

Solution of BVP's can use both shooting & FD

FD to linear ODE's lead to tri-diagonal systems

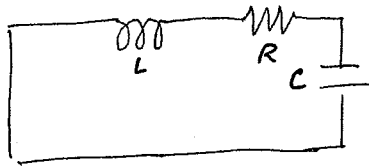
FD to non linear ODE " " an iterative method

- advantage (no need to convert to a set of 1st order ODE's)
- accuracy depends on mesh size (smaller mesh - more eqns)
- shooting method can be used for linear & non linear ODEs
 - easy to implement since we can use IVP method (RK, Adams etc)
 - no guarantee of convergence. When it converges, they converge faster than ~~the~~ FD

STIFF ODES ARISE

- WHEN SYSTEM IS MODELED BY DIFF. EQS WHOSE EIGENVALUES VARY WIDELY

- CONTROL SYSTEMS
- SYSTEMS W/ FLUID BOUNDARY LAYERS
- ELECTRICAL CIRCUITS
- CAUSE PROBLEMS OF STABILITY & ACCURACY



$$\frac{R}{L} = 10,001 \frac{1}{\text{sec}}$$

$$\frac{1}{LC} = 10,000 \frac{1}{\text{sec}^2}$$

Consider circuits in which

$$\frac{d^2v}{dt^2} + \frac{R}{L} \frac{dv}{dt} + \frac{1}{LC} v = 0$$

with $v(0) = 1$ volt & $\frac{dv}{dt}(0) = -1$ volt/sec

solution will be $v = e^{st}$ & $(s^2 + \frac{R}{L}s + \frac{1}{LC}) e^{st} = 0 \Rightarrow s^2 + 10,001s + 10,000 = 0$

and $v = a e^{-t} + b e^{-10000t}$

• EV are -1 & -10000 i.e. $(s+10000)(s+1) = 0$

• IC give that $a = 1$ $b = 0 \Rightarrow v = e^{-t}$

5th order or Adams Moulton

however: Runge Kutta blows up (10^{293} volts in 0.2 sec) using $\Delta t = .001$

• unstable at $\Delta t = 5 \times 10^{-4}$

• using $\Delta t = 1 \times 10^{-4}$ sec works i.e. Δt is governed by EV which is

larger i.e. 10000

• must use larger EV to determine Δt i.e. $e^{-st} \sim e^{-1}$ & $|st| \approx 1 \Rightarrow t = \frac{1}{|s|}$

Total Error in Solution of D.E.

depends on

1) Round off error ^{due to significant digits} (~~integration~~ error)

2) Truncation ~~error~~ error due to representation of y' ^{by an approximate formula} (stepsize error)

3) e_{n+1} depends on errors that existed before hand i.e. $e_{n+1} = f(e_n)$
at some step

- Double Precision can combat round off error.
- RK or RKF or formulas that have ~~high~~ high α $O(h^\alpha)$ can take care of truncation errors.
- Stable methods can reduce effects of truncation errors.

SELECTING A NUMERICAL INTEGRATION METHOD

- IF RANGE OF INTEGRATION MODERATE (COMPUTING TIME NOT A FACTOR)
& NO NEED FOR STEP SIZE CONTROL USE R-K
- IF MANY INTEGRATIONS MUST BE DONE (TIME IS IMPORTANT)
BUT ACCURACY NOT REQUIRED USE MODIFIED EULER
- IF RANGE OF INTEGRATION LARGE $\Rightarrow$ COMPUTING TIME IMPORTANT
USE HIGH ORDER ACCURACY LIKE ADAMS-MOULTON
- IF COMPUTING TIME IS NOT IMPORTANT BUT NEED ACCURACY USE RK45