Chapter 6: Mechanical Properties

Why mechanical properties?

Need to design materials that can withstand applied load...

e.g. materials used in building bridges that can hold up automobiles, pedestrians...



materials for skyscrapers in the Windy City...





materials for space exploration...

NASA

materials for and designing MEMs and NEMs...







ISSUES TO ADDRESS...

- Stress and strain: What are they and why are they used instead of load and deformation?
- Elastic behavior: When loads are small, how much deformation occurs? What materials deform least?
- Plastic behavior: At what point does permanent deformation occur? What materials are most resistant to permanent deformation?
- Toughness and ductility: What are they and how do we measure them?



Stress and Strain

Stress: Pressure due to applied load.

tension, compression, shear, torsion, and their combination.

stress =
$$\sigma = \frac{force}{area}$$

Strain: response of the material to stress (i.e. physical deformation such as elongation due to tension).





COMMON STATES OF STRESS

• Simple tension: cable-

 $F \leftarrow F$ $A_0 = \text{cross sectional}$ Area (when unloaded) $\sigma = \frac{F}{A_0} \quad \sigma \leftarrow \sigma$



Ski lift (photo courtesy P.M. Anderson)

From Callister 6e resource CD.



COMMON STATES OF STRESS

• Simple compression:



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COMMON STATES OF STRESS

• Hydrostatic compression:



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Tension and Compression



Engineering stress = $\sigma = \frac{F}{A_o}$ Engineering strain = $\mathcal{E} = \frac{l_i - l_o}{l_o} = \frac{\Delta l}{l_o}$ A_o = original cross sectional area l_i = instantaneous length l_o = original length Note: strain is unitless.

<u>Compression</u>

Same as tension but in the opposite direction (stress and strain defined in the same manner).

By convention, stress and strain are negative for compression.

Shear



Pure shear stress = $\tau = \frac{F}{A_o}$

Pure shear strain = $\gamma = \tan \theta$

Strain is always dimensionless.



Elastic Deformation



Plastic Deformation (Metals)



Stress-Strain Testing



Adapted from Fig. 6.3, Callister 7e. (Fig. 6.3 is taken from H.W. Hayden, W.G. Moffatt, and J. Wulff, The Structure and Properties of Materials, Vol. III, Mechanical Behavior, p. 2, John Wiley and Sons, New York, 1965.)

Adapted from Fig. 6.2, Callister 7e.



Linear Elastic Properties



For metals, typically $E \sim 45 - 400$ GPa

Note: some materials do not have linear elastic region (e.g. cast iron, concrete, many polymers...)

Define secant modulus and tangent modulus.



	Moo Ela	dulus of asticity	Shear	Poisson's	
Metal Alloy	GPa	10 ⁶ psi	GPa	10 ⁶ psi	Ratio
Aluminum	69	10	25	3.6	0.33
Brass	97	14	37	5.4	0.34
Copper	110	16	46	6.7	0.34
Magnesium	45	6.5	17	2.5	0.29
Nickel	207	30	76	11.0	0.31
Steel	207	30	83	12.0	0.30
Titanium	107	15.5	45	6.5	0.34
Tungsten	407	59	160	23.2	0.28

Table 6.1Room-Temperature Elastic and Shear Moduli, andPoisson's Ratio for Various Metal Alloys

Silicon (single crystal) Glass (pyrex) SiC (fused or sintered) Graphite (molded) High modulus C-fiber **Carbon Nanotubes** 120 - 190 (depends on crystallographic direction) 70 207 - 483 ~12 400 ~**1000**



If we normalize to density: ~20 times that of steel wire Density normalized strength is ~56X that of steel

Poisson Ratio

So far, we've considered stress only along one dimension...



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Poisson Ratio

• *Poisson Ratio* has a range $-1 \le v \le 1/2$

Look at extremes

• No change in aspect ratio: $\Delta w / w = \Delta \ell / \ell$

$$\nu = -\frac{\Delta w / w}{\Delta \ell / \ell} = -1$$

• Volume (V = AL) remains constant: $\Delta V = 0$ or $l\Delta A = -A \Delta l$

Hence,
$$\Delta V = (l \Delta A + A \Delta l) = 0$$
.

In terms of width, $A = w^2$, and $\Delta A = w^2 - (w + \Delta w)^2 = 2w \Delta w + \Delta w^2$

then
$$\Delta A/A = 2 \Delta w/w + \Delta w^2/w^2$$





Poisson's ratio, v



Units: *E*: [GPa] or [psi] v: dimensionless

- -v > 0.50 density increases
- -v < 0.50 density decreases (voids form)



Poisson Ratio: materials specific

Metals:	lr 0.26	W 0.29	Ni 0.31	Cu 0.34	AI 0.34	Ag 0.38	Au 0.42
Solid Argon:	0.25					generik	
Covalent Sol	ids:	Si 0.27	Ge 0.28	Al ₂ O ₃ 0.23	TiC 0.19	generio	c value ~ 1/4
Ionic Solids:	MgO	0.19					
Silica Glass:	0.20						
Polymers: N	letwork	(Bakelit	te) 0.49	Cha	ain (PE)	0.40	
Elastomer:	Hard F	Rubber	(Ebonit	e) 0.39	(Natu	ral) 0.49	
						Cha	apter 6 - 19

Mechanical Properties

 Slope of stress strain plot (which is proportional to the elastic modulus) depends on bond strength of metal



Other Elastic Properties



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Young's Moduli: Comparison



Based on data in Table B2, Composite data based on reinforced epoxy with 60 vol%



Useful Linear Elastic Relationships

Simple tension:

Simple torsion:



- Material, geometric, and loading parameters all contribute to deflection.
- Larger elastic moduli minimize elastic deflection.



Plastic (Permanent) Deformation



- •A permanent deformation (usually considered for $T < T_m/3$).
- •Atoms break bonds and form new ones.

•In metals, plastic deformation occurs typically at strain ≥0.005.



Adapted from Fig. 6.10 (a),

Tensile properties

A. <u>Yield strength</u> (σ_y): the strength required to produce a very slight yet specified amount of plastic deformation.

What is the specified amount of strain?





- 1. Start at 0.002 strain (for most metals).
- 2. Draw a line parallel to the linear region.

3. σ_y = where the dotted line crosses the stress-strain curve.

P = proportional limit (beginning of deviation from linear behavior.

Mixed elastic-plastic behavior

For materials with <u>nonlinear</u> elastic region: σ_y is defined as stress required to produce specific amount of strain (e.g. ~0.005 for most metals)

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Tensile properties

Yield point phenomenon occurs when elastic-plastic transition is welldefined and abrupt.



Yield Strength : Comparison



Tensile Strength, TS

• Maximum stress on engineering stress-strain curve.



- Metals: occurs when noticeable necking starts.
- Polymers: occurs when polymer backbone chains are aligned and about to break.



True stress and strain



Notice that past maximum stress point, σ decreases.

Does this mean that the material is becoming weaker?

 A_o — Original cross sectional area!

Necking leads to smaller cross sectional area!

Recall: Engineering Stress = $\sigma = \frac{F}{A}$

True Stress =
$$\sigma_T = \frac{F}{A_i}$$

True Strain = $\mathcal{E}_T = \ln \frac{l_i}{l_o}$

 A_i = instantaneous area l_i = instantaneous length

If no net volume change (i.e. $A_i l_i = A_o l_o$)

$$\begin{array}{c} \sigma_T = \sigma(1 + \varepsilon) \\ \varepsilon_T = \ln(1 + \varepsilon) \end{array} \end{array} \quad \begin{array}{c} \text{Only true at the onset of} \\ \text{necking} \\ \text{Chapter 6 - 29} \end{array}$$

Example problem



FIGURE 6.12 The stress–strain behavior for the brass specimen discussed in Example Problem 6.3.

Calculate/determine the following for a brass specimen that exhibits stress-strain behavior shown on the left.

- 1) Modulus of elasticity.
- 2) Yield strength.
- 3) Maximum load for a cylindrical specimen with d = 12.8mm.
- Change in length at 345MPa if the initial length is 250mm.



Tensile Strength : Comparison



Tensile properties

C. <u>Ductility</u>: measure of degree of plastic deformation that has been sustained at fracture.

- **Ductile materials** can undergo significant plastic deformation before fracture.
- **Brittle materials** can tolerate only very small plastic deformation.



FIGURE 6.13 Schematic representations of tensile stress–strain behavior for brittle and ductile materials loaded to fracture.



Ductility

• Plastic tensile strain at failure:





• Another ductility measure:

$$\% RA = \frac{A_o - A_f}{A_o} \times 100$$

Toughness

- · Energy to break a unit volume of material
- Approximate by the area under the stress-strain curve.



Brittle fracture: elastic energy Ductile fracture: elastic + plastic energy



Resilience, U_r

- Ability of a material to store energy
 - Energy stored best in elastic region



 $U_r = \int_0^{\varepsilon_y} \sigma d\varepsilon$

If we assume a linear stress-strain curve this simplifies to

$$U_r \cong \frac{1}{2} \sigma_y \varepsilon_y$$

Adapted from Fig. 6.15, *Callister 7e.*



Elastic recovery after plastic deformation



FIGURE 6.17 Schematic tensile stress–strain diagram showing the phenomena of elastic strain recovery and strain hardening. The initial yield strength is designated as σ_{y_0} ; σ_{y_i} is the yield strength after releasing the load at point *D*, and then upon reloading.

> This behavior is exploited to increase yield strengths of metals: **strain hardening** (also called **cold working**).



Hardness

- Resistance to permanently indenting the surface.
- Large hardness means:
 - --resistance to plastic deformation or cracking in compression.
 - --better wear properties.



Hardness: Measurement

- Rockwell
 - No major sample damage
 - Each scale runs to 130 but only useful in range 20-100.
 - Minor load 10 kg
 - Major load 60 (A), 100 (B) & 150 (C) kg
 - A = diamond, B = 1/16 in. ball, C = diamond
- HB = Brinell Hardness
 - -TS (psia) = 500 x HB
 - TS (MPa) = 3.45 x HB



Hardness scales



Hardness: Measurement

		Shape of Indenta		Formula for	
Test	Indenter	Side View	Top View	Load	Hardness Number ^a
Brinell	10-mm sphere of steel or tungsten carbide		_; ⊷ d «	Р	$HB = \frac{2P}{\pi D[D - \sqrt{D^2 - d^2}]}$
Vickers microhardness	Diamond pyramid			Р	$HV = 1.854P/d_1^2$
Knoop microhardness	Diamond pyramid	<i>l/b</i> = 7.11 <i>b/t</i> = 4.00		Р	$\mathbf{HK} = 14.2P/l^2$
Rockwell and Superficial Rockwell	$\begin{cases} Diamond \\ cone \\ \frac{1}{16}, \frac{1}{8}, \frac{1}{4}, \frac{1}{2} \text{ in.} \\ diameter \\ steel spheres \end{cases}$			60 100 150 15 30 45	kg kg kg kg Superficial Rockwell kg

Table 6.5 Hardness Testing Techniques

^a For the hardness formulas given, P (the applied load) is in kg, while D, d, d₁, and l are all in mm.

Source: Adapted from H. W. Hayden, W. G. Moffatt, and J. Wulff, *The Structure and Properties of Materials*, Vol. III, *Mechanical Behavior*. Copyright © 1965 by John Wiley & Sons, New York. Reprinted by permission of John Wiley & Sons, Inc.

True Stress & Strain

Note: S.A. changes when sample stretched

- True stress $\sigma_{\tau} = F/A_i$ $\sigma_{\tau} = \sigma(1+C)$
- True Strain $\epsilon_T = \ln(\ell_i / \ell_o)$





Hardening

• An increase in σ_v due to plastic deformation.



• Curve fit to the stress-strain response:



Variability in Material Properties

- Elastic modulus is material property
- Critical properties depend largely on sample flaws (defects, etc.). Large sample to sample variability.
- Statistics





where *n* is the number of data points



Design or Safety Factors

- Design uncertainties mean we do not push the limit.
- Factor of safety, N



• Example: Calculate a diameter, *d*, to ensure that yield does not occur in the 1045 carbon steel rod below. Use a factor of safety of 5.



Summary

- Stress and strain: These are size-independent measures of load and displacement, respectively.
- Elastic behavior: This reversible behavior often shows a linear relation between stress and strain. To minimize deformation, select a material with a large elastic modulus (*E* or *G*).
- Plastic behavior: This permanent deformation behavior occurs when the tensile (or compressive) uniaxial stress reaches σ_ν.
- Toughness: The energy needed to break a unit volume of material.
- Ductility: The plastic strain at failure.

