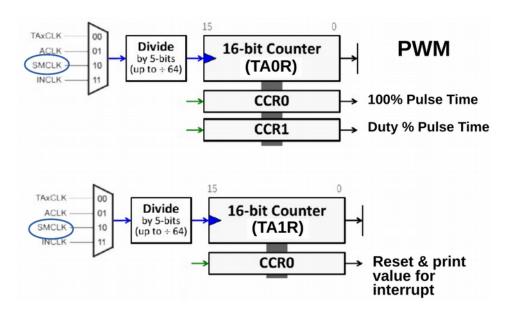
TA0 generates PWM, fixed duty cycle, and TA1 periodically changes the duty cycle value



Connect LaunchPad, download and run - sketch PWMWatsonFade.ino

## DOCUMENT:

Include a screen shot of the 'Successful' download of the code

Include a screen shot of the Serial Plotter showing the waveforms

Include a listing of the sketch code as you run it

Refer to the following initialization code from the 'ino' and answer the questions

## Set Timer for fixed Duty Cycle PWM

- 1. Does the Set-Up lines 54-58 require an interrupt service routine?
- 2. What is the duty cycle after initialization?
- 3. What type of waveform does OUTMOD 7 produce?

## M7 Assignment Timer PWM

- 4. Which mode is used with the counter?
- 5. Which clock signal is used with the counter?
- 6. Which Timer is used in lines 54-58?

```
/*** Timerl_A Set-Up ***/
TAlCCR0 |= 4000;  // Counter value
TAlCCTL0 |= CCIE;  // Enable Timerl_A interrupts
TAlCTL |= TASSEL_2 + MC_1;  // SMCLK, Up Mode (Counts to TAlCCR0)
```

- 7. Lines 60-63 use which Timer?
- 8. What sets the compare register to the count value?
- 9. What frequency is the input clock signal?
- 10. How often with the timer interrupt?
- 11. Output mode is used in this timer?

```
68
69 #pragma vector=TIMER1 AO VECTOR
     __interrupt void Timerl_AO (void) {
71
72
      TAOCCR1 += IncDec PWM;
73
      if( TAOCCR1 > 998 || TAOCCR1 < 2 )
74
         IncDec PWM = -IncDec PWM;
75
76
      // print every 10th value
      if (!DeciMate--)
77
78
79
        DeciMate=10;
        printf("%d\n", TAOCCR1);
80
81
```

- 12. ISR to change duty cycle
- 13. Which timer is the ISR for?
- 14. Which timer CCR value is being modified
- 15. Line 74 reverses the count direction when?

## VIDEO:

Show 'Successful' of download screen from your monitor

Show the board with Green LED fading

Show screen with the Serial Plotter waveform

Be sure to say your name, date, and time