dot{r} = 0 \Rightarrow 0 = \dot{r} \dot{\theta} + r \ddot{\theta} \dot{\theta} + \dot{r} \dot{\theta} \dot{\theta}$$

$$0 = \dot{r} \dot{\theta} + r^2 \dot{\theta} \ddot{\theta} + r \dot{r} \dot{\theta}^2$$

$$r^2 \dot{\theta} \ddot{\theta} = -\dot{r} \dot{\theta} - r \dot{r} \dot{\theta}^2$$

$$\ddot{\theta} = \frac{-\dot{r} \dot{\theta} - r \dot{r} \dot{\theta}^2}{r^2 \dot{\theta}}$$



Florida International University
The State University of Florida at Miami

College of Engineering & Applied Sciences

$$\text{PUT } \alpha_F = -0.542 \text{ IN } \theta \text{ TO GET } F_F$$

$$0.866 N_F - 0.2S = \frac{0.5}{32.2} (-0.542)$$

$$N_F = 0.2790 \text{ lb}$$

$$\text{FROM } \textcircled{B} \Rightarrow F_P = \frac{0.5}{32.2} (0.4263) + 0.5 \cos 30^\circ - 0.2790 \sin 30^\circ$$

$$F_P = 0.30 \text{ lb}$$

HW #7 in 3 pages

14-5, 12, 17



Florida International University
The State University of Florida at Miami

College of Engineering & Applied Sciences

Dynamics, 2-13-90 | Professor Levy

PROB 14-5 Given: $W = 15 \text{ lb}$, $\mu_k = 0.15$

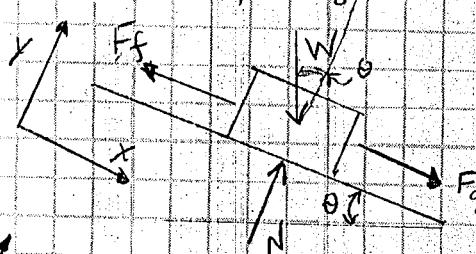
$$v_B = ? , s_B = ?$$

$$\Delta y = 7 \text{ ft}$$

$$s = 25 \text{ ft} = AB$$

$$\theta = 16.26^\circ$$

Free Body Diagram:



$$v_A = 6 \text{ ft/s}$$

$$\Delta y = 7 \text{ ft}$$

$$s_A =$$

$$v_A = 6 \text{ ft/s}, s_A = 3 \text{ ft}$$

$$\rightarrow 3 \text{ ft} = 1$$

$$A$$

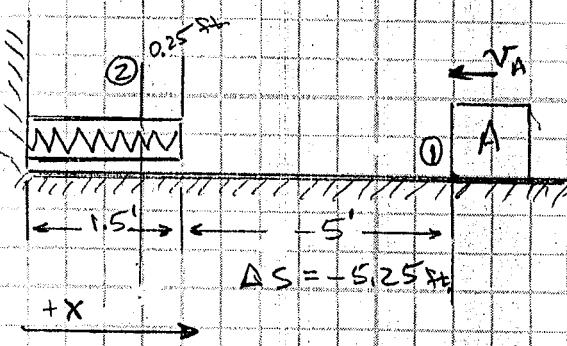
$$\Delta s$$

$$B$$



Dynamics, 2-13-910 | Professor Levy

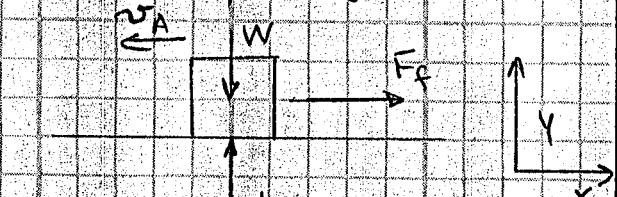
PROBS. 14-12 | GIVEN: $K = 50 \text{ lb/in.}$, $s_0 = 2 \text{ ft.}$, $W = 4 \text{ lb}$.



$$① s_2 = 1.5 \text{ ft.}, \mu_k = 0.2$$

$$② s_1 = 1.25 \text{ ft.}$$

Free Body Diagram



Work due to friction

$$= F_f \Delta s = \mu_k N (-5.25)$$

Work due to spring

$$= -\left(\frac{1}{2}ks_2^2 - \frac{1}{2}ks_1^2\right) = -\frac{1}{2}ks_2^2 + \frac{1}{2}ks_1^2$$

$$T_1 + \sum U_{1-2} = T_2^0, \text{ but } T_2 = 0$$

$$\Rightarrow T_1 = -\sum U_{1-2} = -\left[\mu_k N(-5.25) + \left(-\frac{1}{2}ks_2^2 + \frac{1}{2}ks_1^2\right)\right]$$

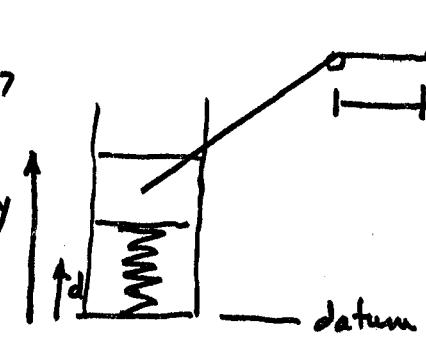
$$\frac{1}{2}m_A v_A^2 = -\left[0.2(4)(-5.25) - \left(\frac{1}{2}(50)(0.75)^2 - \frac{1}{2}(50)(0.5)^2\right)\right]$$

$$v_A \approx 13.91 \text{ ft/s}$$

$$s_2 = s_{f_2} - s_0$$

$$s_1 = s_{f_1} - s_0$$

14-17

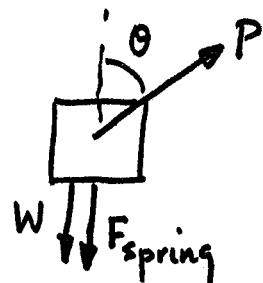


$$\text{since } T_1 + \sum U_{1-2} = T_2$$

and $v|_y = 0 + v|_d = 0$

then $\sum U_{1-2} = 0$

forces that do work are found from FBD



$$U_{1-2} (\text{of weight}) = -W(y-d)$$

$$U_{1-2} (\text{of spring}) = -\frac{1}{2}k(s_2^2 - s_1^2)$$

$$s_2 = y-d \quad] \text{ measured from}$$

$$s_1 = d-d=0 \quad] \text{ unstretched length}$$

$$U_{1-2} (\text{of } P) = \int_d^y P \cos \theta \, dy$$

note: cannot pull $P \cos \theta$ out of integral since θ changes as s changes
and y changes

$$\therefore \sum U_{1-2} = \int_d^y P \cos \theta \, dy - W(y-d) - \frac{1}{2}k([y-d]^2 - 0)$$

$$\therefore \int_d^y P \cos \theta \, dy = U_{1-2} (\text{of } P) = \left[\frac{1}{2}k(y-d) + W \right] (y-d)$$

note: cannot take $\sum F_y = 0$ & multiply by Δy to get this expression
since work = $\int \bar{F} \cdot d\bar{r}$ and \bar{F} changes with position

$$\text{here } \bar{F} = P \cos \theta - W - F_g = P \cos \theta - W - k(y-d)$$

$$\bar{F} \Delta y = P \cos \theta (y-d) - W(y-d) - k(y-d)^2 \neq \sum U_{1-2}$$

HW # 8

14-55, 62, 64 in 4 pages

(55)

$$\frac{21}{30}$$

The stretched length of the rubber band is :

$$l = \sqrt{(240)^2 + (0.05)^2} = 0.245 \text{ m}$$

$$\text{The energy of the band} = \frac{1}{2}(50)(0.245 - 0.200)^2$$

$$\begin{aligned} &= 0.050625 \text{ J.} \\ \text{Now 2 bands} &= 2(0.050625) = 0.10125 \text{ J} \end{aligned}$$

K.E of Pellet = stored energy of the two bands

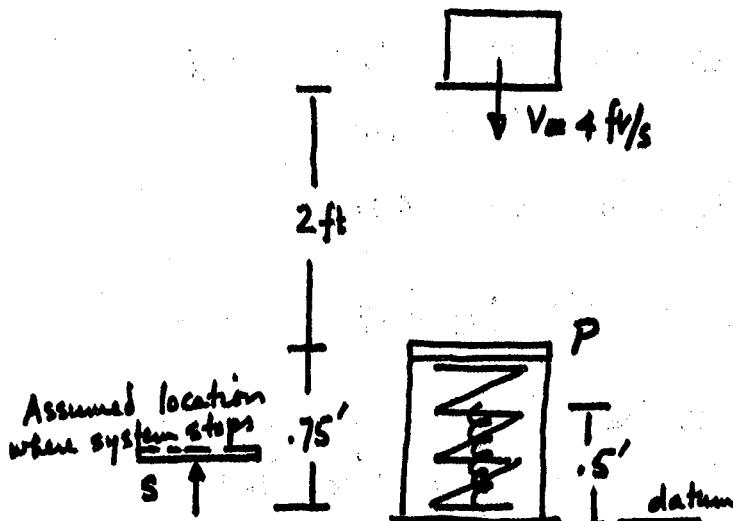
$$\frac{1}{2}mv^2 = 0.10125$$

$$\frac{1}{2}(0.025)(v^2) = 0.10125$$

$$v^2 = 8.1$$

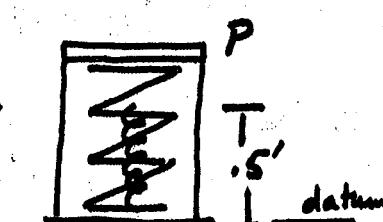
$$v = \underline{\underline{2.85 \text{ m/s}}}$$

(62)



Assumed location
where system stops

.75'



$$\Delta s_2 = 1 - s$$

$$\Delta s_3 = .5 - s$$

$$T_1 + V_1 = 41.2345 = T_2 + V_2$$

$$480s^2 - 650s + 213.7655 = 0$$

$$s = .7915 \text{ ft}$$

$$s = .5626 \text{ ft}$$

] in either case this implies that
the inner spring is not compressed

Therefore

$$V_2 = Ws + \frac{1}{2}k\Delta s_2^2 = 180 - 350s + 180s^2$$

$$\therefore T_1 + V_1 = T_2 + V_2$$

$$41.2345 = 180 - 350s + 180s^2$$

$$180s^2 - 350s + 138.7655 = 0$$

$$s = 1.3897 \text{ ft}$$

$$s = \underline{.5547 \text{ ft}}$$

But we want to find how far the plate P deforms

$$= .75 - .5547 = \underline{\underline{.1953 \text{ ft}}}$$

All forces are conservative

$$T_1 = \frac{1}{2}mv^2 = \frac{1}{2} \frac{10}{32.2} (4)^2 = 16 \text{-ft}$$

$$V_1 = W(2.75) + \frac{1}{2}k\Delta s^2 \\ = 10(2.75) + \frac{1}{2}30 \cdot 12 \cdot (.25)^2 = 38.75 \text{ lb-ft}$$

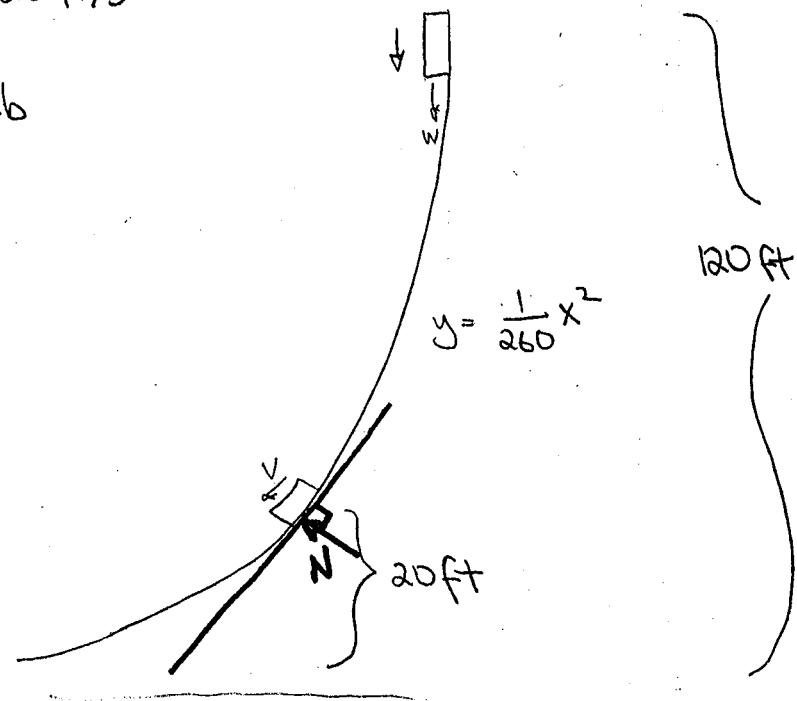
$$T_2 = 0$$

$$V_2 = Ws + \frac{1}{2}k\Delta s_2^2 + \frac{1}{2}k'\Delta s_3^2 \\ = 10s + \frac{1}{2}30 \cdot 12 (1-s)^2 + \frac{1}{2}50 \cdot 12 (.5-s)^2 \\ = 10s + 180(1-2s+s^2) + 300(.25-s+s^2) \\ = 25s - 650s + 480s^2$$

(64)

$$g = 32.2 \text{ ft/s}^2$$

$$W = 5000 \text{ lb}$$



By the conservation of energy :

$$Wh_1 = Wh_2 + \frac{1}{2} MV^2$$

$$500(120) = 500(20) + \frac{1}{2} \left(\frac{500}{32.2}\right) V^2$$

$$60000 = 10000 + 7.764 V^2$$

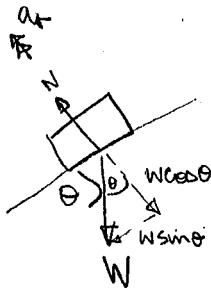
$$V^2 = 6439.98$$

$$V = \underline{\underline{80.25 \text{ ft/s}}} \checkmark$$

$$y = \frac{1}{260} x^2$$

$$\frac{dy}{dx} = \frac{1}{130} x, \quad \frac{d^2y}{dx^2} = \frac{1}{130}$$

$$\text{at } y = 20, x = 72.11$$



$$\theta = \tan^{-1} \frac{72.11}{130} = 29.017^\circ$$

$$\text{Now } P = \left| \sqrt{\frac{1 + (\frac{dy}{dx})^2}{\frac{dy}{dx}} x^2} \right|^{3/2}$$

$$P = \left| \sqrt{\frac{1 + (0.5547)^2}{130}} x \right|^{3/2} = 194.4 \text{ ft}$$

$$a_r = \frac{V^2}{P} = \frac{6439.98}{194.4} = 33.13 \text{ ft/s}^2$$

$$M_{ar} = N - W \cos \theta$$

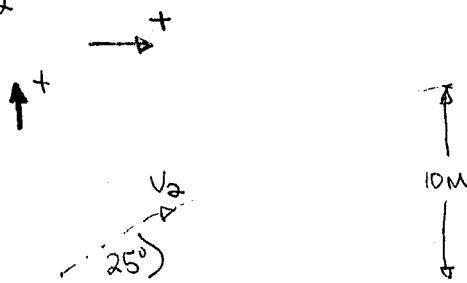
$$N = M_{ar} + W \cos \theta = (500 \frac{3}{32.2}) 33.13 + 500 \cos 29.017^\circ$$

$$N = \underline{951.68 \text{ lb}}$$

HW # 9 in 5 pages EGN 3321

15- 8, 18, 23, 31 & 39

(8)

For v_2 : u = initial velocity

$$\text{Using } v^2 = u^2 + 2as$$

$$0 = + (v_2 \sin 25^\circ)^2 - 2(9.81)10$$

$$v_2 \sin 25^\circ = 14.007$$

$$v_2 = 33.144 \text{ m/s}$$

By conservation of linear momentum: initial velocity is

x+direction

$$\leftarrow 15 \quad \therefore v_x = -15 \text{ m/s}$$

$$v_y = 0 \text{ m/s}$$

$$M(v_x)_1 + I_x = M(v_x)_2$$

$$-M(15) + I_x = M(v_2 \cos 25^\circ)$$

$$I_x = 0.18(30.04) + 0.18(15)$$

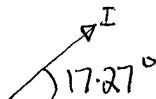
$$I_x = 8.107 \text{ N-s}$$

$$M(v_y)_1 + I_y = M(v_y)_2$$

$$0 + I_y = 0.18(v_2 \sin 25^\circ)$$

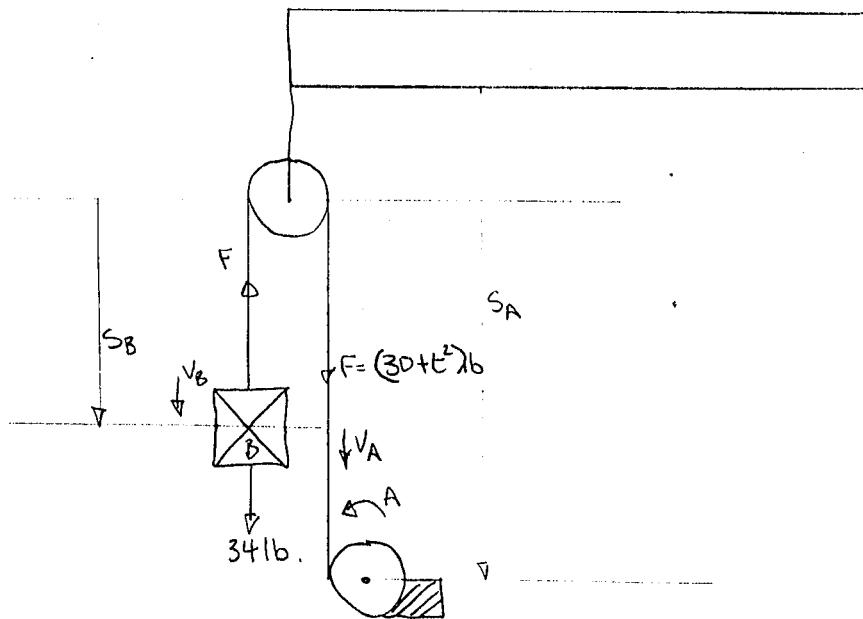
$$I_y = 0.18(14.007) = 2.52126 \text{ N}$$

$$I = \sqrt{(I_x)^2 + (I_y)^2} = \underline{8.5 \text{ N-s}}$$



Homework Problems

(18) Ch 15



For block B to begin moving:

$$30 + t^2 = 34 \Rightarrow t^2 = 4 \Rightarrow t = \pm 2$$

$t = 2 \text{ sec.}$

By conservation of linear momentum: (after 4 sec)

$$34t - \int_2^4 (30 + t^2) dt = MV_2$$

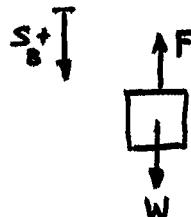
$$34(2) - \left[30t + \frac{1}{3}t^3 \right]_2^4 = MV_2$$

$$68 - (141\frac{1}{3} - 62\frac{2}{3}) = \frac{34}{32 \cdot 2} V_2$$

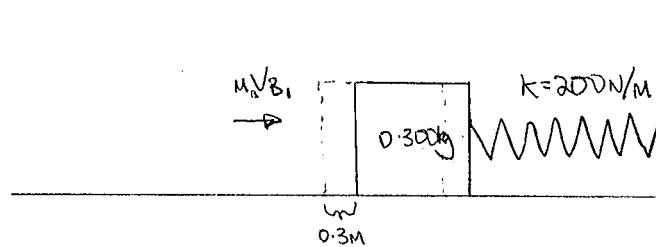
$$68 - 78\frac{2}{3} = \frac{34}{32 \cdot 2} V_2$$

$$-10\frac{2}{3} = \frac{34}{32 \cdot 2} V_2 \Rightarrow V_2 = -10.102 \text{ ft/s}$$

indicates velocity is ↑



(23)



$$m_B = 0.02 \text{ kg}$$

$$0.02 v_{B1} = 0.320 v_{B2}$$

$$v_{B2} = 0.0625 v_{B1}$$

By wording of problem
momentum of bullet becomes
momentum of bullet + block
before block starts moving

By Conservation of energy:

$$\left(\frac{1}{2} \times 0.32 \times (0.0625 v_{B1})^2\right) = \frac{1}{2} (200) (0.3)^2$$

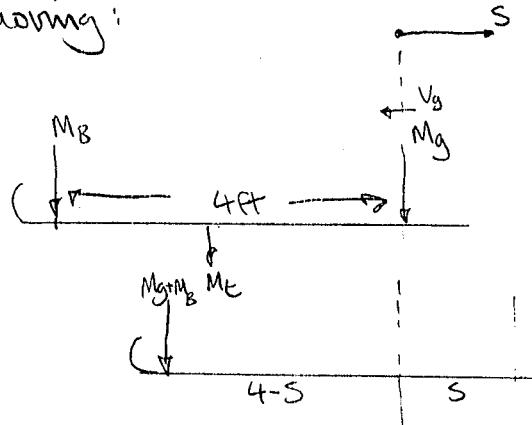
$$(0.00125 v_{B1})^2 = 9$$

$$v_{B1}^2 = 14400$$

$$v_{B1} = \underline{\underline{120 \text{ m/s}}}$$

(31)

For girl moving:



$$-MgV_g + (M_E + M_B)V_E = 0$$

$$MgSg + \frac{100}{32.2} S_E = 0$$

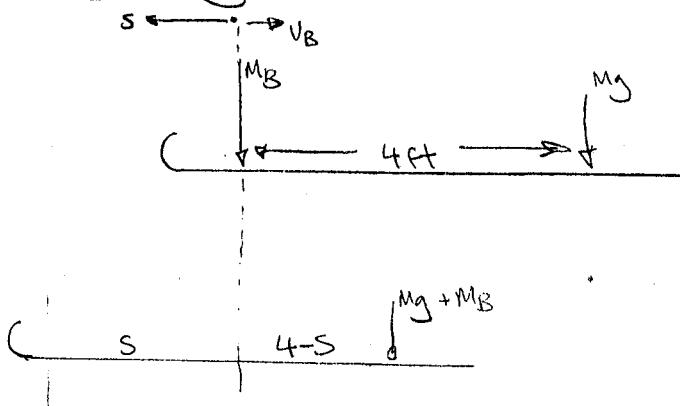
$$-Mg(4-s) + \frac{100}{32.2} S = 0$$

$$\frac{65}{32.2} s + \frac{100}{32.2} S = \frac{65}{32.2}(4)$$

$$S = 1.575757 \text{ ft}$$

integrate and use fact that initially there is no motion

For boy moving:



$$-M_B V_B + (M_E + M_B) V_E = 0$$

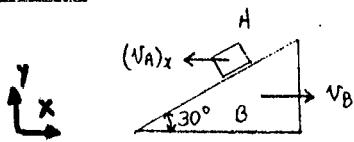
$$-M_B S_B + (M_E + M_B) S_E = 0$$

$$-M_B(4-s) + \frac{85}{32.2} S = 0$$

$$\frac{80}{32.2} S + \frac{85}{32.2} S = \frac{80}{32.2}(4) \Rightarrow S = 1.939394 \text{ ft}$$

Thus the net distance toboggan moves = 0.363636 ft (\rightarrow)

15-39



$$\rightarrow \sum m(v_1) = \sum m(v_2)$$

$$0 = 30 v_B - 5 (v_A)_x$$

$$(v_A)_x = 6 v_B$$

$$\vec{v}_B = \vec{v}_A + \vec{v}_{B/A}$$

$$\rightarrow v_B = -(v_A)_x + (v_{B/A})_x$$

$$v_B = -6v_B + (v_{B/A})_x$$

Here conservation of linear momentum only in x direction
Motion down the block implies
no conservation of linear momentum in y direction

Note here v_{A_x} is assumed to be to left $\therefore -$ sign.

$$(v_{B/A})_x = 7 v_B$$

$$\text{Integrate } (S_{B/A})_x = 7 S_B$$

$$(S_{B/A})_x = 0.5 \text{ m}$$

$$\text{thus } S_B = \frac{0.5}{7} = 0.0714 \text{ m} = \underline{\underline{71.4 \text{ mm}}} \rightarrow$$

Integration leads to
 $(S_{B/A})_x = 7 S_B + C$ ← integrating constant

$$\text{initially no motion } \therefore C = 0$$

A moves a relative distance of
 $\leftarrow 0.5 \text{ m horizontally to B}$

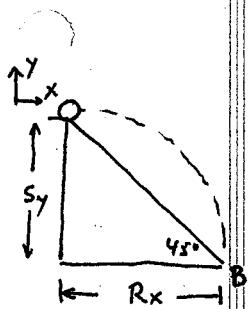
\therefore B moves a relative distance of
 $\rightarrow 0.5 \text{ m horizontally to A}$

HW # 10

in 4 pages

15.51, 15.56, 15.62, 15.53

15-51 This must be looked at as 2 separate events: Projectile motion to just before ball hits, then oblique impact



$$v_{x_0} = v_A = 3 \text{ ft/s} \quad v_{y_0} = 0 \quad R_x = v_A t \quad S_y = S_y^0 + v_{y_0} t - \frac{1}{2} g t^2$$

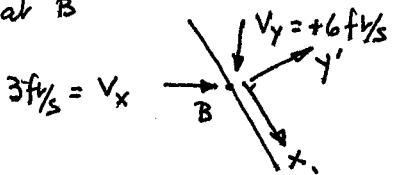
$$\text{also } S_y = R_x \tan 45^\circ \quad (\text{minus since } S_y \text{ is } -)$$

$$\therefore S_y = -\frac{1}{2} g (R_x)^2 / v_A^2 = -R_x \tan 45^\circ \quad \therefore R_x = \frac{2v_A^2 \tan 45^\circ}{g}$$

$$\therefore \text{since } R_x = v_A t = \frac{2v_A^2 \tan 45^\circ}{g} \quad \therefore t = \frac{2v_A \tan 45^\circ}{g}$$

$$\text{also } v_y \text{ at B} = v_{y_0} - gt = -2v_A \tan 45^\circ = -6 \text{ ft/s}$$

at B



} These are components of velocity of Ball. Must now convert them into components along x', y'

$$v_{x' \text{ initial}} = v_x \cos 45^\circ + v_y \cos 45^\circ = 9 \cos 45^\circ$$

$$v_{y' \text{ initial}} = v_x \sin 45^\circ - v_y \sin 45^\circ = -3 \sin 45^\circ$$

Remember along plane of contact (x' axis) velocity is unchanged $\therefore v_{x' \text{ final}} = 9 \cos 45^\circ$

Along line of impact (y' axis) $v_{\text{bearing initial } y'} = -3 \sin 45^\circ = -2.12 \text{ ft/s}$ $v_{\text{plane init}} = 0$

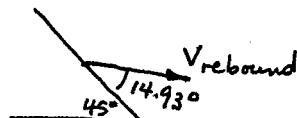
$$v_{\text{bearing final } y'} = ? \quad v_{\text{plane final}} = 0$$

$$\text{also } e = \frac{v_{\text{plane final}} - v_{\text{bearing final } y'}}{v_{\text{bearing initial } y'} - v_{\text{plane initial}}} = 0.8 = \frac{0 - v_{\text{bearing final } y'}}{-2.12 - 0}$$

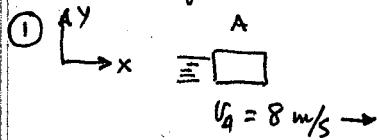
$$v_{\text{bearing final } y'} = (0.8)(2.12) = 1.70 \text{ ft/s} \quad \text{in } +y' \text{ direction}$$

$$\therefore v_{\text{bearing}} = \sqrt{v_{x' \text{ final}}^2 + v_{\text{bearing final } y'}^2} = \sqrt{(6.364)^2 + (1.697)^2} = 6.586 \text{ ft/s}$$

at angle of $\tan^{-1} \left(\frac{1.697}{6.364} \right) = 14.93^\circ$ to the x' axis



15-53 Again we look at this as 2 separate events ① collision
 ② then using velocity of B after collision as the initial velocity for conservation of energy. B initially at rest A has velocity of 8 m/s \rightarrow



$$m_A v_{A_1} + m_B v_{B_1} = m_A v_{A_2} + m_B v_{B_2} \Rightarrow v_{A_1} = v_{A_2} + v_{B_2}$$

also

$$e = \frac{v_{B_2} - v_{A_2}}{v_{A_1} - v_{B_1}^0} \Rightarrow v_{B_2} - v_{A_2} = e v_{A_1}$$

$$\therefore \text{add the 2 eqns } 2v_{B_2} = v_{A_1}(1+e) \quad \text{or} \quad v_{B_2} = \frac{v_{A_1}}{2}(1+e) = .7(8) = 5.6 \text{ m/s}$$

also $v_{A_2} = v_{A_1} - v_{B_2} = 2.4 \text{ m/s}$; let $v_{B_i} = v_{B_2}$ $v_{A_i} = v_{A_2}$

② $T_1 + V_1 = T_2 + V_2$ system is A, B + 2 springs

$$T_1 = \frac{1}{2} m_A v_{A_i}^2 + \frac{1}{2} m_B v_{B_i}^2 = \frac{1}{2}(1.5)(2.4)^2 + \frac{1}{2}(1.5)(5.6)^2$$

$$V_1 = 2 \left[\frac{1}{2} k s_1^2 \right] = 2 \left[\frac{1}{2} (30 \text{ N/m}) (0.5)^2 \right]; s_1 = \text{distance spring is stretched initially}$$

$$T_2 = \frac{1}{2} m_A v_{A_f}^2 + \frac{1}{2} m_B v_{B_f}^2 = \frac{1}{2}(1.5)(2.4)^2 + \frac{1}{2}(1.5)(0)^2$$

note here that block A continues moving unimpeded; B comes to a stop

Note: we could have taken the system as B + 2springs ONLY; then first terms in T_1 & T_2 would be deleted

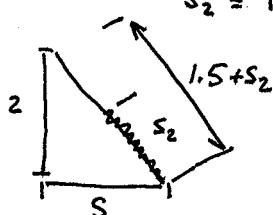
$$V_2 = 2 \left[\frac{1}{2} k s_2^2 \right] = 2 \left[\frac{1}{2} (30) (s_2^2) \right]; s_2 = \text{stretch in the spring when B comes to a stop}$$

$$\therefore \frac{1}{2}(1.5)(2.4)^2 + \frac{1}{2}(1.5)(5.6)^2 + 2 \left(\frac{1}{2} (30) (0.5)^2 \right) = \frac{1}{2}(1.5)(2.4)^2 + \frac{1}{2}(1.5)(0)^2 + 2 \left(\frac{1}{2} (30) (s_2^2) \right)$$

$$s_2 = 1.01686 \text{ m} \quad \text{this represents the stretch as shown,}$$

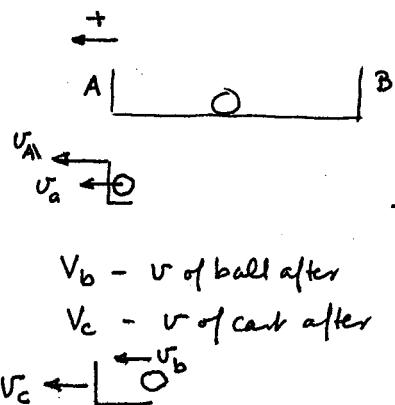
along the direction of the spring, measured from its unstretched length (1.5 m)*

$$s = \sqrt{(1.5+s_2)^2 - (2)^2} = \underline{\underline{1.528 \text{ m}}}$$



* When $s=0$ the spring was stretched 0.5 m. Looking at the diagram the spring was 2 m long when $s=0$ \therefore initial length = $2 - 0.5 \text{ m} = \underline{\underline{1.5 \text{ m}}}$

15-56



By impulse-momentum from start to just before impact

$$M V_0 = M V_a + M_v A$$

V_b - v of ball after

from that point to after the impact

V_c - v of cart after

$$m V_a + M_v A = \underline{m V_b + M V_c} = m V_0 \quad (*)$$

Using e:

$$e = \frac{V_c - V_b}{V_0} \quad (**) \quad \text{if } V_b \text{ is } - \Rightarrow \text{ball moves } \rightarrow$$

Solving

$$e V_0 + V_b = V_c \quad \text{put into} \quad m V_b + M (e V_0 + V_b) = m V_0$$

$$\therefore V_b = \frac{m V_0 - M e V_0}{m + M} = \frac{m - M e}{m + M} V_0 < 0$$

if $M e > m \Rightarrow V_b < 0$

$$\therefore V_c = e V_0 + V_b = e V_0 + \frac{m - M e}{m + M} V_0 = \frac{m(1+e)V_0}{m+M} > 0$$

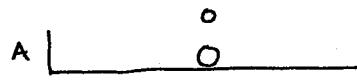
Let's look at B: $m V_b + M V_c = m V'_b + M V'_c = m V_0 \quad V'_b \neq V'_c$ after collision

$$\boxed{V'_c} \quad e = \frac{V'_b - V'_c}{V_c - V_b} = \frac{V'_b - V'_c}{e V_0} \quad \text{from } (**)$$

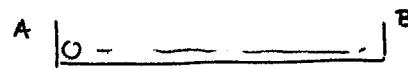
$$\therefore e^2 V_0 = V'_b - V'_c \quad \text{etc} \quad \therefore V'_b = \frac{(m - M e)^2}{m + M} V_0 \quad V'_c = \frac{m(1+e^2)}{m+M} V_0$$

Note: $V'_c < V'_b$ since $e^2 < e$ also $V'_b > V_b$ for same reason

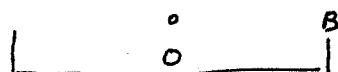
To find the time required travel time = $\frac{\text{distance}}{\text{relative velocity}}$



O-A : rel velocity is V_0



A-B : rel veloz is $V_c - V_b = e V_0$

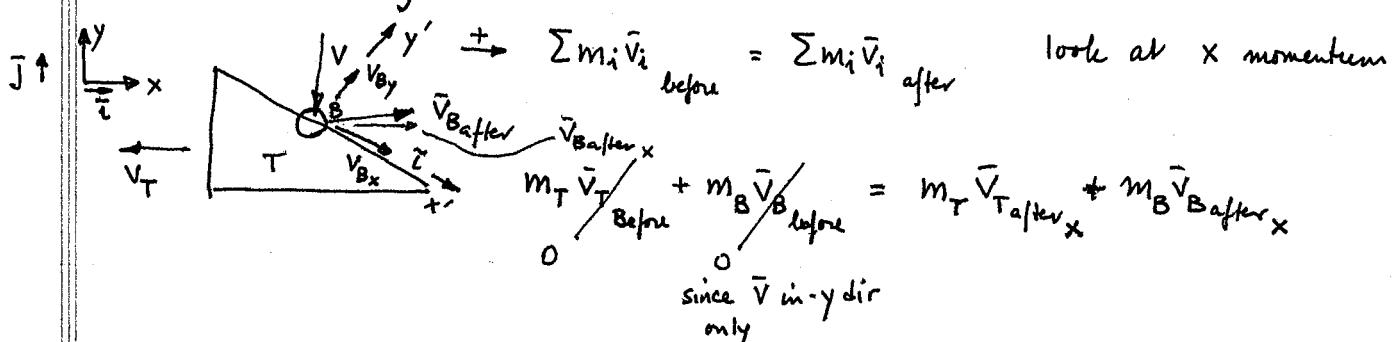


B-O : rel veloz is $V'_b - V'_c = e^2 V_0$

$$\therefore t = \frac{d}{V_0} + \frac{2d}{e V_0} + \frac{d}{e^2 V_0} = d \left[\frac{1 + 2e + e^2}{e^2 V_0} \right] = d \frac{(1+e)^2}{e^2 V_0}$$

15-62

Since all the forces at impact are internal we have conservation of momentum for the ball-triangle system. Also after impact the triangle will move but only in the horizontal direction \leftarrow . Since we want the velocity of the block T



$$\bar{v}_{T \text{ after}} = -\bar{v}_T$$

$$\bar{v}_{B \text{ after}} = V_{B_x}' \tilde{i} + V_{B_y}' \tilde{j}$$

\tilde{i}, \tilde{j} unit vectors in x', y' dir

in terms of \tilde{i}, \tilde{j}

$$\begin{aligned} \bar{v}_{B \text{ after}} &= V_{B_x} \cos 45^\circ \tilde{i} - V_{B_x} \sin 45^\circ \tilde{j} + V_{B_y} \cos 45^\circ \tilde{i} + V_{B_y} \sin 45^\circ \tilde{j} \\ &= (V_{B_x} + V_{B_y}) \frac{1}{\sqrt{2}} \tilde{i} + (-V_{B_x} + V_{B_y}) \frac{1}{\sqrt{2}} \tilde{j} \\ &\underbrace{\quad\quad\quad}_{\bar{v}_{B \text{ after}}} \end{aligned}$$

$$\therefore -3m \bar{v}_T + m (V_{B_x} + V_{B_y}) \frac{1}{\sqrt{2}} = 0 \quad (1)$$

for e : y' along line of impact

$$e = \frac{\bar{v}_{T y' \text{ after}} - \bar{v}_{B y' \text{ after}}}{\bar{v}_{B y' \text{ before}} - \bar{v}_{T y' \text{ before}}} = \frac{-\bar{v}_T \cos 45^\circ - V_{B_y}}{-V \cos 45^\circ - 0}$$

$$\therefore e V \cos 45^\circ = \bar{v}_T \cos 45^\circ + V_{B_y} \quad (2)$$

x' along plane of contact : $\underline{V \sin 45^\circ = V_{B_x}} \quad (3)$

Put (3) & (2) into (1) and solve for \bar{v}_T

$$-3m \bar{v}_T + m (V \sin 45^\circ + \bar{v}_T \cos 45^\circ + e V \cos 45^\circ) \frac{1}{\sqrt{2}} = 0$$

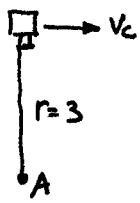
$$-\bar{v}_T \left[3m + \frac{m}{2} \right] + \frac{mV(1+e)}{2} = 0 \quad \text{or}$$

$$\bar{v}_T = \frac{V(1+e)}{7}$$

HW #11 in 3 pages

15-71, 72, 74

To find H_A : since V_c is \perp to distance to pt A from C



$$H_A = rmV_c = 3 \cdot \left(\frac{2}{32.2}\right) (43.95) = 8.19 \text{ ft-lb-s (slug-fr/s)}$$

We can use conserv of energy to find V_D

$$T_D + V_D = T_C + V_C$$

$$T_C = \frac{1}{2}mv_C^2$$

$$V_C = \frac{1}{2}k\Delta s_C^2$$

$$T_D = \frac{1}{2}mV_D^2$$

$V_D = 0$ (cord becomes unstretched
& this is a horizontal plane)

$$V_D = \sqrt{V_C^2 + \frac{k}{m} \Delta s_C^2} = 48.65 \text{ ft/s}$$

We can use the angular momentum since it is conserved to find the θ component of V_D ; thus $\sqrt{V_D^2 - (V_{D_\theta})^2} = V_{D_r}$

$$\therefore H_C = H_D$$

$$r_C \cdot mv_C = r_D \cdot mV_{D_\theta}$$

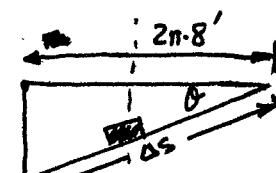
$$V_{D_\theta} = \frac{r_C v_C}{r_D} = \frac{3 \cdot 43.95}{1.5} = 87.9 \text{ ft/s}$$

now we have a problem $|V_D| > |V_{D_\theta}|$ which is impossible since

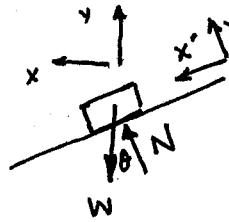
$$V_D^2 = V_{D_\theta}^2 + V_{D_r}^2 \Rightarrow V_D^2 > V_{D_\theta}^2$$

Thus the assumption of the cord becoming unstretched is impossible

15-74 If we look at one revolution of the helix "straightens out"



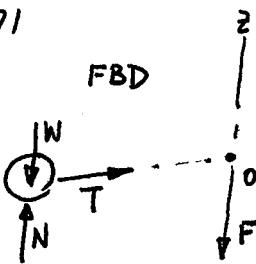
Thus the car drops through an angle $\bar{\theta} = \tan^{-1} \left(\frac{8'}{2\pi \cdot 8'} \right) = 9.04^\circ$



$$\sum F_y = W \cos 9.04 - N = 0 \quad N = 790 \text{ lbs}$$

in the x-y plane $N \sin 9.04$ produces a moment about the center of the helix $\therefore \int r N \sin 9.04 dt = \text{angular impulse}$

15-71



F, W, N, T produce no moments about the z axis

W, N do produce moments but in the x, y plane

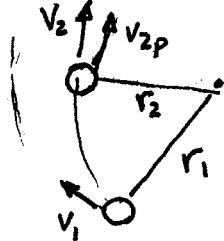
\therefore in the z direction

$$H_{z_1} = H_{z_2} \quad H_{z_1} = r_1 \cdot m v_1$$

since ball is moving in a circular path $\bar{r} \times m\bar{v} = rmv$ since $\bar{r} \perp \bar{v}$

$H_{z_2} = \bar{r}_2 \times m\bar{v}_2$ since \bar{r}_2 & the absolute velocity \bar{v}_2 are not \perp . However we can find a component of v_2 which is \perp to r_2 call this v_{2p}

$$\therefore r_1 m v_1 = r_2 m v_{2p} \quad v_{2p} = r_1 v_1 / r_2 = 6 \cdot 3 / 2 = 9 \text{ ft/s}$$



v_{2p} is $\perp r_2$ meaning it is in the θ direction

we are also told that the rope is pulled with $v_r = 2 \text{ ft/s}$

$$\therefore v_2 = \sqrt{v_\theta^2 + v_r^2} = \sqrt{v_{2p}^2 + v_r^2} = 9.22 \text{ ft/s}$$

Note that \bar{F} has no moment about the z axis since $M = \bar{r} \times \bar{F}$ and $\bar{r} = \bar{0}$ always. \bar{F} is the force used to pull the rope.

$$\text{To find the work of } \bar{F} : \quad T_1 + \sum U_{1 \rightarrow 2} = T_2 \quad T_1 = \frac{1}{2} m v_1^2 \\ T_2 = \frac{1}{2} m v_2^2$$

Note that $W \& N$ do not produce work since they are \perp to path of ball & T is internal $\therefore \sum U_{1 \rightarrow 2}$ is the work of F only

$$\therefore \sum U_{1 \rightarrow 2} = \frac{1}{2} m [v_2^2 - v_1^2] = \frac{1}{2} \left(\frac{4}{32.2} \right) [9.22^2 - 6^2] = 3.04 \text{ lb-ft}$$

- 15-72 To solve - 1) find v_c using conservation of energy
2) Determine v_D

Smooth guide - no friction ; rock weight plays no part ; it is \perp to plane of motion

$$T_B + V_B = T_C + V_C \quad T_B = 0 \quad V_B = \frac{1}{2} k \Delta s_B^2 \quad \Delta s_B = 5 - 1.5 = 3.5'$$

$$T_C = \frac{1}{2} m v_C^2 \quad V_C = \frac{1}{2} k \Delta s_C^2 \quad \Delta s_C = 3 - 1.5 = 1.5'$$

$$\therefore v_C = \sqrt{[V_B - V_C] \cdot \frac{2}{m}} = \sqrt{\frac{1}{2} k [\Delta s_B^2 - \Delta s_C^2] \cdot \frac{2}{m}} = 43.95 \text{ ft/s}$$

and $H_{g_0} = 0$ $H_{y_1} = rmV$ where V is the component of the velocity in the x, z plane

$$\therefore \int_0^4 r N \sin 9.04 dt = \overset{t=8}{\underset{\substack{\uparrow 80 \\ 32.2}}{rmV}} \quad \text{thus } V = 20 \text{ ft/s} \quad \leftarrow$$

but V along the track \leftarrow is $\frac{20}{\cos 9.04^\circ} = 20.24 \text{ ft/s}$

to find the drop: Let the datum be where the car started from rest since N is \perp to the motion & $W \cos \theta$ is \perp to motion; then $W \sin \theta$ produces work.

$$T_1 + \sum U_{1-2} = T_2$$

$$T_1 = 0 \quad T_2 = \frac{1}{2} m (20.24)^2$$

$$\sum U_{1-2} = W \sin \theta \cdot \Delta s = W \cdot \Delta h$$

$$\therefore \underline{\Delta h} = \frac{1}{2} m (20.24)^2 / mg = \underline{6.36'}$$

$$\sum F_x' = \max$$

\rightarrow Could have also found V by using $W \sin \theta = m a_x \Rightarrow a_x = g \sin \theta$
 then $V = V_0 + a_x t = g \sin \theta t = 20.24 \text{ ft/s}$

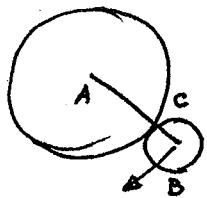
the ^{rest} of problem is as above.

HW # 12

Problems 15, 24, 26, 31, 37 in 2 pages

HW # 12

15-31



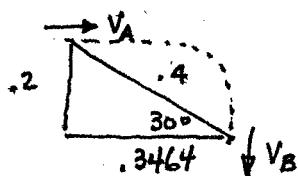
$$\omega_{AB} = 120 \text{ rpm} \times \frac{2\pi \text{ rad}}{1 \text{ rev}} \times \frac{1 \text{ min}}{60 \text{ sec}} = 4\pi \text{ rad/s}$$

$$V_B = \omega_{AB} \cdot r_{B/A} = 4\pi(225) = 9\pi = 2.83 \text{ m/s} \text{ since } V_A = 0$$

$$V_C = V_B = r_{C/A} \omega_A \text{ since } V_A = 0 \Rightarrow \omega_A = 18.85 \text{ rad/s}$$

$$V_B = 2.83 \text{ m/s}$$

15.26



note that A is not in the circular part since

$.283 = r_{B/A}$ is distance that separates whether A is in circle or straight part. $r_{B/A} > .283 \text{ m}$ A is straight

$\vec{k} \leftarrow i + j$

$$\bar{V}_B = -1.2\bar{j} \quad V_A = V_A\bar{i} \quad \bar{r}_{B/A} = .4\cos 30^\circ \bar{i} - .4\sin 30^\circ \bar{j}$$

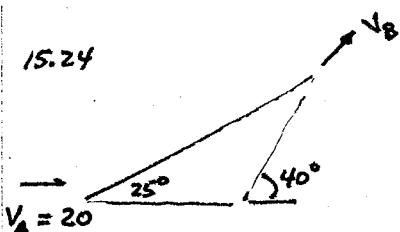
$$\text{let } \bar{\omega} = \omega \bar{k}$$

$$\bar{V}_B = \bar{V}_A + \bar{\omega} \times \bar{r}_{B/A} = V_A\bar{i} + .4\cos 30^\circ \omega \bar{j} + .4\sin 30^\circ \omega \bar{i} = -1.2\bar{j}$$

$$\therefore V_A + \omega (.4\sin 30^\circ) = 0 \quad \& \quad -1.2 = .4\cos 30^\circ \omega \Rightarrow \omega = 3.464 \text{ rad/s}$$

$$V_A = +.693 \text{ m/s} \rightarrow$$

15.24



$$\bar{V}_B = V_B(\cos 40^\circ \bar{i} + \sin 40^\circ \bar{j}) = 20\bar{i} + \bar{\omega} \times \bar{r}_{B/A}$$

$$\bar{r}_{B/A} = 6[\cos 25^\circ \bar{i} + \sin 25^\circ \bar{j}] ; \text{ let } \bar{\omega} = \bar{\omega} \bar{k}$$

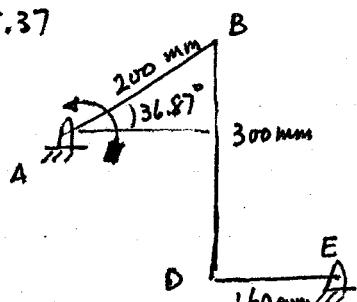
$$V_B \cos 40^\circ \bar{i} + V_B \sin 40^\circ \bar{j} = 20\bar{i} + \bar{\omega} \cdot 6 \cos 25^\circ \bar{j} + 6\bar{\omega} \sin 25^\circ \bar{j}$$

$$\therefore V_B \sin 40^\circ = +6\bar{\omega} \sin 25^\circ \quad] \quad \tan 40^\circ = \frac{+6\bar{\omega} \sin 25^\circ}{20 + 6\bar{\omega} \sin 25^\circ}$$

$$\therefore 20 \tan 40^\circ = +\bar{\omega} [6 \tan 40^\circ \sin 25^\circ + 6 \cos 25^\circ]$$

$$\bar{\omega} = 2.218 \text{ rad/s} \quad \bar{V}_B = 18.77 \text{ m/s} \angle 40^\circ$$

15.37



$$V_B = \bar{\omega} r_{B/A} = .6[-\sin 36.87 \bar{i} + \cos 36.87 \bar{j}]$$

$$\text{if } \bar{\omega}_{DE} = \bar{\omega}_{DE} \bar{k} \Rightarrow \bar{V}_D = .16 \bar{\omega}_{DE} \bar{k}$$

$$\text{also } \bar{V}_{D/B} = \bar{\omega} (.3) \rightarrow \text{if } \bar{\omega}_{DB} = \bar{\omega}_{DB} \bar{k}$$

$$\therefore \bar{V}_D = \bar{V}_B + \bar{V}_{D/B}$$

$$-.16 w_{DE} \bar{j} = .6 [-.6 \bar{i} + .8 \bar{j}] + .3 w_{DB} \bar{i}$$

$$\Rightarrow -.36 + .3 w_{DB} = 0 \quad \text{or } w_{DB} = 12 \text{ rad/sec} \uparrow$$

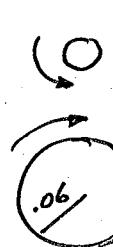
$$-.16 w_{DE} = .48 \quad \text{or } w_{DE} = 3 \text{ rad/sec} \downarrow$$

EGN 3321

HW # 13

16 - 16, 19, 36, 37 in 2 pages

16-16



$$\alpha_A = 0.6 \theta_A^2$$

$$\alpha_B = \frac{1}{5} \alpha_A = .012 \theta_A^2 = .3 \theta_B^2$$

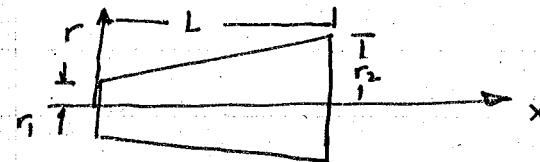
$$\text{now } \alpha_A d\theta_A = w_A d\omega_A$$

$$\text{or } \frac{.06 \theta_A^3}{3} = \frac{(w_{A_2}^2 - w_{A_1}^2)}{2} \quad \text{with } \theta_A = 10 \text{ rev} = 20\pi \text{ rad}$$

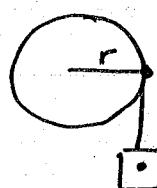
$$w_{A_1} = 50 \text{ rad/s}$$

$$\Rightarrow w_{A_2} = 111.454 \text{ rad/s}$$

$$\text{now at contact pt } w_A r_A = w_B r_B \quad \therefore w_{B_2} = w_{A_2} r_A / r_B = 22.29 \text{ rad/s}$$

16-19 The tapered drum's radius as a fn. of x 

$$r = r_1 + \frac{(r_2 - r_1)}{L} x$$

also $w = \text{const.}$ 

$$\text{at P } V = wr \quad \text{and since the rope is taught } V_p = V_B$$

$$\therefore \frac{dV_B}{dt} = a_B = \frac{dV_p}{dt} = \frac{dw/r}{dt} + dr \cdot w$$

$$\therefore a_p = w \frac{dr}{dt}$$

now for one full revolution

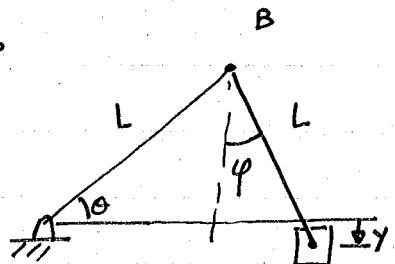
$$dr \text{ increases by } \frac{(r_2 - r_1)}{L}$$

distance; also dx increases by an amount

$$\therefore a_p = w \frac{dr}{dt} = w \frac{dr}{d\theta} \frac{d\theta}{dt} \frac{dx}{d\theta} = w \frac{(r_2 - r_1)/L}{\frac{1}{2\pi}} \cdot w \cdot \frac{d}{2\pi}$$

$$= \frac{w^2 d}{2\pi} \left(\frac{r_2 - r_1}{L} \right)$$

16-36



$$L\cos\theta + L\sin\phi = L \quad (1)$$

$$\text{and } y = L\cos\phi - L\sin\theta \quad (2)$$

$$\text{take } \frac{d}{dt} (1) \Rightarrow \dot{\phi} = \dot{\theta} \frac{\sin\theta}{\cos\phi}$$

$$\text{and } \ddot{\phi} = \frac{\cos\theta \dot{\theta}^2 + \sin\phi \dot{\phi}^2}{\cos\phi}$$

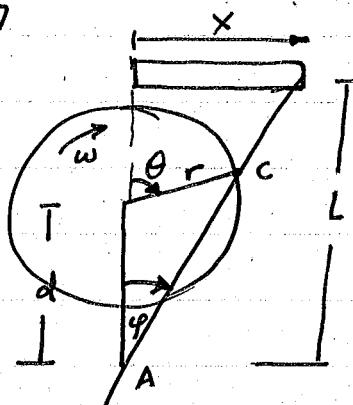
$$\text{for } \theta = 60^\circ \Rightarrow \phi = 30^\circ \Rightarrow \dot{\phi} = \dot{\theta} = \omega$$

$$\text{take } \frac{d}{dt} (2) \Rightarrow v = \frac{dy}{dt} = -L [\sin\phi \dot{\phi} + \cos\theta \dot{\theta}] = -L\omega$$

$$\text{take } \frac{d}{dt} v = a = -L [\cos\phi \dot{\phi}^2 + \sin\phi \ddot{\phi} + \sin\theta \dot{\theta}^2 + \cos\theta \ddot{\theta}] = -\frac{1}{\sqrt{3}} L\omega^2$$

$$\text{this means } v = L\omega \uparrow \text{ and } a = \frac{1}{\sqrt{3}} L\omega^2 \uparrow$$

16-37



$$\therefore x = L \tan\phi$$

$$\bar{AC} \cos\phi = d + r \cos\theta$$

$$\bar{AC} \sin\phi = r \sin\theta$$

$$\therefore \tan\phi = \frac{r \sin\theta}{d + r \cos\theta}$$

$$\text{now } \dot{x} = L \frac{d}{dt} \tan\phi = L \frac{d}{dt} \left(\frac{r \sin\theta}{d + r \cos\theta} \right)$$

$$v = \dot{x} = L \theta r \frac{(r + d \cos\theta)}{(d + r \cos\theta)^2}$$

$$\text{and } a = \dot{v} = \ddot{x} = L r \theta^2 \sin\theta \frac{[2r^2 - d^2 + rd \cos\theta]}{(d + r \cos\theta)^3}$$

$$\dot{\phi} = \frac{r \dot{\theta} (r + d \cos\theta)}{d^2 + 2rd \cos\theta + r^2} \Rightarrow \text{this is the angular velocity of bar AC}$$

note that it is not the same as that of the disk (which is ω)

EGN 3321

HW # 14

17-9 , 11, 14, 22, 37, 41 in 5 pages



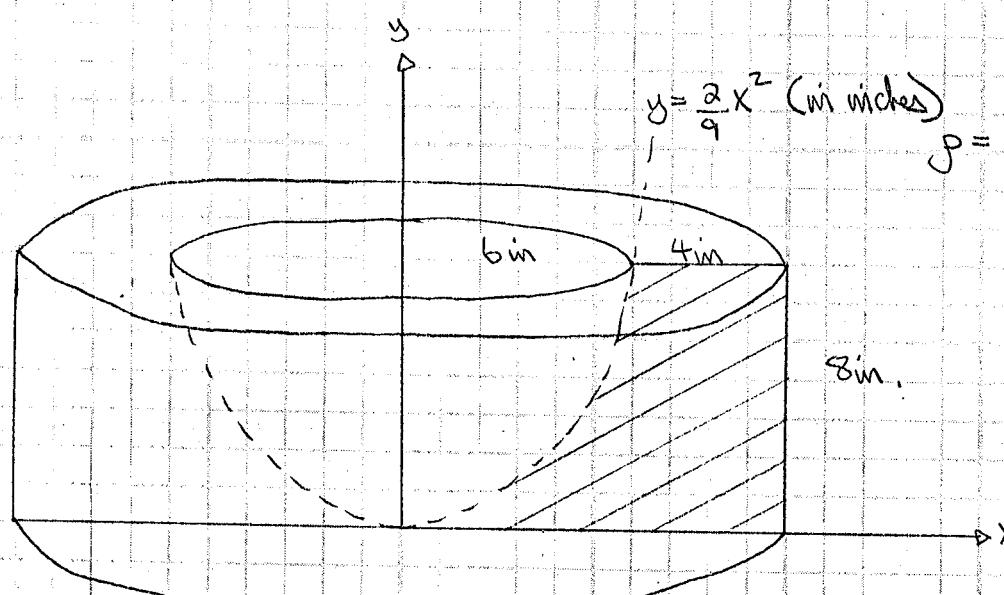
Florida International University
The State University of Florida at Miami

College of Engineering & Applied Sciences

Homework Problem

Ch 17

(9)



$$y = \frac{2}{9}x^2 \text{ (in inches)}$$

$$\rho = \frac{150}{32.2} \text{ slugs/ft}^3$$

For a solid cylinder of radius $\frac{10}{12}$ ft and height $\frac{8}{12}$ ft.

$$dV = (2\pi r)(h) dr$$

$$dm = \rho dV = (2\pi rh\rho)dr$$

$$dI_y = r^2 dm = 2\pi r^3 h \rho dr$$

$$I_y = \int_{r_0}^{r_1} r^2 dm = \rho 2\pi h \int_{0}^{\frac{10}{12}} r^3 dr = \frac{\rho \pi}{2} \left(\frac{10}{12}\right)^4 \left(\frac{8}{12}\right)$$

$$I_y = 2.3526 \text{ slugs/ft}^2$$

For a solid inner cup only:

$$dm = \rho dV = \rho(\pi x^2) dy$$

$$dI_y = \frac{1}{2}(dm)x^2 = \frac{1}{2}[\rho(\pi x^2) dy]x^2$$

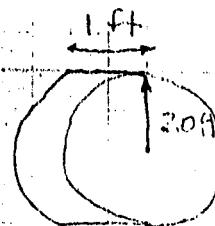
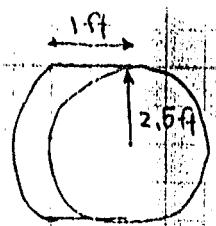
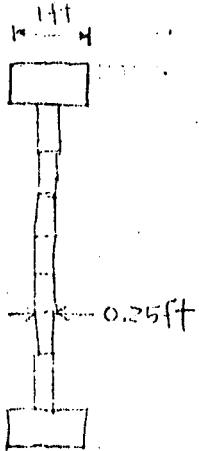
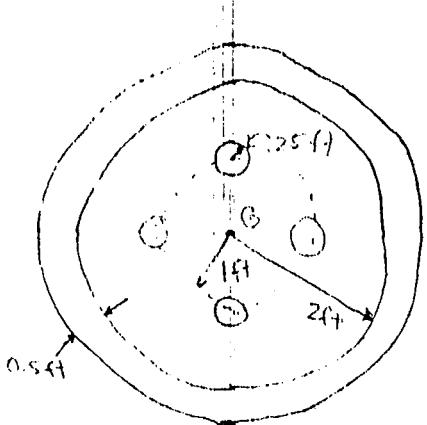
$$I_y = \frac{\pi \rho}{2} \int_0^{8/12} x^4 dy = \frac{\pi \rho}{2} \int_0^{8/12} \frac{9}{64} y^2 dy$$

$$I_y = \frac{\pi \rho}{2} \left[\frac{9}{128} y^3 \right]_0^{8/12} = 0.1016 \text{ slugs/ft}^2$$

The equation becomes $y = \frac{8}{3}x^2$ (in ft)

Note: SINCE x, y have units of inches \Rightarrow constant $\frac{2}{9}$ also must have units of $\frac{1}{in}$, THUS must also convert it.

Moment of Inertia of shaded regions = 2.25 slugs/ft^2



$$\gamma = 90 \text{ lb/ft}^3 \quad t = \text{thickness}$$

$$P = \frac{\gamma}{G} = \frac{90}{32.2} = 4.66 \text{ slugs ft}^3 \quad V = \pi r^2 t$$

$$m = \rho V \quad I_G = \frac{1}{2} mr^2$$

$$m_1 = (4.6) [\pi (2.5)^2 (1)]$$

$$= 54.8 \text{ slugs}$$

$$I_1 = \frac{1}{2} (54.8)(2.5)^2$$

$$= 171.5 \text{ slugs ft}^2$$

$$m_2 = (4.6) [\pi (2.0)^2 (1)]$$

$$= 35.12 \text{ slugs}$$

$$I_2 = \frac{1}{2} (35.12)(2.0)^2$$

$$= 70.24 \text{ slugs ft}^2$$

$$m_3 = (4.6) [\pi (2.0)^2 (0.25)]$$

$$= 8.78 \text{ slugs}$$

$$I_3 = \frac{1}{2} (8.78)(2.0)^2$$

$$= 17.56 \text{ slugs ft}^2$$

$$4m_4 = (4.6) [\pi (0.25)^2 (0.25)] 4$$

$$= .5488 \text{ slugs}$$

$$I_4 = I_{G4} + 4m_4(d)^2$$

$$= .017 + (.5488)(1)^2$$

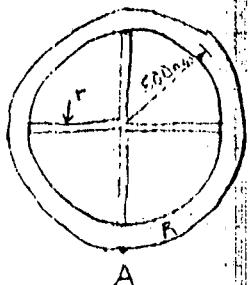
$$I_{G4} = \frac{1}{2} (.5488)(0.25)^2$$

$$= 0.017 \text{ slugs ft}^2$$

$$= .5659 \text{ slugs ft}^2$$

$$I = I_1 - I_2 + I_3 - I_4$$

$$= 118.21 \text{ slugs ft}^2$$



$$M_R = 10 \text{ kg}$$

$$M_r = 2 \text{ kg}$$

$$l = r = 500 \text{ mm}$$

$$= 0.5 \text{ m}$$

$$d = r$$

$$m = M_R + 4M_r$$

$$= 10 + 8 = 18 \text{ kg}$$

$$I_G = I_R + I_r$$

$$= m_R R^2 + \left[\frac{1}{3} m_r l^2 \right] 4 \quad (\text{four rods})$$

$$= (10)(0.5)^2 + \frac{4}{3}(2)(0.5)^2$$

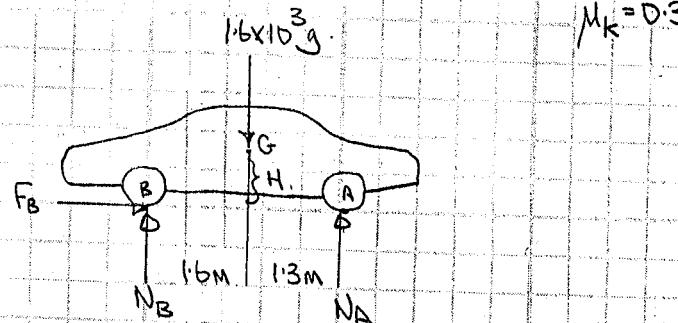
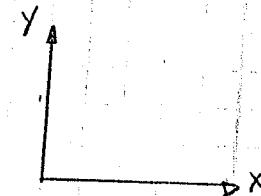
$$= 3.16 \text{ kg-m}^2$$

$$I = I_G + md^2$$

$$= 3.16 + (18)(0.5)^2$$

$$T = 2\sqrt{\frac{I}{k}} \text{ rad/sec}$$

(37)



Eq of Motion:

$$+\sum F_x = m(a_g)_x ; \quad 0.3 N_B = 1.6 \times 10^3 a_g \quad \checkmark$$

$$+\sum F_y = m(a_g)_y ; \quad N_A + N_B - 1.6 \times 10^3 (9.81) = 0 \quad \checkmark$$

$$(\text{+} \sum M_G = 0 ; \quad -N_B(1.6) + 0.3 N_B(H) + N_A(1.3) = 0) \quad \checkmark$$

Now for regular car, $H = 0.4 \text{ m}$

$$N_A + N_B = 15696$$

$$-1.48 N_B + 1.3 N_A = 0$$

$$N_A = 8356.14 \text{ N} \quad N_B = 7339.86 \text{ N}$$

$$a_g = 1.376 \text{ m/s}^2 \quad \checkmark$$

For "Raked" car; $H = 0.6 \text{ m}$

$$N_A + N_B = 15696$$

$$-1.42 N_B + 1.3 N_A = 0$$

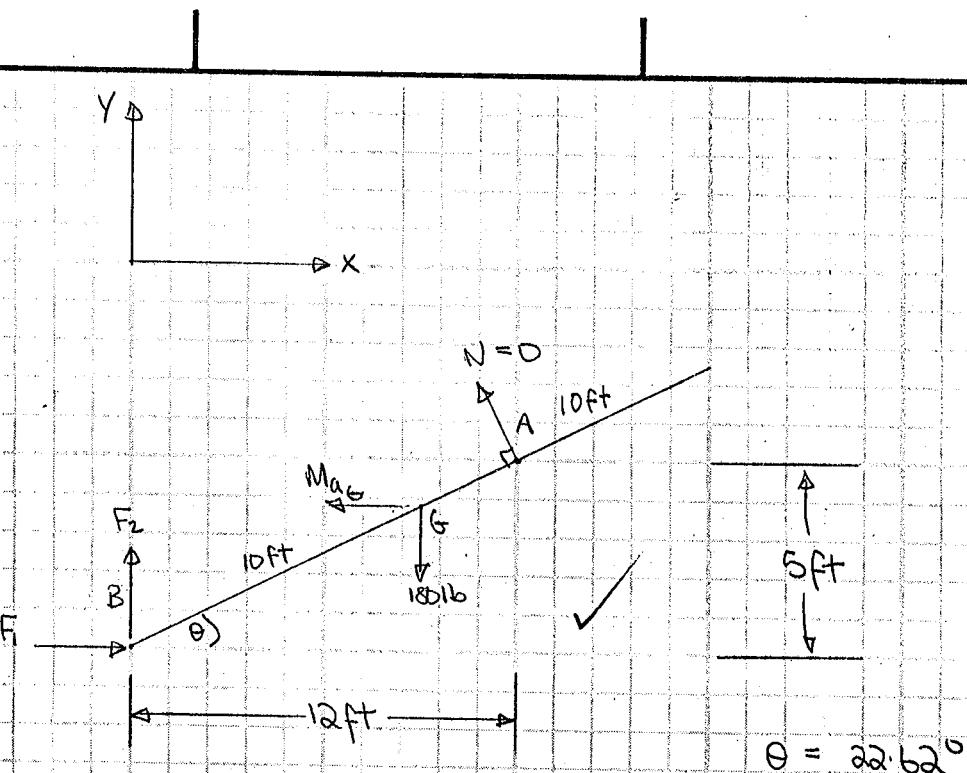
$$N_A = 8194.24 \text{ N}$$

$$N_B = 7501.76 \text{ N}$$

$$a_g = 1.407 \text{ m/s}^2 \quad \checkmark$$



(22)



Summing moments about B:

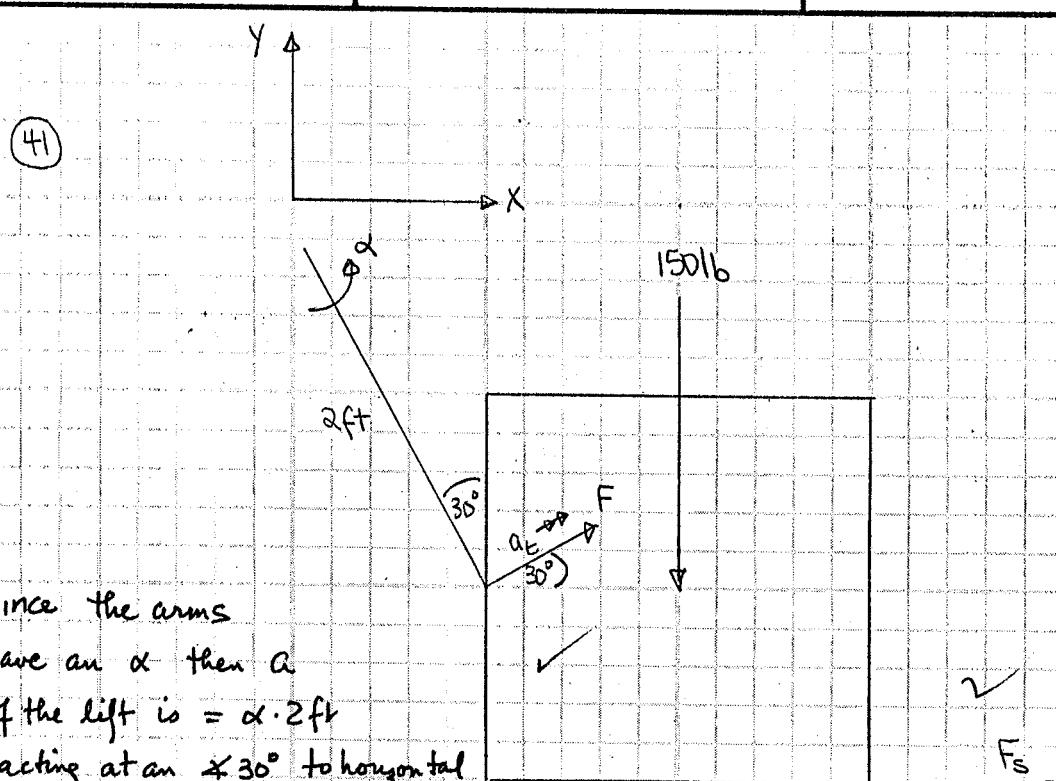
$$180(10 \cos 22.62^\circ) = \frac{180}{32.2} (10 \sin 22.62^\circ) a_g$$

$$a_g = \frac{32.2 \cos 22.62^\circ}{\sin 22.62^\circ} = 77.3 \text{ ft/s}^2$$

Resolving Forces in the X - y directions.

$$F_2 = 180 \text{ lb}$$

$$F_1 = M a_g = 432 \text{ lb}$$



since the arms have an α then α of the left $\omega = \alpha \cdot 2 \text{ ft}$ acting at an $\angle 30^\circ$ to horizontal

$$\therefore m\bar{a}_g = m\alpha \cdot 2 [\sin 30^\circ j + \cos 30^\circ i]$$

call this $\bar{F} = m\bar{a}_g$

$$\therefore F_x = m\bar{a}_{gx} = \sum F_x$$

$$F_y = m\bar{a}_{gy} = \sum F_y$$

For limiting friction $F_s = \mu s N = 0.4 N$

Resolving forces in the +Y direction:

$$F \sin 30^\circ = N - 150 \quad \text{--- (1)}$$

Resolving forces in the +X direction:

$$F \cos 30^\circ = 0.4 N \quad \text{--- (2)}$$

$$F \cos 30^\circ = 0.4(150 + F \sin 30^\circ)$$

$$F \cos 30^\circ - 0.4(F \sin 30^\circ) = 60 \Rightarrow F = 90.0866 \text{ lb}$$

$$a_t = F/M = 19338 \text{ ft/s}^2$$

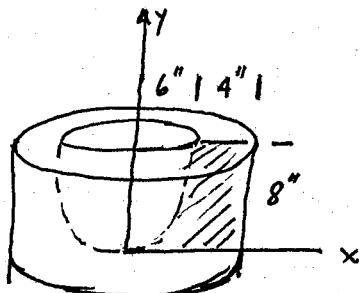
$$\alpha = 9.67 \text{ rad/s}^2$$

EGN 3321

HW #15

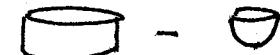
Problems 17- 9, 11, 14, 22, 37, 41 in 3 pages

17-9



$$y = \frac{2}{9}x^2 \text{ units in inches} \quad \gamma = \frac{\text{weight}}{\text{volume}} = 150 \text{ lb/ft}^3$$

solve this as



$$\text{for cylinder } I_y = \frac{1}{2}mR^2 = \frac{1}{2}\frac{W}{g}R^2 = \frac{1}{2}\frac{\gamma}{g} \text{ Volume} \cdot R^2 \\ = \frac{1}{2}\frac{\gamma}{g}(\pi R^2 h)R^2 = \frac{1}{2}\frac{\gamma}{g}\pi R^4 h = \frac{1}{2}\frac{150}{32.2}\pi\left(\frac{10}{12}\right)^4\left(\frac{8}{12}\right) \\ = 2.3526 \text{ slug-ft}^2 \text{ Here inches are converted to ft.}$$

for parabola x, y are in inches \Rightarrow constant $2/\gamma$ is in $(\text{inches})^{-1}$ \therefore in feet the equation becomes $y = \frac{8}{3}x^2$. Now $dI_y = \frac{1}{2}dmR^2 = \frac{1}{2}dmx^2$ with $dm = \pi x^2 dy$

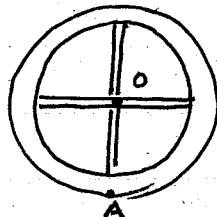
$$\text{Thus } dI_y = \frac{1}{2}(\rho\pi x^2 dy)x^2 = \frac{1}{2}\rho\pi x^4 dy \quad \rho = \frac{m}{V} = \frac{W}{Vg} = \frac{\gamma}{g}$$

$$\therefore \int dI_y = \int \frac{1}{2}\frac{\gamma}{g}\pi\left(\frac{3}{8}\right)^2y^2 dy = \frac{9}{128}\frac{\gamma}{g}\pi \int_0^{8/2} y^2 dy$$

$$I_y = \frac{9}{128}\frac{\gamma}{g}\pi \left.\frac{y^3}{3}\right|_0^{.667} = .1016 \text{ slug-ft}^2$$

$$\therefore I_y = 2.3526 - .1016 = \underline{2.251 \text{ slug-ft}^2}$$

17-11

Solve this by finding I_G first then $I_A = I_G + m d^2$

$$\text{for ring } I_G = I_0 = mR^2 \quad I_A = mR^2 + mR^2 = 2mR^2$$

$$I_{\text{ring}} = 2 \cdot 10 (.5)^2 = \underline{5 \text{ kg-m}^2}$$

$$I_G \text{ of horizontal spokes} = \frac{1}{12}ml^2 = \frac{1}{12}(4)(1)^2 = .333 \text{ kg-m}^2 = I_0$$

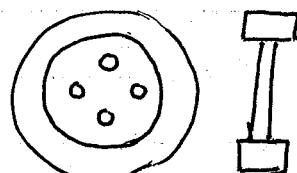
$$\text{using the whole horizontal spoke } I_A = I_G + mR^2 = I_G + 4(.5)^2 = 1.333 \text{ kg-m}^2$$

I_G for the vertical is same as for the two horizontal and I_A is also the same

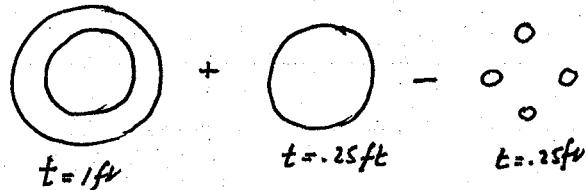
$$\therefore \underline{\text{total } I_A \text{ spokes}} = 2(1.333) = \underline{2.667 \text{ kg-m}^2}$$

$$\text{Total } I_A = 5 + 2.667 = \underline{7.667 \text{ kg-m}^2}$$

17-14

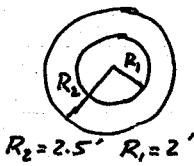


solve as



$$\text{Given } \gamma = 90 \text{ lb/ft}^3 = \frac{\text{weight}}{\text{volume}} = \frac{W}{V}$$

for the ring $I_G = \left(\frac{1}{2}mR^2\right)$ for outer $= \left(\frac{1}{2}mR^2\right)$ for inner $m = \frac{\gamma V}{g}$ $V = \pi R^2 t$



$$I_G = \frac{1}{2} \frac{\gamma}{g} \pi R_2^2 t \cdot R_2^2 - \frac{1}{2} \frac{\gamma}{g} \pi R_1^2 t \cdot R_1^2 = \frac{1}{2} \frac{\gamma}{g} \pi t (R_2^4 - R_1^4) = 101.254 \text{ slug ft}^2$$

for inner plate $I_G = \frac{1}{2}mR^2 = \frac{1}{2} \frac{\gamma}{g} \pi R^2 t \cdot R^2 = \frac{1}{2} \frac{\gamma}{g} \pi R^4 t = 17.562 \text{ slug ft}^2$



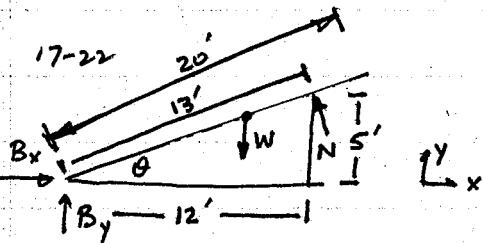
for the holes: each hole is equidistant from G \therefore find $I_{\text{hole about its centroid}}$ then add $m(l)^2$

$$I = \frac{1}{2}mR^2 = \frac{1}{2} \frac{\gamma}{g} \pi R^2 t \cdot \frac{1}{9} R^2 = \frac{1}{2} \frac{\gamma}{g} \pi R^4 t = \frac{1}{2} \pi \left(\frac{90}{32.2}\right) (.25)^4 = .00136 \text{ slug ft}^2$$

$$\text{add } m(l)^2 = \frac{\gamma}{g} \pi R^2 t l^2 = .1372 \text{ slug ft}^2 \therefore \text{total is } .13856 \text{ slug ft}^2$$

I_G for one hole is $.13856 \text{ slug ft}^2$

$$\therefore \underline{\underline{I_{G_{\text{tot}}} = 101.254 + 17.562 - 4(.13856) = 118.26 \text{ slug ft}^2}}$$



$$\begin{aligned} \cos \theta &= 12/13 & \sum F_x &= B_x - N \sin \theta = ma_{Gx} \\ \sin \theta &= 5/13 & + \sum F_y &= -W + B_y + N \cos \theta = 0 \\ + (\sum M &= I_{Gx} \alpha = 0 = N \cdot 3 - B_y \cdot 10 \cos \theta + B_x \cdot 10 \sin \theta) \end{aligned}$$

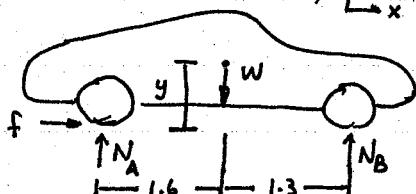
since $N=0$ for max $a_{Gx} \Rightarrow W=B_y = 180 \text{ lb}$

$$B_y = B_x \tan \theta \Rightarrow B_x = 432 \text{ lb}$$

$$a_{Gx} = \frac{B_x}{m} = \left(\frac{W}{g}\right) B_x = 77.3 \text{ ft/s}^2$$

ALWAYS DRAW FBD; Contact forces are \perp to contact surface

17-37



SEE EXAMPLE 17-5 AS TO THE FORCES ON THE BODY

unbraked $y = 0.4 \text{ m}$

$$N_A = \frac{N_B(1.3)}{1.6 - \mu y}$$

braked $y = 0.6 \text{ m}$

$$N_A = \frac{N_B(1.3)}{1.48}$$

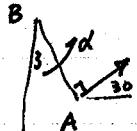
$$\text{unraked } N_B = W \frac{(1.48)}{2.78} = 8356 \text{ N} \quad N_A = 7339.9 \text{ N} \quad Q_g = 1.376 \text{ m/s}^2$$

$$\text{raked } N_B = W \frac{(1.42)}{2.72} = 8194 \text{ N} \quad N_A = 7501.8 \text{ N} \quad Q_g = 1.407 \text{ m/s}^2$$

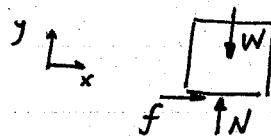
Thus raked gives a higher acceleration

17-41. The elevator is in curvilinear translation. Since it starts from rest $\omega = 0$

$$\text{and } \bar{a}_A = \bar{a}_B = \bar{a}_{\text{elevator}} = \alpha r = \alpha(2) \angle 30^\circ \quad \therefore \alpha \cdot 2 [\cos 30^\circ \hat{i} + \sin 30^\circ \hat{j}]$$



This is also \bar{a}_g of cent.



$$\sum F_x = f = ma_{gx} = m2\alpha \cos 30^\circ$$

$$+ \sum F_y = N - W = ma_{gy} = m \cdot 2\alpha \sin 30^\circ$$

$$f = \mu N \quad \text{for slip to occur}$$

$$\therefore \mu N = ma_{gx} \quad \text{or} \quad N = \frac{m}{\mu} a_{gx} \quad \therefore \frac{m}{\mu} a_{gx} - W = ma_{gy}$$

$$\text{so } \frac{m}{\mu} [2 \cdot \alpha \cos 30^\circ] - W = m [2\alpha \sin 30^\circ] \quad \text{or}$$

$$\left[\frac{1}{\mu} \cdot 2 \cos 30^\circ - 2 \sin 30^\circ \right] \alpha = g \quad \alpha = 9.67 \text{ rad/s}^2$$

HW #16

17-57, 60, 90, 94, 98 in 6 pages



Dynamics, 4-5-90

Professor Levy

PROB. 17-60

Given: $\alpha_A = 4 \text{ rad/s}^2$

$W_A = 5 \text{ lb}$, $W_B = 10 \text{ lb}$, no slipping

Determine couple M needed for disk A

to have $\alpha = 4 \text{ rad/s}^2$

$$(\alpha_t)_A = (\alpha_t)_B \text{ at pt. P} \Rightarrow \Gamma \alpha_A = \Gamma \alpha_B$$

$$(0.5)4 = (0.75)\alpha_B \Rightarrow \alpha_B = 2.67 \text{ rad/s}^2$$

Disk A

$$\text{G} \sum M_A = I_A \alpha_A \Rightarrow M - F_P(0.5) = \frac{1}{2} m_A r_A^2 (4)$$

$$\Rightarrow M - F_P(0.5) = \frac{1}{2} \left(\frac{5}{32.2} \right) (0.5)^2 (4)$$

$$\Rightarrow ① M - F_P(0.5) = (77.64 \times 10^{-3}) \text{ ft-lb}$$

Disk B

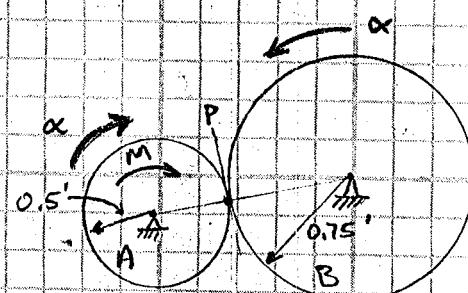
$$\text{G} \sum M_B = I_B \alpha_B \Rightarrow M + F_P(0.75) = \frac{1}{2} m_B r_B^2 (2.67)$$

$$\Rightarrow F_P(0.75) = \frac{1}{2} \left(\frac{10}{32.2} \right) (0.75)^2 (2.67)$$

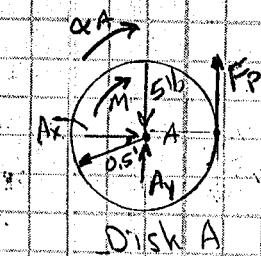
$$F_P = 0.311 \text{ lb}$$

$$① M - (0.311)(0.5) = (77.64 \times 10^{-3})$$

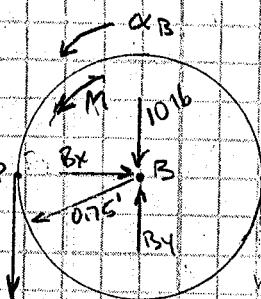
$$M = 0.233 \text{ ft-lb}$$



FBD



Disk A



Disk B



Dynamics, 4-5-90 | Professor Levy

PROB. 17-67

Given: $W_A = 10 \text{ lb}$, $W_B = 5 \text{ lb}$,

$W_P = 3 \text{ lb}$, $K_0 = 0.5 \text{ ft/lb}$,

If blocks released from rest, ($v_0 = 0$)

det. their speed just when A has descended 3 ft.

$$I_0 = m_p v_0^2 = \left(\frac{3}{32.2}\right)(0.5)^2 = 23.3 \times 10^{-3} \text{ slug} \cdot \text{ft}^2$$

$$a = \alpha \cdot r = \alpha(0.75) = a_c$$

Solution I - (system as a whole)

$$\nabla \sum M_O = \sum (m_k)_o$$

$$10(0.75) - 5(0.75) = I_0 \alpha + m_A a \tau + m_B a \tau$$

$$3.75 = (23.3 \times 10^{-3})\alpha + 0.175\alpha + 0.087\alpha$$

$$\alpha = 13.14 \text{ rad/s}^2, a_c = \alpha(0.75) = 9.86 \text{ ft/s}^2 \downarrow$$

$$v_{Cf}^2 = 2a_c(s_f - s_0) \quad (v_c = v_A)$$

$$v_c^2 = 2(-9.86)(0-3) \Rightarrow v_c = 7.69 \text{ ft/s} \downarrow = v_A$$

Solution II - (system as separate parts)

Block-A + n:

$$\nabla \sum F_y = m(a_g)_y \Rightarrow T_A - 10 = \left(\frac{10}{32.2}\right)\alpha(0.75)$$

$$T_A = 10 + 0.233\alpha$$

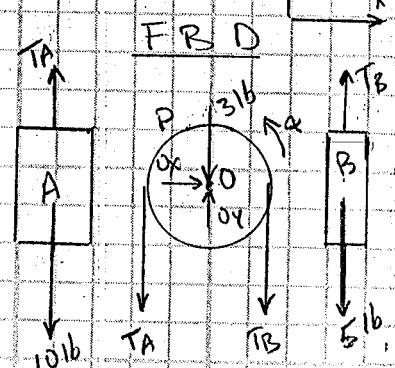
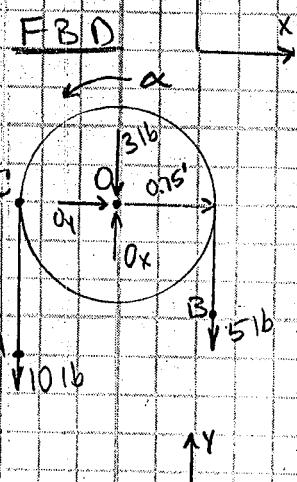
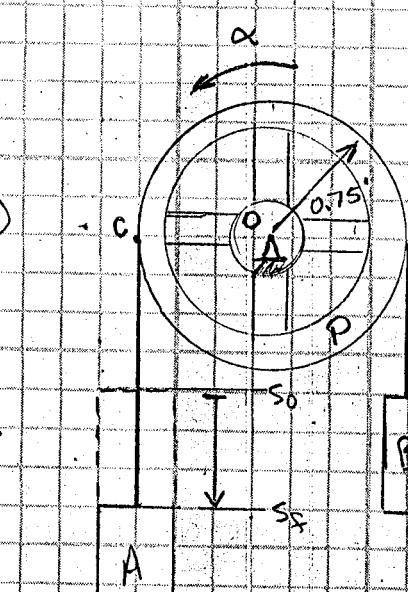
Pulley-P - take $\sum M_O$ to eliminate O_x & O_y .

$$\nabla \sum M_O = I_0 \alpha \Rightarrow T_A(0.75) - T_B(0.75) = (23.3 \times 10^{-3})\alpha$$

$$\text{Block-B} \quad \sum F_y = m(a_g)_y \Rightarrow T_B - 5 = \left(\frac{5}{32.2}\right)\alpha(0.75) \Rightarrow T_B = 5 + 0.116\alpha$$

$$\alpha = 13.14 \text{ rad/s}^2, a = 9.86 \text{ ft/s}^2$$

$$\therefore v_A = 7.69 \text{ ft/s}$$





Dynamics, 4-5-90 | Professor Levy

Prob. 17-94

Given: $m_w = 50 \text{ kg}$, $m_p = 20 \text{ kg}$

$\mu_g = 0.4$, W rolls w/o slipping

(means some force exerted at contact pt.)

Assume A_x , A_y , & N_B

Det. those reactions & forces

To find R_x 's & F 's exerted at supports,

1st need to find all F 's acting on P including those of W
FOR Wheel

$$\rightarrow \sum F_x = m(a_G)_x \Rightarrow a_G = -r\alpha = -0.6\alpha, W_w = 490.5 \text{ N}, \boxed{\text{FBD}}$$

$$F - W_w \sin 30 = -30\alpha \Rightarrow \textcircled{1} F - 245.25 = 30\alpha$$

$$\uparrow \sum F_y = m(a_G)_y, (a_G)_y = 0$$

$$N_c - W_w \cos 30 = 0 \Rightarrow N_c = 425 \text{ N}$$

$$\rightarrow \sum M_c = \sum (M_x)_c \Rightarrow W_w \sin 30 (0.6) = I_0 \alpha + F_r$$

$$\Rightarrow 147.15 = m l^2 \alpha + m(0.6\alpha)(0.6) \Rightarrow 147.15 = 26\alpha \Rightarrow \alpha = 5.66 \frac{\text{rad}}{\text{s}^2}$$

$$\textcircled{1} F - 245.25 = -30(5.66) \Rightarrow F = 75.45 \text{ N}$$

For Plank,

$$\rightarrow \sum F_x = 0 \Rightarrow A_x + N_c \sin 30 - F \cos 30 - N_B \sin 30 = 0$$

$$\textcircled{2} A_x + 147.15 - N_B \sin 30 = 0$$

$$\uparrow \sum F_y = 0$$

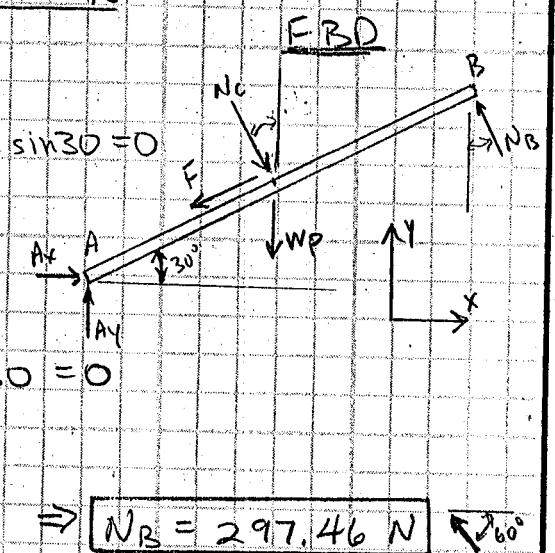
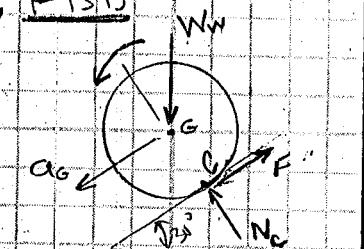
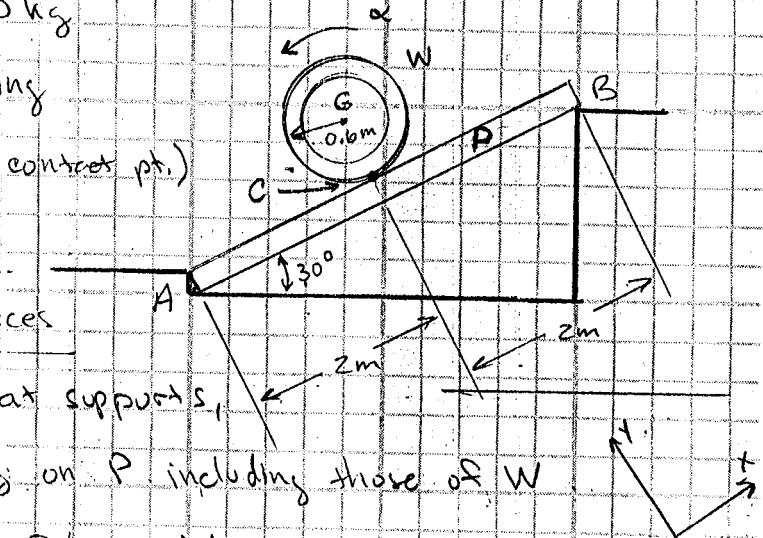
$$\Rightarrow A_y + N_B \cos 30 - N_c \cos 30 - W_p - F \sin 30 = 0$$

$$\textcircled{3} A_y + N_B \cos 30 = 602$$

$$\rightarrow \sum M_A = 0 \quad W_p(2 \cos 30) + N_c(2) - N_B(4) = 0 \Rightarrow N_B = 297.46 \text{ N} \quad \textcircled{4}$$

$$\textcircled{5} A_y + (297.46) \cos 30 = 602 \Rightarrow A_y = 344.4 \text{ N} \uparrow$$

$$\textcircled{6} A_x + 147.15 - (297.46) \sin 30 = 0 \Rightarrow A_x = 1.57 \text{ N} \rightarrow$$





Dynamics, 4-5-90

Professor Levy

Prob. 17-90

Given $W_D = 10 \text{ lb}$, $W_B = 21 \text{ lb}$

$$v_x = 0$$

$$\text{Det. } v_B - \omega t = 3 \text{ s}$$

$$\mu_s = 0.2, \mu_k = 0.15 \text{ at A}$$

For Disc $a_G = r\alpha$

$$\rightarrow \sum F_x = m(a_G)x \Rightarrow f + T = \left(\frac{10}{32.2}\right)(0.5)\alpha = \left(\frac{5}{32.2}\right)\alpha$$

$$\uparrow \sum F_y = m(a_G)y \Rightarrow N - W_D = 0 \Rightarrow N = 10 \text{ lbs}$$

$$\rightarrow \sum M_G = I_G\alpha \Rightarrow J(0.5) - S(0.5) = \frac{1}{2} \left(\frac{10}{32.2}\right)(0.5)^2 \alpha$$

$$\Rightarrow 0.5(T-f) = \frac{1.25}{32.2} \alpha \Rightarrow T-f = \frac{2.5}{32.2} \alpha$$

For Block

$$\uparrow \sum F_y = m(a_B)y \Rightarrow 2T - W_B = -\left(\frac{4}{32.2}\right)a_B$$

$$\Rightarrow 2T - 4 = -\frac{4}{32.2}a_B \Rightarrow 2T = 4 - \frac{4}{32.2}a_B$$

$$\textcircled{1} \& \textcircled{2} \quad T + f = \frac{5}{32.2}\alpha + T - f = \frac{2.5}{32.2}\alpha$$

$$\textcircled{5} \quad \Rightarrow 2T = \frac{7.5}{32.2}\alpha \Rightarrow 2T = \frac{15}{32.2}a_B$$

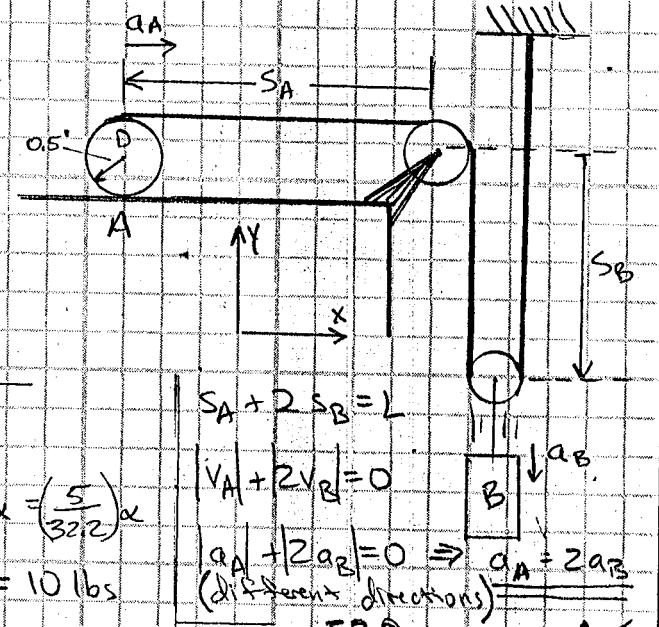
$$\textcircled{4} \& \textcircled{5} \quad 4 - \frac{4}{32.2}a_B = \frac{15}{32.2}a_B \Rightarrow 4 = \frac{19}{32.2}a_B$$

$$a_B = 6.78 \text{ ft/s}^2$$

$$v_F = v_0 + at$$

$$v_F = 6.78(3)$$

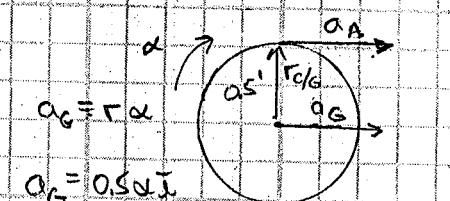
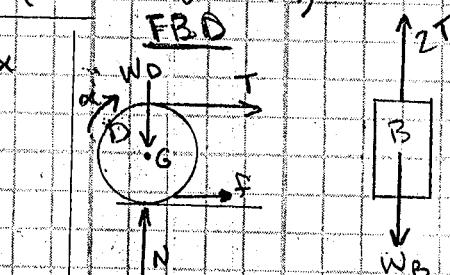
$$v_F = 20.34 \text{ ft/s}$$



$$f_A + 2f_B = 0$$

$$N_A + 2N_B = 0$$

$$f_A + 2f_B = 0 \Rightarrow f_A = 2f_B \quad (\text{dir. of each direction})$$



$$a_G = r\alpha$$

$$a_A = a_G + a_{CG}$$

$$a_A = 0.5\alpha + (-\alpha \sin 30^\circ)$$

$$a_A = 0.5\alpha + 0.5\alpha$$

$$a_A = \alpha, \text{ if } a_A = 2a_B$$



Dynamics, 4-5-90

Professor Levy

Prob. 17-98 cont.

So far, we have:

$$① 4(g - (a_G)_y) \cos \theta - 6(a_G)_x \sin \theta = L\alpha$$

$$② (a_G)_x = a_A - \frac{L}{2} \alpha \sin \theta, (a_G)_y = \frac{L}{2} \alpha \cos \theta$$

$$③ a_A = L\alpha \sin \theta$$

$$3 \Rightarrow ④ (a_G)_x = L\alpha \sin \theta - \frac{L}{2} \alpha \sin \theta = \frac{L}{2} \alpha \sin \theta$$

$$(2b) \& (4) \rightarrow (1) \Rightarrow 6\left(g - \frac{L}{2} \alpha \cos \theta\right) \cos \theta - 6\left(\frac{L}{2} \alpha \sin \theta\right) \sin \theta = L\alpha$$

$$6g \cos \theta - 3L\alpha \cos^2 \theta - 3L\alpha \sin^2 \theta = L\alpha$$

$$6g \cos \theta - L\alpha = 3L\alpha (\cos^2 \theta + \sin^2 \theta)$$

$$4L\alpha = 6g \cos \theta$$

$$\boxed{\alpha = \frac{3g \cos \theta}{2L}}$$



Florida International University
The State University of Florida at Miami

College of Engineering & Applied Sciences

Dynamics, 4-5-90 | Professor Levy

PROB. 17-98

Given: mass m , no friction

Det α : when released from rest from position θ and allowed to slide downward

from rest $\omega = 0$

$$\leftarrow \sum F_x = m(a_G)_x \Rightarrow B_x = m(a_G)_x$$

$$\downarrow \sum F_y = m(a_G)_y \Rightarrow W - A_y = m(a_G)_y$$

$$\leftarrow \sum M_G = I_G \alpha$$

$$\Rightarrow A_y \left(\frac{L}{2} \right) \cos \theta - B_x \left(\frac{L}{2} \right) \sin \theta = \frac{1}{12} m L^2 \alpha$$

$$\Rightarrow (W - m(a_G)_y) \left(\frac{L}{2} \right) \cos \theta + m(a_G)_x \left(\frac{L}{2} \right) \sin \theta = \frac{1}{12} m L^2 \alpha$$

$$\Rightarrow (W - m(a_G)_y) \cos \theta - (m(a_G)_x) \sin \theta = \frac{1}{12} m L^2 \alpha$$

$$\Rightarrow (g - (a_G)_y) \cos \theta - (a_G)_x \sin \theta = \frac{1}{12} m L^2 \alpha$$

$$a_G = a_A + a_G/A, \omega = 0 \Rightarrow (a_G/A)_n = 0$$

$$\alpha = -\alpha \bar{\kappa}, r_{G/A} = -\frac{L}{2} \cos \theta \bar{i} - \frac{L}{2} \sin \theta \bar{j}$$

$$a_{Gx} \bar{i} + a_{Gy} \bar{j} = a_A \bar{i} + (\alpha \times r_{G/A})$$

$$(a_{Gx}) \bar{i} + (a_{Gy}) \bar{j} = a_A \bar{i} + \frac{L}{2} \alpha \cos \theta \bar{j} - \frac{L}{2} \alpha \sin \theta \bar{i}$$

Eq. Coeff.

$$(a_G)_x = a_A - \frac{L}{2} \alpha \sin \theta, (a_G)_y = \frac{L}{2} \alpha \cos \theta$$

$$a_B = a_A + a_B/A, \omega = 0 \Rightarrow (a_B/A)_n = 0, \alpha = -\alpha \bar{\kappa}, r_{B/A} = -L \cos \theta \bar{i} - L \sin \theta \bar{j}$$

$$a_{Bx} \bar{i} + a_{By} \bar{j} = a_A \bar{i} + L \alpha \cos \theta \bar{j} - L \alpha \sin \theta \bar{i}$$

Eq. Coeff.

$$a_B = L \alpha \cos \theta$$

$$0 = a_A - L \alpha \sin \theta \Rightarrow a_A = L \alpha \sin \theta$$

