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efficients but if a_i shown in

(8.17)

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(8.18)

her-order ond-order one filter pler filter We characterize each second-order filter section by the frequencies of the magnitude response extremes and by the 3-dB frequencies. The 3-dB frequencies, denoted by $f_{3dB} = \theta_{3dB}/(2\pi)$, are frequencies at which the magnitude response $M(f) = |H(e^{j2\pi f})|$ is $\sqrt{2}$ times smaller than the magnitude response at some reference frequency f_r (3 dB only approximately corresponds to $\sqrt{2}$, strictly speaking it is $10^{3/20}$):

$$\frac{M(f_{3dB})}{M(f_r)} = \frac{|H(e^{j2\pi f_{3dB}})|}{|H(e^{j2\pi f_r})|} = \frac{1}{\sqrt{2}}$$
(8.19)

For example, for lowpass filters, the reference frequency is $f_r = 0$.

In filter design, we prefer to use the *normalized transfer function*, $H_n(z)$, defined by

$$H_n(z) = \frac{H(z)}{\max_f M(f)}$$
(8.20)

The transfer function can be obtained by scaling the normalized transfer function by a constant:

$$H(z) = kH_n(z) (8.21)$$

Quite generally, the normalization constant k can take any real value.

8.2.1 Second-Order Transfer Functions

In this section we analyze the properties of the basic second-order transfer functions. We examine the magnitude response $M(f) = |H(e^{j2\pi f})|$ for real positive digital angular frequencies $\theta = 2\pi f$. The angular frequencies of the magnitude response local extrema are designated by $\theta_e = 2\pi f_e$. We find it convenient to define the frequency f_j at which the frequency response becomes purely imaginary, $\text{Re}(H(e^{j2\pi f_j})) = 0$.

Lowpass Transfer Function. The second-order lowpass transfer function is defined

$$H_{LP}(z) = \frac{1+a+b}{4} \frac{(z+1)^2}{z^2+bz+a} = \frac{1+a+b}{4} \frac{(1+z^{-1})^2}{1+bz^{-1}+az^{-2}}$$
(8.22)

At higher frequencies $(f > f_i > f_e)$, where

$$f_j = \frac{1}{2\pi} \cos^{-1} \frac{-b}{1+a} \tag{8.23}$$

the magnitude response $M(f) = |H_{LP}(e^{j2\pi f})|$ decreases and, thus, high-frequency sinusoidal sequences are rejected.

The key properties of the lowpass transfer function are summarized below:

$$M(0) = H_{LP}(1) = 1, z = 1, f = 0$$

$$M(0.5) = H_{LP}(-1) = 0, z = -1, f = 0$$

$$M(f_j) = |H_{LP}(e^{j2\pi f_j})| = |jQ_p| = Q_p, z = e^{j2\pi f_j}, f = f_0$$

$$M_e = \max_{0 \le f \le 0.5} (M(f)) = |H_{LP}(e^{j2\pi f_e})| = \frac{Q_p}{\sqrt{1 - \frac{1}{4Q_p^2}}}, z = e^{j2\pi f_e}, f = f_0$$
where f_e is the frequency at which $M(f)$ has its maximal value M_e :

where f_e is the frequency at which M(f) has its maximal value M_e :

$$f_e = \frac{1}{2\pi} \cos^{-1} \frac{(1-a)^2 - b(1+a-b)}{4a-b-ab}$$
 (82)

and the pole Q-factor is

$$Q_p = \frac{\sqrt{(1+a)^2 - b^2}}{2(1-a)} \tag{82}$$

The maximal value of the magnitude response is approximately equal to Q_p for $Q_p \gg 1$ (i.e., for $a \approx 1$), as shown in Fig. 8.8:

$$\max_{0 \le f \le 0.5} \left| H_{LP} \left(e^{j2\pi f} \right) \right| = \left| H_{LP} \left(e^{j2\pi f_e} \right) \right| \approx Q_p, \quad f_e \approx f_j, \quad Q_p \gg 1$$
 (82)

This fact is very important for digital filters implemented in fixed point arithmetic Suppose that the filter output sequence, y_k , must be bounded to $-1 \le y_k \le 1$. That the amplitude of the sinusoidal sequence of frequency f_e , at the input of the lowest second-order filter, must be smaller than $1/Q_p$, so that, after filtering, the amplitude the output sequence remains within the prescribed range, $-1 \le y_k \le 1$.

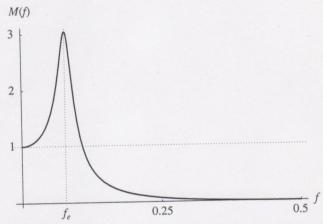


Figure 8.8 Magnitude of second-order lowpass transfer function: $Q_p = 3$, a = 0.85117, and b = -1.621545.

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$$H_{LPn}(z) = \frac{F}{-}$$

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For $Q_p \leq 1/\sqrt{2}$ $1/\sqrt{2}$ the maximal ma

The maximal val M_e , in terms of the coe approaches to 1, while

Highpass Transfer Full

$$H_{HP}(z) = \frac{1+a}{4}$$



Figure lowpa

The maximal value of the magnitude response, M_e , can be expressed in terms of the coefficients a and b:

$$M_e = \max_{0 \le f \le 0.5} (M(f)) = \frac{(1+a)^2 - b^2}{2(1-a)\sqrt{4a-b^2}}$$
(8.28)

The magnitude of the normalized transfer function, $H_{LPn}(z)$, is shown in Fig. 8.9. This normalized transfer function is defined as

$$H_{LPn}(z) = \frac{H_{LP}(z)}{M_e} = \frac{(1-a)\sqrt{4a-b^2}}{2(1+a-b)} \frac{(z^{-1}+1)^2}{1+bz^{-1}+az^{-2}}$$
(8.29)

and it has the maximal magnitude, equal to 1, at the frequency f_e .

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.25)

.26)

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For $Q_p \le 1/\sqrt{2}$ we find $f_e = 0$ as shown in Fig. 8.10. Therefore, for $1/2 < Q_p \le 1/\sqrt{2}$ the maximal magnitude function is at frequency $f_e = 0$.

The maximal value of the magnitude of second-order lowpass transfer functions, M_e , in terms of the coefficients is shown in Fig. 8.11. M_e dramatically increases when a approaches to 1, while the influence of b is negligible.

Highpass Transfer Function. The second-order *highpass transfer function* is defined as

$$H_{HP}(z) = \frac{1+a-b}{4} \frac{(z-1)^2}{z^2+bz+a} = \frac{1+a-b}{4} \frac{(z^{-1}-1)^2}{1+bz^{-1}+az^{-2}}$$
(8.30)

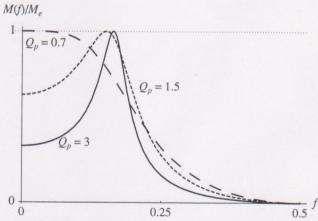


Figure 8.9 Magnitude of second-order normalized lowpass transfer functions $M(f)/M_e$: $Q_p = 3, 1.5, 0.7$.

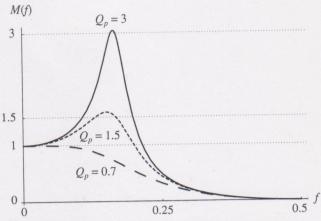


Figure 8.10 Magnitude of second-order lowpass transfer functions: $Q_p = 3, 1.5, 0.7$.

At lower frequencies, $f < f_j < f_e$, where

$$f_j = \frac{1}{2\pi} \cos^{-1} \frac{-b}{1+a} \tag{83}$$

the magnitude response $M(f) = |H_{HP}(e^{j2\pi f})|$ decreases when f approaches zero and, thus, low-frequency sinusoidal sequences are rejected, while the high-frequency sinusoidal sequences, $f \geq f_p$, pass without attenuation.

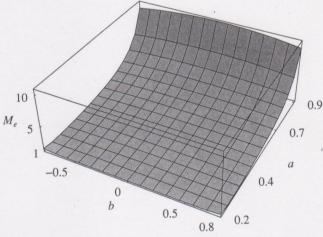


Figure 8.11 Maximal value of magnitude of second-order lowpass transfer functions in terms of filter coefficients.

The key proper

$$M(0) = H_{HP}(1) =$$
 $M(0.5) = H_{HP}(-1)$
 $M(f_j) = |H_{HP}(e^{j2\pi})|$
 $M_e = \max_{0 \le f \le 0.5} (M(f))$

where f_e is the frequency

 f_{ϵ}

and the pole Q-factor

The maximal va $Q_p \gg 1$ (i.e., for $a \approx$

$$\max_{0 \le f \le 0.5} \left| H_{HP} \left(e^{j2} \right. \right|$$

As in the case of response is approximathat $f_e = 0.5$, as show



Figure trans b = 0

The key properties of the highpass transfer function are summarized below:

$$M(0) = H_{HP}(1) = 0, z = 1, f = 0$$

$$M(0.5) = H_{HP}(-1) = 1, z = -1, f = 0.5$$

$$M(f_j) = |H_{HP}(e^{j2\pi f_j})| = |jQ_p| = Q_p, z = e^{j2\pi f_j}, f = f_j$$

$$M_e = \max_{0 \le f \le 0.5} (M(f)) = |H_{HP}(e^{j2\pi f_e})| = \frac{Q_p}{\sqrt{1 - \frac{1}{4Q_p^2}}}, z = e^{j2\pi f_e}, f = f_e$$

$$(8.32)$$

where f_e is the frequency at which M(f) has its maximal value M_e

$$f_e = -\frac{1}{2\pi} \cos^{-1} - \frac{(1-a)^2 + b(1+a+b)}{4a+b+ab}$$
 (8.33)

and the pole Q-factor is

ro

$$Q_p = \frac{\sqrt{(1+a)^2 - b^2}}{2(1-a)} \tag{8.34}$$

The maximal value of the magnitude response is approximately equal to Q_p for $Q_p \gg 1$ (i.e., for $a \approx 1$), as shown in Fig. 8.12:

$$\max_{0 \le f \le 0.5} \left| H_{HP} \left(e^{j2\pi f} \right) \right| = \left| H_{HP} \left(e^{j2\pi f_e} \right) \right| \approx Q_p, \quad f_e \approx f_j, \quad Q_p \gg 1$$
 (8.35)

As in the case of the lowpass transfer function, the maximal value of the magnitude response is approximately equal to Q_p , as shown in Fig. 8.12. For $Q_p \le 1/\sqrt{2}$ we find that $f_e = 0.5$, as shown in Fig. 8.13.

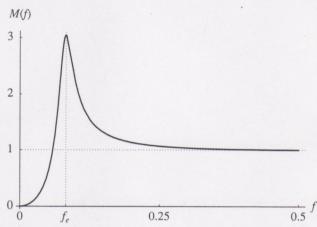


Figure 8.12 Magnitude of second-order highpass transfer function: $Q_p = 3$, a = 0.85117, and b = -1.621545.

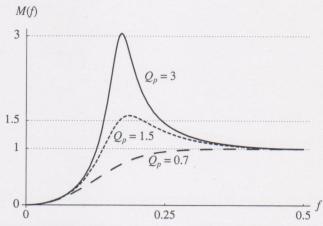


Figure 8.13 Magnitude of second-order highpass transfer functions: $Q_p = 3, 1.5, 0.7$.

The maximal value of the magnitude response, M_e , can be expressed in terms the coefficients a and b:

$$M_e = \frac{(1+a)^2 - b^2}{2(1-a)\sqrt{4a-b^2}} \tag{83}$$

The magnitude of the normalized transfer function, $H_{HPn}(z)$, is shown in Fig. 8.14. In normalized transfer function

$$H_{HPn}(z) = \frac{H_{HP}(z)}{M_e} = \frac{(1-a)\sqrt{4a-b^2}}{2(1+a+b)} \frac{(z^{-1}-1)^2}{1+bz^{-1}+az^{-2}}$$
(83)

has the maximal magnitude, equal to 1, at the frequency f_e .

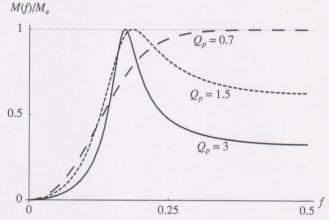


Figure 8.14 Magnitude of second-order normalized highpass transfer functions $M(f)/M_e$: $Q_p = 3$, 1.5, 0.7.

The maximal va M_e , in terms of the c functions shown in Fi

Bandpass Transfer F fined as

$$H_{BP}(z) =$$

The key properti

$$M(0) = H_{BP}(1) =$$

$$M(0.5) = H_{BP}(-1)$$

$$M_e = \max_{0 \le f \le 0.5} (M(f$$

where

The frequency at t times called the *resonal* Second-order ban cies $f_{low,3dB} < f < f_{low,3dB}$ 3dB), but reject sinusoid

$$\frac{1}{\sqrt{2}} \le M(f) =$$

$$|H_{BP}(e^{j2\pi f_{low,3dB}})| =$$

$$f_{low,3dB} =$$

$$f_{high,3dB} =$$

The pole Q-factor

The maximum of the $f_{low,3dB}$, is affected by Q_i (Fig. 8.16).

The maximal value of the magnitude of second-order highpass transfer functions, M_e , in terms of the coefficients is the same as for the second-order lowpass transfer functions shown in Fig. 8.11.

Bandpass Transfer Function. The second-order *bandpass transfer function* is defined as

$$H_{BP}(z) = \frac{1-a}{2} \frac{z^2 - 1}{z^2 + bz + a} = \frac{1-a}{2} \frac{1-z^{-2}}{1 + bz^{-1} + az^{-2}}$$
(8.38)

The key properties of the bandpass transfer function are summarized below:

$$M(0) = H_{BP}(1) = 0,$$
 $z = 1,$ $f = 0$
 $M(0.5) = H_{BP}(-1) = 0,$ $z = -1,$ $f = 0.5$ (8.39)
 $M_e = \max_{0 \le f \le 0.5} (M(f)) = |H_{BP}(e^{j2\pi f_e})| = 1,$ $z = e^{j2\pi f_e},$ $f = f_e$

where

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8.36)

This

8.37)

$$f_e = \frac{1}{2\pi} \cos^{-1} \frac{-b}{1+a} \tag{8.40}$$

The frequency at which the magnitude response reaches its maximum, f_e , is sometimes called the resonant frequency or the central frequency.

Second-order bandpass filters pass sinusoidal sequences from the band of frequencies $f_{low,3\text{dB}} < f < f_{high,3\text{dB}}$ with insignificant attenuation (less than $20\log_{10}\sqrt{2} \approx 3\text{dB}$), but reject sinusoidal sequences whose frequencies are on either side of this band:

$$\frac{1}{\sqrt{2}} \le M(f) = |H_{BP}(e^{j2\pi f})| \le 1, \quad f_{low,3dB} \le f \le f_{high,3dB}$$

$$|H_{BP}(e^{j2\pi f_{low,3dB}})| = |H_{BP}(e^{j2\pi f_{high,3dB}})| = \frac{1}{\sqrt{2}}$$

$$f_{low,3dB} = \frac{1}{2\pi} \cos^{-1} \frac{-b(1+a) - (1-a)\sqrt{2+2a^2-b^2}}{2(1+a^2)}$$

$$f_{high,3dB} = \frac{1}{2\pi} \cos^{-1} \frac{-b(1+a) + (1-a)\sqrt{2+2a^2-b^2}}{2(1+a^2)}$$
(8.41)

The pole Q-factor of the bandpass filter is

$$Q_p = \frac{\sqrt{(1+a)^2 - b^2}}{2(1-a)} \tag{8.42}$$

The maximum of the magnitude response is 1. The 3-dB bandwidth, $f_{high,3dB} - f_{low,3dB}$, is affected by Q_p (Fig. 8.15). Higher Q-factors produce narrower bandwidths (Fig. 8.16).